CodingLab5

May 25, 2025

Neural Data Science

Lecturer: Dr. Jan Lause, Prof. Dr. Philipp Berens

Tutors: Jonas Beck, Fabio Seel, Julius Würzler

Summer term 2025

Student names: Jannis Ahlert, Julius Grote , Hun Seok Choi

LLM Disclaimer: Github Copilot and Chat GPT, used for autompletion and debugging.

1 Coding Lab 5

The jupyter_black extension is already loaded. To reload it, use:

%reload_ext jupyter_black

The watermark extension is already loaded. To reload it, use:

%reload_ext watermark

Last updated: 2025-05-25 17:46:34Mitteleuropäische Sommerzeit

Python implementation: CPython Python version : 3.10.11 IPython version : 8.22.2

sklearn: 1.4.2

numpy : 1.26.4
sklearn : 1.4.2
pyglmnet : 1.1
scipy : 1.12.0
matplotlib: 3.8.3

Watermark: 2.5.0

2 Task 1: Fit RF on simulated data

We will start with toy data generated from an LNP model neuron to make sure everything works right. The model LNP neuron consists of one Gaussian linear filter, an exponential nonlinearity and a Poisson spike count generator. We look at it in discrete time with time bins of width δt . The model is:

$$c_t \sim Poisson(r_t)r_t = \exp(w^T s_t) \cdot \Delta t \cdot R$$

Here, c_t is the spike count in time window t of length Δt , s_t is the stimulus and w is the receptive field of the neuron. The receptive field variable \mathbf{w} is 15 × 15 pixels and normalized to ||w|| = 1. A stimulus frame is a 15 × 15 pixel image, for which we use uncorrelated checkerboard noise (binary) with a stimulus intesity of 5 (peak to peak). R can be used to bring the firing rate into the right regime (e.g. by setting R = 50).

For computational ease, we reformat the stimulus and the receptive field in a 225 by 1 array. The function sample_lnp can be used to generate data from this model. It returns a spike count vector c with samples from the model (dimensions: 1 by $nT = T/\Delta t$), a stimulus matrix s (dimensions: $225 \times nT$) and the mean firing rate r (dimensions: $nT \times 1$).

Here we assume that the receptive field influences the spike count instantaneously just as in the above equations. Implement a Maximum Likelihood approach to fit the receptive field.

To this end derive mathematically and implement the log-likelihood function L(w) and its gradient $\frac{L(w)}{dw}$ with respect to w (negloglike_lnp). The log-likelihood of the model is

$$L(w) = \log \prod_t \frac{r_t^{c_t}}{c_t!} \exp(-r_t).$$

Make sure you include intermediate steps of the mathematical derivation in your answer, and you give as final form the maximally simplified expression, substituting the corresponding variables.

Plot the stimulus for one frame, the cell's response over time and the spike count vs firing rate. Plot the true and the estimated receptive field.

Grading: 2 pts (calculations) + 4 pts (generation) + 4 pts (implementation)

2.0.1 Calculations (2 pts)

You can add your calculations in LATEX here.

$$L(\omega) = \dots$$
$$\frac{dL(\omega)}{d\omega} = \dots$$

$$\begin{split} L(w) &= \log \prod_{t=1}^{n_T} \frac{r_t^{c_t}}{c_t!} e^{-r_t} = \sum_{t=1}^{n_T} \big[c_t \log r_t - r_t - \log(c_t!) \big]. \end{split}$$
 where
$$r_t = \exp(w^\top s_t) \, \Delta t \, R.$$

Thus

$$\begin{split} L(w) &= \sum_{t=1}^{n_T} \Big[\, c_t \big(w^\top s_t + \log(\Delta t \, R) \big) - \exp(w^\top s_t) \, \Delta t \, R - \log(c_t!) \Big], \\ -L(w) &= \sum_{t=1}^{n_T} \Big[\exp(w^\top s_t) \, \Delta t \, R - c_t \, (w^\top s_t) \Big] + \underbrace{\sum_{t=1}^{n_T} \big[- c_t \log(\Delta t \, R) + \log(c_t!) \big]}_{\text{constant in } w}. \end{split}$$

