

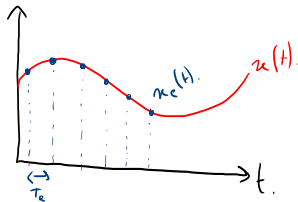
TDS

Exercise 1:

$$x_e(t) = \sum_{-\infty}^{+\infty} x(nT_e) \delta(t - nT_e)$$

$$\begin{aligned} \text{TD} \rightarrow X_e(f) &= T_e \sum_{-\infty}^{+\infty} x(nT_e) e^{-j2\pi f nT_e} \\ &= T_e \sum_{-\infty}^{+\infty} x(nT_e) \left(e^{j2\pi f T_e} \right)^{-n} \end{aligned}$$

$$X_e(f) = T_e X(z) \Big|_{z = e^{j2\pi f T_e}}$$



$$T Z(f) = \sum_{-\infty}^{+\infty} x(n) z^{-n}$$

Exercice 2:

$$\textcircled{1} u_k = \begin{cases} 1 & \text{si } k \geq 0 \\ 0 & \text{sinon.} \end{cases}$$

$$TZ(u_k) = \sum_{-\infty}^{+\infty} u_n z^{-n} = \sum_{-\infty}^{-1} u_n z^{-n} + \sum_0^{+\infty} u_n z^{-n}$$

$$TZ(u_k) = \sum_0^{+\infty} z^{-n}$$

$$(1) TZ(u_k) = 1 + z^{-1} + z^{-2} + \dots + z^{-n} \quad \left. \vphantom{1 + z^{-1} + z^{-2} + \dots + z^{-n}} \right\} (1)-(2)$$

$$(2) z^{-1} TZ(u_k) = z^{-1} + z^{-2} + \dots + z^{-n} + z^{-(n+1)} \quad \left. \vphantom{z^{-1} + z^{-2} + \dots + z^{-n} + z^{-(n+1)}} \right\} (1-z^{-1}) TZ(u_k) = 1 - z^{-(n+1)}$$

$$\hookrightarrow TZ(u_k) = \lim_{n \rightarrow +\infty} \frac{1 - z^{-(n+1)}}{1 - z^{-1}}$$

$$TZ(u_k) = \frac{1}{1 - z^{-1}}$$

⚠ dénominateur s'annule pour $z = 0$.

$$(2) y_k = a^k x_k.$$

$$\begin{aligned} T\mathcal{Z}(y_k) &= Y(z) = \sum_{n=-\infty}^{+\infty} a^n x_n z^{-n} \\ &= \sum_{n=-\infty}^{+\infty} \left(\frac{1}{a}\right)^{-n} x_n z^{-n} \\ &= \sum_{n=-\infty}^{+\infty} x_n \left(\frac{z}{a}\right)^{-n}. \end{aligned}$$

Formule

$$T\mathcal{Z}(x) = X(z) = \sum_{n=-\infty}^{+\infty} x_n z^{-n}.$$

$$\boxed{Y(z) = X\left(\frac{z}{a}\right)} \quad \text{ou} \quad T\mathcal{Z}(a^k x_k) = X\left(\frac{z}{a}\right).$$

$$(3) h_{1k} = u_k - u_{k-3}.$$

Application linéaire $T\mathcal{Z}(x+y) = T\mathcal{Z}(x) + T\mathcal{Z}(y).$

$$T\mathcal{Z} \downarrow \quad H_1(z) = U(z) - T\mathcal{Z}(u_{k-3}).$$

Théorème du retard $T\mathcal{Z}(x_{k-n_0}) = z^{-n_0} T\mathcal{Z}(x_k).$

On démontre le théorème du retard.

$$\begin{aligned} \mathcal{TZ}(x_{k-n_0}) &= \sum_{-\infty}^{+\infty} x(n-n_0) z^{-n} \quad \text{on pose } n' = n - n_0 \\ & \quad n = n' + n_0 \\ &= \sum_{-\infty}^{+\infty} x(n') z^{-(n'+n_0)} = \underbrace{\sum_{-\infty}^{+\infty} x(n') z^{-n'}}_{X(z)} z^{-n_0} \end{aligned}$$

$$\boxed{\mathcal{L} \mathcal{TZ}(x_{k-n_0}) = z^{-n_0} X(z)} \quad (\text{Théorème du retard})$$

On revient à $H_1(z)$.

