

# Demand-oriented Optimal Feeding of Agricultural Anaerobic Digestion Plant under Uncertain Substrate Characterization

Julius Frontzek <sup>1)</sup>  
Simon Hellmann <sup>2)</sup>  
Stefan Streif <sup>1)</sup>

Sören Weinrich <sup>3)</sup>  
Terrance Wilms <sup>4)</sup>  
Steffi Knorn <sup>4)</sup>

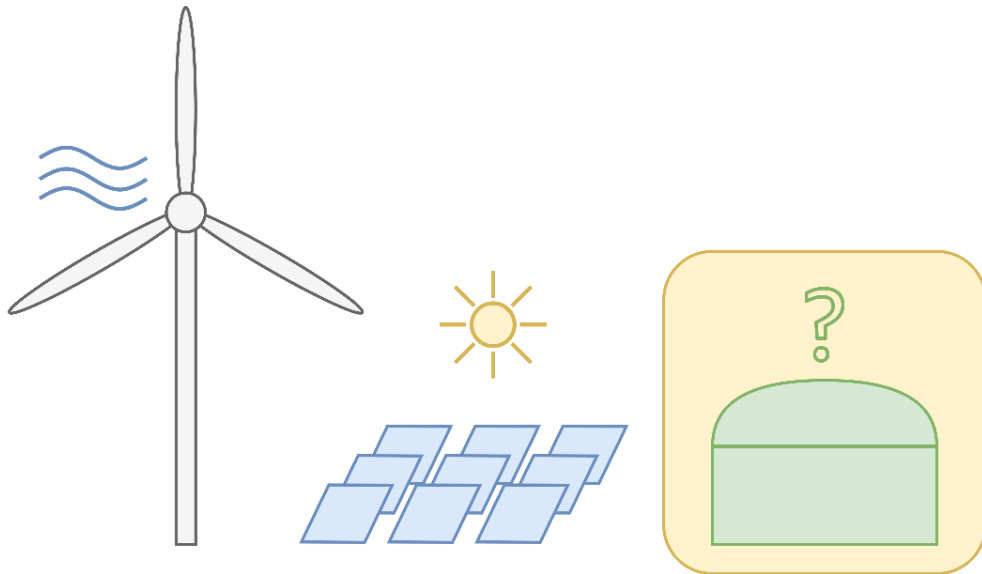
## Problem

- more than 9000 biogas plants in Germany (as of 2017)
- typically subsidized through Renewable Energy Act (German: “EEG”)
  - ➡ guaranteed feed-in tariffs for electricity
- biogas plant operation for electricity generation significantly less profitable after EEG funding period ends

## Motivation for biogas plants to stay

biogas production not directly dependent on environmental conditions

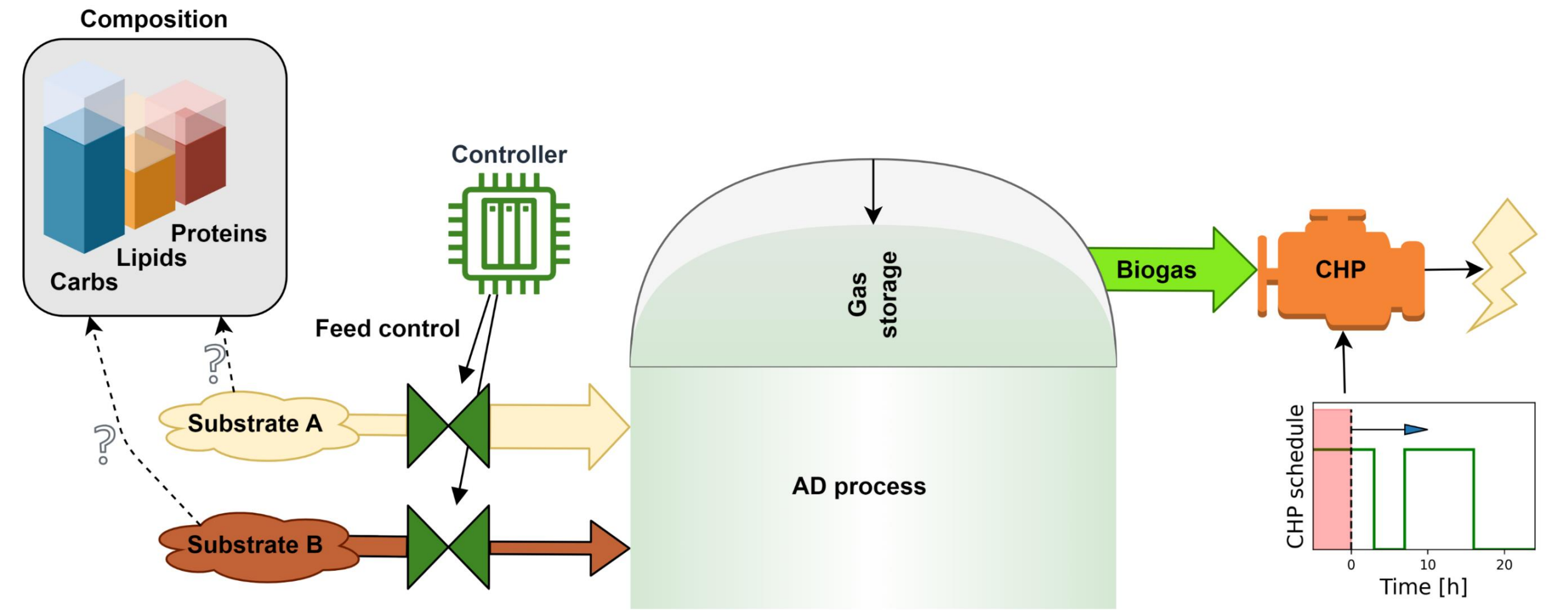
➡ controllable, reliable renewable energy