Discarding the constant term, our objective is

$$\mathcal{J}(w) = \sum_{t=1}^{n_T} \Bigl[\exp(w^\top s_t) \, \Delta t \, R \, - \, c_t \, (w^\top s_t) \Bigr].$$

Its gradient is

$$\nabla_w \mathcal{J}(w) = \sum_{t=1}^{n_T} \Bigl[\exp(w^\top s_t) \, \Delta t \, R - c_t \Bigr] \, s_t = \sum_{t=1}^{n_T} (r_t - c_t) \, s_t.$$

2.0.2 Generate data (2 pts)

```
def gen_gauss_rf(D: int, width: float, center: tuple = (0, 0)) -> np.ndarray:
    """
    Generate a Gaussian receptive field.

Args:
    D (int): Size of the receptive field (DxD).
    width (float): Width parameter of the Gaussian.
    center (tuple, optional): Center coordinates of the receptive field.
    CPDefaults to (0, 0).

Returns:
    np.ndarray: Gaussian receptive field.
"""

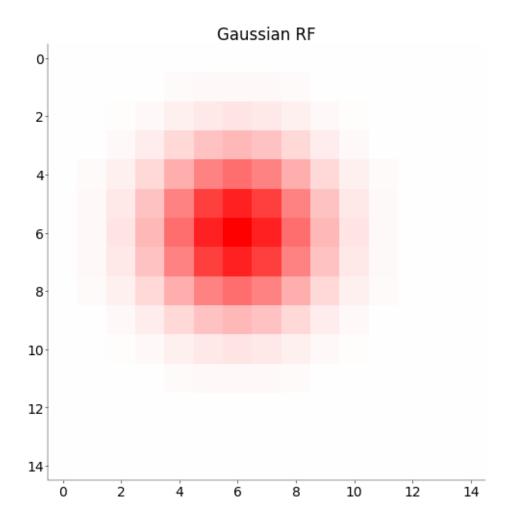
sz = (D - 1) / 2
    x, y = np.meshgrid(np.arange(-sz, sz + 1), np.arange(-sz, sz + 1))
    x = x + center[0]
    y = y + center[1]
    w = np.exp(-(x**2 / width + y**2 / width))
```

```
w = w / np.sum(w.flatten())
return w

w = gen_gauss_rf(15, 7, (1, 1))

vlim = np.max(np.abs(w))
fig, ax = plt.subplots(1, 1, figsize=(5, 5))
ax.imshow(w, cmap="bwr", vmin=-vlim, vmax=vlim)
ax.set_title("Gaussian RF")
```

[72]: Text(0.5, 1.0, 'Gaussian RF')



```
[73]: def sample_lnp(
     w: np.array, nT: int, dt: float, R: float, s_i: float, random_seed: int = 10
):
```

```
"""Generate samples from an instantaneous LNP model neuron with
receptive field kernel w.
Parameters
_____
w: np.array, (Dx * Dy, )
    (flattened) receptive field kernel.
nT: int
    number of time steps
dt: float
    duration of a frame in s
R: float
    rate parameter
s_i: float
    stimulus intensity peak to peak
random_seed: int
    seed for random number generator
Returns
-----
c: np.array, (nT, )
    sampled spike counts in time bins
r: np.array, (nT, )
   mean rate in time bins
s: np.array, (Dx * Dy, nT)
   stimulus frames used
Note
See equations in task description above for a precise definition
of the individual parameters.
11 11 11
rng = np.random.default_rng(random_seed)
```

```
[74]: D = 15  # number of pixels
nT = 1000  # number of time bins
dt = 0.1  # bins of 100 ms
R = 50  # firing rate in Hz
s_i = 5  # stimulus intensity

w = gen_gauss_rf(D, 7, (1, 1))
w = w.flatten()

c, r, s = sample_lnp(w, nT, dt, R, s_i)
```

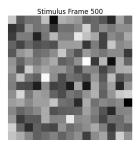
Plot the stimulus for one frame, the cell's response over time and the spike count vs firing rate.

