Hey! I'm Pitch!

Hello World!

I am Pitch!

I was born to win games and entertain whoever wants to play with me!

Explore my brain here:



(66)

1997 was an unpleasant experience, but it helped me understand the future of human-machine collaboration. We thought we were unbeatable, at chess, Go, shogi. All these games, they have been gradually pushed to the side [by increasingly powerful AI programs]. But it doesn't mean that life is over. We have to find out how we can turn it to our advantage.

Garry Kasparov,

after his chess defeat against AI

Our goal: entertain people

3 games, only 1 winner!

Simon says ...

Rock Paper Scissors

Spin the Wheel

1. Pitch's infrastructure

A bodybuilded robot!

1. Pitch's infrastructure

2 axis servoed camera -

Remote control

Buzzer -

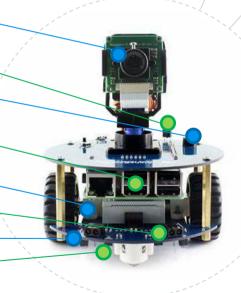
Raspberry Pi 4B

DC motorised wheels-

Infrared proximity sensors-

LEDs -

IR line trackers



Pitch's infrastructure



Ubuntu 20.04 LTS

- Heavier than Raspbian
- + More compatible with libraries



ROS Noetic

- + designed for ubuntu 20.04
- + Noetic means intellect.



Libraries sources

LEDs <u>rpi_ws281x</u>

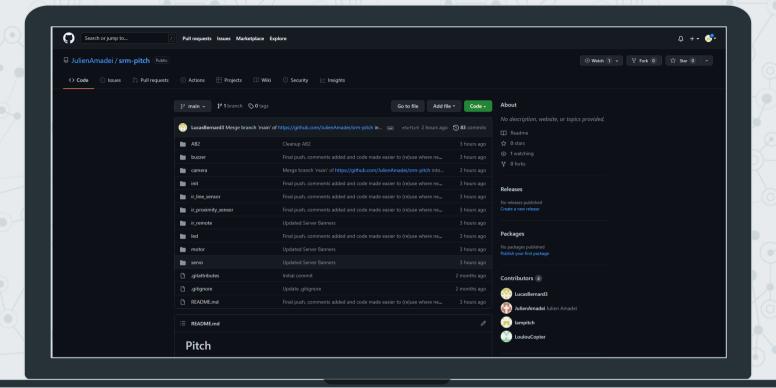
Camera

<u>PCA9685</u> <u>Mediapipe</u>

<u>Cvzone</u>

Alphabot

Alphabot2 standard libraries



Git project

For an optimized programmation collaboration.

ROS and GIT, a great collab!



Time

Fast to tranfer files using git instead of a USB key.

ROS locates errors with precision.



Windows / Linux

Nodes can be edited on Windows and added to the ROS project on Linux.



Collaboration

Nodes can be edited separately and connected with only a node name.



Flexible coding

Three teammates, three coding habits, but it works, doesn't it?



Updates & Versioning

With git, data is updated with a log registry to follow its evolution.

Avoids overwritting.



Easy to use

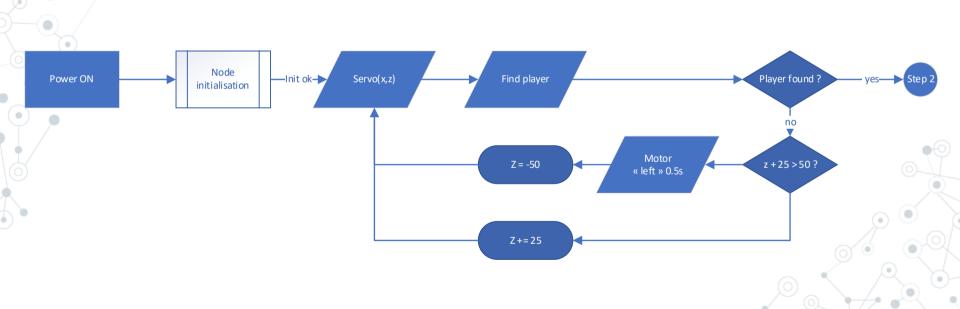
ROS is adapted to many languages, you don't have to learn a specific one!



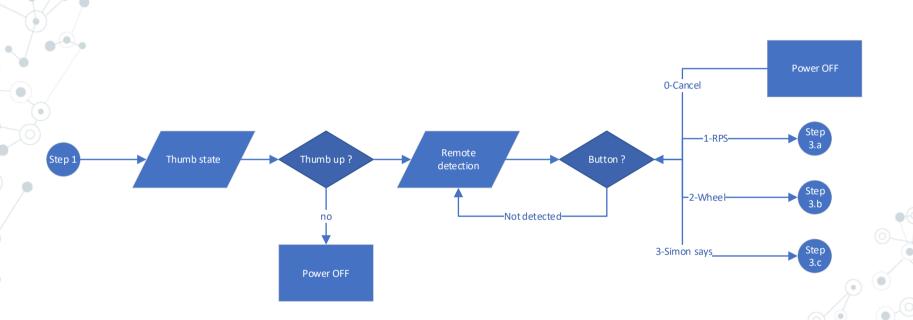
2. The initialization

Pitch, wake up!