## Profitability increase approaches

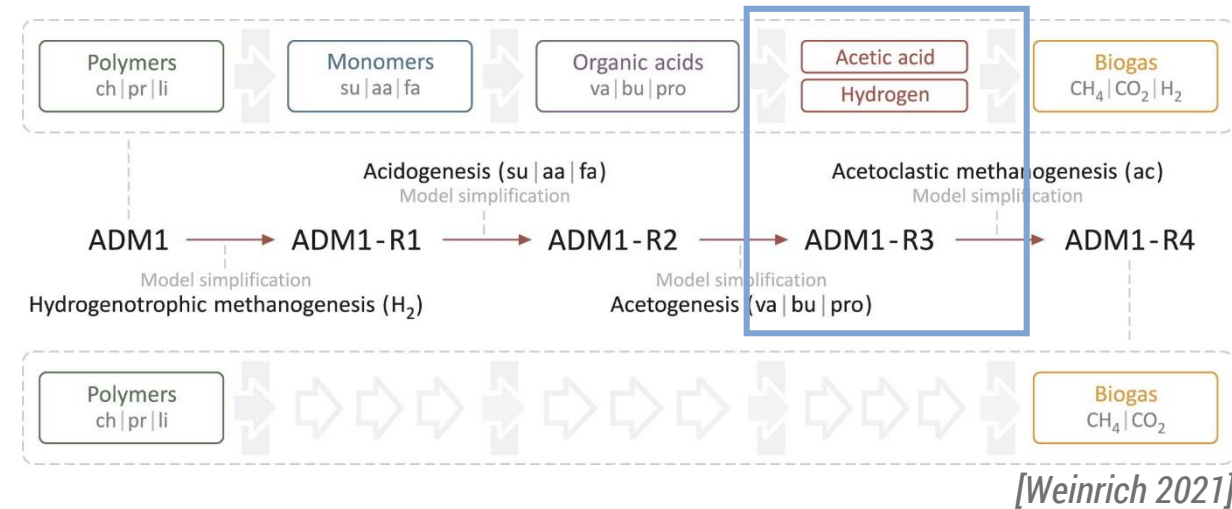
- increase revenue:
  - demand-oriented electricity production
    - ➡ higher feed-in tariffs
- reduce costs:
  - substrates
  - infrastructure

**Approach**  
produce biogas on demand by controlling AD process through feeding of not measured waste substrates  
➡ allowing for smaller gas storage



## AD plant

- CSTR based on simplified ADM1 model (ADM1-R3-frac) with multiple inputs
- inputs: Feed volume flows of respective substrate
- 18 states
  - soluble and particulate components in liquid phase
  - gaseous components in gas phase
  - differentiation between fast and slowly digestible carbohydrates



