

Big O Notation

Big O Notation is used to describe the upper bound of an algorithm's running time. It focuses on the worst-case scenario and gives an idea of the algorithm's efficiency as the input size grows.

Common Rates of Growth

Constant:

$O(1)$

Logarithmic:

$O(\log n)$

Linearithmic:

$O(n \log n)$

Linear:

$O(n)$

Quadratic:

$O(n^2)$

Cubic:

$O(n^3)$

Exponential:

$O(2^n)$

Factorial:

$O(n!)$

Table of Algorithms, Time, and Space Complexities:

Algorithm	Time Complexity	Space Complexity	Use Case
Sorting Algorithms			
Bubble Sort	$O(n^2)$	$O(1)$	Simple but inefficient; use for small datasets.
Merge Sort	$O(n \log n)$	$O(n)$	Efficient sorting for large datasets.
Quick Sort	$O(n \log n)$ (Average)	$O(\log n)$	Fast sorting; worst-case $O(n^2)$

Heap Sort	$O(n \log n)$	$O(1)$	In-place, reliable sorting algorithm.
Insertion Sort	$O(n)^2$	$O(1)$	Efficient for small or nearly sorted arrays.
Searching Algorithms			
Linear Search	$O(n)$	$O(1)$	Simple search in unsorted data.
Binary Search	$O(\log n)$	$O(1)$	Fast search in sorted data.
Graph Algorithms			
Depth-First Search (DFS)	$O(V + E)$	$O(V)$	Exploring all vertices in a graph.
Breadth-First Search (BFS)	$O(V + E)$	$O(V)$	Shortest path in unweighted graphs.
Dijkstra's Algorithm	$O((V + E) \log V)$	$O(V)$	Shortest path in weighted graphs.
Bellman-Ford Algorithm	$O(V \times E)$	$O(V)$	Shortest path with negative weights.
Floyd-Warshall Algorithm	$O(V)^3$	$O(V)^2$	All-pairs shortest paths.

Algorithm	Time Complexity	Space Complexity	Use Case
Tree Traversal Algorithms			
Inorder Traversal	$O(n)$	$O(h)$	Traverse BST in non decreasing order.
Preorder Traversal	$O(n)$	$O(h)$	Traverse tree in root-first order.

Postorder Traversal	$O(n)$	$O(h)$	Traverse tree in child-first order.
Level Order Traversal (BFS)	$O(n)$	$O(w)$	Traverse level by level.
Dynamic Programming			
Longest Common Subsequence (LCS)	$O(m \times n)$	$O(m \times n)$	Sequence alignment.
Longest Increasing Subsequence (LIS)	$O(n)^2$ $O(n \log n)$	$O(n)$	Finding the longest increasing subsequence.
Knapsack Problem	$O(n \times W)$	$O(n \times W)$	Optimal selection of items.
Fibonacci Series (Top Down)	$O(n)$	$O(n)$	Compute Fibonacci numbers efficiently.
Matrix Chain Multiplication	$O(n)^3$	$O(n)^2$	Optimal parenthesization of matrix products.
Advanced Algorithms			
Segment Tree	$O(\log n)$ (query/update)	$O(n)$	Efficient range queries and updates.
Fenwick Tree (Binary Indexed Tree)	$O(\log n)$ (query/update)	$O(n)$	Efficient prefix sum queries.
Mo's Algorithm	$O((n + q) n)$	$O(n)$	Efficient range query processing.

Algorithm	Time Complexity	Space Complexity	Use Case
Kruskal's Algorithm (MST)	$O(E \log E)$	$O(V)$	Minimum spanning tree in a graph.
Prim's Algorithm (MST)	$O(E \log V)$	$O(V)$	Minimum spanning tree in a graph.

Union-Find (Disjoint Set)	$O(\alpha(n))$	$O(n)$	Efficient set operations.
Trie (Prefix Tree)	$O(L)$ (insert/search)	$O(L \times n)$	Fast retrieval of strings.
Rabin-Karp Algorithm (String Matching)	$O(n + m)$ (average)	$O(1)$	Pattern searching in a string.

This table provides a structured overview of the algorithms, their complexities, and typical use cases, making it easier to reference the information quickly.

