

pyCGNS.intro/Manual

Release 4.0.1

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pyCGNS is a Python package for the CGNS standard.

The package gathers various tools and libraries for end-users and Python application developpers. The main object of *pyCGNS* is to provide the application developpers with a Python interface to *CGNS/SIDS*, the data model. The *MAP* and *PAT* modules are dedicated to this goal: map the *CGNS/SIDS* data model to a *Python implementation*. The *WRA* module contains wrapper on *CGNS/MLL* and a *MLL-like* set of functions that uses the *CGNS/Python* mapping as implementation.

The package uses *numpy* and *HDF5* you should install before pyCGNS. The *CGNS.NAV* tools has an optional *VTK* viewer which requires the *VTK lib* and its python interface.

The *CGNS/SIDS* data model has a mapping the *HDF5* for file storage. The *MAP* module uses *CHLone* instead of *CGNS/MLL* to map its *CGNS/Python* trees to *HDF5*.

Note: The *pyCGNS* python package is released under LGPL2 license and hosted by sourceforge where you can find source download, help forum, wiki and bug tracking.

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1.1 About pyCGNS

1.1.1 Package contents

The pyCGNS Python module is a collection of 7 modules around the CGNS standard. Before v4, these modules were independent Python modules with more or less dependancies to each other. We gather all of them to have a common build/install/doc and test process, moreover this insures a better consistency between them.

The pyCGNS module now includes (former package names)

- **MAP, the Mapper, new in v4 gives basic load/save** function from/to *CGNS/SIDS* and *CGNS/HDF5*. This very sinple module is able to read/write GCNS/HDF5 files and translate them to CGNS/Python. This is the main feature of pyCGNS v4.0.
- **PAT, the PatterMaker, a full** *CGNS/SIDS* **patterns using** the *CGNS/Python* mapping. This is pure python module, it creates and modify CGNS/Python trees without the help of any HDF5 or even ADf calls.
- **NAV, the Navigater (pyS7), a graphical browser that can** handle *CGNS/Python*, *CGNS/HDF5* and *CGNS/ADF* file formats. It is slightly different to *adfviewer* because it actually a tree editor, you can copy/cut/paste CGNS/Python trees and quickly draft or modify your CGNS tree.
- **WRA, the Wrapper (pyCGNS), is a** *CGNS/MLL* **and** *CGNS/ADF* Python wrapping. All the CGNS/MLL functions are mapped to their Python clone.

VAL, the Validater (pyC5), an XML grammar based validation of a *CGNS/Python* tree, for example produced using *MAP* or *PAT*. *Unsuable in v4.0*

TRA, the Translater (pyCRAB), a set of translators from/to various formats. Unsuable in v4.0

DAT, the DataTracer (pyDAX), some DBMS services for CGNS/HDF5 files. Unsuable in v4.0

1.1.2 Quick start

Loading a CGNS/HDF file with MAP

The *CGNS.MAP* module implements the *CGNS/Python* mapping. You can load/save a *CGNS/HDF5* file using the simple *MAP* functions (below, the >>> string is the python interpreter prompt):

```
>>>import CGNS.MAP
>>>(tree,links)=CGNS.MAP.load("./001Disk.hdf",CGNS.MAP.S2P_FOLLOWLINKS)
>>>print tree
['CGNSTree', None, [['CGNSLibraryVersion',array([ 2.4000001],dtype=float32),
[], 'CGNSLibraryVersion_t'], ['Disk', array([3, 3], dtype=int32),
[['.Solver#Command', ...
```

Now tree is a Python list with the whole "./001Disk.hdf" CGNS tree into, with the data structure as described in SIDS-to-Python.

Using PAT to modify a CGNS tree

The previously loaded *CGNS/Python* tree is modified using plain Python functions and types. The *CGNS.APP* module contains utilities, we use the getNodeByPath function which returns a *CGNS/Python* node with the target tree and the target node path as parameters.:

```
import CGNS.APP.path_utils as U
node=U.getNodeByPath("/Disk/zone1/ZoneBC/ext1/PointRange", tree)
```

The returned node is a list of 4 Python values, the name (a string), the value of the node (a *Numpy* array), the list of children and the CGNS type of the node (string).