## Gas storage

- mixture of ideal gases at isobaric conditions
- modeled using volume balance
- comprises CH<sub>4</sub>, CO<sub>2</sub>, H<sub>2</sub>O gases
- 2 states for CH<sub>4</sub> and CO<sub>2</sub> volumes respectively
- H<sub>2</sub>O volume computed dependently

$$\begin{aligned}\dot{V}_{\text{CH}_4, \text{tank}} &= \dot{V}_{\text{CH}_4, \text{in}} - \dot{V}_{\text{CH}_4, \text{out}} \\ \dot{V}_{\text{CO}_2, \text{tank}} &= \dot{V}_{\text{CO}_2, \text{in}} - \dot{V}_{\text{CO}_2, \text{out}}\end{aligned}$$

From AD model

Defined by CHP power demand

# Substrate composition

## Problem

- AD model requires inlet concentrations  $\xi_i$  of macronutrients
- can be computed from other properties
  - Example:  $\xi_{ch} = \overline{FQ}_{ch} \cdot \overline{X}_{ch} \cdot DM \cdot \rho_{FM}$

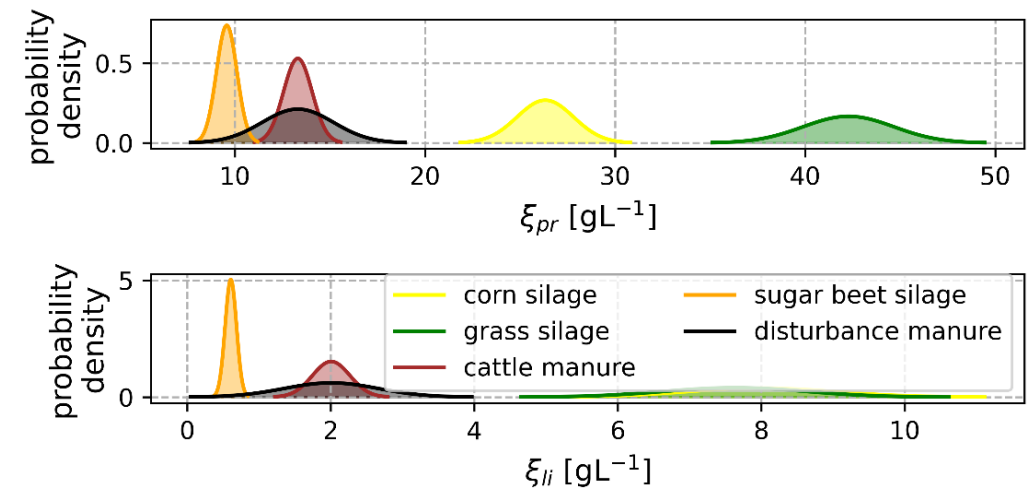
with  $\xi_{ch}$  inlet concentration of carbohydrates  
 $\overline{FQ}_{ch}$  fermentable fraction of carbohydrates  
 $\overline{X}_{ch}$  raw concentration of carbohydrates  
 $DM$  dry matter fraction  
 $\rho_{FM}$  density of fresh matter

- fermentable fraction of macronutrients cannot be measured directly

## Approach

- proteins and lipids assumed to be fully fermentable
- carbohydrate fermentability adjusted to meet total fermentation quotient of substrate
- data taken from literature and not yet published ring trials
- uncertainties of  $\xi_i$  linearly propagated

computed probability densities of inlet concentrations



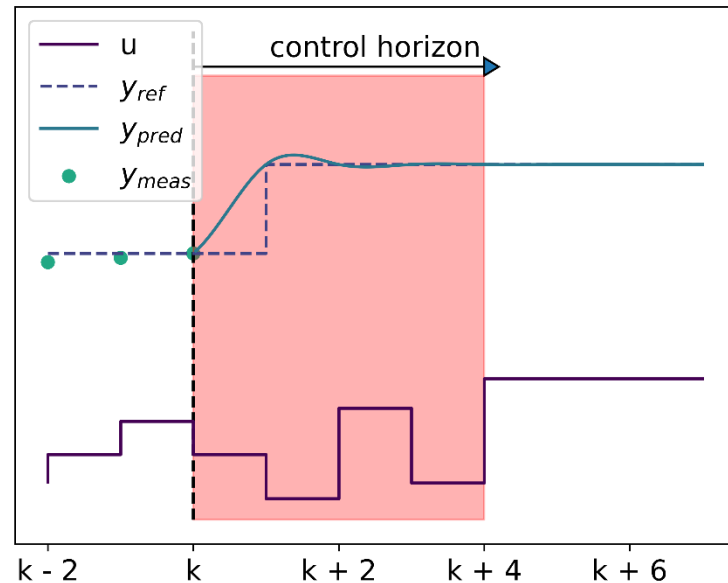
➡ Substrate macronutrient composition uncertainty quantified