2. The initialization



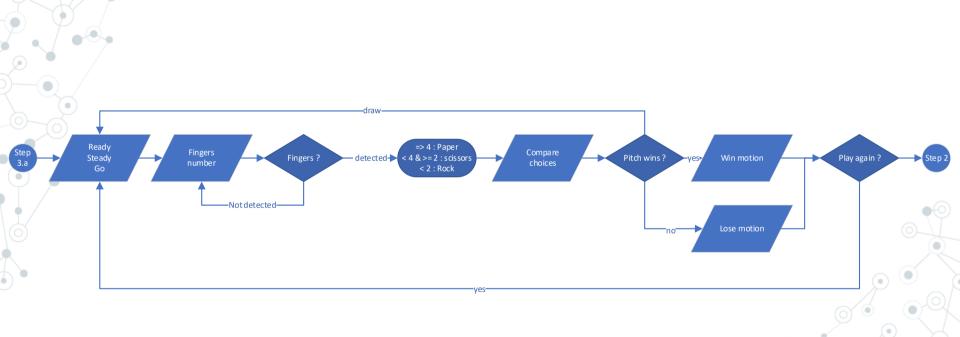
2. The initialization



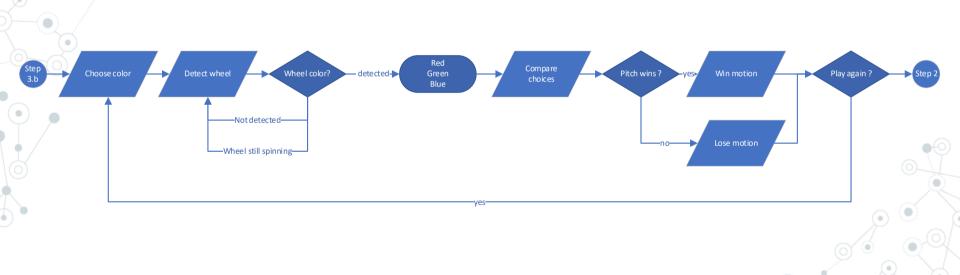
3. The Games

Let's win.

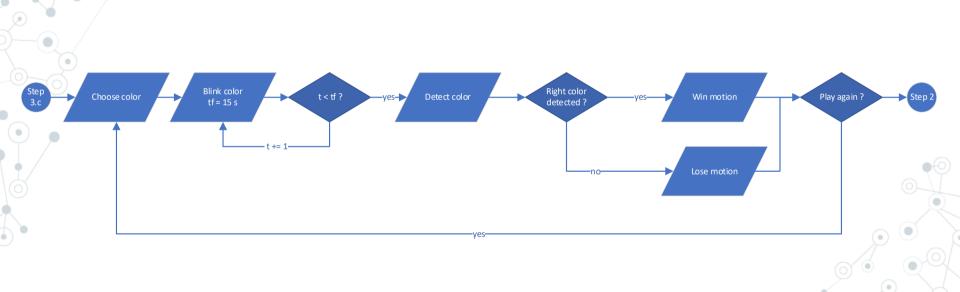
3. Game 1: Rock, Paper, Scissors



3. Game 2: Spin the Wheel



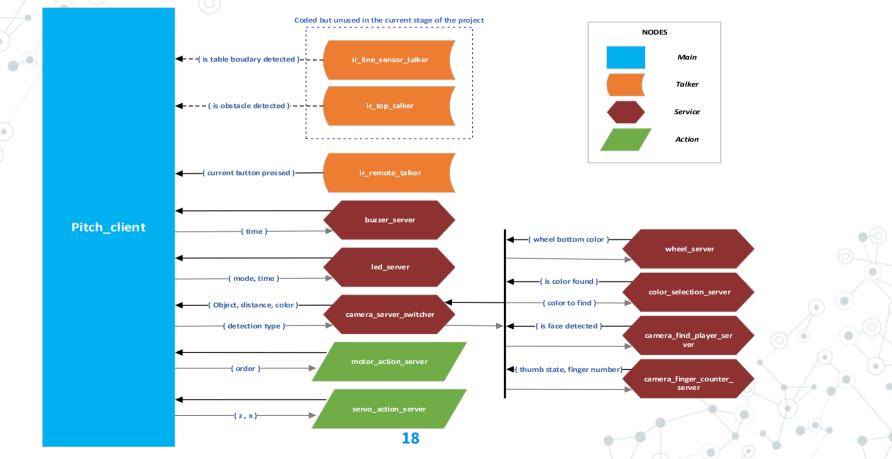
3. Game 3: Simon Says



Structure with ROS

Is it that efficient?

4. Structure with ROS



Structure with ROS /motor_action_server/action_topics /motor_action_server /wheel_server /statistics /rqt_gui_py_node_8024 /pitch_client /remote_input /color_selection_server /buzzer_server /camera_find_player_server /servo_action_server/ /rosout /rosout /rosout agg /camera_finger_counter_server /servo_action_server/action_topics /ir_remote_talker /servo_action_server /led_server /camera_server_switcher /ir_topL /ir_topR /ir_top_talker /ir_line_sensor_talker /ir_line_sensor

Let's play!

Will you defeat it?

6. Conclusion.

Worth it?