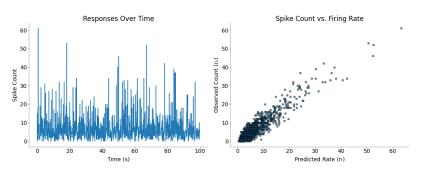
```
time = np.arange(nT) * dt
ax["responses"].plot(time, c, drawstyle="steps-mid")
ax["responses"].set_xlabel("Time (s)")
ax["responses"].set_ylabel("Spike Count")
ax["responses"].set_title("Responses Over Time")

# Plot spike count vs. predicted firing rate
ax["count/rate"].scatter(r, c, alpha=0.6, edgecolor="k")
ax["count/rate"].set_xlabel("Predicted Rate (r)")
ax["count/rate"].set_ylabel("Observed Count (c)")
ax["count/rate"].set_title("Spike Count vs. Firing Rate")

plt.tight_layout()
plt.show()
```

C:\Users\Julius\AppData\Local\Temp\ipykernel_18288\851930843.py:31: UserWarning:
The figure layout has changed to tight
 plt.tight_layout()





2.0.3 Implementation (3 pts)

Implement the negative log-likelihood of the LNP and its gradient with respect to the receptive field using the simplified equations you calculated earlier (1 pt)

```
[76]: def negloglike_lnp(
    w: np.array, c: np.array, s: np.array, dt: float = 0.1, R: float = 50
) -> float:
    """Implements the negative (!) log-likelihood of the LNP model

    Parameters
    ------
    w: np.array, (Dx * Dy, )
        current receptive field

    c: np.array, (nT, )
```

```
spike counts
   s: np.array, (Dx * Dy, nT)
     stimulus matrix
   Returns
   f: float
     function value of the negative log likelihood at w
   11 11 11
   # Implement the negative log-likelihood of the LNP
   lin = w @ s
   r = np.exp(lin) * dt * R
   # Negative log-likelihood (omit constant terms)
   return np.sum(r) - c.dot(lin)
def deriv_negloglike_lnp(
   w: np.array, c: np.array, s: np.array, dt: float = 0.1, R: float = 50
) -> np.array:
   """Implements the gradient of the negative log-likelihood of the LNP model
   Parameters
   _____
   see negloglike_lnp
   Returns
   df: np.array, (Dx * Dy, )
     gradient of the negative log likelihood with respect to w
   # -----
   # Implement the gradient with respect to the receptive field `w`
   # -----
   lin = w @ s
   r = np.exp(lin) * dt * R
```

```
return s @ (r - c)
```

The helper function check_grad in scipy.optimize can help you to make sure your equations and implementations are correct. It might be helpful to validate the gradient before you run your optimizer.

```
[77]: # Check gradient
from scipy.optimize import minimize
from scipy.optimize import check_grad

# Initial guess
w0 = np.zeros_like(w)

# Perform the gradient check
error = check_grad(negloglike_lnp, deriv_negloglike_lnp, w0, c, s, dt, R)
print(f"Gradient check error: {error:.2e}")
```

Gradient check error: 1.43e-02

Fit receptive field maximizing the log likelihood.

The scipy optimize package also has suitable functions for optimization. If you generate a large number of samples, the fitted receptive field will look more similar to the true receptive field. With more samples, the optimization takes longer, however.

Optimization terminated successfully.