# Model Predictive Control

- optimization based control scheme
- desired system behavior (e.g. setpoint tracking) described in cost function
- prerequisite: Model description for system

## Algorithm idea

1. computation of optimal input trajectory across control horizon
  2. application of first computed input
  3. measure system states
- repeat



## Pros

- Easy implementation of process constraints
- Multi-variable control
- Incorporation of economic incentives in cost function

# Multi-stage NMPC

## Problem

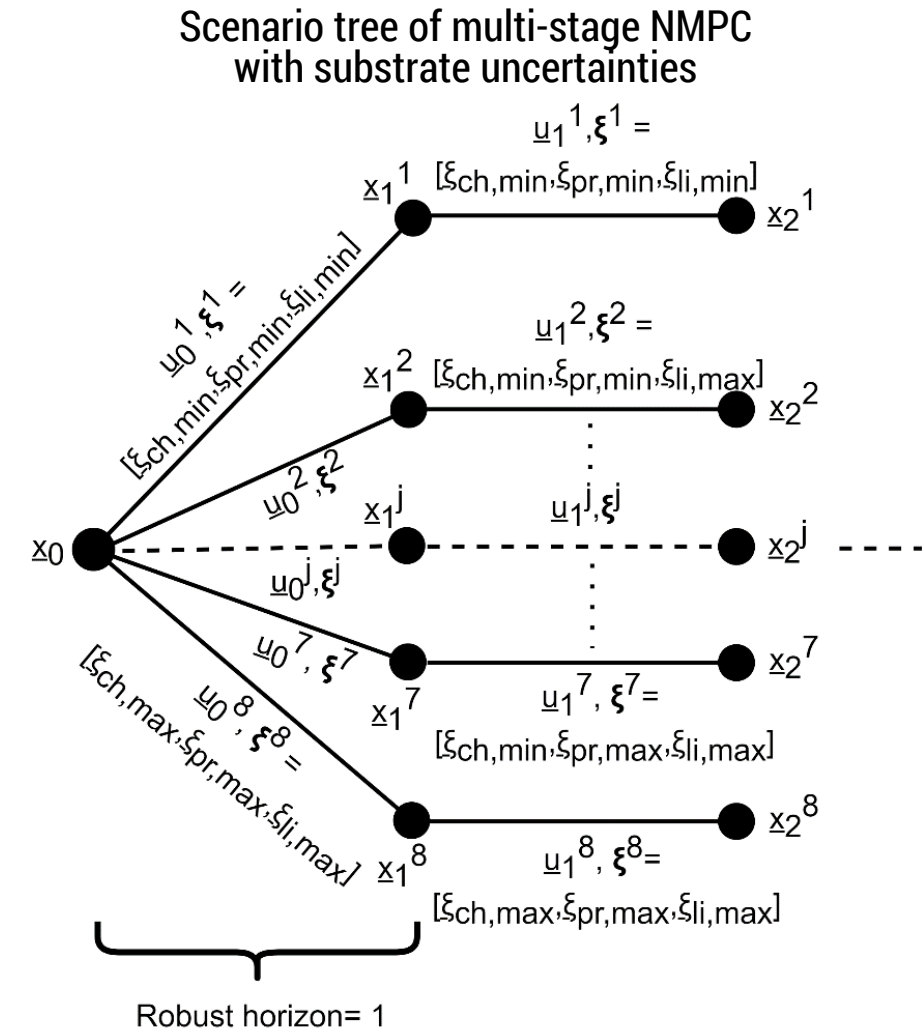
- true substrate composition unknown  $\Rightarrow$  parametric uncertainty
- robust control strategy required to guarantee constraint satisfaction

## Assumption

uncertain parameters only have discrete realization values

## Multi-stage NMPC – Methodology [Lucia 2013]

- combine all discrete uncertainty realizations
- each combination of realizations represents scenario
- optimize control action over entire tree  $\Rightarrow$  weighted summation of scenario specific cost functions