Using PAT to create a CGNS tree

We want to create a CGNS/HDF5 file with a simple base and a reference state:

```
import CGNS.MAP
import CGNS.PAT

T=CGNS.PAT.newCGNS()

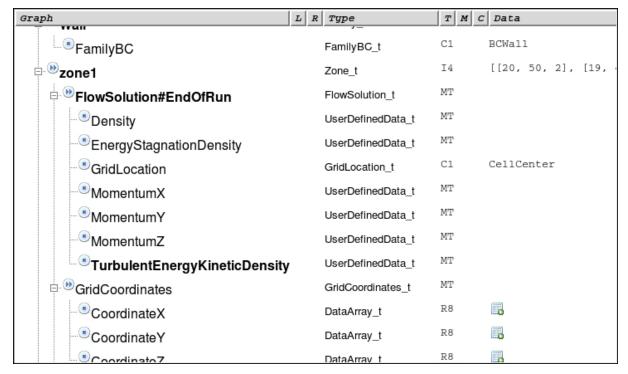
CGNS.PAT.newBase(T,'Test Case 01',3,3) # name, physical dim, topological dim

CGNS.PAT.newSimulationType(T)

CGNS.PAT.newReferenceState(T)
```

Browsing your CGNS tree with NAV

The CGNS.NAV tool is a CGNS tree brower. You start it typing CGNS.NAV and you can open several views on your file.



Re-using your CGNS/MLL scripts

If you really want to use CGNS/MLL, for example if you have a large toolbox with old pyCGNS scripts, you can import CGNS.WRA but you have to change your imports:

```
import CGNS.WRA.wrapper
filesol=CGNS.WRA.wrapper.pyCGNS(sname, CGNS.WRA.wrapper.MODE_WRITE)
filesol.basewrite('Base', 3, 3)
filesol.close()
```

1.2 Build and Install

1.2.1 Required libraries

The first step of the installation is to make sure you have the required libraries. The mandatory libs are *Python*, *numpy*, *HDF5* and *CHLone*. Then, if you wan to build *CGNS.WRA* (we recommend to do so), you need *libcgns*.

Warning: OUPS! you mean I don't need *libcgns* for the *CGNS/Python* mapping? **NO** you don't, *CGNS* is a data model (so-called *CGNS/SIDS*) and some mapping definitions of this model (such as *CGNS/HDF* for example). *pyCGNS* uses '*CHLone <http://chlone.sourceforge.net>* '_ which is another *CGNS/HDF5* compliant implementation.

- Python (starting from v2.4)
- numpy (v1.1 +)
- hdf5 (v1.8.5 +)
- CHLone (v0.4 +)
- tktreectrl (v2.2 +)

1.2.2 Optional libraries

The so-called *mid-level* library is not mandatory, the *WRA module* is the only one to have dependancies on. The *NAV module* also uses *CGNS/MLL* as optional if you want to be able to read *CGNS/ADF* files (see *File formats*)

• CGNS/MLL (libcgns) (starting v3.0)

1.2.3 Installation process

Once you have these installed you can proceed with pyCGNS. You go into the top directory and you edit the pyCGNSconfig.py.in (see *Configuration file contents*). You have to set the correct paths and various values such as directory search libs or flags.

Then you run:

```
python setup.py build
and then:
python setup.py install
or:
python setup.py install --prefix=/local/tools/installation
```

All the modules of the pyCGNS package are installed and you can now proceed with tutorial examples.

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1.2.4 Single module installation

You can ask for a single module installation:

```
python setup.py build --single-module=MAP
python setup.py install
```

You have to check that this installation doesn't overwrite an existing installation with the other pyCGNS modules.

1.2.5 Configuration file contents

The pyCGNSconfig_user.py should work with no modification if you have a standard installation. All you have to declare is the directory in which we can find *Python/numpy/hdf5/CHLone/cgns* libraries.

