

Zygote

Building a Differentiable Programming Language

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$$y = \sigma(W^*x + b)$$

$$y = \sigma(W * x + b)$$

$$\frac{dy}{dx}$$



How will a small
change in the input
change the output?



Distance 0.68m
Height 0m
Time 0.03s
Wind Speed 1m/s
Release Angle 45deg

```
[(v1.2) pkg> add Zygote
Resolving package versions...
Updating `~/.julia/environments/v1.2/Project.toml`
[e88e6eb3] + Zygote v0.3.2
Updating `~/.julia/environments/v1.2/Manifest.toml`
[1a297f60] + FillArrays v0.6.3
[7869d1d1] + IRTools v0.2.2
[e88e6eb3] + Zygote v0.3.2
```

```
[julia> using Zygote
```

```
[julia> function pow(x, n)
    r = 1
    while n > 0
        n -= 1
        r *= x
    end
    return r
end
pow (generic function with 1 method)
```

```
[julia> pow(5, 3)
125
```

```
[julia> gradient(x -> pow(x, 3), 5)
(75,)
```

```
julia> █
```

User Function

```
function pow(x, n)
  r = 1
  while n > 0
    n -= 1
    r *= x
  end
  return r
end
```

Primal

```
1: (%2, %3)
  br 2 (%3, 1)
2: (%4, %5)
  %6 = %4 > 0
  br 4 unless %6
  br 3
3:
  %7 = %4 - 1
  %8 = %5 * %2
  br 2 (%7, %8)
4:
  return %5
```

Adjoint

```
1: (%1)
  br 2 (%1, 0)
2: (%2, %4)
  br 4 unless @6
  br 3
3:
  %10 = %2 * @2
  %11 = %2 * @5
  %14 = %4 + %11
  br 2 (%10, %14)
4:
  return (%4, 0)
```

```
pow(5, 3) == 125
gradient(pow, 5, 3) == (75, 0)
```

```
[julia> y, back = J(pow, 5, 3);
```

```
[julia> back(1)  
(75, nothing)
```

$$y = f(x_1, x_2, \dots)$$

$$y, \mathcal{B} = \mathcal{J}(f, x_1, x_2, \dots)$$

$$\bar{x}_1, \bar{x}_2, \dots = \mathcal{B}(\bar{y})$$

```
function foo(x)
    a = bar(x)
    b = baz(a)
    return b
end
```



```
function J(::typeof(foo), x)
    a, da = J(bar, x)
    b, db = J(baz, a)
    return b, function(b-)
        ā = db(b-)
        x- = da(ā)
        return x-
    end
end
```



```
Type "?" for help, "]?" for Pkg help.
```

release-1.2/3fcb168ceb (fork: 74 commits, 81 days)

```
julia> f(x) = fs[readline()](x)
f (generic function with 1 method)
```

```
julia> gradient(f, 1)
sin
(0.5403023058681398,)
```

```
julia> 
```

`J(::typeof(sin), x) = sin(x), \bar{y} -> \bar{y} *cos(x)`



`@adjoint sin(x) = sin(x), \bar{y} -> \bar{y} *cos(x)`

Core compiler pass is ~200 lines of code

All semantics added via custom adjoints –
mutation, data structures, checkpointing, etc.

```
nestlevel() = 0
```

```
@adjoint nestlevel() = nestlevel()+1, _ -> nothing
```

```
julia> function f(x)
           println(nestlevel(), " levels of nesting")
           return x
       end
```

```
julia> f(1);
0 levels of nesting
```

```
julia> grad(f, 1);
1 levels of nesting
```

```
julia> grad(x -> x*grad(f, x), 1);
2 levels of nesting
```

```
@adjoint hook(f, x) = x, x- -> (f(x-),)
```

```
hook(-, x) # reverse the gradient of x
```

```
@adjoint checkpoint(f, x...) =  
    f(x...), Δ -> J(f, x...)[2](Δ)
```

```
@adjoint function forwarddiff(f, x)  
    y, J = forward_jacobian(f, x)  
    y, Δ -> (J'Δ,)  
end
```

```
julia> hook(f, x) = x
hook (generic function with 1 method)
```

```
julia> @adjoint hook(f, x) = x,  $\Delta$  -> (nothing, f( $\Delta$ ),)
```

```
julia> gradient(2, 3) do a, b
    a*b
end
(3, 2)
```

```
julia> gradient(2, 3) do a, b
    hook(-, a) * b
end
(-3, 2)
```

```
julia> gradient(2, 3) do a, b
    hook( $\bar{a}$  -> @show( $\bar{a}$ ), a) * b
end
 $\bar{a}$  = 3
(3, 2)
```

