Observer in original coordinates Measuring x6 1.0 x₁ System x₁ Error 10^{7} ––– \hat{x}_1 Observer 0.5 x^1 √ 10³ 0.0 -0.5 10^{-1} -1.010⁹ x₂ System x₂ Error 0.5 --- \hat{x}_2 Observer 10^{5} 0.0 χ_2 \boldsymbol{x}_2 10^{1} -0.5 10^{-3} -1.0*x*₃ System x₃ Error 10⁸ 1 -––– \hat{x}_3 Observer 10⁵ χ_3 $\overset{\mathsf{x}}{\mathsf{x}}$ 0 10² 10^{-1} -10.5 x₄ Error x₄ System 10^{7} \hat{x}_4 Observer 0.0 10^{4} [₹] -0.5 **X** 10^{1} -1.0 10^{-2} -1.5 10^{12} x₅ Error 5 10⁸ \boldsymbol{x}_{5} x_5 0 10^{4} x₅ System 10^{0} **-**5 \hat{x}_5 Observer 10 x₆ Error 10⁹ 5 ့ 10⁵ 0 x₆ System 10^{1} \hat{x}_6 Observer -102 8 10 0 4 6 8 10 2 4 6 Time (s) Time (s)