Julian Ing

Robotics Engineer



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Key Skills

- Problem solving Quick to find alternative solutions when confronted with obstacles
- Adaptability Able to rapidly devise working products in previously unknown fields
- Great teamworking Through collaborations with other businesses and leading several group projects at university
- Process improvement Wealth of experience streamlining operational processes to be as efficient as possible
- Entrepreneurial Established my own profitable buisness and constantly looking for new business opportunities
- Interpersonal skills Managing customer relationships for over five years
- Bilingual Fluent in French speaking, reading and writing

Proficient in

- ROS + ROS2
- Python
- Solidworks
- Machine learning/ Neural networks
- Kinematics
- Signal processing
- Autonomous + robotic system design
- Problem anticipation
- Technical writing
- Critical thinking
- Project management

Confident with

- C++
- Embedded systems
- Sensor intergration
- Power electronics
- Control systems
- Altium
- Computer vision
- Matlab/Simscape/Simulink

Interests

- Actively engaged in exploring advancements in Robotics, Brain-Computer Interfaces, and Aerospace, through regular reading, podcasts, and attending live talks
- Nature, Hiking, Philosophical debate

Profile

- · Dedicated, astute, and effective.
- Incredibly passionate about the advancement of technology, particularly within the fields of robotics and bioengineering.
- Driven to push the boundaries of human potential by integrating biology with technology,
 whether through direct augmentation or by advancing robotics to become an active part of society
- Proven ability to rapidly acquire new skills and implement complex systems
- Practical experience in a wide range of robotic disciplines
- My continued success during my studies has refined my excellent problem solving skills, effective analytical abilities, and a competence in adapting to any environment or task.
- Lead several projects, gaining great experience in working with a multidisciplinary team.
- I maintain a logical, and down-to-earth approach to life

Education

Imperial / Meng Human and biological robotics

October 2023 / October 2024

Awarded Master of science with merit, and a distinction for my masters thesis

Middlesex University / Beng Robotics

September 2019 / June 2022

Achieved a first with honours degree classification

Richmond College /Electronic and Electrical Engineering

September 2017 / June 2019

Achieved D*DD NVQ level 3

Coombe Boys School

September 2013 / June 2017

Achieved 11 A*-C

Projects

Dual thumb anthropomorphic robotic hand for advanced dexterity

ROS, Python, Solidworks, Kinematics, Rapid prototyping, Project management, Autonomous + robotic system design, Embedded systems.

Developed a novel robotic hand (Bi-TILDA) to enhance dexterity, grasp stability, and manipulation capabilities, demonstrating significant improvements in workspace reach and complex manipulation tasks compared to traditional anthropomorphic designs.

EEG motor imagery control of a robotic manipulator

Python, Neural Networks, Signal Processing

Devised and implemented a brain-computer interface to control a UR10 robotic arm with imagined hand movements, captured from the motor cortex.

Motorised augmentation for manual wheelchair

Embedded systems, Rapid Prototyping, Human centered design, Power electronics. Repurposed e-scooter parts to create a convertible wheelchair attachment with an accessibile control interface.

Uno! opponent software

Computer vision, Neural networks, Python

Devised a CNN to identify Uno cards and play appropriate moves according to its deck.

Experience

Middlesex University / Student Learning Assistant

September 2021 - September 2022

Due to my exceptional performance, I was asked to be a teaching assistant for the year below's robotics and mechatronics module. I Assisted in technical tutoring.

Seraph Clothing Ltd. / Cheif Executive Director

March 2020 - October 2024

Meticulously managed all aspects of the business, from customer liaison to regulatory compliance.