$\Rightarrow$  control scheme tailored to problems with parametric uncertainties

## General

- preceding steady state initialization (300 days)
- 30 day optimal feeding
- 4 input substrates: 3 silages, 1 manure

## Noise/errors

- uniform random noise in gas storage filling states
- random uniform feeding errors of  $\pm 5\%$

## Disturbance

- forced feeding of cattle manure
- 2.5 times larger composition uncertainty

## Substrate composition

variation of  $\pm 1.5\sigma$  w.r.t. nominal value

➡ parametric plant-model mismatch

Parameter	Value
CHP electrical capacity	50 kW
Digester liquid volume	163 m <sup>3</sup>
Gas storage volume	296 m <sup>3</sup>
Average week day CHP operation	13.8 h/d
Average weekend CHP operation	9 h/d
Time step	0.5 h

## Scenarios

- methanation scenario
  - ➡ set-point tracking of methane volume outflow
- demand-oriented scenario
  - ➡ fulfillment of typical CHP schedule

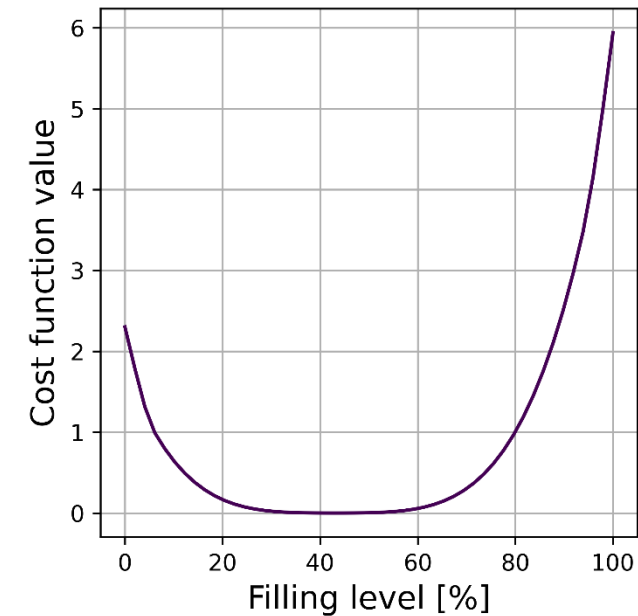
➡ application of controllers in two different simulation scenarios



## Scenario specific cost function (demand-oriented scenario)

$$\begin{aligned}
 \min_{\underline{u}_{0:N_c-1}, \underline{x}_{0:N_c}} \quad & J_l(\underline{x}_k, \underline{u}_k) = \sum_{k=0}^{N_c-1} \left( c_1 \cdot \left( \text{Deviation from filling level setpoint} \right)^2 \right. \\
 & \left. + c_2 \cdot \left( \text{Deviation from filling level setpoint} \right)^4 \right) \\
 & + \sum_{k=0}^{N_c-1} \sum_{i=1}^M \frac{\text{cost}_i}{\text{cost}_{\max}} \cdot u_{i,k} \\
 \text{subject to} \quad & \underline{x}_{k+1} = \mathbf{F}(\underline{x}_k, \underline{u}_k) \\
 & \underline{y}_k = \mathbf{H}(\underline{x}_k) \\
 & u_{i,k} \in [0, 1] \quad \forall \quad i \in \{1, \dots, 4\}, k \in \{0, \dots, N_c\} \\
 & \text{Hard and soft constraints for gas fill}
 \end{aligned}$$

Cost function with respect to filling level (demand-oriented scenario)



