

Artificial Neural Networks to solve dynamic programming problems: a bias-corrected Monte Carlo estimator¹

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Table of Contents

1 Introduction

2 Theory

3 A large scale model

4 Conclusion

Context: The Unreasonable Effectiveness of Machine Learning

Figure: The success of AlphaGo

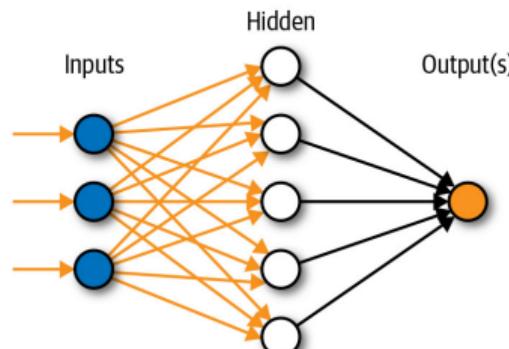


Source: [AlphaGo \(film\)](#)

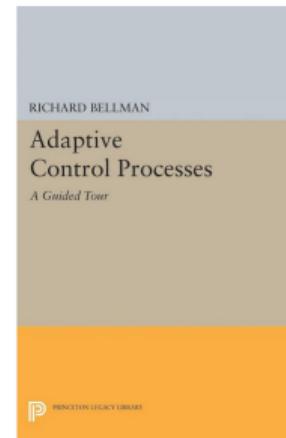
This Paper

Global approach that uses **Artificial Neural Networks** to solve **Economic Models**

Artificial Neural Network



Artificial Neural Network



$$\mathbf{x} \rightarrow \mathcal{N}_\rho(\mathbf{x}) = \sigma_K(\mathbf{W}_K \dots \sigma_2(\mathbf{W}_2 \sigma_1(\mathbf{W}_1 \mathbf{x} + \mathbf{b}_1) + \mathbf{b}_2) \dots + \mathbf{b}_K)$$

Why this paper?

- **High Dimensional Models in Economics**
 - HA models: Aiyagari (1994), Krusell and Smith (1998)
 - HANK models: Kaplan et al. (2018)
 - firm dynamics (Khan and Thomas, 2008), multi-country models (Backus et al., 1992), OLG models (Marchiori and Pierrard, 2015)
- **Why Global Methods?**
 - non-differentiable models
 - linearization may eliminate interesting amplification mechanisms (certainty equivalence)
 - a non-stochastic steady-state may not exist in the first place
- **Why ANNs?**
 - theory: universal function approximation theorems (Hornik et al., 1989), resilient to the curse of dimensionality (Barron, 1993)
 - practice: backpropagation algorithm (Rumelhart et al., 1986), GPUs

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Literature Review

① Global methods:

- Smolyak's sparse grid Krueger and Kubler (2004) and Judd et al. (2014)
- Adaptive sparse grid Brumm and Scheidegger (2017)
- Gaussian processes Scheidegger and Bilionis (2019)

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Contributions

- ① Contribution 1: generalize the all-in-one expectation operator of Maliar et al. (2021) with the bc-MC operator. all-in-one
- ② Contribution 2: derive theoretical properties for the bc-MC operator
- ③ Contribution 3: numerical illustrations and discussion on time-accuracy trade-offs

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Table of Contents

① Introduction

② Theory

③ A large scale model

④ Conclusion

General Structure of Economic Models

Example

 J equations

- Functional stochastic equation:

$$\mathbb{E}_\epsilon \left(f(s, \epsilon) \right) = 0 \text{ for } \forall s \in S \quad (1)$$

Examples: Euler or Bellman equations.

- Solution is a parametric decision function $\underbrace{\mathcal{ANN}(s|\theta)}_{\text{neural network}} = s'$, which minimizes the loss:

$$\mathcal{L}(\theta) = \mathbb{E}_s \left[\mathbb{E}_\epsilon \left(f(s, \epsilon|\theta) \right)^2 \right] \quad (2)$$

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The biased Monte Carlo Estimation

To approximate $\mathcal{L}(\theta)$, replace **population means** by **sample averages** (Monte Carlo integration):

$$\mathcal{L}_{M,N}^B(\theta) = \frac{1}{M} \sum_{m=1}^M \left[\frac{1}{N} \sum_{n=1}^N f(s_m, \epsilon_n | \theta) \right]^2 \quad (3)$$

