

1                   Multi-Source Asynchrony Time Series  
2                   Classification\*

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4                   **Abstract**

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6                   **Keywords:**

7                   **1 Introduction**

8     Wearable devices enable non-intrusive measurement of physiological biomarkers  
9     that correlate with stress levels, emotional states, and other biological responses.  
10    Those measurements often include heart rate Variability (HRV), Electrodermal  
11    Activity (ADA), Heart Rate (HR), and three-axis acceleration (ACC) [1]. Ad-  
12    vances in machine learning have allowed us to predict emotional states from  
13    these biomarkers, reflecting a shift toward recognizing mental well-being as an  
14    integral component of human health.

15    Authors in [2] evaluate a set of traditional machine learning algorithms to  
16    predict people's stress based on EDA activity, including K-Nearest Neighbor,  
17    Support Vector Machine (SVM), Naive Bayes, Logistic Regression, and Random  
18    Forest. They trained models on both statistical features and raw sensor read-  
19    ings, finding that SVM achieved the highest accuracy, although performance  
20    varied inconsistently between feature-based and raw-data approaches.

21    Despite their utility, shallow models often lack expressiveness and capacity to  
22    generalize well [3]. Moreover, features often rely on statistics, forgetting sequen-  
23    tial dependencies in the data. A closer overview dives us into a multi-modality  
24    scenario, where signals are sampled at different frequencies, introducing addi-  
25    tional challenges for feature extraction and fusion.

26    Deep learning approaches address these limitations by automatically lever-  
27    aging data structures as time dependencies for sequential recordings or spatial  
28    patterns for images through feature representation from multiple data entities.  
29    However, a key challenge lies in effectively combining heterogeneous data sources  
30    [4, 5].

31    The work developed by [6] demonstrated the power of multimodal fusion by  
32    integrating autoencoders for genetic data with 3D CNNs for imaging, outper-  
33    forming shallow and single-modality baselines. In the domain of physiological  
34    sensing, [7] proposed a CNN-based feature extractor for time-series sensor data,  
35    while [8] developed an attention-based LSTM framework to fuse smartphone  
36    and wearable signals for emotion recognition. Prior studies by [9, 10] further

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<sup>37</sup> highlight the effectiveness of LSTM architectures in modeling inter-participant  
<sup>38</sup> variability and integrating multiple modalities.

## <sup>39</sup> 2 Mathematical Framework

### <sup>40</sup> 2.1 Problem Definition

<sup>41</sup> Consider a set of  $P$  variables, where the  $p$ -th variable contains  $L_p$  observations  
<sup>42</sup> as  $\mathbf{x} = \{(t_l^{(p)}, x_l^{(p)})\}_{l=1,p=1}^{L_p,P}$ , being  $x_l^{(p)} \in \mathbb{R}$  the corresponding observation at  
<sup>43</sup> time  $t_l^{(p)} \in \mathbb{R}$ . A graph representation of that structure with  $P = 3$  is plotted in  
<sup>44</sup> Figure 1. Each  $\mathbf{x}$  has its own target variable  $\mathbf{y} \in \mathbb{R}^D$ , leading to a collection of  $N$   
<sup>45</sup> input-output i.i.d. pairs denoted as  $\mathcal{D} = \{\mathbf{x}_n, \mathbf{y}_n\}_{n=1}^N = \{\mathbf{X}, \mathbf{Y}\}$  called training  
<sup>46</sup> set. The task is to generalize the map from each input  $\mathbf{x}$  to its corresponding  
<sup>47</sup> target output  $\mathbf{y}$  in a stochastic fashion.

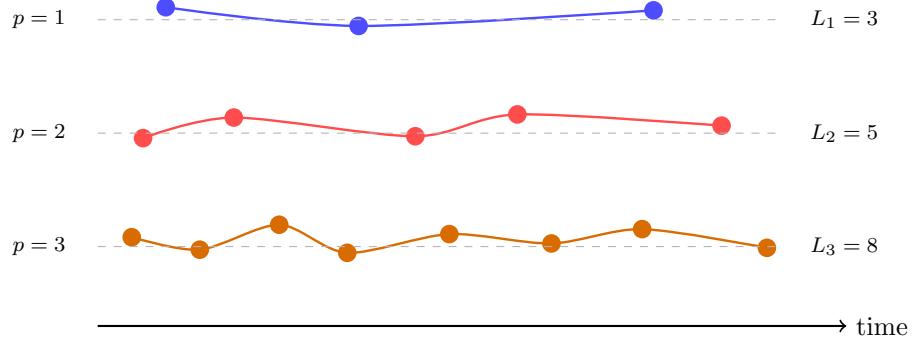


Figure 1: Structure of input samples. Each dot represent a pair  $(t_l^{(p)}, x_l^{(p)})$ .

### <sup>48</sup> 2.2 Likelihood Model

<sup>49</sup> For this propose, consider a likelihood functions that rule the generation of  
<sup>50</sup> recorded targets  $\mathbf{Y}$  from inputs  $\mathbf{X}$  through some set of parameters  $\boldsymbol{\theta} \subseteq \mathbb{R}^J$

$$p(\mathbf{Y} | \boldsymbol{\theta}(\mathbf{X})) = \prod_{n=1}^N p(\mathbf{y}_n | \boldsymbol{\theta}(\mathbf{x}_n)). \quad (1)$$

<sup>51</sup> Each element of  $\boldsymbol{\theta}(\mathbf{x})$ , denoted as  $\theta_j(\mathbf{x})$ , could be restricted to some subset  
<sup>52</sup> of  $\mathbb{R}$ . To handle that, we model  $\theta_j(\mathbf{x}) = h_j(f_j(\mathbf{x}))$  as a transformation of an  
<sup>53</sup> unrestricted latent variable  $f_j(\mathbf{x})$  via a link function  $h_j$ . Our task boils down  
<sup>54</sup> to finding the latent vector function  $\mathbf{f}(\mathbf{x}) = [f_1(\mathbf{x}), \dots, f_J(\mathbf{x})]^\top \in \mathbb{R}^J$ .

55    **3 Results**

56    **4 Conclusions**

57    **References**

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