$$H_1(z) = U(z) - z^{-3} U(z) = \frac{1 - z^{-3}}{1 - z^{-1}}$$

$$h_{2k} = a^k (u_k - u_{k-3}) = a^k h_{1k} \quad \rightarrow \mathcal{TZ}(a^k x_k) = X\left(\frac{z}{a}\right)$$

$$\mathcal{TZ} \hookrightarrow H_2(z) = H_1\left(\frac{z}{a}\right) = \frac{1 - \left(\frac{z}{a}\right)^{-3}}{1 - \left(\frac{z}{a}\right)^{-1}}$$

Exercice 3 :

$$\bullet y_k = u_{k-N}.$$

Théorème du retard

$$Y(z) = z^{-N} U(z) \rightarrow Y(z) = \frac{z^{-N}}{1 - z^{-1}}.$$

$$\bullet y_k = \left(\frac{1}{2}\right)^k u_k.$$

$$\text{TZ} \rightarrow Y(z) = U\left(\frac{z}{1/2}\right) = U(2z).$$

$$Y(z) = \frac{1}{1 - (2z)^{-1}}.$$

$$\bullet y_k = \left(\frac{1}{3}\right)^k u_{k-N} \rightarrow y_k = \left(\frac{1}{3}\right)^N \underbrace{\left(\frac{1}{3}\right)^{k-N} u_{k-N}}_{v_{k-N}}.$$

$$\text{on définit } v_k = \left(\frac{1}{3}\right)^k u_k \xrightarrow{\text{TZ}} V(z) = \frac{1}{1 - (3z)^{-1}}.$$

$$U(z) = \frac{1}{1 - z^{-1}}.$$

$$Y(z) = \left(\frac{1}{3}\right)^N z^{-N} V(z).$$

$$Y(z) = \left(\frac{1}{3}\right)^N \frac{z^{-N}}{1 - (3z)^{-1}} = \left(\frac{1}{3}\right)^N \frac{z^{-N}}{1 - \frac{1}{3} z^{-1}}.$$

$$\bullet y_k = e^{-ak} u_k = (e^{-a})^k u_k.$$

$$\text{TT} \hookrightarrow Y(z) = U\left(\frac{z}{e^{-a}}\right)$$

$$= \frac{1}{1 - (z/e^{-a})^{-1}} \Rightarrow Y(z) = \frac{1}{1 - e^{-a} z^{-1}}.$$

$$\bullet y_k = -a_1 y_{k-1} - a_2 y_{k-2} + b u_{k-1}.$$

$$\text{TT} \hookrightarrow Y(z) = -a_1 z^{-1} Y(z) - a_2 z^{-2} Y(z) + b z^{-1} U(z).$$

$$Y(z)(1 + a_1 z^{-1} + a_2 z^{-2}) = \frac{b z^{-1}}{1 - z^{-1}}$$

$$Y(z) = \frac{b z^{-1}}{(1 - z^{-1})(1 + a_1 z^{-1} + a_2 z^{-2})}$$

Exercice 4:

$$X_1(z) = \frac{1}{z^3 - \frac{1}{2}z^2} = \frac{1}{z^2(1 - \frac{1}{2}z^{-1})} = \frac{z^{-3}}{1 - \frac{1}{2}z^{-1}}$$

$$\mathcal{Z}^{-1} \hookrightarrow x_k = \left(\frac{1}{2}\right)^{k-3} u_{k-3}$$

$$\bullet X_2(z) = \frac{3z^2 - 6z + 2}{(z-1)(z-2)}$$

Décomposition en éléments simples:

$$\frac{3z^2 - 6z + 2}{(z-1)(z-2)} = \frac{A}{(z-1)} + \frac{B}{(z-2)} + C$$

$$\frac{3z^2 - 6z + 2}{(z-1)(z-2)} = \frac{Az - 2A + Bz - B + C(z-1)(z-2)}{(z-1)(z-2)}$$

$$\frac{3z^2 - 6z + 2}{(z-1)(z-2)} = \frac{(A+B)z - 2A - B + C(z^2 - 3z + 2)}{(z-1)(z-2)}$$

$$\begin{cases} C = 3 \\ A + B - 3C = -6 \\ -2A - B + 2C = 2 \end{cases}$$

$$\rightarrow \begin{cases} C = 3 \\ A = 3 - B \\ -6 + 2B - B + 6 = 2 \end{cases}$$