Bias ($\text{Var}[g(x)] = \mathbb{E}[g(x)^2] - \mathbb{E}[g(x)]^2 \Leftrightarrow \mathbb{E}[g(x)^2] = \mathbb{E}[g(x)]^2 + \text{Var}[g(x)]$) :

$$\begin{aligned} \mathbb{E}_\epsilon \left[\left(\frac{1}{N} \sum_{n=1}^N f(s_m, \epsilon_n | \theta) \right)^2 \right] &= \left(\mathbb{E}_\epsilon \left[\frac{1}{N} \sum_{n=1}^N f(s_m, \epsilon_n | \theta) \right] \right)^2 + \text{Var}_\epsilon \left(\frac{1}{N} \sum_{n=1}^N f(s_m, \epsilon_n | \theta) \right) \\ \mathbb{E}_\epsilon \left[\left(\frac{1}{N} \sum_{n=1}^N f(s_m, \epsilon_n | \theta) \right)^2 \right] &= \underbrace{\mu_{s_m}^2}_{\text{true value}} + \underbrace{\frac{\sigma_{f,s_m}^2}{N}}_{\text{bias}} \end{aligned} \quad (4)$$

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The biased-corrected Monte Carlo estimator

The **minimum variance unbiased estimator** (MVUE) of μ^2 is $\hat{\mu}^2 - \frac{S_n^2}{N}$ (Das (1975)):

$$\mathcal{L}_{M,N}^U(\theta) = \frac{1}{M} \sum_{m=1}^M \left\{ \left[\frac{1}{N} \sum_{n=1}^N f(s_m, \epsilon_n | \theta) \right]^2 - \underbrace{\frac{S_{m,n}^2}{N}}_{\text{remove the bias with s. variance}} \right\} \quad (5)$$

Proposition

- ① The biased-corrected Monte Carlo estimator (5) can be expressed as:

$$\mathcal{L}_{M,N}^U(\theta) = \frac{2}{MN(N-1)} \sum_{m=1}^M \sum_{1 \leq i < j}^N f(s_m, \epsilon_m^i | \theta) f(s_m, \epsilon_m^j | \theta) \quad (6)$$

where ϵ^i and ϵ^j are i.i.d shocks with the same distribution as ϵ (N series of i.i.d shocks).

- ② In the special case with $N = 2$:

$$\mathcal{L}_{M,2}^U(\theta) = \frac{1}{M} \sum_{m=1}^M f(s_m, \epsilon_m^1 | \theta) f(s_m, \epsilon_m^2 | \theta)$$

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Proposition (choice of hyperparameters M and N)

Proposition 4

- ① Let $e_{M,N}(f|\theta)$ denote the **integration error**:

$$e_{M,N}(f|\theta) \equiv \mathbb{E}_s \left[\mathbb{E}_{\epsilon} \left(f(s, \epsilon | \theta) \right)^2 \right] - \underbrace{\mathcal{L}_{M,N}^U(\theta)}_{\text{stochastic}}$$

- ② The mean squared integration error is equal to:

$$\mathbb{E} \left[e_{M,N}(f|\theta)^2 \right] = \underbrace{\text{Var}(\mathcal{L}_{M,N}^U(\theta))}_{\text{calculable}} \quad (7)$$

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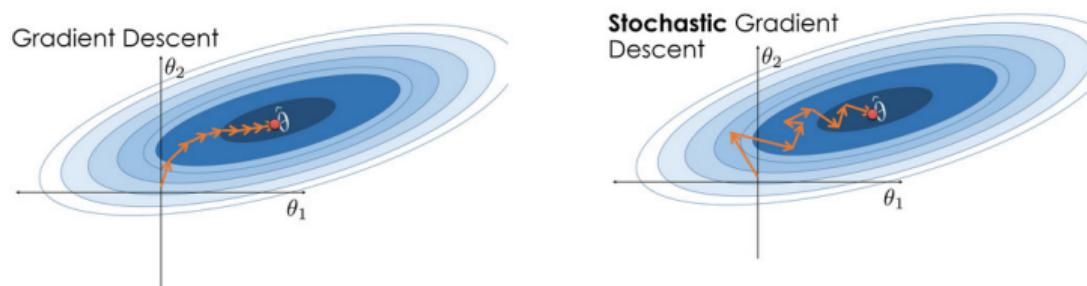
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Training by stochastic gradient descent

$$\theta_{i+1} = \theta_i - \gamma \nabla_{\theta} \mathcal{L}_{M,N}^U(\theta_i) \quad (8)$$

Figure: GD and SGD



Source

The **smaller the variance** of the stochastic gradient, the **faster the training** (Katharopoulos and Fleuret (2018)).

