

Deep Learning Methods for Reynolds-Averaged Navier-Stokes Simulations of Airfoil Flows

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Introduction





Background – RANS

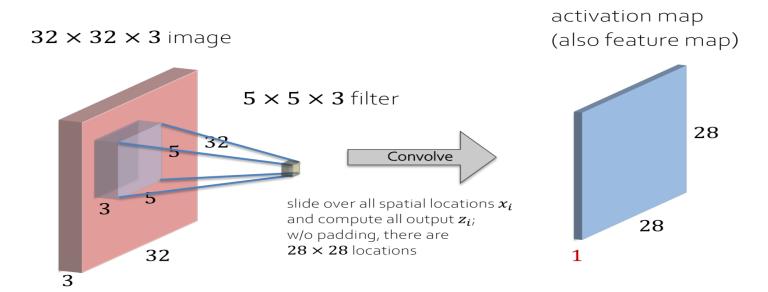




Background – RANS



Background – Convolutions

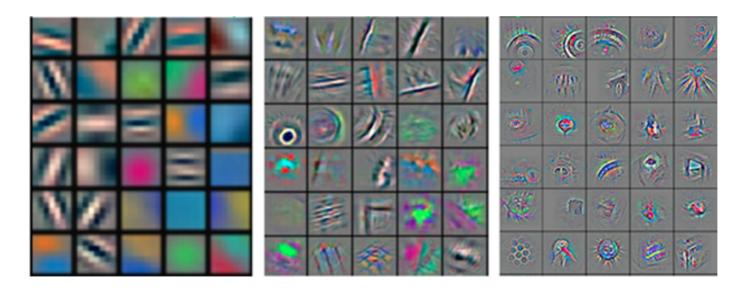


Taken from I2DL WS19/20 (TUM)



Background – Convolutions

Low-Level Features, Mid-Level Features, High-Level Features: each filter captures different characteristics



Taken from https://arxiv.org/pdf/1311.2901.pdf





Pre-processing





Pre-processing – Evaluation





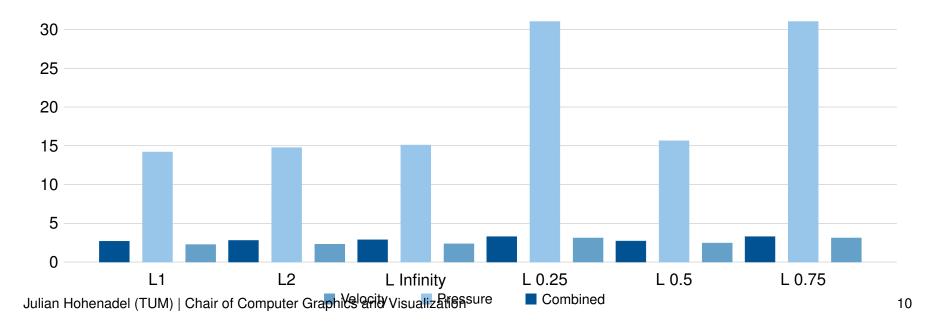
Pre-processing – Evaluation



Pre-processing – Evaluation

Vector norms used in pre-processing comparision wrt. error, L2 default (in %)

L1 normalization achieves the best error rates (pressure, velocity, combined: 14.19%, 2.251%, 2.646% – L2: 14.76%, 2.291%, 2.780%)

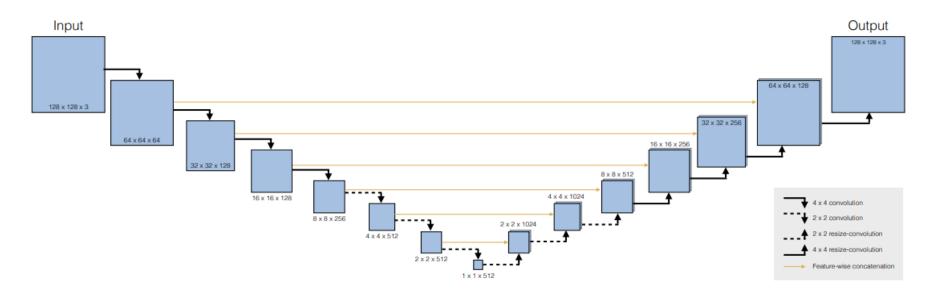






Architecture

U-Net derivative proposed in the paper:



Taken from https://arxiv.org/pdf/1810.08217.pdf



Architecture

Convolutional blocks:

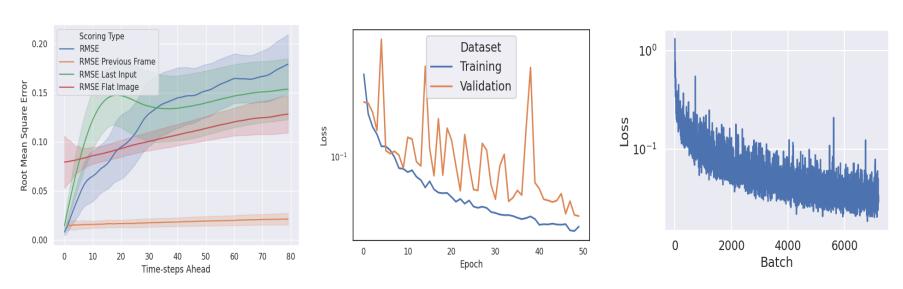


Architecture – Evaluation



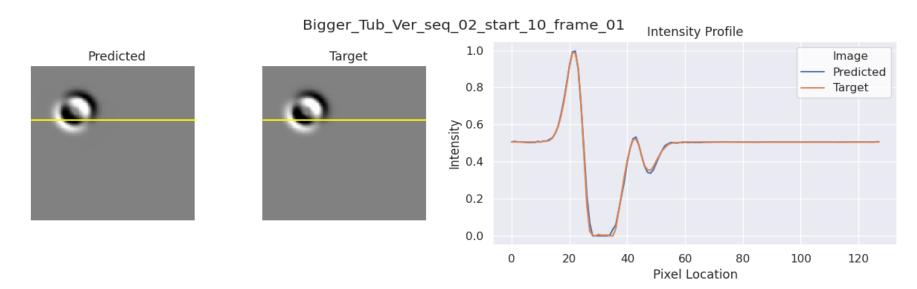


RMSE with variance, validation loss and batch loss on Bigger Tub environment:

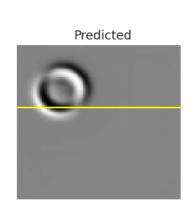


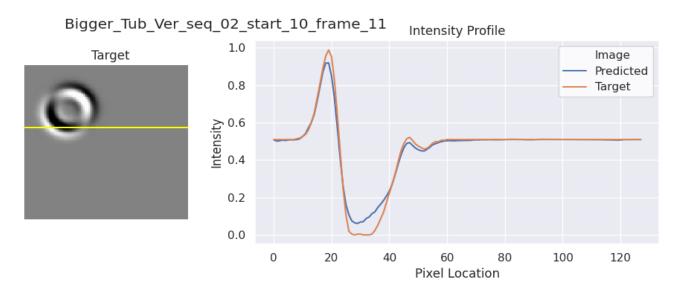
All plots in Transfer were made with https://github.com/stathius/wave_propagation



