

# acc\_data\_gps.c

---

This program works with the TD1205P module from TDNEXT. The aim is to send some information about the device, which are its GPS coordinates, its battery level and the temperature. At the same time, it prints information about accelerometer if the user decides to use serial communication. It will print x, y and z values. These data will appear 3 minutes after the launching of the program. A keepalive message is sent at every boot.

## Useful information

- For configuring the environment, use the tutorial: <http://www.instructables.com/id/Sigfox-GPS-Tracker/>
- This example is only built and tested for TD1205P module.
- In order to see the received messages, use Sigfox backend: <https://backend.sigfox.com>

## General message format

For transceiving information on the Sigfox network, this program uses a 12 bytes format. Message is formed by using some code from the tutorial:

- 4 bytes: GPS longitude or free
- 4 bytes: GPS latitude or free
- 1 byte: voltage
- 1 byte: temperature
- 2 bytes: free

The baud rate which is used here is 9600 bits/s.

## Commands

Users can change some parameters of the program using serial communication. Indeed, it is possible to communicate with the module thanks to putty.exe, a free and open-source terminal emulator and serial console. Commands must be typed during the 3 minutes after the launching of the program.

### *AT\$ACCFREQ=*

- Used for choosing the frequency to retrieve accelerometer data.
- If empty, it prints the current value.
- (value: frequency) - (1: 1Hz), (2: 10Hz), (3: 25Hz), (4: 50Hz), (5: 100Hz), (6: 200Hz), (7: 400Hz), (8: 1.25KHz).
- Default value: 1Hz.

#### *AT\$ACCSCALE=*

- Used for choosing the scale to detect movement. This value has an impact on the accuracy of the accelerometer data.

- If empty, it prints the current value.
- (value: scale) - (1: 2G), (2: 4G), (3, 8G), (4: 16G)
- Default value: 2G.

#### *AT\$ACCDATA=*

- Possibility to choose if accelerometer data has to be printed on the serial console.
- If empty, it prints the current configuration.
- 0: x, y and z values will not be printed on putty.exe.
- 1: x, y and z values will be printed on putty.exe. This display will be stopped a few moments when the module sends a message on the Sigfox network.
- Default value: 1.

#### *AT\$INTERVAL=*

- This interval is the time between two consecutive messages sent on the Sigfox network.
- If empty, it prints the current value.
- When there is a positive value after this command, this value become the new interval in seconds. Don't forget that Sigfox supports 140 messages a day!
- Default value: 3600 seconds (1 hour).

#### *AT\$MODE=*

- Used for choosing GPS Power mode.
- 0 for *TD\_GEOLOC\_OFF* mode: with this mode, there is no RAM retention, everything is off, there is no consumption. The module doesn't store any information about the fixing and the satellites.
- 1 for *TD\_GEOLOC\_HW\_BCKP* mode: with this mode, there is RAM retention. The module can store the last information about the fixing and the satellites in the RAM. It means that the fixing time for finding GPS data will be significantly shorter the next time the GPS will wake up in order to get data.
- 2 for *TD\_GEOLOC\_POWER\_SAVE\_MODE* mode: this mode is like the navigation mode (fully on) but the receiver is switched on/off every couple of seconds in order to save power.
- Default value: *TD\_GEOLOC\_HW\_BCKP*.

*AT\$TIMEOUT=*

- This data is the duration during which the GPS tries to find satellites in order to have GPS coordinates.
- If empty, it prints the current value.
- When there is a positive value after this command, this number will be the new timeout.
- Default value: 120 seconds.