Lecture 26: Expectation Maximization(EM algorithm)

April 12, 2016

AIM: Suppose we get only partial observations/samples from a parametrized population, then how can we perform efficient maximum likelihood parameter estimation?

Applications:

- 1. Machine Learning
- 2. Clustering (Unsupervised learning)
- 3. Bio-informatics, Genomics, Speech Processing(BAUM-WELCH ALGORITHM)

1 Estimating Mixtures of Gaussians (MoG)

The MoG model is a joint distribution on (\boldsymbol{x}, z) with $\boldsymbol{x} \in \mathbb{R}^d, z \in [k]$ and z has multinomial distribution,

$$z \sim \text{Multinomial Distribution}(\boldsymbol{\phi})$$

i.e. Multinomial $[[\phi_1, \phi_2, ... \phi_k]^T]$ with $\phi_i \geq 0$; $\sum_{j=1}^k \phi_j = 1$. Given z, the random vector $\boldsymbol{x}|(z=j)$ is Gaussian distributed $\sim \mathcal{N}(\boldsymbol{\mu}_j, \Sigma_j)$. Here, $\boldsymbol{\phi}$ is the mixture distribution, $\{\boldsymbol{\mu}_j\}$ is the cluster centre and $\{\Sigma_j\}$ is the cluster size.

Example 1: For d = k = 2, let

$$oldsymbol{\mu}_1 = egin{bmatrix} 1 \\ 1 \end{bmatrix} \; ; \; oldsymbol{\mu}_2 = egin{bmatrix} -1 \\ -1 \end{bmatrix} \ \Sigma_1 = \Sigma_2 = I_2 \ oldsymbol{\phi} = egin{bmatrix} 0.5 & 0.5 \end{bmatrix}$$

Here, cluster concentration is uniform as seen in the Figure 1 and roughly centres of clusters are μ_1 and μ_2 .

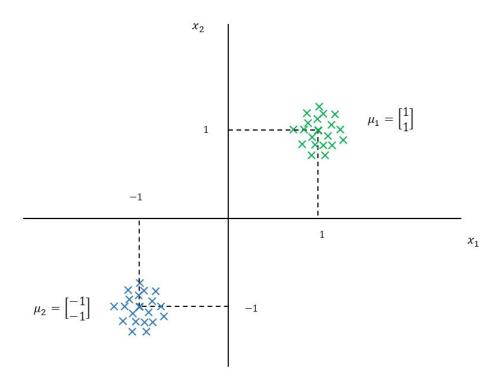


Figure 1: Example 1

Example 2: For d = k = 2, let

$$\boldsymbol{\mu}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \; ; \; \boldsymbol{\mu}_2 = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

$$\Sigma_1 = \Sigma_2 = I_2$$

$$\boldsymbol{\phi} = \begin{bmatrix} 0.25 & 0.75 \end{bmatrix}$$

Since the distribution is non-uniform, cluster density is also different (see Figure 2)

We define parameter

$$\theta \equiv (\boldsymbol{\phi}, \underbrace{\boldsymbol{\mu}_1, \boldsymbol{\mu}_2, ..., \boldsymbol{\mu}_k}_{\boldsymbol{\mu}}, \underbrace{\Sigma_1, \Sigma_2, ..., \Sigma_k}_{\Sigma})$$

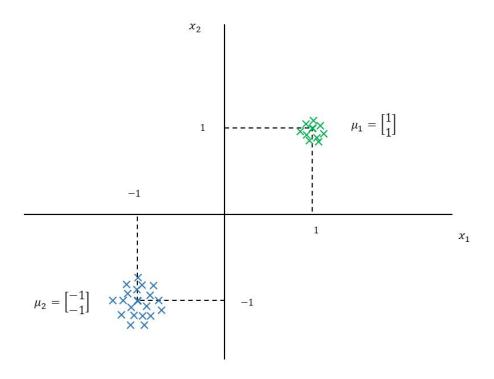


Figure 2: Example 2

Suppose we only observe $x_1, x_2, ..., x_m \in \mathbb{R}^d$ where $(x_i, z_i) \stackrel{iid}{\sim}$ mixture of Gaussians with parameter $\theta(\text{Here}, z_i \text{ is LATENT VARIABLE})$. We want to find the MAXIMUM LIKELIHOOD estimate of θ .

$$\theta_{\text{MLE}} = \underset{\theta \equiv (\boldsymbol{\phi}, \boldsymbol{\mu}, \Sigma)}{\operatorname{arg max}} \sum_{i=1}^{m} \log p\left(\boldsymbol{x_i} | \boldsymbol{\phi}, \boldsymbol{\mu}, \Sigma\right)$$
(1)

$$= \underset{\boldsymbol{\phi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}}{\operatorname{arg max}} \sum_{i=1}^{m} \log \sum_{z_{i} \in [k]} p\left(\boldsymbol{x}_{i}, z_{i} | \boldsymbol{\phi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}\right)$$
(2)

$$= \underset{\boldsymbol{\phi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}}{\operatorname{arg max}} \sum_{i=1}^{m} \log \sum_{z_{i}=1}^{k} \phi(z_{i}) f(\boldsymbol{x}_{i})$$
(3)

where $\boldsymbol{x_i}|(z=z_i) \sim \mathcal{N}\left(\boldsymbol{\mu}_{z_i}, \Sigma_{z_i}\right)$