Data Structures

Arrays

	$O(1)$
Search	Insert:
:	$O(n)$
$O(n)$	Delete:
Lookup	$O(n)$
p:	
Space	Pros:
Complexity:	Fast lookups
	$O(n)$

- Fast push/pop operations
- Ordered

Cons:

- Slow inserts and deletes
- Fixed size (if using static array)

Linked Lists

	Appen
Prepen	d:
d:	
$O(1)$	Lookup

: $O(n)$
 $O(1)$ **Delete:**
 $O(n)$ $O(n)$
Insert:
Space **Pros:**
Complexity: $O(n)$

Fast insertion and deletion

Flexible size

Cons:

Slow lookup

More memory overhead due to pointers

Doubly Linked Lists

Prepend: $O(1)$
Delete: $O(n)$
 $O(1)$ **Insert:**
Append: $O(n)$
Delete: $O(1)$
Lookup:
 :
Delete: (once the node is found)
Space **Pros:**
Complexity: $O(n)$

Fast insertions/deletions from both ends

Can traverse in both directions

Cons:

More memory usage due to extra pointer

Slower lookups

Stacks (LIFO)

Push: $O(1)$
Pop: $O(1)$
Peek: $O(1)$

Pros:

Lookups:

$O(n)$ Fast

Space operations

Complexity: $O(n)$

Exit:

Simple and easy to implement

Cons:

Slow lookup

Queues (FIFO)

Enqueue:

$O(1)$

Dequeue: $O(1)$

Peek:

$O(1)$

Lookups:

Space:

$O(n)$ Complexity

exity: d

Pros: Cons:

Fast Slow
operati lookup
ons $O(n)$
Ordere

Priority Queues (using Binary Heap)

$n)$
Insert:
 $O(\log$
Delete (Extract Complexity:
Max/Min):
 $O(\log n)$ **Pros:**
Peek (Find
Max/Min): $O(n)$
 $O(1)$
Space

Fast access to highest/lowest priority element

Cons:

Slower operations than simple queues

Hash Tables

Search: $O(1)$

h:

Insert: $O(1)$

:

Delete: $O(1)$ $O(n)$

$O(1)$

Lookup: (Average Case) or (Worst Case, if collisions are high)

Space: **Pros:**

Complexity: $O(n)$

Extremely fast lookups, inserts, and deletes

Flexible keys

Cons:

Unordered

Performance depends on a good hash function

Potential for hash collisions, leading to $O(n)$ operations in the worst case

Binary Search Trees (BST)

$O(\log n)$ $O(n)$

Search: (Average Case), (Worst Case, if unbalanced) $O(\log n)$ $O(n)$

Insert: (Average Case), (Worst Case)

$O(\log n)$ $O(n)$

Delete: (Average Case), (Worst Case)

Space: Ordered structure

Complexity: $O(n)$

Pros:

Efficient searching, insertion, and deletion

Cons:

Can become unbalanced, leading to poor performance

Balanced Binary Search Trees (e.g., AVL, Red-Black Tree)

Search: $O(\log n)$ **Space**
Complexity:

Insert: $O(\log n)$ **Pros:**

Delete: $O(\log n)$

$O(\log n)$
Guaranteed operations
Self-balancing

Cons:

More complex to implement
Higher memory overhead

Heaps (Min-Heap, Max-Heap)

$n)$
Insert: $O(\log n)$
Delete (Extract Max/Min): $O(\log n)$ **Space**
Complexity:
Peek (Find Max/Min): $O(1)$ **Pros:**

$O(n)$

Efficient for priority queue operations

Easy to implement

Cons:

Not suitable for searching specific elements

Not sorted

Fenwick Tree (Binary Indexed Tree)

Space

Update: Complex

$O(\log n)$ **ity:**

Prefix **Pros:**

Sum $O(\log$

Query: $n) O(n)$

Efficient for cumulative frequency tables

Easy to implement

Cons:

Limited to operations like range sum, not general-purpose

Segment Tree

Range **Space**

Query:

$O(\log n)$ **Complexity**

Update:

$O(\log n)$: **Pros:**

$O(n)$

Handles range queries efficiently

Flexible for various operations (sum, min, max)

Cons:

Complex implementation

Higher memory usage compared to Fenwick Tree

Graphs

Adjacency List Representation:

Space $O(V + E)$

Complexity: $O(V + E)$

Search: using DFS/BFS **Adjacency**

Matrix Representation:

Space $O(V)^2$

Complexity:

$O(V)^2$

Search: using DFS/BFS

Pros:

Useful for modeling relationships between entities

Cons:

High space complexity, especially with adjacency matrix

Algorithms

Sorting Algorithms

1. Bubble Sort

Time Complexity: $O(n)^2$

Space Complexity: $O(1)$

3. Insertion Sort

2. Selection Sort

Sort $O(1)$

$O(1)$

Time

$O(n)$ $O(n)^2$

Time Complexity: (Best Case), (Worst Case)

