Runge Kutta Method For Stochastical Integration

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Suppose we have the following stochastic process \mathbf{X}_t presented as:

$$d\mathbf{X}_t = \sigma(\mathbf{X}_t, t)d\mathbf{W}_t + \mu(\mathbf{X}_t, t)dt,$$

where \mathbf{W}_t is the Brownian motion.

We aim to perform numerical integration from 0 to T with respect to $f(\mathbf{X}_t)$. Assume f is C^3 , and denote $\Pi = \{0 = t_0 < t_1 < \cdots < t_N = T\}$ as a generic partition of the interval [0, T].

To control the local truncation error during the numerical integration, we apply the Runge-Kutta method by comparing the Stratonovich integral and Itô's formula, thereby dynamically updating the time step Δt .

The Stratonovich integral is given as:

$$df(\mathbf{X}_t) = f'(\mathbf{X}_t) \circ d\mathbf{X}_t.$$

Numerically, this can be expressed as:

$$f(\mathbf{X}_{t_i}) - f(\mathbf{X}_{t_{i-1}}) \approx f'\left(\frac{\mathbf{X}_{t_{i-1}} + \mathbf{X}_{t_i}}{2}\right) \left(\mathbf{X}_{t_i} - \mathbf{X}_{t_{i-1}}\right).$$

By applying Taylor's formula with a remainder term, we obtain:

$$f'\left(\frac{\mathbf{X}_{t_{i-1}} + \mathbf{X}_{t_{i}}}{2}\right) \left(\mathbf{X}_{t_{i}} - \mathbf{X}_{t_{i-1}}\right) = f'(\mathbf{X}_{t_{i-1}}) \left(\mathbf{X}_{t_{i}} - \mathbf{X}_{t_{i-1}}\right) + \frac{1}{2} f''(\mathbf{X}_{t_{i-1}}) \left(\mathbf{X}_{t_{i}} - \mathbf{X}_{t_{i-1}}\right)^{2} + \frac{1}{8} f'''(\mathbf{X}_{t_{i-1}}) \left(\mathbf{X}_{t_{i}} - \mathbf{X}_{t_{i-1}}\right)^{3} + o\left(\mathbf{X}_{t_{i}} - \mathbf{X}_{t_{i-1}}\right)^{3}$$

where ξ lies between $\mathbf{X}_{t_{i-1}}$ and \mathbf{X}_{t_i} .

Itô's formula provides another expression for the numerical integration as:

$$f(\mathbf{X}_{t_i}) - f(\mathbf{X}_{t_{i-1}}) \approx f'(\mathbf{X}_{t_{i-1}}) \left(\mathbf{X}_{t_i} - \mathbf{X}_{t_{i-1}}\right) + \frac{1}{2} f''(\mathbf{X}_{t_{i-1}}) \left(\mathbf{X}_{t_i} - \mathbf{X}_{t_{i-1}}\right)^2.$$

Next, we consider the quadratic term $(\mathbf{X}_{t_i} - \mathbf{X}_{t_{i-1}})^2$. We first investigate the variation of the process $\langle \mathbf{X}_T, \mathbf{X}_T \rangle$, which is defined as:

$$\langle \mathbf{X}_T, \mathbf{X}_T \rangle = \lim_{N \to \infty} \sum \left(\mathbf{X}_{t_i} - \mathbf{X}_{t_{i-1}} \right)^2.$$

Since

$$\mathbf{X}_T = \mathbf{X}_0 + \int \sigma(\mathbf{X}_t, t) d\mathbf{W}_t + \int \mu(\mathbf{X}_t, t) dt,$$

we have

$$\langle \mathbf{X}_T, \mathbf{X}_T \rangle = \langle \sigma(\mathbf{X}_T, T) \mathbf{W}_T, \sigma(\mathbf{X}_T, T) \mathbf{W}_T \rangle + 2 \langle \sigma(\mathbf{X}_T, T) \mathbf{W}_T, \mu(\mathbf{X}_T, T) T \rangle + \langle \mu(\mathbf{X}_T, T) T, \mu(\mathbf{X}_T, T) T \rangle.$$

Due to the relation:

$$\langle W, W \rangle_t \stackrel{p}{=} t,$$

we get

$$(\mathbf{X}_{t_i} - \mathbf{X}_{t_{i-1}})(t_i - t_{i-1}) \stackrel{p}{\approx} (\Delta t)^{\frac{3}{2}},$$

and

$$(t_i - t_{i-1})(t_i - t_{i-1}) \approx (\Delta t)^2.$$

By dropping higher-order terms, we can estimate the local truncation error (LTE) as:

$$\mathbf{LTE} \approx \frac{1}{8} \| f'''(\mathbf{X}_{t_{i-1}}) \| \| \sigma(\mathbf{X}_{t_{i-1}}, t_{i-1}) \|^{3} (\Delta t)^{\frac{3}{2}}.$$

The error **err** is estimated as:

$$\mathbf{err} = \left\| \frac{\text{LTE}}{s} \right\|,$$

where $s = \text{atol} + \text{rtol} \cdot \max(\|f(\mathbf{X}_{i-1})\|, \|f(\mathbf{X}_i)\|)$, with 'atol' and 'rtol' being the prescribed error tolerances.

Thus, we have the following estimated relation:

$$rac{ extbf{LTE}_{ ext{new}}}{ extbf{LTE}_{ ext{old}}} \sim rac{(\Delta t_{ ext{new}})^{rac{3}{2}}}{(\Delta t_{ ext{old}})^{rac{3}{2}}}.$$

We choose the $\Delta t_{\rm new}$ such that

$$\mathbf{err}_{\mathrm{new}} = 1 \Rightarrow \Delta t_{\mathrm{new}} = \frac{\Delta t_{\mathrm{old}}}{(\mathbf{err}_{\mathrm{old}})^{\frac{2}{3}}}.$$

By introducing safety factors α , α_{\min} , and α_{\max} , along with the above results, we obtain the time step updating formula:

$$\Delta t_{\text{new}} = \Delta t_{\text{old}} \cdot \min \left(\alpha_{\text{max}}, \max \left(\alpha_{\text{min}}, \alpha \cdot \left(\frac{1}{\text{err}} \right)^{\frac{2}{3}} \right) \right).$$