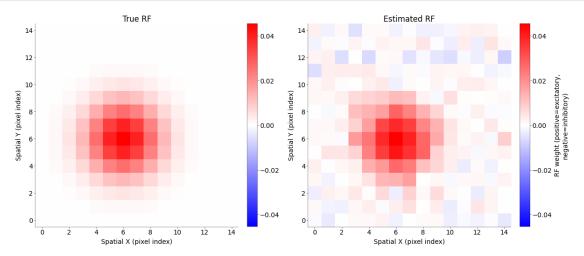
Current function value: 2114.826542

Iterations: 246

Function evaluations: 423 Gradient evaluations: 423

Plot the true and the estimated receptive field.

```
[79]: # -----
      # Plot the ground truth and estimated
      # `w` side by side. (1 pt)
      mosaic = [["True", "Estimated"]]
      fig, ax = plt.subplot_mosaic(mosaic=mosaic, figsize=(12, 5))
      # make sure to add a colorbar. 'bwr' is a reasonable choice for the cmap.
      vlim = np.max(np.abs(w))
      # True RF
      im0 = ax["True"].imshow(
          w.reshape(w_est.shape), cmap="bwr", vmin=-vlim, vmax=vlim, origin="lower"
      ax["True"].set_title("True RF")
      ax["True"].set_xlabel("Spatial X (pixel index)")
      ax["True"].set_ylabel("Spatial Y (pixel index)")
      cbar0 = fig.colorbar(im0, ax=ax["True"], fraction=0.046, pad=0.04)
      # Estimated RF
      im1 = ax["Estimated"].imshow(w est, cmap="bwr", vmin=-vlim, vmax=vlim,
       ⇔origin="lower")
      ax["Estimated"].set_title("Estimated RF")
      ax["Estimated"].set_xlabel("Spatial X (pixel index)")
      ax["Estimated"].set_ylabel("Spatial Y (pixel index)")
      cbar1 = fig.colorbar(im1, ax=ax["Estimated"], fraction=0.046, pad=0.04)
      cbar1.set_label("RF weight (positive=excitatory,\nnegative=inhibitory)")
      plt.show()
```



3 Task 2: Apply to real neuron

Download the dataset for this task from Ilias (nds_cl_5_data.mat). It contains a stimulus matrix (s) in the same format you used before and the spike times. In addition, there is an array called trigger which contains the times at which the stimulus frames were swapped.

- Generate an array of spike counts at the same temporal resolution as the stimulus frames
- Fit the receptive field with time lags of 0 to 4 frames. Fit them one lag at a time (the ML fit is very sensitive to the number of parameters estimated and will not produce good results if you fit the full space-time receptive field for more than two time lags at once).
- Plot the resulting filters

Grading: 3.5 pts

```
[80]: var = io.loadmat("../data/nds_cl_5_data.mat")

# t contains the spike times of the neuron
t = var["DN_spiketimes"].flatten()

# trigger contains the times at which the stimulus flipped
trigger = var["DN_triggertimes"].flatten()

# contains the stimulus movie with black and white pixels
s = var["DN_stim"]
print(s.shape)
s = s.reshape((300, 1500)) # the shape of each frame is (20, 15)
s = s[:, 1 : len(trigger)]
```

(20, 15, 1500)

Create vector of spike counts

```
# Bin the spike counts at the same temporal
# resolution as the stimulus (0.5 pts)
# -------

# histogram function:
# spike_counts[0] = spikes in trigger[0] to trigger[1]
# spike_counts[-1] = spikes in trigger[-2] to trigger[-1]
# so there is one more trigger entry than stimulus frame and spike count entry
spike_counts, _ = np.histogram(t, bins=trigger)
assert (
    len(spike_counts) == len(trigger) - 1 and len(spike_counts) == s.shape[1]
), "mismatch in number of bins"
```

