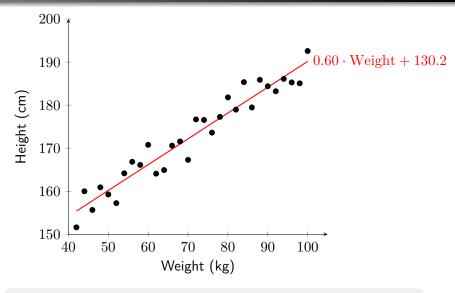
Data Mining Lectures - Support Vector Machines

Piotr Wąsiewicz

Institute of Computer Science pwasiewi@elka.pw.edu.pl

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Linear regression



Linear Regression Height = g(Weight) finds a trend in data.

Linear regression classifiers

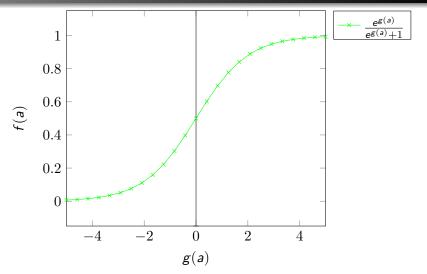
• Two-class classification - domain linear partition into the positive and negative regions by comparing against the threshold $g(a) = \langle \mathbf{wa} \rangle = \langle w_{n+1}^1 a_{n+1}^1 \rangle$, where $a_{n+1} = 1$ for the intercept term $b = w_0 = w_{n+1}$ from $g(a) = w_n^1 a_n^1 + w_0$

$$h(a) = H(g(a)) = \begin{cases} 1 & \text{if } g(a) \ge 0 \\ 0 & \text{otherwise} \end{cases}$$

• Class probability modeling - the logit representation $logit(p) = \ln \frac{p}{1-p}$, especially its inverse function called the logistic function

$$P(1|a) = logit^{-1}(g(a)) = \frac{e^{g(a)}}{e^{g(a)} + 1}$$

Logistic function



 The logistic function estimates probability (e.g. needed for ROC) of logical regression classification results.

VC (Vapnik–Chervonenkis) dimension of hyperplanes in \mathbb{R}^n

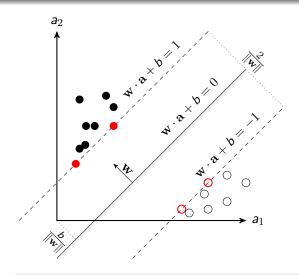
- For 4 points in 2D (a square or a matrix 2x2) and two classes:
 - it is not always possible to separate them with lines.

- n+1 points in \mathbb{R}^n can not be separated linearly
- The VC dimension of hyperplanes in \mathbb{R}^n is n+1

Support Vector Machines: basic linear examples

- Linear separation for two classes
- Some training data $\{\mathbf{a}_i, c_i\}_m^i$, $\mathbf{a}_i \in \mathbb{R}^n$, and $c_i \in \{-1, 1\}$
- Train to obtain the separation hyperplane:
 - ullet Minimize $d_+ + d_-$ to receive the shortest distances from the hyperplane
 - to closest positive point d₊
 - ullet to closest negative point d_-
- The goal is to find the separating hyperplane: wa + b = 0, where
 - a vector w is normal to the hyperplane
 - $\frac{|b|}{\|\mathbf{w}\|}$ is the distance to origin (0,0)
 - $\bullet \parallel \mathbf{w} \parallel$ the length of the vector \mathbf{w}
- Designing a road between trees on the left and rocks on the right.

Support Vector Machines



• $\max \frac{2}{\|w\|}$ - maximize the margin between parallel lines

Support Vector Machines

- d₊, d₋ the shortest distances from labeled points to hyperplane
- A margin $m = d_+ + d_-$
- The optimal separating hyperplane maximizes m and minimizes the VC dimension
- For the separating hyperplane:

$$\mathbf{wa}_i + b \ge +1, \quad c_i = +1 \tag{1}$$

$$\mathbf{w}\mathbf{a}_i + b \le -1, \quad c_i = -1 \tag{2}$$

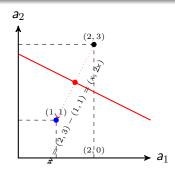
$$\equiv$$
 (3)