Takeaways

The biased-corrected Monte Carlo estimator:

$$\mathcal{L}_{M,N}^U(\theta) = \frac{2}{MN(N-1)} \sum_{m=1}^M \sum_{1 \leq i < j}^N f(s_m, \epsilon_m^i | \theta) f(s_m, \epsilon_m^j | \theta)$$

- Model with a **lot of uncertainty**: set N high (use many different series of independent shocks)
Neogrowth model
- Model with a **lot of non-linearities**: set M high (use many draws in the state space)
Model with a borrowing constraint
- See proposition 4 in the paper
Proposition 4

Table of Contents

① Introduction

② Theory

③ A large scale model

④ Conclusion

Model with a borrowing constraint

Case $l = 2$

$$\max_{\{c_t\}_{t=0}^{\infty}} \mathbb{E} \left[\sum_{t=0}^{\infty} \beta^t u(c_t) \exp(\delta_t) \right] \quad (9)$$

- constraint: $0 \leq c_t \leq w_t$
- $w_{t+1} = (w_t - c_t)\bar{r} \exp(r_{t+1}) + \exp(y_{t+1})$, $y_t = \exp(\sum_{i=1}^l p_{i,t})$
- $\beta \in (0, 1)$, $\bar{r} \in (0, \frac{1}{\beta})$, $u(c) = \frac{c^{1-\gamma}}{1-\gamma}$

AR(1) processes:

$$\begin{aligned} p_{i,t+1} &= \rho_{i,p} p_{i,t} + \sigma_{i,p} \varepsilon_{i,t+1}^p, \quad \forall i \in 1, 2, \dots, l \\ r_{t+1} &= \rho_r r_t + \sigma_r \varepsilon_{t+1}^r \\ \delta_{t+1} &= \rho_\delta \delta_t + \sigma_\delta \varepsilon_{t+1}^\delta \end{aligned} \quad (10)$$

state $s = (w, r, \delta, p_1, \dots, p_l)$ with $d_s \equiv 3 + l$ elements, shock $\varepsilon = (\varepsilon^r, \varepsilon^\delta, \varepsilon_1^p, \dots, \varepsilon_l^p)$
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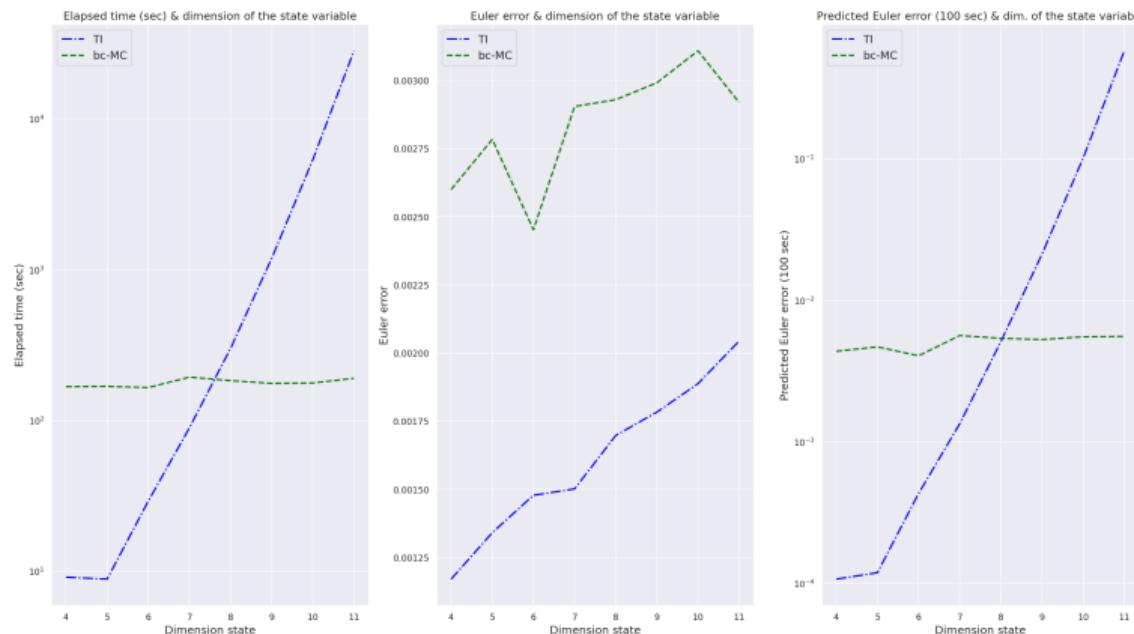
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bc-MC and Time Iteration: time-accuracy trade-off

