

# LI, Yixuan

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## EDUCATION

Zhejiang University, Hangzhou, China

Sept 2020–Present

Morningside Cultural China Scholar

**Major:** Electronic Engineering,

**Overall GPA:** 3.93/4.0,

**Advisor:** Professor Haoliang Qian

**Coursework:** Electromagnetic Fields & Waves (93), Fundamentals of Optoelectronics (96), Quantum Mechanics (95), RF Circuits and Systems (96), Numerical Analysis (95)

## PUBLICATIONS

- **Y. Li**, S. Zheng, Z. Yu, B. Yu, S.-Y. Cao, L. Luo, and H.-L. Shen, “I2P-Rec: Recognizing Images on Large-Scale Point Cloud Maps through Bird’s-Eye View Projections,” 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (**IROS**), Detroit, USA, 2023. **Oral Presentation.** [[PDF](#)]
- L. Luo, S. Zheng, **Y. Li**, Y. Fa, B. Yu, S. Cao, and H. Shen, “BEVPlace: Learning Lidar-Based Place Recognition Using Bird’s-Eye View Images,” 2023 IEEE/CVF International Conference on Computer Vision (**ICCV**), Paris, France, 2023. [[PDF](#)]

## RESEARCH EXPERIENCE

**Primary Interests:** Quantum Optics, Nanophotonics

**Multilayer Structure for Dispersion-Engineered Nonlinear Waveguide | Nonlinear Optics** Oct 2023–Present

- Working on a project in nonlinear optics with Professor [Martin Fejer](#) to implement a multilayer structured waveguide based on LiNbO<sub>3</sub> to control the group velocity dispersion in nonlinear interactions.

**Tunable Nonlinear Edge Detection | Nanophotonics**

Jun 2022–Oct 2022

- Proposed a multilayer structured thin film based on metallic quantum wells to perform edge detection, whose effect varies accordingly by tuning the pump light intensity.
- Simulated reflected image of the film based on Fresnel diffraction under both coherent and incoherent incident light.

**Anti-Scattering Optical Image Transmission Based on K-Space Manipulation | Optics**

May 2022–Jul 2022

- Combined phase space compression with deep learning based on DMD for optical imaging through scattering media
- Conducted numerical simulations on scattering effects on Gaussian beams

**Image-to-Point Cloud Cross-Modal Localization | Robotics**

Dec 2022–Feb 2023

- Suggested a novel framework for cross-modal localization between LiDAR (point cloud) and camera (image).
- Implemented the overall pipeline, including monocular and stereo depth estimation, point cloud generation, bird’s-eye view projection, feature extraction and aggregation.
- Delivered oral presentation and presented poster at the IROS 2023 conference in Detroit, USA.

**LiDAR-Based Localization | Robotics** Open-source at GitHub [BEVPlace](#), ★104

Jul 2022–Dec 2022

- Proposed a rotation-invariant network BEVPlace for LiDAR-based localization problems in autonomous driving.
- Developed a position estimation method by mapping the feature distance to the geometric space.
- Outperforms the state-of-the-art methods, is robust to view variation, and generalizes well to previously unseen environments. Benefits various applications, including loop closure detection, global localization, and SLAM.

## HONORS AND AWARDS

National Scholarship (Top 0.2% nationwide) (2 Times)

Dec 2021 & Dec 2022

Zhejiang University Scholarship – First Prize (Top 3%) (2 Times)

Dec 2021 & Dec 2022

Second place, ICRA 2022 General Place Recognition Competition (Co-hosted by Carnegie Mellon University) Oct 2022

## PERSONAL EXPERIENCE

**Co-organizer**, the Morningside Scholars’ Academic Visit to the U.S.

Aug–Sept 2023

Visited 50+ guests from academic and political sectors, including Presidents of MIT, Harvard, Yale, AAAS, etc.

**Second Place**, Zhejiang University badminton competition women’s single

May 2022

Involved actively in many sports activities, including orienteering, soccer, badminton, etc.

**Volunteer**, Volunteer Teaching Program in Zhejiang University

Jun 2021

Taught math and literature courses to elementary school students in Gansu Province

**Volunteer**, Electrical Volunteer Association in Zhejiang University

Oct 2020–Present

Offered free computer repair services for all school faculty and students

## SKILLS

Tools:  $\text{\LaTeX}$ , Linux shell, PyTorch, OpenCV, COMSOL Multiphysics

Programming Languages: Python, MATLAB, C, Java, Verilog | Language: TOEFL 108