

 $egin{aligned} x_k^j - & \text{State at time } k \text{ of scenario } j \\ u_k^j - & \text{Input at time } k \text{ of scenario } j \end{aligned}$ 

 $oldsymbol{\xi}^j-$  Vector of influent macronutrients (CH, PR, LI) of scenario j

 $N_p-$  Prediction horizon

 $N_r-$  Robust horizon

 $\xi_{
m ch}^j$  — Influent CH concentration of scenario j