Figure: bc-MC vs TI: time and accuracy



bc-MC and Time Iteration: time-accuracy trade-off

Figure: bc-MC vs TI: time and accuracy large scale model

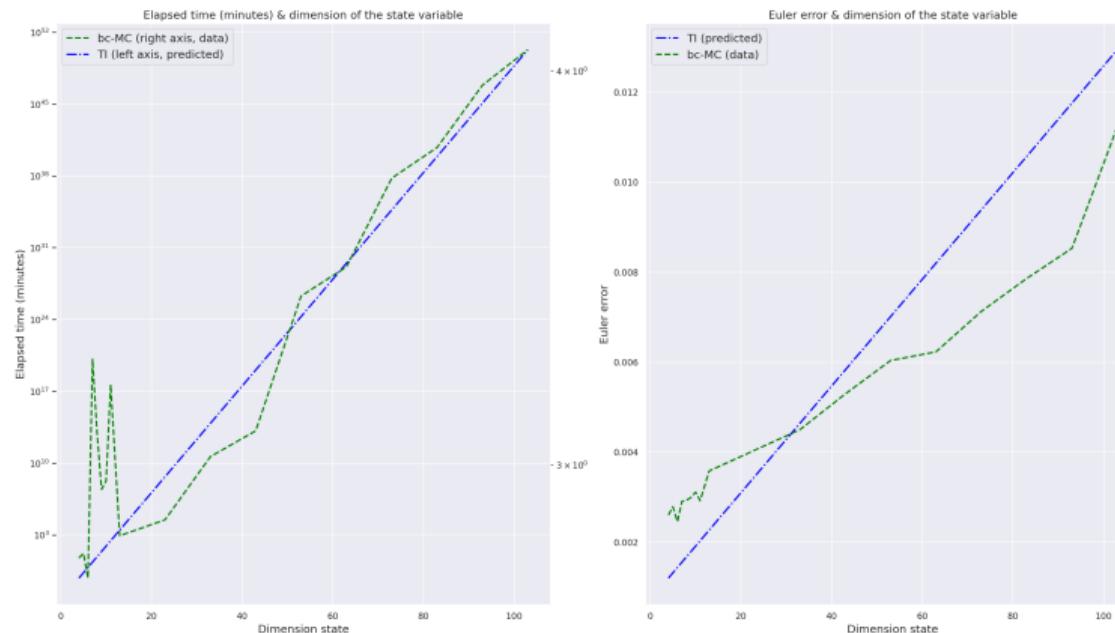


Table of Contents

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② Theory

③ A large scale model

④ Conclusion

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Introduction
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Theory
oooooooo

A large scale model
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Conclusion
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References

Thank You

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All-in-one Maliar et al. (2021)

Contributions

Proposition 2

Key idea (AIO):

$$\left(E_{\varepsilon}[f(\varepsilon)] \right)^2 = E_{\varepsilon_1}[f(\varepsilon_1)]E_{\varepsilon_2}[f(\varepsilon_2)]$$

But also (bc-MC):

$$\left(E_{\varepsilon}[f(\varepsilon)] \right)^2 = \frac{1}{3} \left(E_{\varepsilon_1}[f(\varepsilon_1)]E_{\varepsilon_2}[f(\varepsilon_2)] + E_{\varepsilon_1}[f(\varepsilon_1)]E_{\varepsilon_3}[f(\varepsilon_3)] + E_{\varepsilon_2}[f(\varepsilon_2)]E_{\varepsilon_3}[f(\varepsilon_3)] \right)$$

Or

$$\left(E_{\varepsilon}[f(\varepsilon)] \right)^2 = \frac{1}{6} \left(E_{\varepsilon_1}[f(\varepsilon_1)]E_{\varepsilon_2}[f(\varepsilon_2)] + E_{\varepsilon_1}[f(\varepsilon_1)]E_{\varepsilon_3}[f(\varepsilon_3)] + E_{\varepsilon_1}[f(\varepsilon_1)]E_{\varepsilon_4}[f(\varepsilon_4)] + \dots \right)$$

etc.

