



Elektrobit



UDACITY

# Software Safety Requirements and Architecture

## Lane Assistance

Document Version: [Version]

Template Version 1.0, Released on 2017-06-21



## Document history

Date	Version	Editor	Description
11/13/2017	1	JP	First Submission
11/27/2017	2	JP	Second Submission

## Table of Contents

Document history

Table of Contents

Purpose

Inputs to the Software Requirements and Architecture Document

    Technical safety requirements

    Refined Architecture Diagram from the Technical Safety Concept

Software Requirements

Refined Architecture Diagram

## Purpose

The purpose of software safety requirements and architecture document is to identify new detailed requirements and allocate these software requirements to component level diagrams for the lane assistance functional safety project that is related to the potential malfunctions of the electrical and electronic system as defined by ISO26262.

## Inputs to the Software Requirements and Architecture Document

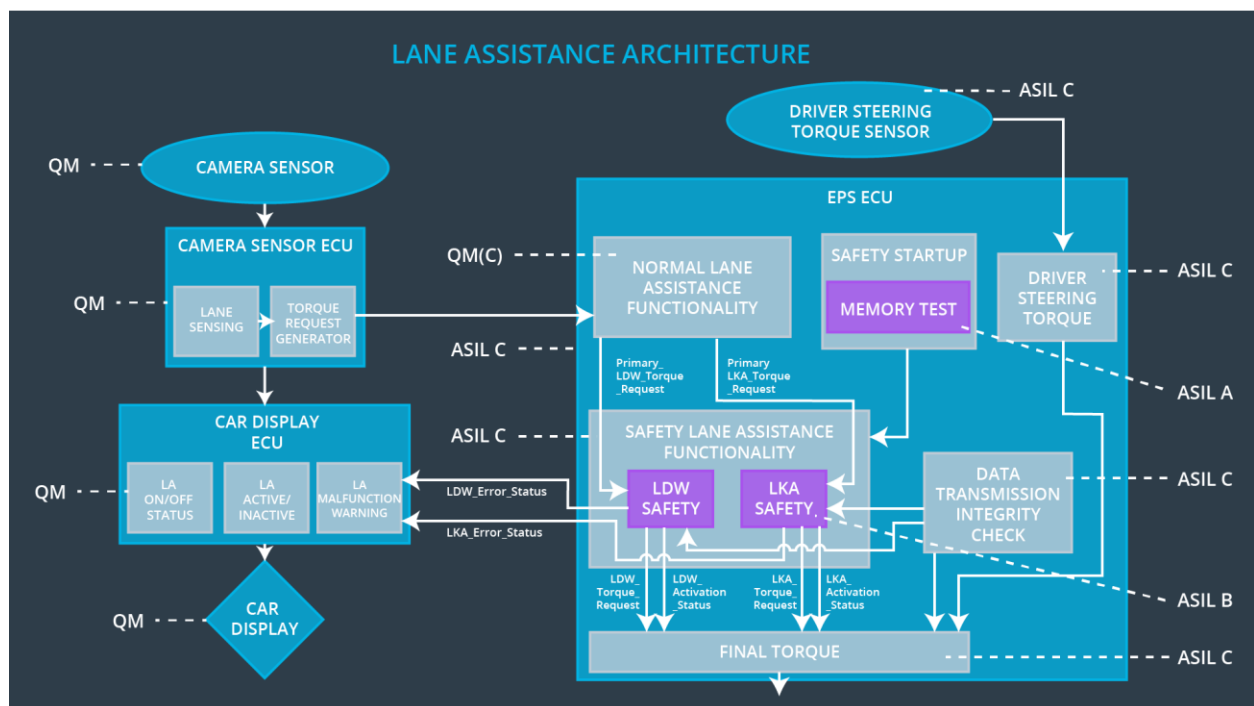
### Technical safety requirements

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

ID	Technical Safety Requirement	ASIL	Fault Tolerant Time Interval	Architecture Allocation	Safe State
Technical Safety Requirement 01-01-01	The LDW safety component shall ensure that the amplitude of the 'LDW_Torque_Request' sent to the 'Final electronic power steering Torque' component is below 'Max_Torque_Amplitude.	B	50 ms	LDW Safety block	Set LDW torque to zero
Technical Safety Requirement 01-01-02	As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light.	B	50 ms	LDW Safety block	Set LDW torque to zero
Technical Safety Requirement	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and	B	50 ms	LDW safety block	Set LDW torque to zero

ent 01-01-03	the 'LDW_Torque_Request' shall be set to zero.				
Technical Safety Requirem ent 01-01-04	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	B	50 ms	Data transmission integrity check	Set LDW torque to zero
Technical Safety Requirem ent 01-01-05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory	A	Ignition cycle	Safety startup - Memory test	Set LDW torque to zero