Differentiation á la Carte

- Mixed-mode AD (forward, reverse, Taylor series, ...)
- Forward-over-reverse (Hessians)
- Cross-language AD
- Support for Complex and other number types
- Easy custom gradients
- Checkpointing
- Gradient hooks
- Custom types (colours!)
- Hardware backends: CPU, CUDA, TPU, ...
- Concurrency, parallelism and distribution
- ~~Deeply nested AD~~ (WIP)

Data Structures & Mutation

```
julia> using Colors
```

```
julia> a, b = RGB(1, 0, 0), RGB(0, 1, 0)  
(RGB{N0f8}(1.0,0.0,0.0), RGB{N0f8}(0.0,1.0,0.0))
```

```
julia> a.r^2  
1.0N0f8
```

```
julia> gradient(c -> c.r^2, a)  
((r = 2.0f0, g = nothing, b = nothing),)
```

```
julia> colordiff(a, b)  
86.60823557376344
```

```
julia> gradient(a -> colordiff(a, b), a)  
((r = 0.4590887719632896, g = -9.598786801605689, b = 14.181383399012862),)
```



```

196 dense(W, b, σ = identity) =
197   x → σ.(W * x .+ b)
198
199 chain(f ... ) = foldl(∘, reverse(f))
200
201 mlp = chain(
202   dense(randn(5, 10), randn(5), tanh),
203   dense(randn(2, 5), randn(2)))
204
205 x = rand(10)

```

206

```

207 mlp(x)
208   ▾ Float64[2]
209     0.646...
210     2.51...

```

210

```

211 m̃ = gradient(mlp) do m
212   sum(m(x))

```

```

213 end ((f = (W = [-0.9909137325976834 0.11388709497399903 ... -0.7210152885786678 0.99010

```

214

```

215 m -= η * m̃ # Gradient descent

```

216

Deep learning in 5 lines.

```
julia> vars = Dict{:r => 0, :n => 0}
Dict{Symbol,Int64} with 2 entries:
  :n => 0
  :r => 0
```

```
julia> function pow(x, n)
    vars[:r] = 1
    vars[:n] = n
    while vars[:n] > 0
        vars[:n] -= 1
        vars[:r] *= x
    end
end
pow (generic function with 1 method)
```

```
julia> pow(5, 3); vars[:r]
125
```

```
julia> gradient(x -> (pow(x, 3); vars[:r]), 5)
(75,)
```

```
julia> vars[:r]
125
```

Some Bonus Features

```
6 @grad function (a::Real * b::Real)
7   c = a*b
8   function back(Δ)
9     0//0
10  end
11  c, back
12 end | > _forward
```

```
13
14 function pow(x, n)
15   r = one(x)
16   while n > 0
17     r *= x
18     n -= 1
19   end
20   return r
21 end | > pow
```

```
22
23 gradient(pow, 2, 3)
```

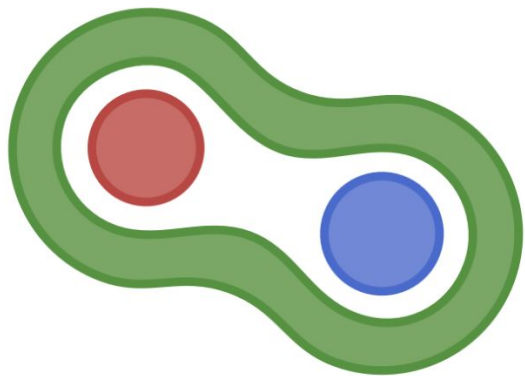
```

24
25 ~ ArgumentError: invalid rational: zero(Int64)//zero(Int64)
26   in top-level scope at base/none
27   in gradient at Zygote/src/compiler/interface.jl:34
28   in at Zygote/src/compiler/interface.jl:28
29   in at Zygote/src/compiler/interface2.jl
30   in pow at test.jl:17
31   in at Zygote/src/lib/lib.jl:33
32   in at test.jl:9
33   in // at base/rational.jl:13
```

```
8 using Zygote
9
10 function f(x)
11     for i = 1:5
12         x = sin(cos(x))
13     end
14     return x
15 end
16
17 function loop(x, n)
18     r = x/x
19     for i = 1:n
20         r *= f(x)
21     end
22     return sin(cos(r))
23 end
24
25 gradient(loop, 2, 3)
26
27 Zygote.@profile loop(2, 3)
28
29 function logsumexp(x::Array{Float64,1})
```



```
@adjoint function pycall(f, x...; kw...)
  x = map(py, x)
  y = pycall(f, x...; kw...)
  y.detach().numpy(), function ( $\bar{y}$ )
    y.backward(gradient = py( $\bar{y}$ ))
    (nothing, map(x -> x.grad.numpy(), x)...)
end
end
```

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