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J stochastic functional equations

Structure

Economic model:

$$\mathbb{E}_\epsilon \left(f_j(s, \epsilon) \right) = 0 \quad \text{for } s \in S \text{ and } j \in 1, \dots, J \quad (11)$$

Loss:

$$\mathcal{L}(\theta) = \sum_{j=1}^J \vartheta_j \mathbb{E}_s \left[\mathbb{E}_\epsilon \left(f_j(s, \epsilon | \theta) \right)^2 \right] \quad (12)$$

The biased-corrected Monte Carlo estimator writes:

$$\mathcal{L}_{M,N}^U(\theta) = \sum_{j=1}^J \vartheta_j \left(\frac{1}{M} \sum_{m=1}^M \left\{ \left[\frac{1}{N} \sum_{n=1}^N f_j(s_m, \epsilon_n | \theta) \right]^2 - \frac{S_{j,m,n}^2}{N} \right\} \right) \quad (13)$$

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Stochastic neogrowth model

[Structure](#)
[Takeaways](#)

$$\max_{\{c_t\}_{t=0}^{\infty}} \mathbb{E} \left[\sum_{t=0}^{\infty} \beta^t u(c_t) \right] \quad (14)$$

- constraints $0 \leq c_t \leq y_t$
- $y_{t+1} = g(y_t - c_t)\eta_{t+1}$, $\eta_t \equiv \eta(\nu_t) = \exp(\mu + \sigma_\nu \nu_t)$, $\nu \sim \mathcal{N}(0, 1)$
- $u(c) = \log(c)$, $g(k) = k^\alpha$, $\beta \in (0, 1)$

Euler equation characterizing the model:

$$\mathbb{E}_\nu \left[u' \left(c(y|\theta) \right) - \beta u' \left(c \left(g(y - c(y|\theta))\eta(\nu) \middle| \theta \right) g'(y - c(y|\theta))\eta(\nu) \right) \right] = 0 \quad (15)$$

Equation (15) is an example of equation (1):

$$f(s, \varepsilon) = u' \left(c(s|\theta) \right) - \beta u' \left(c \left(g(s - c(s|\theta))\eta(\varepsilon) \middle| \theta \right) g'(s - c(s|\theta))\eta(\varepsilon) \right)$$