$$\rightarrow \begin{cases} C = 3 \\ A = 1 \\ B = 2 \end{cases} \Rightarrow X_2(z) = \frac{1}{(z-1)} + \frac{2}{z-2} + 3$$

$$X_2(z) = \frac{1}{z^{-1}} + \frac{2}{z^{-2}} + 3$$

$$X_2(z) = \underbrace{\frac{z^{-1}}{1-z^{-1}}}_{U_{k-1}} + 2 \underbrace{\frac{z^{-1}}{1-z^{-1}}}_{\left(\frac{z}{2}\right)^{-1}} + 3 \rightarrow Tz(\delta(k)) = 1$$

$$\frac{\left(\frac{z}{2}\right)^{-1}}{1 - \left(\frac{z}{2}\right)^{-1}} = U\left(\frac{z}{2}\right) \xrightarrow{Tz^{-1}} \underbrace{2^{k-1}}_{U_{k-1}}$$

$$\xrightarrow{Tz^{-1}} x_{2k} = U_{k-1} + 2^{k-1} U_{k-1} + 3\delta_k$$

$f(t) \cdot u(t)$	$F(p)$	$F(z)$
$\delta(t)$	1	1
$\delta(t - kT_e)$	$\exp(-kT_e p)$	z^{-k}
$u(t)$	$\frac{1}{p}$	$\frac{1}{1-z^{-1}}$
$t \cdot u(t)$	$\frac{1}{p^2}$	$\frac{T_e z^{-1}}{(1-z^{-1})^2}$

$f(t) \cdot u(t)$	$F(p)$	$F(z)$
$\delta(t)$	1	1
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$u(t)$	$\frac{1}{p}$	$\frac{1}{1-z^{-1}}$
$t \cdot u(t)$	$\frac{1}{p^2}$	$\frac{T_e z^{-1}}{(1-z^{-1})^2}$
$\frac{t^2}{2!} \cdot u(t)$	$\frac{1}{p^3}$	$\frac{T_e^2 z^{-1} (1+z^{-1})}{2(1-z^{-1})^3}$
$e^{-at} \cdot u(t)$	$\frac{1}{p+a}$	$\frac{1}{1-e^{-aT_e} z^{-1}}$
$t \cdot e^{-at} \cdot u(t)$	$\frac{1}{(p+a)^2}$	$\frac{T_e \cdot e^{-aT_e} \cdot z^{-1}}{(1-e^{-aT_e} \cdot z^{-1})^2}$
$\cos(\omega t) \cdot u(t)$	$\frac{p}{p^2 + \omega^2}$	$\frac{1 - \cos(\omega T_e) \cdot z^{-1}}{1 - 2 \cdot \cos(\omega T_e) \cdot z^{-1} + z^{-2}}$
$\sin(\omega t) \cdot u(t)$	$\frac{\omega}{p^2 + \omega^2}$	$\frac{\sin(\omega T_e) \cdot z^{-1}}{1 - 2 \cdot \cos(\omega T_e) \cdot z^{-1} + z^{-2}}$
$e^{-at} \cdot \cos(\omega t) \cdot u(t)$	$\frac{p+a}{(p+a)^2 + \omega^2}$	$\frac{z^2 - e^{-aT_e} \cdot \cos(\omega T_e) \cdot z}{z^2 - 2 \cdot e^{-aT_e} \cdot \cos(\omega T_e) \cdot z + e^{-2aT_e}}$
$e^{-at} \cdot \sin(\omega t) \cdot u(t)$	$\frac{\omega}{(p+a)^2 + \omega^2}$	$\frac{e^{-aT_e} \cdot \sin(\omega T_e) \cdot z}{z^2 - 2 \cdot e^{-aT_e} \cdot \cos(\omega T_e) \cdot z + e^{-2aT_e}}$
$e^{-at} \cdot f(t) \cdot u(t)$	$F(p+a)$	$F(e^{aT_e} z)$
$t^k \cdot u(t)$	$\frac{k!}{p^{k+1}}$	$-T_e z \cdot \frac{d}{dz} Z(t^{k-1} \cdot u(t))$
Théorème de la valeur finale	$\lim_{t \rightarrow \infty} f(t) = \lim_{p \rightarrow 0} (p \cdot F(p))$	$\lim_{t \rightarrow \infty} f(nT_e) = \lim_{z \rightarrow 1} ((1-z^{-1}) \cdot F(z))$