

# My Title

Timothy E. Holy<sup>1,\*</sup>

<sup>1</sup>Department of Anatomy & Neurobiology, Washington University  
School of Medicine, St. Louis, Missouri

\*To whom correspondence should be addressed. Email:  
holy@wustl.edu

November 8, 2018

## Abstract

Here's the abstract

## 1 Simple case

Consider the problem

$$\text{minimize} \quad \frac{1}{2} \mathbf{x}^T \mathbf{Q}_0 \mathbf{x} + \mathbf{g}_0^T \mathbf{x} \quad (1a)$$

$$\text{subject to} \quad \frac{1}{2} \mathbf{x}^T \mathbf{Q}_1 \mathbf{x} \leq c \quad (1b)$$

for positive-semidefinite  $\mathbf{Q}_1$ . Following chapter 4.3 of Nocedal & Wright, consider  $\mathbf{Q}_0 + \lambda \mathbf{Q}_1$  and assume that  $\lambda$  is big enough to make this sum positive-definite. We seek a  $\lambda$  such that Eq. (1b) is satisfied at

$$\mathbf{x} = (\mathbf{Q}_0 + \lambda \mathbf{Q}_1)^{-1} (-\mathbf{g}_0). \quad (2)$$

Consider

$$\phi_2(\lambda) = \frac{1}{c} - \frac{2}{\mathbf{x}^T \mathbf{Q}_1 \mathbf{x}}, \quad (3)$$

which exhibits a root at  $\lambda$  such that Eq. (1b) becomes an equality. We can therefore update  $\lambda$  by Newton's method

$$\lambda^{(l+1)} = \lambda^{(l)} - \frac{\phi_2(\lambda)}{\phi_2'(\lambda)}. \quad (4)$$

Since

$$\phi_2'(\lambda) = \frac{4\mathbf{x}^T \mathbf{Q}_1 \frac{d\mathbf{x}}{d\lambda}}{(\mathbf{x}^T \mathbf{Q}_1 \mathbf{x})^2}, \quad (5)$$

we have

$$\frac{\phi_2(\lambda)}{\phi_2'(\lambda)} = \frac{\mathbf{x}^T \mathbf{Q}_1 \mathbf{x}}{2\mathbf{x}^T \mathbf{Q}_1 \frac{d\mathbf{x}}{d\lambda}} \frac{\frac{1}{2}\mathbf{x}^T \mathbf{Q}_1 \mathbf{x} - c}{c}. \quad (6)$$

From Eq. (2), we have

$$\frac{d\mathbf{x}}{d\lambda} = -(\mathbf{Q}_0 + \lambda \mathbf{Q}_1)^{-1} \mathbf{Q}_1 (\mathbf{Q}_0 + \lambda \mathbf{Q}_1)^{-1} (-\mathbf{g}_0) \quad (7)$$

$$= -(\mathbf{Q}_0 + \lambda \mathbf{Q}_1)^{-1} \mathbf{Q}_1 \mathbf{x}. \quad (8)$$

## 2 Cholesky factorization of symmetric tridiagonal matrices

In this case the factorization is simple:

$$A_{ii} = L_{i,i-1}^2 + L_{ii}^2 \quad (9a)$$

$$A_{i+1,i} = L_{i+1,i} L_{ii}. \quad (9b)$$

We initiate it with  $L_{11} = \sqrt{A_{11}}$ , and then iterate

$$L_{i+1,i} = \frac{A_{i+1,i}}{L_{ii}}; \quad (10a)$$

$$L_{i+1,i+1} = \sqrt{A_{i+1,i+1} - L_{i+1,i}^2}. \quad (10b)$$

[http://www.mat.uc.pt/~cmf/papers/tri\\_positive\\_definite\\_revisited.pdf](http://www.mat.uc.pt/~cmf/papers/tri_positive_definite_revisited.pdf) contains a number of potential conditions that could be leveraged for guessing an initial  $\lambda$ , for example

$$4 \cos^2 \left( \frac{\pi}{n+1} \right) b_i^2 < a_i a_{i+1}, \quad (11)$$

where  $b_i$  are the off-diagonal values and  $a_i$  the diagonals. This results in a quadratic inequality for  $\lambda$ .

Figure 1: What a figure!

Table 1: Who needs tables?