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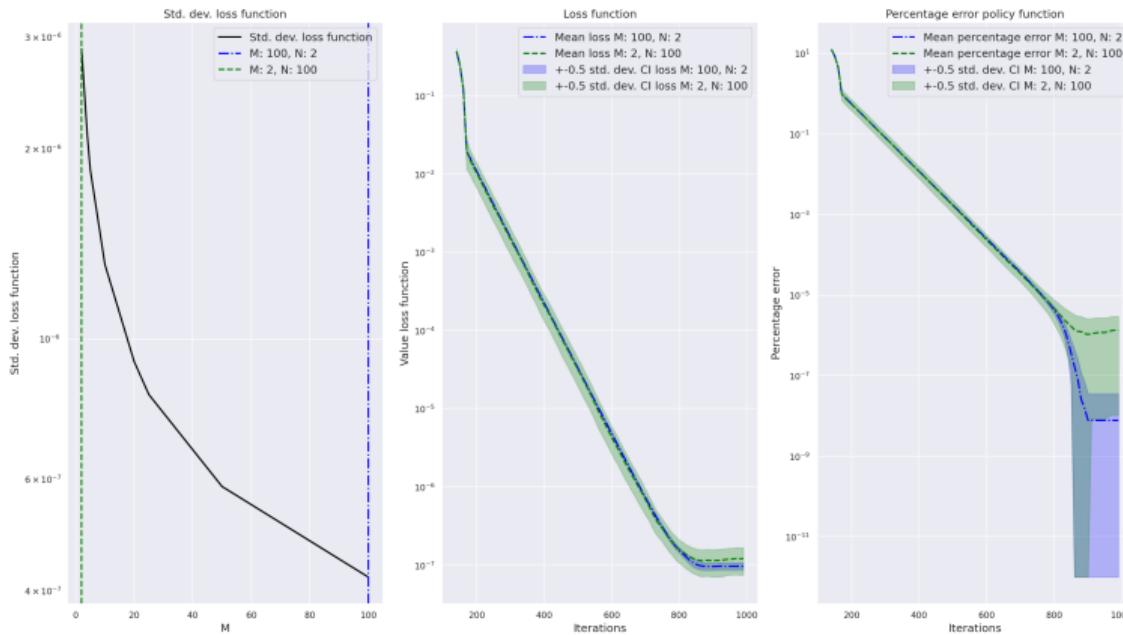
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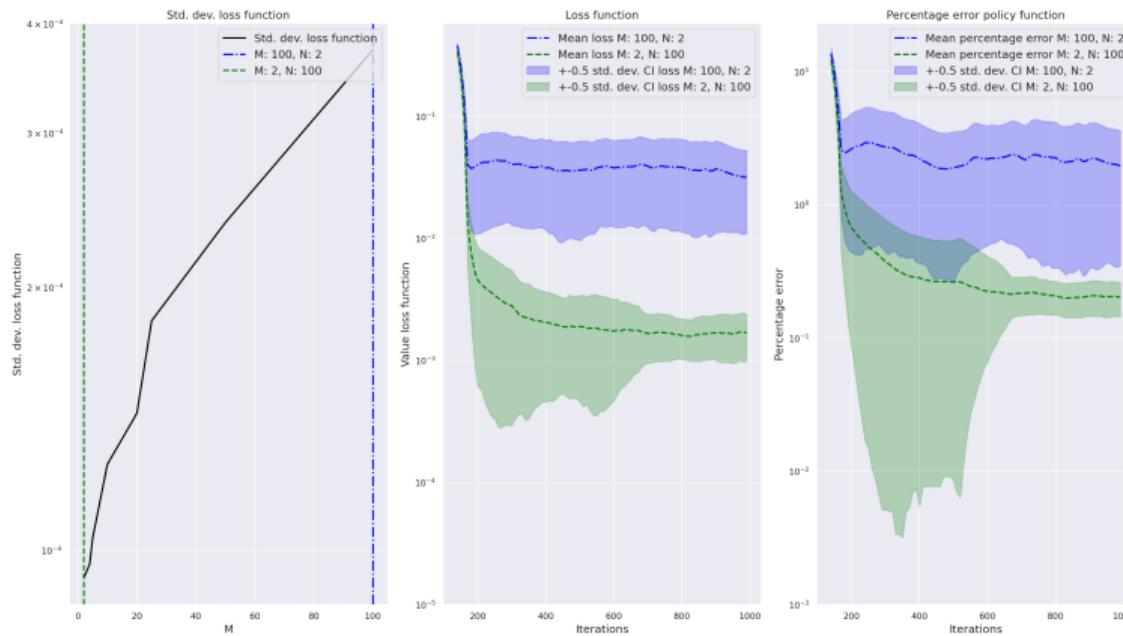
Stochastic neogrowth model

Figure: Low-uncertainty parametrization ($\sigma_\nu = 0.5$)



Stochastic neogrowth model

Figure: High-uncertainty parametrization ($\sigma_\nu = 1.5$)



Optimal consumption with a borrowing constraint

Takeaways

$$\max_{\{c_t\}_{t=0}^{\infty}} \mathbb{E} \left[\sum_{t=0}^{\infty} \beta^t u(c_t) \exp(\delta_t) \right] \quad (16)$$

- constraint: $0 \leq c_t \leq w_t + b$
- $w_{t+1} = (w_t - c_t)\bar{r} \exp(r_{t+1}) + \exp(y_{t+1})$, $y_t = \exp(p_t + q_t)$
- $\beta \in (0, 1)$, $\bar{r} \in (0, \frac{1}{\beta})$, $u(c) = \frac{c^{1-\gamma}}{1-\gamma}$

The four exogenous variables are assumed to follow AR(1) processes:

$$\begin{aligned} p_{t+1} &= \rho_p p_t + \sigma_p \varepsilon_{t+1}^p \\ q_{t+1} &= \rho_q q_t + \sigma_q \varepsilon_{t+1}^q \\ r_{t+1} &= \rho_r r_t + \sigma_r \varepsilon_{t+1}^r \\ \delta_{t+1} &= \rho_\delta \delta_t + \sigma_\delta \varepsilon_{t+1}^\delta \end{aligned} \quad (17)$$

