

Priority queues

Priority queues?



A priority queue is a **data structure**.

Data structures

Data structure = data + operations on it

Data:

- ▶ Normally structured as an ID plus additional data. The ID is also called a key.
- ▶ We usually do not mention the additional data. That is, elements are referred to simply as ID, but they are actually (ID, data) or (ID, reference to data).
- ▶ The ID is often from an ordered universe (has an order), e.g., int, float, String.

Operations:

- ▶ The properties of the data structure are defined by the **provided operations** and their **runtime performance**.
- ▶ The goals are **flexibility** and **efficiency** (which are usually conflicting objectives).

Priority queues

Data:

- **Element** = key (ID) from an ordered universe, possibly with additional data.

Core operations (max-version of priority queue):

- **Q.Extract-Max**: Returns the element with the largest key in the priority queue Q (an arbitrary such element if multiple have the same key). The element is removed from Q .
- **Q.Insert(e : element)**: Adds the element e to the priority queue Q .

Note: We can sort using these operations.

$n \times \text{Insert}$

$n \times \text{Extract-Max}$

Priority queues

Additional operations:

- ▶ **Q.Increase-Key(*r*: reference to an element in Q, *k* key)**: Changes the key to $\max\{k, \text{old key}\}$ for the element referenced by *r*.
- ▶ **Q.Build(*L*: list of elements)**: Builds a priority queue containing the elements in list *L*.

Trivial operations for all data structures:

- ▶ **Q.CreateNewEmpty(), Q.RemoveEmpty(), Q.IsEmpty()**?

(These will not be mentioned going forward.)

Implementation via heaps

A possible implementation: Use the heap structure from Heapsort.

[Note: The array version of heaps requires a known maximum size n of the queue. Alternatively, the array can be replaced by an extendible array, such as `java.util.ArrayList` in Java or lists in Python. The heap tree can also be implemented using pointers/references.]

We already have:

- ▶ **Extract-Max:** Essentially the same as the second phase of Heapsort – remove the root, move the last leaf up as the new root, and call Heapify.

Runtime: $O(\log n)$.

- ▶ **Build:** Use **Heapify** repeatedly in a bottom-up manner.

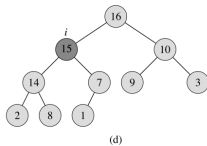
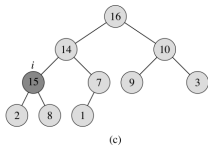
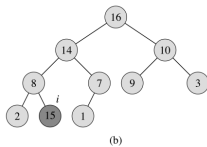
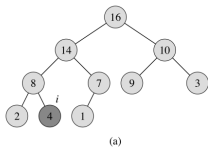
Runtime: $O(n)$.

Missing:

- ▶ Insert
- ▶ Increase-Key

Increase Key

1. Change the key for the element.
2. Restore heap order: as long as the element is greater than its parent, swap places with it.



Runtime: The height of the tree, i.e. $O(\log n)$.

Insert

1. **Insert** the new element at the end (\Rightarrow heap property is maintained).
2. Restore heap order exactly as in **Increase-Key**: as long as the element is greater than its parent, swap places with it.

Runtime: The height of the tree, i.e., $O(\log n)$.

Different implementations of priority queues

	<i>Heap</i>	Unsorted list	Sorted list
EXTRACT-MAX	$O(\log n)$	$O(n)$ <small>go through the whole list</small>	$O(1)$ <small>take the first</small>
BUILD	$O(n)$	$O(1)$	$O(n \log n)$ <small>sort using fx Quicksort</small>
INCREASE-KEY	$O(\log n)$	$O(1)$	$O(n)$
INSERT	$O(\log n)$	$O(1)$	$O(n)$

The above operations are for max-priority queues. It is, of course, easy to create min-priority queues with the operations Extract-Min, Build, Decrease-Key, and Insert, simply by reversing all inequalities between keys in the definitions and algorithms.

