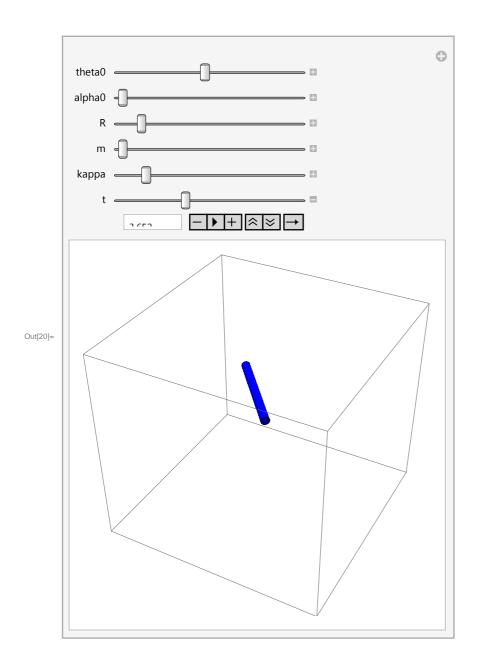
```
In[8]:= M = -kappa * theta[t]
          I * theta''[t] = -kappa * theta[t]
          I = 1 / 2 m * R^2
          DSolve[{(1/2m*R^2)*theta''[t] == -kappa*theta[t],}
              theta[0] == theta0, theta'[0] == alpha0}, theta[t], t]
 Out[8]= -kappa theta[t]
          Set::write: Tag Times in i theta"[t] is Protected. \gg
 Out[9]= -kappa theta[t]
          Set::wrsym : Symbol i is Protected. \gg
\text{Out[11]= } \left\{ \left\{ \text{theta[t]} \rightarrow \frac{1}{2\sqrt{\text{kappa}}} \right. \right.
                \left|2\sqrt{\text{kappa theta0}} \cos \left[\frac{\sqrt{2}\sqrt{\text{kappa t}}}{\sqrt{\text{m}}}\right] + \sqrt{2} \text{ alpha0} \sqrt{\text{m}} \text{ R} \sin \left[\frac{\sqrt{2}\sqrt{\text{kappa t}}}{\sqrt{\text{m}} \text{ R}}\right]\right|\right\}\right\}
 In[20]:= Manipulate [
                theta = \frac{2\sqrt{\text{kappa}} \text{ theta0 Cos}\Big[\frac{\sqrt{2}\sqrt{\text{kappa}} \text{ t}}{\sqrt{\text{m } \text{R}}}\Big] + \sqrt{2} \text{ alpha0 } \sqrt{\text{m } \text{R Sin}}\Big[\frac{\sqrt{2}\sqrt{\text{kappa}} \text{ t}}{\sqrt{\text{m } \text{R}}}\Big]}{2\sqrt{\text{kappa}}};
                Graphics3D[
                  {Blue, Cylinder[{{0,0,0}, {R * Sin[theta], R * Cos[theta], 0}}, 0.001]},
                  PlotRange \rightarrow \{\{-1.1*R, 1.1*R\}, \{-1.1*R, 1.1*R\}, \{-R, R\}\}
              }[[1]],
            \{\{\text{theta0}, \pi/4\}, 0, \pi/2\},\
            {alpha0, 0, \pi / 2},
            {R, 0.001, 0.2},
            {m, 0.1, 1},
            {kappa, 0.1, 10},
            {t, 0, 10}
```



```
ln[35] = m1 = 0.02;
                              m2 = 0.03;
                               11 = 0.3;
                               12 = 0.4;
                               \theta 10 = 25 * \frac{\pi}{180};
                               \theta 20 = 5 * \frac{\pi}{180};
                               \omega10 = 0;
                               \omega 20 = 0;
                               g = 10;
                               sol = NDSolve[\{(m1 + m2) \ 11^2 \ \theta1''[t] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * 12 * \theta2''[t] * Cos[\theta1[t] - \theta2[t]] + m2 * 11 * (12 * \theta2[t] - t] * Cos[\theta1[t] 
                                                               m2 * 11 * 12 * (\theta 2'[t])^{2} * Sin[\theta 1[t] - \theta 2[t]] + 11 * g * (m1 + m2) * Sin[\theta 1[t]] == 0,
                                                 m2 * 12^{2} \theta 2''[t] + m2 * 11 * 12 * \theta 1''[t] * Cos[\theta 1[t] - \theta 2[t]] -
                                                               m2 * 11 * 12 * (\theta 1'[t])^{2} * Sin[\theta 1[t] - \theta 2[t]] + 12 * m2 * g * Sin[\theta 2[t]] == 0,
                                                  \theta1[0] = \theta10, \theta2[0] = \theta20, \theta1'[0] = \omega10, \theta2'[0] = \omega20 \right\}, \left\{\theta1[t], \theta2[t]\right\}, \left\{t, 0, 10\right\}
                               Plot[{Evaluate[\theta2[t] /. sol][[1]], Evaluate[\theta1[t] /. sol][[1]]},
                                      \{t, 0, 10\}, PlotRange \rightarrow Full]
\label{eq:out_44} \textsc{Out_{44}= } \left\{ \left\{ \theta 1 \left[ t \right] \rightarrow \textsc{InterpolatingFunction} \left[ \left\{ \left\{ 0., \, 10. \right\} \right\}, \, <> \right] \left[ t \right], \right. \right.
                                           \theta 2[t] \rightarrow InterpolatingFunction[\{\{0., 10.\}\}, <>][t]\}\}
                                    0.4
                                    0.2
Out[45]=
                               -0.2
                               -0.4
```