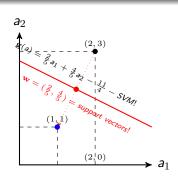
$$c_i(\mathbf{wa}_i + b) - 1 \ge 0, \quad \forall i$$
 (4)

For the closest points the equalities are satisfied, so:

$$d_{+} + d_{-} = \frac{|1 - b|}{\|w\|} + \frac{|-1 - b|}{\|w\|} = \frac{2}{\|w\|}$$
 (5)

Support Vector Machines: the linear example





$$\mathbf{w} = (2,3) - (1,1) = (x,2x) \tag{1}$$

for point
$$(2,3)$$
: $wa + b = +1$ (2)

$$2x + 6x + b = 1$$
 (3)
 $b = 1 - 8x$ (4)

$$b = 1 - 8x$$
 (4)
for point $(1, 1) : \mathbf{wa} + b = -1$ (5)

$$x + 2x + b = -1$$
 (6)

$$x + 2x + 1 - 8x = -1 \tag{7}$$

$$\frac{2}{11}$$
 (8)

$$a = \frac{2}{5} b = -\frac{11}{5}$$
 (8)

Support vectors :
$$w = (\frac{2}{5}, \frac{4}{5})$$

$$\underline{SVM}: g(a) = \mathbf{wa} + b \tag{10}$$

(9)

$$\underline{SVM}: g(a) = \frac{2}{5}a_1 + \frac{4}{5}a_2 - \frac{11}{4}$$
 (11)

$$\forall c(a) \in c_1 \ g(a) >= 1 \tag{12}$$

$$\forall c(a) \in c_2 \ g(a) <= -1 \tag{13}$$

Support Vector Machines: Lagrangian

- The constraints is more easy to handle.
- Using dual form SVM models predictions and calculations can be performed without using any attribute values other than inside dot products.
- Instead of calculating model parameters Lagrange multipliers are used.
- Prepared for the kernel trick to swap the dot product with the kernel special function.

Optimization problem with constraints

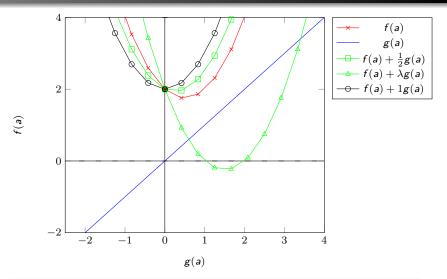
Minimize f(a) as a primal optimization problem

$$\min_{a} f(a)$$
 with constraints: $g_i(a) = 0, i = 1, ..., m$.

- Lagrangian is made of f(a) and constraints: $L(a, \lambda) = f(a) + \lambda g(a)$
- Minimize $L(a, \lambda)$ in a domain a in a dual optimization problem.
- After minimization with derivatives of Lagrangian $L(a, \lambda)$ equal to 0, maximize $L(a, \lambda)$ in a domain lambda.

$$\min_{a} \max_{\lambda} f(a) + \lambda g(a)$$

Optimization primal and dual problem example



- $\qquad \qquad \lambda = 1 \text{ for Lagrangian } \max_{\lambda > 0} \min_{\mathbf{a}} f(\mathbf{a}) + \lambda g(\mathbf{a}) \text{ dual optimal solution}.$
- ullet Result is the same for primal and dual problem solution: (0,2)

Support Vector Machines: Lagrangian

• For $\{\mathbf{a}_i, c_i\} \in \mathbb{R}^N \times \{-1, 1\}$ a primal problem minimization:

$$\min_{\mathbf{w},b} \qquad \frac{1}{2}||\mathbf{w}||^2$$
 Subject to $c_i\left(\langle \mathbf{w}, \mathbf{a} \rangle + b\right) \geq 1.$ (1)

• An unconstrained problem with the Lagrange multipliers for minimization $\min_{\mathbf{w},b} L(\mathbf{w},b,\lambda)$

$$L(\mathbf{w}, b, \lambda) = \frac{1}{2} ||\mathbf{w}||^2 - \sum_{i} \lambda_i \left(c_i(\langle \mathbf{w}, \mathbf{a} \rangle + b) - 1 \right), \qquad (2)$$