If you have specific installations you can change some paths/flags for each external library: *hdf5*, *numpy*, *CGNS/MLL* and *CHLone*. The configuration file is a Python file, it is imported after the default configuration. The changes you make in the configuration file will overwrite the defaults:

To avoid overwriting, use Python to update the config:

Release Notes

Many changes in this v4 release, you can only use MAP, WRA, PAT and NAV. The other modules, VAL, TRA and DAT are present for archival/development purpose but you should NOT use them.

Please go to http://www.python-science.org/projects/pyCGNS to have the version/tickets list.

Module dependancies

The pyCGNS modules have dependancies with their brothers. The list below gives you the required modules (or optional) for each of them.

```
MAP : NonePAT : MAPWRA : PAT MAP
```

• APP : PAT MAP

• NAV : PAT MAP APP (WRA)

1.2.6 NAV depends

The *TkTreectrl* module is required. You first need to install *tktreectrl* (last version tested is *tktreectrl-2.3*) and **TkinterTreectrl* to map it to Python (last version tested is *TkinterTreectrl-1.0*). You may have to add the *tktreectrl* path into a *TCLLIBPATH* shell variable (maybe you should add a *LD_LIBRARY_PATH* as well).

1.2.7 MAP depends

The *CHLone* librarie is required and thus *HDF5* is required.

1.2.8 WRA depends

CGNS/MLL and CGNS/ADF libraries are required. You should build the CGNS libraries with the CG_BUILD_SCOPE set to True. To do so, edit your CMakeCache.txt file and set the following variable to ON.

//Enable or disable scoping of enumeration values ${\tt ENABLE_SCOPING:BOOL=ON}$

1.3 Tests

1.3.1 Cross Matrix for data integrity

WRA can read/write CINS/ADF and CGNS/HDF5 files. MAP can read/write CGNS/HDF and CGNS/Python files PAT can read/write CGNS/Python files. APP can read/write CGNS/Python files. NAV can read/write all CGNS formats (using previous modules)

The matrix here after shows the tested translations.

write: WRA/ADF WRA/HDF MAP/HDF MAP/PY PAT/PY APP/PY NAV/ADF NAV/HDF NAV/PY

read: WRA/ADF | x WRA/HDF | x MAP/HDF | MAP/PY | PAT/PY | APP/PY | NAV/ADF | NAV/HDF | NAV/PY |

1.4 Glossary

- **CGNS** The specific purpose of the CFD General Notation System (CGNS) project is to provide a standard for recording and recovering computer data associated with the numerical solution of the equations of fluid dynamics. Read more here....
- **CGNS/SIDS** The *Standard Interface Data Structure* is the specification of the data model. This public document describes the syntax and the semantics of all tree-structured data required or proposed for a CFD simulation. Both an HTML and a PDF version are available here.
- **CGNS/MLL** The *Mid-Level Library* is an example implementation of *CGNS/SIDS* on top of *CGNS/ADF* and *CGNS/HDF5* mappings. This library has a C and a Fortran API.
- **CGNS/ADF** The *Advanced Data Format CGNS/SIDS* implementation. A binary storage format and its companion library, developped by *Boeing*.
- **CGNS/HDF5** The *Hierarchical Data Format CGNS/SIDS* implementation. A binary storage format and its companion library (see below).
- **CGNS/Python** The Python programming language *CGNS/SIDS* implementation. See the *SIDS-to-Python* page.
- **CHLone** A *CGNS/HDF5* compliant implementation. The CHLone library is available on SourceForge.

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HDF5 A powerful storage system for large data. The HDF5 library should be seen as a middleware system with a lot of powerful features related to efficient, portable and trustable storage mean.

numpy The numerical library for Python. *Numpy* is used to store the data in Python arrays which have a direct memory mapping to actual C or Fortran memory.

VTK A visualization toolkit used to display 3D objects ni CGNS.NAV.

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