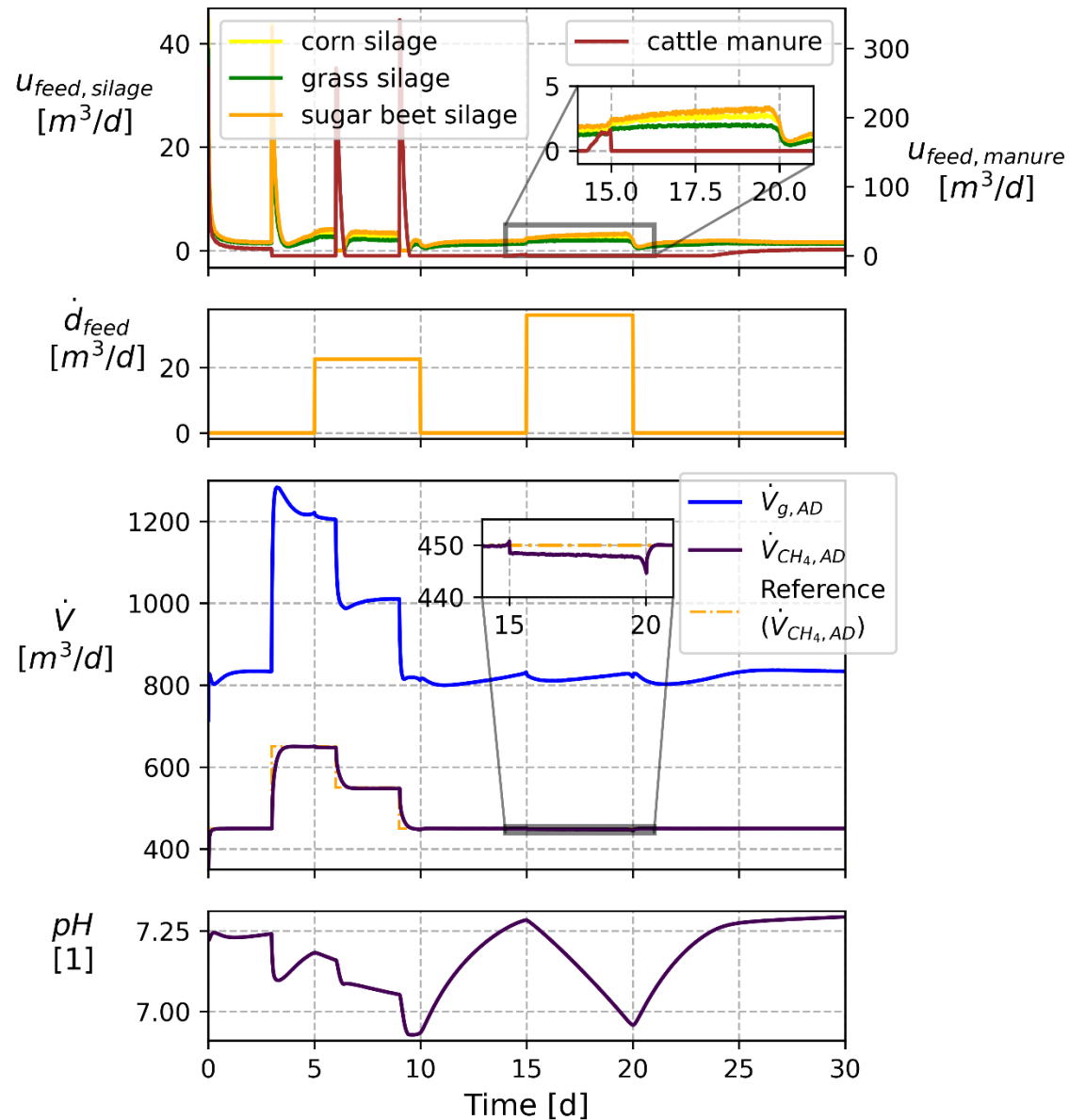
## Cost function components

- deviation of filling level from setpoint at 43%
  - below 50% ➡ production increase easier than decrease
  - filling level comprised of three normalized gases
- substrate usage weighted by respective substrate cost