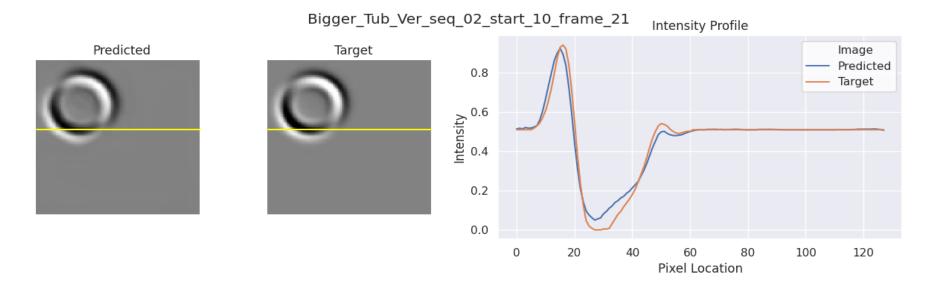




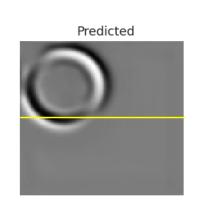


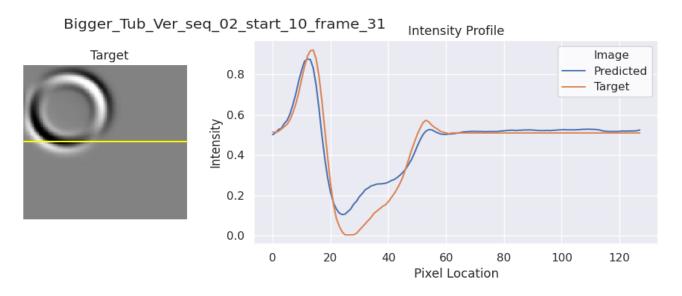




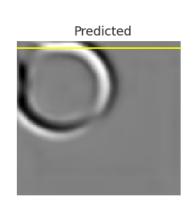


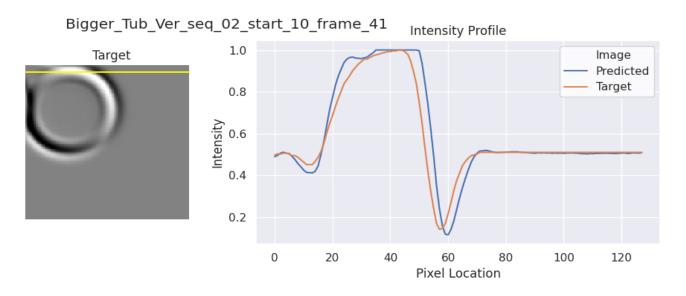




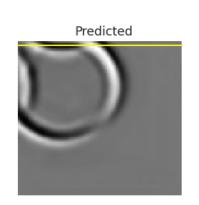


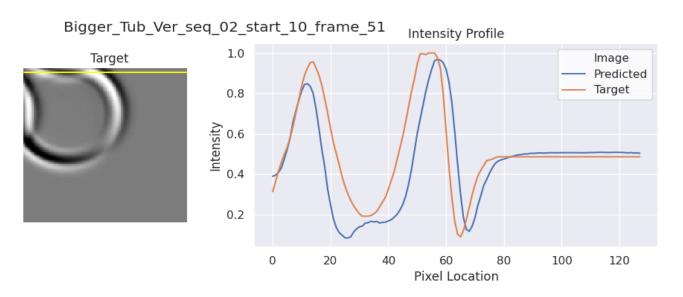




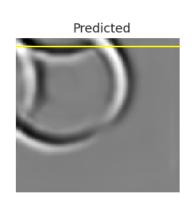


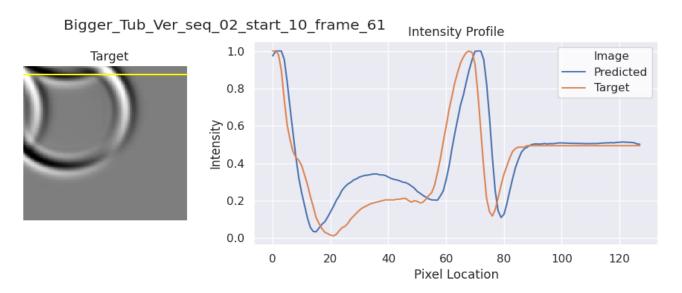




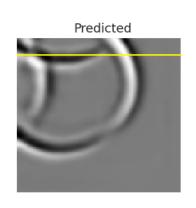


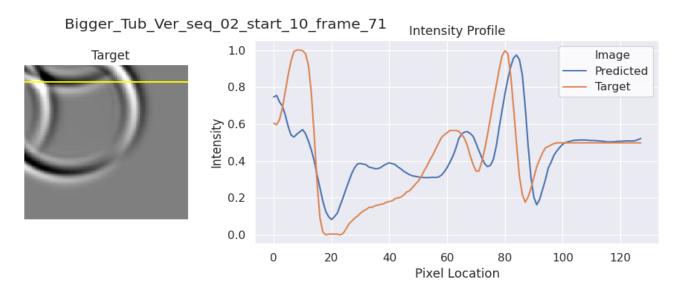












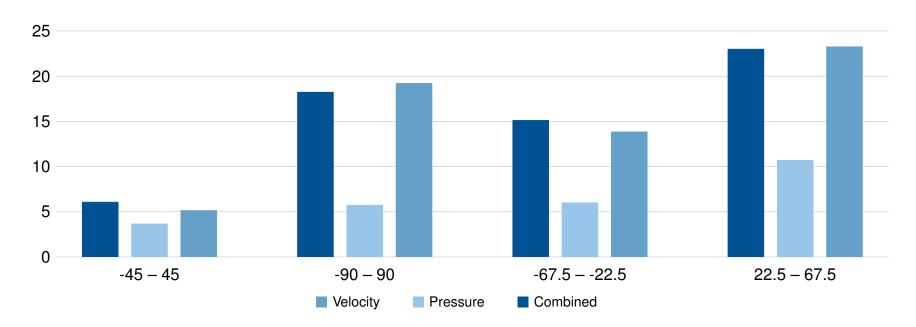


Generalization



Generalization

Error percentage of different angle of attack intervals wrt. ground truth [-22.5, 22.5]





Discussion



Summary



Backup slides