This optimization is impossible to solve in closed form over (ϕ, μ, Σ) . However,

MLE solution is easy if $\{z_i\}_{i=1}^m$ were observed. In that case

$$\widetilde{\theta}_{\text{MLE}} = \underset{\boldsymbol{\phi}, \boldsymbol{\mu}, \Sigma}{\operatorname{arg max}} \sum_{i=1}^{m} \log p\left(\boldsymbol{x}_{i}, z_{i} | \boldsymbol{\phi}, \boldsymbol{\mu}, \Sigma\right)$$
(4)

$$= \underset{\boldsymbol{\phi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}}{\operatorname{arg max}} \sum_{i=1}^{m} \left[\log \phi(z_i) + \underset{\sim \mathcal{N}(\boldsymbol{\mu}_{z_i}, \boldsymbol{\Sigma}_{z_i})}{\log f(\boldsymbol{x_i})} \right]$$
(5)

$$= \underset{\boldsymbol{\phi}, \boldsymbol{\mu}, \Sigma}{\operatorname{arg max}} \sum_{i=1}^{m} \sum_{j=1}^{k} \mathbb{1}_{\{z_i = j\}} \left[\log \phi(j) + \log f(\boldsymbol{x_i}) \right]$$

$$\sim \mathcal{N}(\boldsymbol{\mu_j}, \Sigma_j)$$
(6)

$$= \underset{\boldsymbol{\phi}, \boldsymbol{\mu}, \Sigma}{\operatorname{arg max}} \left[\sum_{j=1}^{k} \log \phi(j) \sum_{i=1}^{m} \mathbb{1}_{\{z_{i}=j\}} + \sum_{j=1}^{k} \sum_{i=1}^{m} \mathbb{1}_{\{z_{i}=j\}} \log f(\boldsymbol{x}_{i}) \right]$$
(7)

$$= \left(\widetilde{\boldsymbol{\phi}}, \widetilde{\boldsymbol{\mu}}, \widetilde{\Sigma}\right) \tag{8}$$

where,

$$\widetilde{\mu}_j = \frac{\sum_{i=1}^m \mathbb{1}_{\{z_i=j\}} x_i}{\sum_{i=1}^m \mathbb{1}_{\{z_i=j\}}}$$
(9)

$$\widetilde{\Sigma}_{j} = \frac{1}{\sum_{i=1}^{m} \mathbb{1}_{\{z_{i}=j\}}} \sum_{i=1}^{m} \mathbb{1}_{\{z_{i}=j\}} \left(x_{i} - \widetilde{\mu}_{j} \right) \left(x_{i} - \widetilde{\mu}_{j} \right)^{T}$$
(10)

$$\overset{\sim}{\phi}_{j} = \frac{1}{m} \sum_{i=1}^{m} \mathbb{1}_{\{z_{i}=j\}} \tag{11}$$

Thus if $z_1, z_2...z_m$ are observed, we have an efficient way to solve this problem. This observation leads us to an algorithm that solves this problem efficiently.

2 EM algorithm

EM algorithm is an iterative algorithm involving two steps in every iteration. In the first step which is called the E-step, an arbitrary value for $\theta = (\phi, \mu, \Sigma)$ is assumed to guess the values for the latent variables $(z_1, z_2, ..., z_m)$. In the next step which is called the M-step, the guessed values for $(z_1, z_2, ..., z_m)$ are used to find the MLE solution for (ϕ, μ, Σ) which is easy to find as seen in the previous section. The *EM-algorithm* is described in Algorithm 1 in the next page.

Algorithm 1 EM algorithm

```
1: procedure
2: Initialize (\phi, \mu, \Sigma) arbitrarily.
3: Repeat until convergence {
4: E-step:
5: \forall i \in [m], j \in [k],
6: w_{ij} = \mathbb{P}[z_i = j | x_i, \phi, \mu, \Sigma].
7: M-step: Update procedure
8: \forall j \in [k].
9: \mu_j = \sum_{i=1}^m \left(\frac{w_{ij}x_i}{\sum\limits_{i=1}^m w_{ij}}\right), \Sigma_j = \sum_{i=1}^m \left(\frac{w_{ij}(x_i - \mu_j)(x_i - \mu_j)^T}{\sum\limits_{i=1}^m w_{ij}}\right),
10: \phi_j = \frac{1}{m} \sum_{i=1}^m w_{ij}.
11: }
```

In the next section we try to answer 2 fundamental questions related EM-algorithm:

- 1. Is there a deeper principle behind EM algorithm?
- 2. Does it converge?