## Constraints

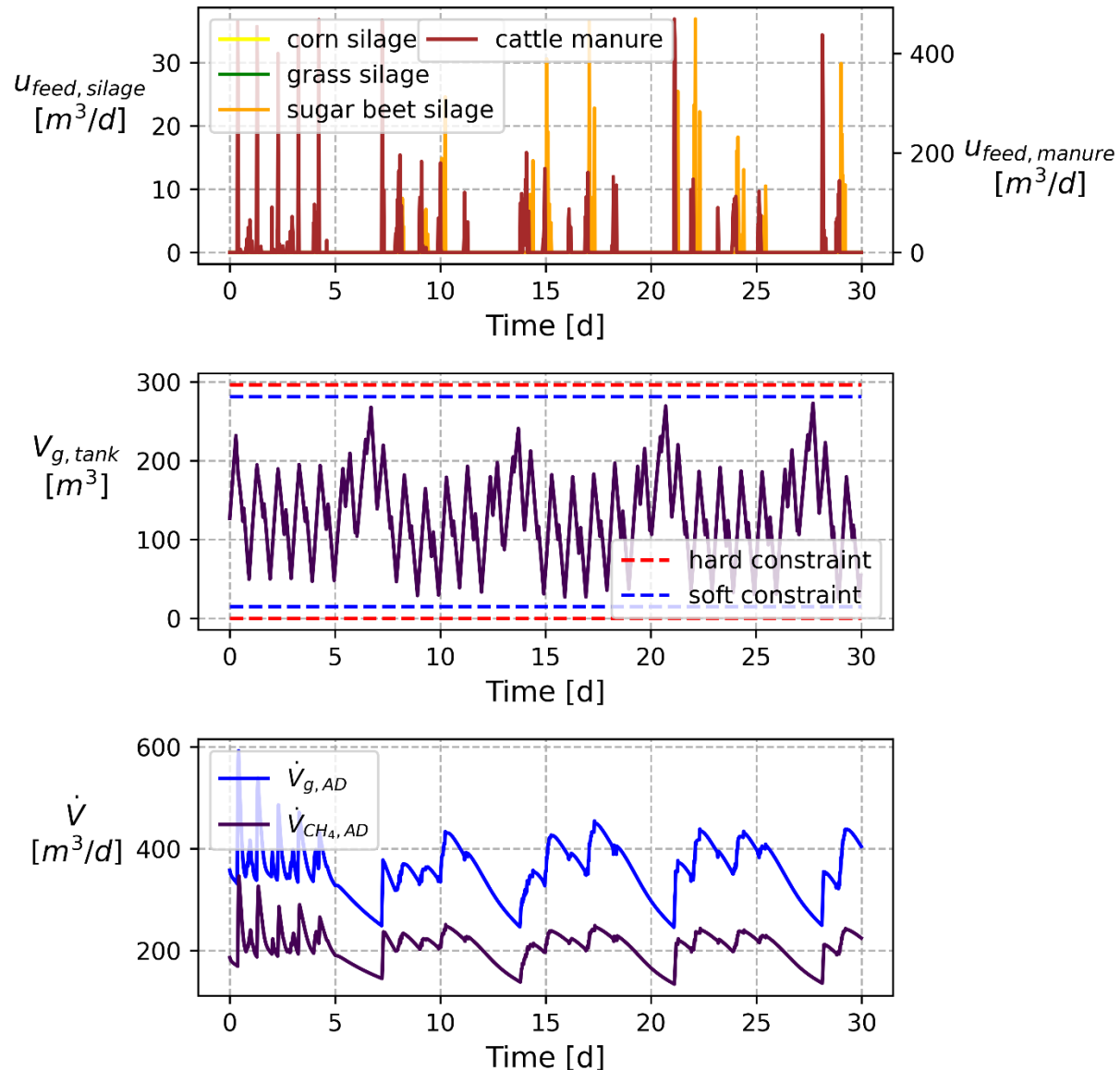
- hard and soft constraints of filling level representing physical limits
- individual hard constraints for CO<sub>2</sub> and CH<sub>4</sub> to prevent negative individual volumes

➡ cost function for demand-oriented scenario incorporates filling level and substrate costs