Optimal consumption with a borrowing constraint

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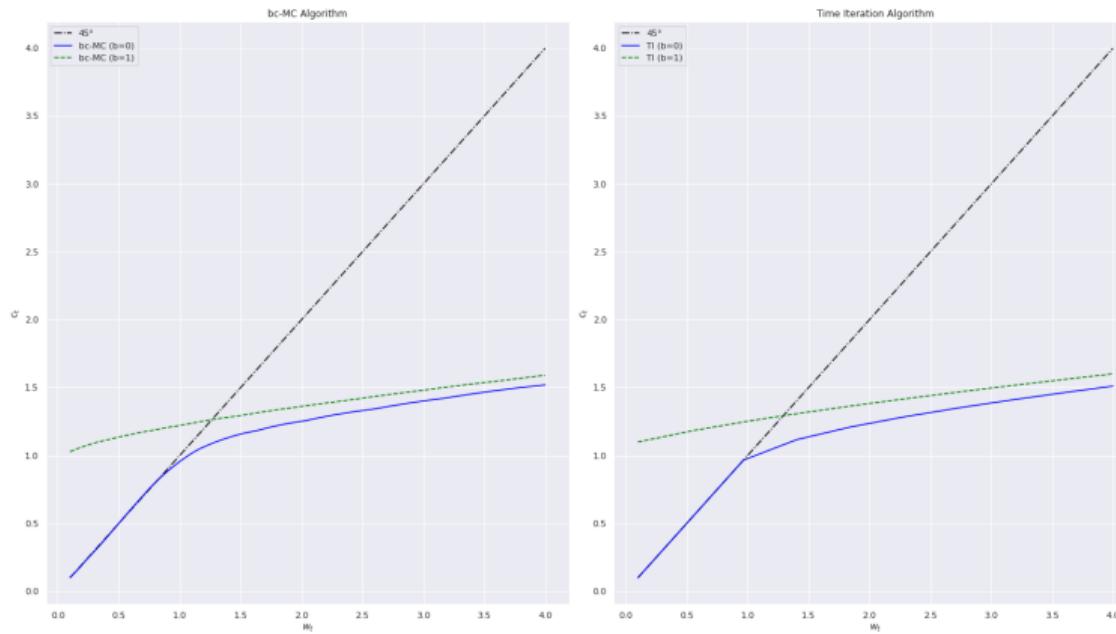
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Optimal consumption with a borrowing constraint

[Back](#)[Large scale model](#)

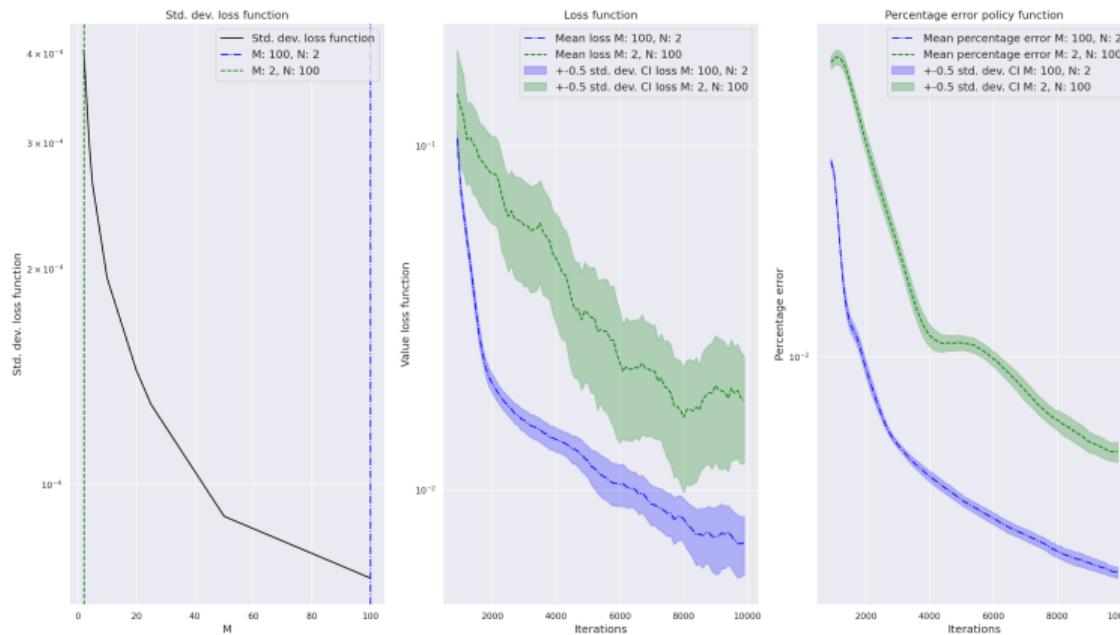
Figure: bc-MC estimator (left) and Time Iteration (right)



