

# LI, Yixuan

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## EDUCATION

Zhejiang University, Hangzhou, China

Sep 2020–Present

Morningside Cultural China Scholar

**Major:** Electronic Engineering, **GPA:** 3.94/4.0

**Supervisor:** Professor Haoliang Qian (Zhejiang Uni.), Professor Martin M. Fejer (Stanford Uni., final year project)

**Coursework:** Electromagnetic Fields & Waves (93/100), Fundamentals of Optoelectronics (96), Quantum Mechanics (95), RF Circuits and Systems (96), Numerical Analysis (95)

## RESEARCH EXPERIENCE

**Multilayer Structure for Dispersion-Engineered Nonlinear Waveguide | Nonlinear Optics** Oct 2023–Present

- My current final year project in nonlinear optics with Professor Martin Fejer is to implement a multilayer structured waveguide based on LiNb to control the group velocity dispersion in second-order nonlinear interactions. We carry out the project by inverse design.

**Tunable Nonlinear Edge Detection | Nanophotonics**

Jun 2022–Nov 2022

- Proposed a multilayer structured thin film based on metallic quantum wells that perform edge detection. The effect varies accordingly by tuning the pump light intensity.

**LiDAR-based Localization | Robotics** Open-source at [zjuluolun/BEVPlace](https://github.com/zjuluolun/BEVPlace), ☆99

Jul 2022–Dec 2022

- Proposed a rotation-invariant network BEVPlace for LiDAR-based localization problems in autonomous driving. Developed a position estimation method by mapping the feature distance to the geometric space.
- Outperforms the state-of-the-art methods, is robust to view variation, and generalizes well to previously unseen environments. It benefits various applications, including loop closure detection, global localization, and SLAM.

**Image-to-point cloud Cross-Modal Localization | Robotics**

Dec 2022–Feb 2023

- The motivation is to combine the strengths of LiDAR and cameras, the two types of sensors widely used in localization. Proposed a method to get the location of an image within a large-scale point cloud map. Employ bird's-eye view representation to boost the performance in cross-modal localization.
- Oral presentation and poster session presentation at IROS 2023 conference in Detroit, U.S.

## PUBLICATIONS

- **Y. Li**, S. Zheng, Z. Yu, B. Yu, S.-Y. Cao, L. Luo, and H.-L. Shen, "I2p-rec: Recognizing images on large-scale point cloud maps through bird's eye view projections," Accepted to **IROS'23 (Oral Presentation)** [PDF]
- L. Luo, S. Zheng, **Y. Li**, Y. Fa, B. Yu, S. Cao, and H. Shen, "Bevplace: Learning lidar-based place recognition using bird's eye view images," Accepted to **ICCV'23** [PDF]

## HONORS AND AWARDS

National Scholarship (Top 0.2% nationwide) (2 Times)

Dec 2021 & Dec 2022

Zhejiang University Scholarship – First Prize (Top 3%) (2 Times)

Dec 2021 & Dec 2022

Second place, ICRA 2022 General Place Recognition Competition (Co-hosted by Carnegie Mellon University)

Oct 2022

## PERSONAL EXPERIENCES

**Co-organizer**, the Morningside Scholars' Academic Visit to the U.S.

Aug–Sep 2023

Visited 50+ guests from academic and political sectors, including Presidents of MIT, Harvard, Yale, AAAS, etc.

**Second Place**, Zhejiang University badminton competition women's single

May 2022

**Volunteer** at Electrical Volunteer Association in Zhejiang University

Oct 2020–Present

Offering free computer repair services for all school faculty and students

## SKILLS

Tools: L<sup>A</sup>T<sub>E</sub>X, Linux shell, PyTorch, OpenCV, COMSOL Multiphysics

Programming Languages: Python, MATLAB, C, Java, Verilog | Language: TOEFL 108