Space Complexity: $O(n \log n)$

4. Merge Sort

Space Complexity: $O(1)$

5. Quick Sort

Time $O(n)$

$O(n \log n)$ $O(n)^2$

Time Complexity: (Average Case), (Worst Case)

Space Complexity: $O(1)$

7. Counting Sort

6. Heap Sort $O(1)$

$O(\log n)$

Time Complexity:

Time Complexity: $O(n + k)$

$O(n \log n)$ $O(k)$ k

Space

Space Complexity: (where k is the range of input values)

8. Radix Sort

$O(nk)$ k

Time Complexity: (where k is the number of digits)

Space

Complexity: Time Complexity:

9. Bucket Sort $O(n + k)$

$O(n + k)$ Space

Complexity: $O(\log n)$
Space Complexity:
Search 2. Linear Search
 $O(1)$

Algorithms 1.
Binary Search Time Complexity:
 $O(n)$
Space Complexity:
 $O(n + k)$ $O(1)$

Time Complexity:

3. Breadth-First Search (BFS)

Time Complexity: $O(V + E)$
Space Complexity: $O(V)$

4. Depth-First Search (DFS)

Time Complexity: $O(V + E)$
Space Complexity: $O(V)$

5. Dijkstra's Algorithm

$O((V + E) \log V)$

Time Complexity:

Space Complexity: $O(V)$

6. A Search*

$O((V + E) \log V)$

Time Complexity:

Space Complexity: $O(V)$

7. Bellman-Ford Algorithm

Time Complexity: $O(V \times E)$

Space Complexity:

Space Complexity: (

$O(V))$

8. Floyd-Warshall Algorithm

Time Complexity:	Space Complexity:
$O(V)^3$	$O(V)^2$

Tree Traversal Algorithms

1. Inorder Traversal

Time Complexity:	Space Complexity:
$O(n)$	$O(h)$ (where h is the height of the tree)

Preorder Traversal

Time Complexity:	Space Complexity:
$O(n)$	$O(n)$

Time Complexity:	Space Complexity:
$O(n)$	$O(h)$

4. Level Order Traversal (BFS)

Time Complexity:	Space Complexity:
$O(n)$	$O(w)$ (where w is the maximum width of the tree)

Dynamic Programming

1. Longest Common Subsequence (LCS)

Time Complexity:	Space Complexity:
$O(m \times n)$	$O(m \times n)$

2. Longest Increasing Subsequence (LIS)

Time Complexity:
$O(n)^2$ or $O(n \log n)$ (with a binary search approach)

Space Complexity:	Problem
$O(n)$	

3. Knapsack

$$O(n \times W)$$

Time Complexity: (where W is the capacity of the knapsack)

Space Complexity: $O(n \times W)$

Complexity:

4. Fibonacci Series (Top-Down Approach)

Time Complexity: $O(n)$

Space Complexity: $O(n)$

Complexity:

5. Matrix Chain Multiplication

Time Complexity: $O(n)^3$

Space Complexity: $O(n)^2$

Complexity:

Other Advanced Algorithms

1. Segment Tree

Range Query: $O(\log n)$

Update: $O(\log n)$

Space Complexity: $O(n)$

Use Case: Efficient range queries and updates (sum, min, max).

2. Fenwick Tree (Binary Indexed Tree)

Update: $O(\log n)$

Space Complexity: $O(n)$

Prefix Sum Query: $O(\log n)$

Complexity:

Use Case: Efficient range sum queries.

3. Mo's Algorithm

$$O((n + q) \sqrt{n})$$

Time Complexity: (where q is the number of queries)

Space Complexity: $O(n)$

Complexity:

Use Case: Efficient answering of range queries offline.

4. Kruskal's Algorithm (Minimum Spanning Tree)

Time Complexity:

$O(V^2)$

$O(E \log E)$

Space

Use Case: Finding a minimum spanning tree in a graph.

5. Prim's Algorithm (Minimum Spanning Tree)

Time Complexity:

$O(V^2)$

$O(E \log V)$

Space

Use Case: Finding a minimum spanning tree in a graph.

6. Union-Find (Disjoint Set)

$O(\alpha(n))$

Find: (Inverse Ackermann function)

Union: **Complexity:**

$O(\alpha(n))$

Space

Use Case: Efficient set operations.

7. Trie (Prefix Tree)

$O(L)$

Insert: (where L is the length of the word)

Search $O(L)$

:

Space $O(L \times n)$

Complexity:

Use Case: Fast retrieval of keys in a large dataset of strings.

8. Rabin-Karp Algorithm (String Matching)

$O(n + m)$

Time Complexity: (Average Case)

Space $O(1)$

Complexity:

Use Case: Pattern searching in a string.