3 General EM-algorithm

Before getting into the details of the *General EM-algorithm*, lets review the Jensen's inequality which is the tool used in this algorithm.

<u>Jensen's Inequality</u>: If X is a random variable and f() is a convex function (f() is a convex function if $\forall \lambda \in [0,1] f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y))$, then $f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]$.

Suppose we have the observations $x_1, x_2, ..., x_m$ where $(x_i, z_i) \stackrel{i.i.d}{\sim} f(x, z|\theta), \theta \in$

 Θ , MLE of θ given x is,

$$\hat{\theta}_{MLE} = \underset{\theta \in \Theta}{\operatorname{arg max}} \log L_{\theta}(x)$$

$$= \underset{\theta \in \Theta}{\operatorname{arg max}} \sum_{i=1}^{m} \log p(x_{i}|\theta)$$

$$= \underset{\theta \in \Theta}{\operatorname{arg max}} \sum_{i=1}^{m} \log \sum_{z} p(x_{i}, z_{i}|\theta)$$

If however, the MLE is easy with observed $\mathbf{z} = (z_1, z_2...z_m)$, then *EM-algorithms's* strategy is to construct an "easy" uniform lower bound for $L_{\theta}(x)$ across $\theta \in \Theta$ and maximize it.

For each $i \in [m]$, let Q_i be some distribution for Z. Consider,

$$\log L_{\theta}(x) = \sum_{i=1}^{m} \log \sum_{z_{i}} p(x_{i}, z_{i} | \theta)$$

$$= \sum_{i=1}^{m} \log \sum_{z_{i}} Q(z_{i}) \frac{p(x_{i}, z_{i} | \theta)}{Q(z_{i})}$$

$$\geq \sum_{i=1}^{m} \sum_{z_{i}} Q(z_{i}) \log \left[\frac{p(x_{i}, z_{i} | \theta)}{Q(z_{i})} \right] \quad (\text{-By Jensen's inequality}).$$

This uniform lower bound for $\log L_{\theta}(x)$ is valid for all choice of $Q_1, Q_2, ..., Q_m$. Suppose we choose $Q_1, Q_2, ..., Q_m$ such that the lower bound is tight at some $\theta \in \Theta$. This can be achieved if the random variable in Jensen's inequality is constant, which in turn implies,

$$\forall i \in [m], \frac{p(x_i, z_i | \theta)}{Q_i(z_i)} = C \quad (\text{-constant not depending on } z_i)$$

$$Q_i(z_i) = \frac{p(x_i, z_i | \theta)}{C}$$

$$Q_i(z_i) = \frac{p(x_i, z_i | \theta)}{\sum_{z_i} p(x_i, z_i | \theta)} \quad \forall z_i$$

$$= \frac{p(x_i, z_i | \theta)}{p(x_i | \theta)}$$

$$= p(z_i | x_i, \theta)$$

which is the posterior probability of z_i given x_i under pdf defined by θ . The General EM-algorithm is described in Algorithm 2 in the next page.

Algorithm 2 General EM algorithm

```
1: procedure
2: Initialize \theta \in \Theta arbitrarily.
3: Repeat until convergence {
4: E-step:
5: \forall i \in [m], \forall z_i,
6: Q_i(z_i) = p(z_i|x_i, \theta).
7: \underline{M}-step:
8: \theta \leftarrow \arg\max_{\theta \in \Theta} \sum_{i=1}^m \sum_{z_i} Q(z_i) \log\left[\frac{p(x_i, z_i|\theta)}{Q(z_i)}\right]
9: }
```

3.1 Convergence of EM-algorithm

Claim: Suppose $\theta_t \in \Theta$ and $\theta_{t+1} \in \Theta$ are parameters that are the outputs of 2 successive EM iterations. Then,

$$\log L_{\theta_t}(x) \le \log L_{\theta_{t+1}}(x).$$

Proof. Consider starting at $\theta_t \in \Theta$. Then, E-step chooses

$$Q_i^{(t)}(z_i) = p(z_i|x_i, \theta_t).$$

This makes Jensen's inequality tight at θ_t . Let

$$\log L_{\theta_t}(x) = \sum_{i=1}^m \sum_{z_i} Q_i^{(t)}(z_i) \log \left[\frac{p(x_i, z_i | \theta_t)}{Q_i^{(t)}(z_i)} \right] = g(\theta_t).$$

 θ_{t+1} is simply the maximizer of g() over $\theta \in \Theta$. Therefore, we must have

$$\log L_{\theta_{t+1}}(x) \overset{Jensen's}{\geq} \sum_{i=1}^{m} \sum_{z_i} Q_i^{(t)}(z_i) \log \left[\frac{p(x_i, z_i | \theta_{t+1})}{Q_i^{(t)}(z_i)} \right] = g(\theta_{t+1}) \geq g(\theta_t) = \log L_{\theta_t}(x).$$

Since $\log L_{\theta_t}(x)$ is a monotonically increasing sequence, the algorithm converges to a maximum (local) at infinity.