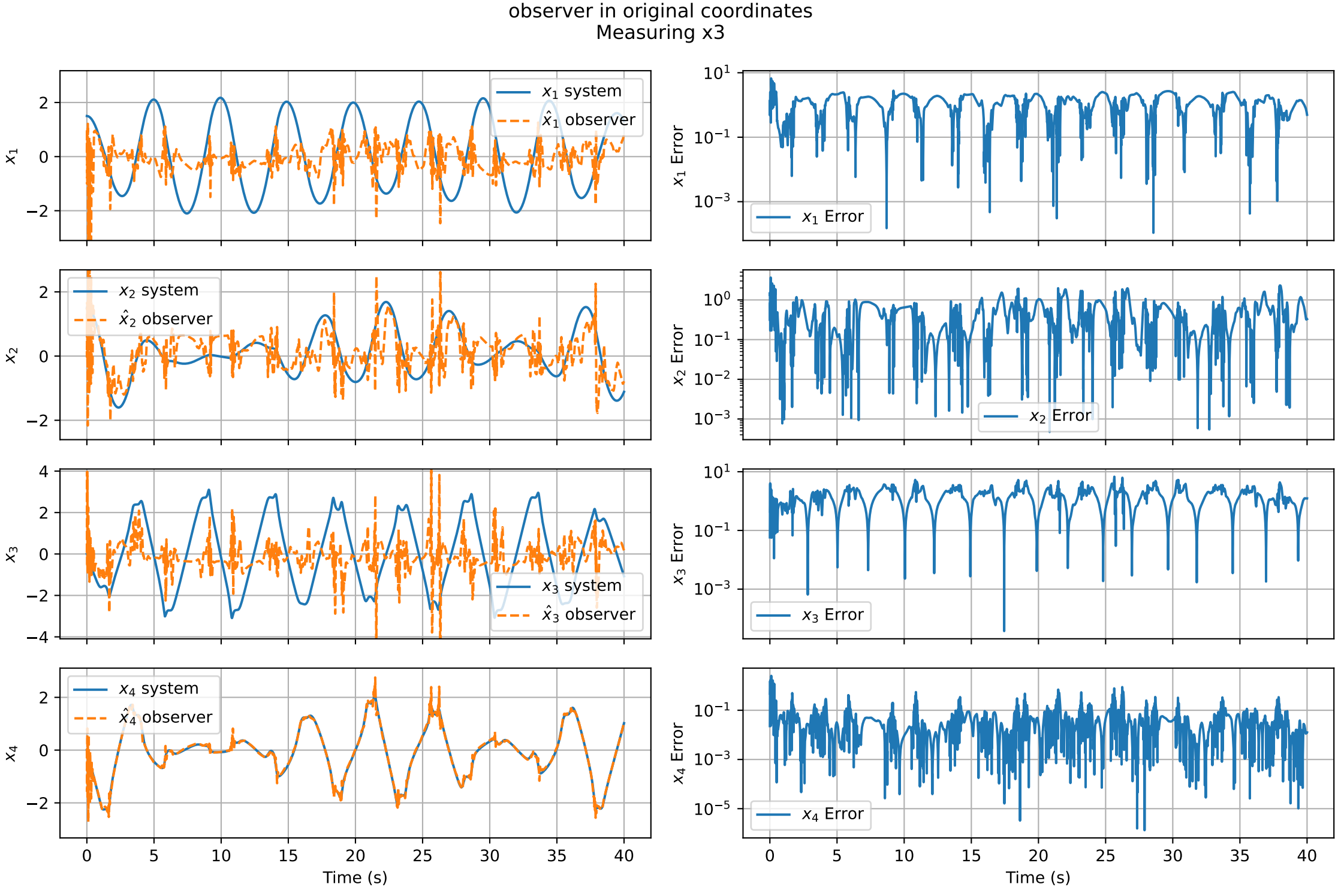
observer in original coordinates
Measuring x3
x_1 system
$\hat{x}_1$ observer
x_2 system
$\hat{x}_2$ observer
x_3 system
$\hat{x}_3$ observer
x_4 system
$\hat{x}_4$ observer
x_1 Error
x_2 Error
x_3 Error
x_4 Error
Time (s)
Time (s)