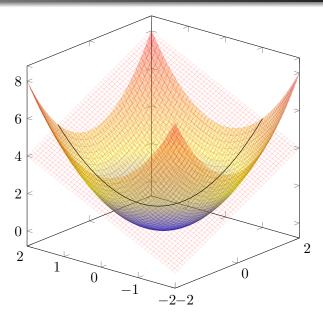
ullet Convex quadratic programming dual problem $\max_{\lambda>0} L_D$

$$L_D = \sum_{i=1}^{l} \lambda_i - \frac{1}{2} \sum_{i,j=1}^{l} \lambda_i \lambda_j c_i c_j \langle \mathbf{a}_i \mathbf{a}_j \rangle$$
 (3)

$$C \ge \lambda_i \ge 0 \tag{4}$$

$$\sum_{i} \lambda_{i} c_{i} = 0 \tag{5}$$

The dot product surface $x^2 + y^2$ cut by a plane x + y + 4



Support Vector Machines: Lagrangian

From dual problem

$$\max_{\lambda>0} \min_{\mathbf{w},b} \qquad L(\mathbf{w},b,\lambda)$$

• to a quadratic optimization problem

$$\max_{\lambda>0} \sum_{i} \lambda_{i} - \frac{1}{2} \sum_{i,j} \alpha^{t} K \alpha$$
$$K_{ij} = \langle \mathbf{a}_{i} \mathbf{a}_{j} \rangle$$
$$\alpha_{i} = \lambda_{i} c_{i}$$

- Solution only depends on support vectors $\mathbf{w}_{\lambda>0}$
- All others have $\lambda_i=0$ and can be moved arbitrarily far from the decision hyperplane or removed
- Such the dual problem is solved with the help of a gradient descent, which is appropriate for dot products.
- The kernel trick can be applied and K can be replaced by an inner product $\phi(x_i).\phi(x_j)$ in a higher dimensional space.

Support Vector Machines: space transformation

• Take points from \mathbb{R}^d to some space \mathcal{H} :

$$\Phi: \mathbb{R}^d \to \mathcal{H} \tag{1}$$

Choose kernel function K such that

$$K(a_i, a_j) = \Phi(\mathbf{a}_i)\Phi(\mathbf{a}_j) \tag{2}$$

• Since in the Lagrangian formula we only have a_i in dot products, we don't even need to know Φ !

Support Vector Machines: kernel

- Replacing $\langle \mathbf{a}_i \mathbf{a}_j \rangle$ with $K(\mathbf{a}_i, \mathbf{a}_j)$ everywhere do all the magic.
- Training is identical and takes almost similar time.
- Separation is still linear, but in a different space (infinite-dimensional!)
- Kernel examples:
 - Gaussian Kernel

$$K(\mathbf{a}_i, \mathbf{a}_j) = e^{\frac{-\|\mathbf{a}_i - \mathbf{a}_j\|^2}{2\sigma^2}} \tag{1}$$

Polynomial

$$K(\mathbf{a}_i, \mathbf{a}_j) = (\gamma \langle \mathbf{a}_i \mathbf{a}_j \rangle + b)^p \tag{2}$$

Based on neural net elements

$$K(\mathbf{a}_i, \mathbf{a}_j) = \tanh(\kappa \langle \mathbf{a}_i \mathbf{a}_j \rangle - \delta)^p \tag{3}$$

SVM For Multiple Classes

- Build n "1-vs-all" classifiers:
 - It costs *n* times the complexity of one classifier and the most confident answer should be chosen.
- Build $\frac{n(n-1)}{2}$ "1-vs-1" classifiers:
 - The instances are assigned by voting, so many classifiers have a small number of instances.
- Large Margin DAG's for Multiclass Classifications (Platt)
 means the Decision Directed Acyclic Graph (DDAG), which is
 used to combine many two-class classifiers into a multiclass
 classifier.
- Probabilities are calibrated by logistic regression on the SVM's scores.

Conclusions

- Effective in cases where number of dimensions is greater than the number of samples.
- Support Vector Machines have different performance depending on the scaling of the data.
- Uses a subset of training points in the decision function (called support vectors), so it is also memory efficient.
- Complexity dependent on the number of support vectors (and also the kernel type) and is generally between $O(n^2)$ and $O(n^3)$ with n the amount of training instances.
- Performance depends on choice of kernel and parameters.
- If the number of features is much greater than the number of samples, the method is likely to give poor performances.