Optimal consumption with a borrowing constraint

[Back](#)

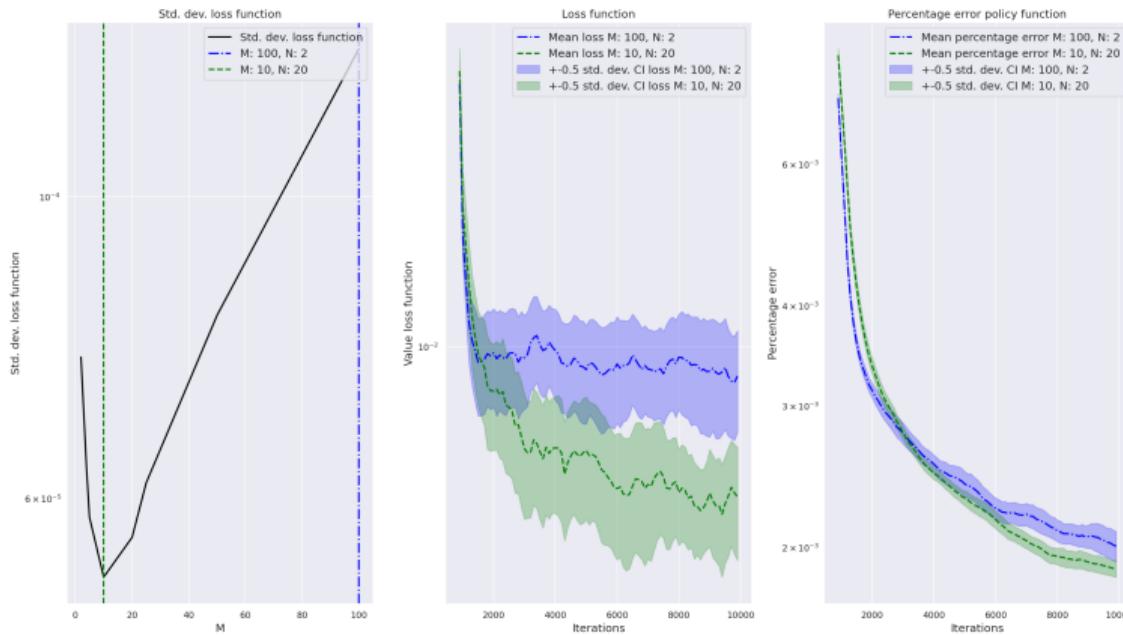
Figure: Model with a borrowing constraint ($b = 0$) solved with the bc-MC estimator



Optimal consumption with a borrowing constraint

[Back](#)

Figure: Model with a borrowing constraint ($b = 1$) solved with the bc-MC estimator



Proposition

[Back](#)

Define $T \equiv \frac{MN}{2}$, $2T$ is the number of function calls $f(\cdot)$ within the loss function

- ① $\text{Var}(\mathcal{L}_{M,N}^U(\theta))$ is proportional to $\frac{1}{T}$
- ② If $f(s_m, \varepsilon_m | \theta) = f(\varepsilon_m | \theta)$, $\forall s \in S$ (\approx high-variance model):

$$\text{Var}(\mathcal{L}_{M,N}^U(\theta)) = \frac{1}{T(N-1)} \text{Var} \left(f(s_m, \varepsilon_m^1 | \theta) \right)^2 + \frac{2}{T} \mathbb{E} \left[f(s_m, \varepsilon_m^1 | \theta) \right]^2 \text{Var} \left(f(s_m, \varepsilon_m^1 | \theta) \right) \quad (18)$$

- ③ If $f(s_m, \varepsilon_m | \theta) = f(s_m | \theta)$, $\forall \varepsilon_m \in \mathcal{E}$ (\approx highly non-linear model):

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