## Refined Architecture Diagram from the Technical Safety Concept



# Software Requirements

## Lane Departure Warning (LDW) Amplitude Malfunction Software Requirements:

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 01-01-01	The LDW safety component shall ensure that the amplitude of the LDW_Torque_Request sent to the Final Electronic Power Steering Torque component is below Max_Torque_Amplitude	B	50 ms	LDW Safety block	Set LDW torque to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 01-01	The input signal "Primary_LDW_Torq_Req" shall be read and pre-processed to determine the torque request coming from the "Basic/Main LAF functionality" SW Component. Signal "processed_LDW_Torq_Req" shall be generated at the end of the processing.	C	LDW_SAFETY_INPUT_P ROCESSING	N/A
Software Safety	In case the "processed_LDW_Torq_Req" signal has a value greater	C	TORQUE_LIMITER	"limited_LDW_Torq_Req" = 0 (Nm)

Requirement 01-02	than“Max_Torque_Amplitude_LD W”(maximum allowed safe torque), the torque signal “limited_LDW_Torq_Req” shall be set to 0, else“limited_LDW_Torq_Req” shall take the value of “processed_LDW_Torq_Req”.			
Software Safety Requirement 01-03	The 'limited_LDW_torque_Request' shall be transformed into a signal 'LDW_Torque_Request' which is suitable to be transmitted outside of the LDW Safety component (LDW_SAFETY) to the 'Final EPS Torque' component.	C	LDW_SAFETY_OUTPUT_ GENERATOR	LDW_Torque_R equest = 0 (Nm)

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 02	The validity and integrity of the data transmission for LDW_Torque_Request signal shall be ensured	B	50 ms	Data transmission Integrity Check	N/A

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 02-01	Any data to be transmitted outside of the LDW Safety component ("LDW Safety") including "LDW_Torque_Req" and "activation_status" (see SofSafReq03-02) shall be protected by an End2End(E2E) protection mechanism	C	E2E Calc	LDW_Torq_Re q= 0 (Nm)
Software Safety Requirement 02-02	The E2E protection protocol shall contain and attach the control data: alive counter (SQC) and CRC to the data to be transmitted.	C	E2E Calc	LDW_Torq_Re q= 0 (Nm)

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 03	As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the LDW_Torque_Request shall be set to zero	B	50 ms	LDW Safety block	Set LDW torque to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 03-01	Each of the SW elements shall output a signal to indicate any error which is detected by the element. Error signal = error_status_input(LDW_SAFETY_INPUT_PROCESSING), error_status_torque_limiter (TORQUE_LIMITER), error_status_output_gen(LDW_SAFETY_OUTPUT_GENERATOR)	C	All	N/A
Software Safety Requirement 03-02	A software element shall evaluate the error status of all the other software elements and in case any one of them indicates an error, it shall deactivate the LDW feature ('activation_status' = 0)	C	LDW_SAFETY_ACTIVATION	Activation_status = 0 (LDW function deactivated)
Software Safety Requirement 03-03	In case of no errors from the software elements, the status of LDW feature shall be set to activated ('activation_status' = 1)	C	LDW_SAFETY_ACTIVATION	N/A
Software Safety Requirement 03-04	In case of an error is detected by any of the software elements, it shall set the value of its corresponding torque to 0 so that 'LDW_Torque_Request' is set to 0	C	All	LDW_Torque_Request = 0



Software Safety Requirement 03-05	Once the LDW functionality has been deactivated, it shall stay deactivated till the time the ignition is switched from off to on again	C	LDW_SAFETY_ACTIVATION	Activation_status = 0 (LDW function deactivated)
--	--	---	-----------------------	---

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 04	As soon as the LDW function deactivates the LDW feature, the LDW Safety software block shall send a signal to the car display ECU to turn on a warning light	B	50 ms	Data transmission integrity check	Set LDW torque to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 04-01	When the LDW function is deactivated (activation_status set to 0), the activation_status shall be sent to the car display ECU.	C	LDW_SAFETY_ACTIVATION, CarDisplay ECU	N/A

ID	Technical Safety Requirement	A S I L	Fault Tolerant Time Interval	Allocation to Architecture	Safe State
Technical Safety Requirement 05	Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory	A	Ignition cycle	Safety startup - Memory test	Set LDW torque to zero

ID	Software Safety Requirement	A S I L	Allocation Software Elements	Safe State
Software Safety Requirement 05-01	A CRC verification check over the software code in the Flash memory shall be done every time the ignition is switched from off to on to check for any corruption of content	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement 05-02	Standard RAM tests to check the data bus, address bus and device integrity shall be done every time the ignition is switched from off to on	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement 05-03	The test result of the RAM or Flash memory shall be indicated to the LDW_Safety component via the 'test_status' signal	A	MEMORYTEST	Activation_status = 0
Software Safety Requirement 05-04	In case any fault is indicated via the 'test_status' signal the INPUT_LDW_PROCESSING shall set an error on error_status_input (=1) so that the LDW functionality is deactivated and the LDW Torque is set to 0	A	LDW_SAFETY_INPUT_PROCESSING	Activation_status = 0

# Refined Architecture Diagram

