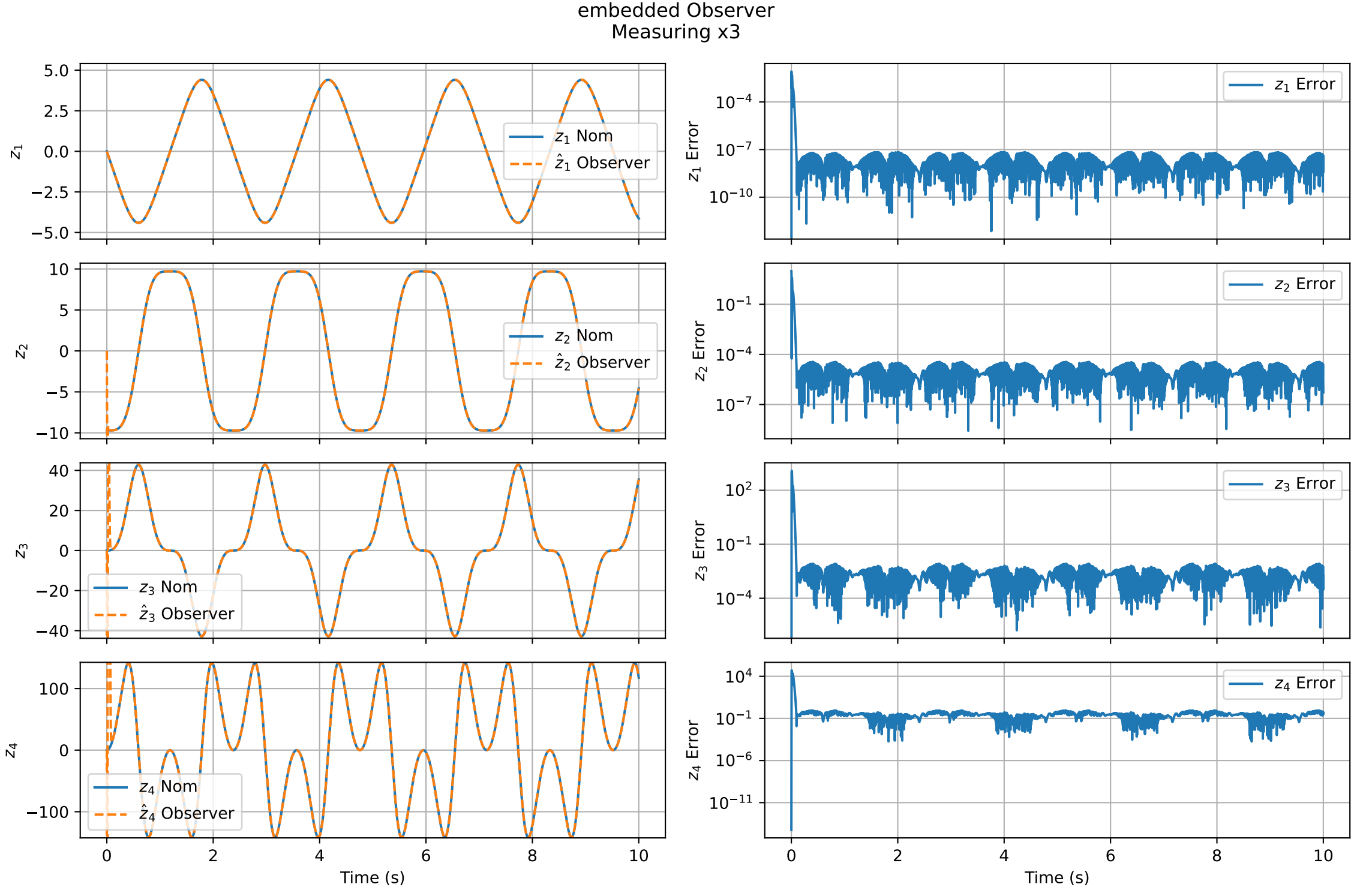
embedded Observer
Measuring x3
z_1 Nom
$\hat{z}_1$ Observer
z_2 Nom
$\hat{z}_2$ Observer
z_3 Nom
$\hat{z}_3$ Observer
z_4 Nom
$\hat{z}_4$ Observer
z_1 Error
z_2 Error
z_3 Error
z_4 Error
Time (s)
Time (s)