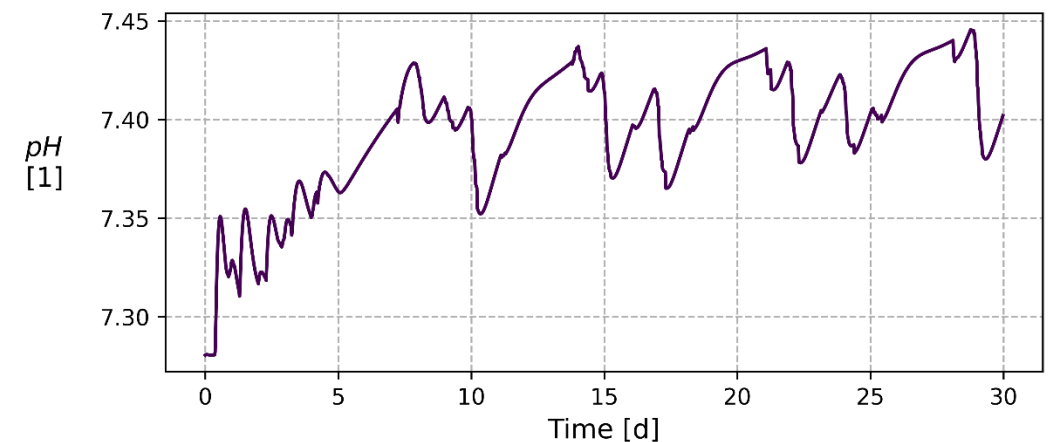
## Findings

- generally very good reference tracking
- setpoint changes addressed by large feeding inputs  
 ➡ but: accompanied by significant pH drops
- silages fed to increase biogas production
  - larger macronutrient density as compared to manure ➡ quickly digestible
- manure fed to brake biogas production
  - due to low density of macronutrients and in absence of buffer solution
- pH drops due to large disturbance feeding could not be compensated



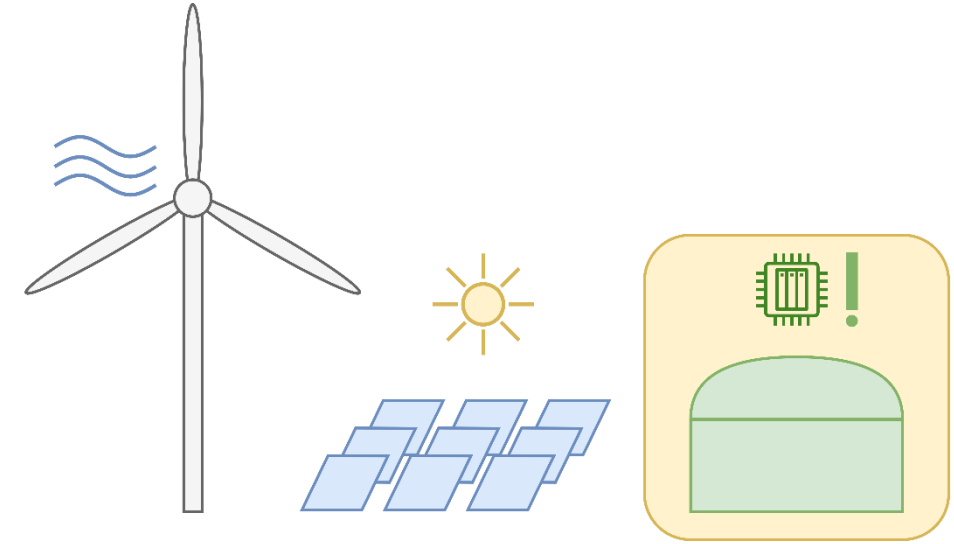
## Findings

- constraints were not violated
- shorter CHP operating times (e.g. on weekends) could only be handled for a certain time
- gas storage size larger than in comparable study with simpler model [Mauky 2016] but smaller than in other studies
- process stability maintained ➡ see pH plot
- significant changes in biogas production realized dependent on CHP demand schedule



## Summary

- explored a potentially more profitable pathway for biogas plant operation: demand-oriented feed control with substrates of uncertain composition
- developed multi-stage and nominal NMPC controllers
- tested on two different simulation scenarios
- developed a software framework
  - extensible with observers, etc.
  - real-time application computationally feasible



## Limitations

- simulations only
- full state information assumed
- power demand assumed to be known

## Outlook

- comparison between multi-stage NMPC and nominal NMPC for demand-oriented scenario
- observer implementation for non-measurable state variables
- economic assessment of proposed control scheme
- hierarchical control design with top level optimizing for optimal filling level

*[Lucia 2013]* Lucia, S.; Finkler, T.; Engell, S. 2013. Multi-stage nonlinear model predictive control applied to a semi-batch polymerization reactor under uncertainty. *Journal of Process Control* 23: 1306–1319.

*[Mauky 2016]* Mauky, E.; Weinrich, S.; Nägele, H.-J.; Jacobi, H.F.; Liebetrau, J.; Nelles, M. 2016. Model Predictive Control for Demand-Driven Biogas Production in Full Scale. *Chemical Engineering & Technology* 39: 652–664.

*[Weinrich 2021]* Weinrich, S.; Nelles, M. 2021. Systematic simplification of the Anaerobic Digestion Model No. 1 (ADM1) – Model development and stoichiometric analysis. *Bioresource Technology* 333: 125124.