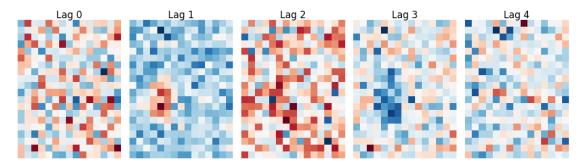
Fit receptive field for each frame separately

```
[82]: # -----
      # Fit the receptive field with time lags of
      # 0 to 4 frames separately (1 pt)
      # The final receptive field (`w_hat`) should
      # be in the shape of (Dx * Dy, 5)
      # specify the time lags
      delta = [0, 1, 2, 3, 4]
      # fit for each delay
      # Initialize the final receptive field matrix
      Dx, Dy = 20, 15 # stimulus frame dimensions
      w_hat = np.zeros((Dx * Dy, len(delta)))
      # Use Standard Parameters for the LNP model
      dt = 0.1
      R = 50
      # fit for each delay
      for i, lag in enumerate(delta):
          print(f"Fitting receptive field for lag {lag}...")
          # Create time-lagged stimulus matrix
          # For lag=0: use frames 0 to end-1
          # For lag=1: use frames 0 to end-2 (stimulus leads spikes by 1 frame)
          # etc.
          max_frame = s.shape[1] - lag
          s_lagged = s[:, :max_frame]
          # Align spike counts with lagged stimulus
          # For lag=0: use spike_counts[0:end]
          # For lag=1: use spike_counts[1:end] (spikes follow stimulus by 1 frame)
          c_aligned = spike_counts[lag : lag + max_frame]
          # Initial guess for receptive field weights
          w0 = np.zeros(Dx * Dy)
          # Optimize the receptive field for this lag
          res = minimize(
             fun=negloglike_lnp,
              x0=w0,
              args=(c_aligned, s_lagged, dt, R),
              jac=deriv_negloglike_lnp,
```

```
Fitting receptive field for lag 0...
Fitting receptive field for lag 1...
Fitting receptive field for lag 2...
Fitting receptive field for lag 3...
Fitting receptive field for lag 4...
```

Plot the frames one by one and explain what you see.

C:\Users\Julius\AppData\Local\Temp\ipykernel_18288\1503553562.py:11:
UserWarning: The figure layout has changed to tight
 plt.tight_layout()



Explanation (1 pt) It looks like there are two lags at which there is a particularly pronounced circular receptive field on the lower left side: first the neuron is excited by the stimulus (around a lack of 1) and then the pattern reverses and the stimulus at the same location has an inhibitory

influence around a lag of 3. The other frames are less pronounced and do not show a clear pattern.

4 Task 3: Separate space/time components

The receptive field of the neuron can be decomposed into a spatial and a temporal component. Because of the way we computed them, both are independent and the resulting spatio-temporal component is thus called separable. As discussed in the lecture, you can use singular-value decomposition to separate these two:

$$W = u_1 s_1 v_1^T$$

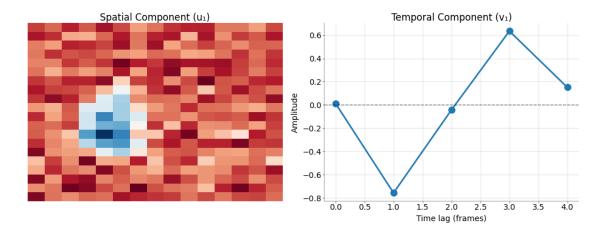
Here u_1 and v_1 are the singular vectors belonging to the 1st singular value s_1 and provide a long rank approximation of W, the array with all receptive fields. It is important that the mean is subtracted before computing the SVD.

Plot the first temporal component and the first spatial component. You can use a Python implementation of SVD. The results can look a bit puzzling, because the sign of the components is arbitrary.

Grading: 1.5 pts

```
[84]: # -----
     # Apply SVD to the fitted receptive field,
     # you can use either numpy or sklearn (0.5 pt)
     # Decompose receptive field using SVD
     # subtract mean and perform SVD
     W_centered = w_hat - np.mean(w_hat, axis=1, keepdims=True)
     U, S, Vt = np.linalg.svd(W_centered, full_matrices=False)
     # Extract first components (rank-1 approximation)
     u1 = U[:, 0] # First spatial component
     s1 = S[0] # First singular value
     v1 = Vt[0, :] # First temporal component
     print(f"Singular values: {S}")
     print(f"First singular value explains {S[0]**2 / np.sum(S**2) * 100:.1f}% of
      ⇔variance")
     # Reconstruct using rank-1 approximation
     W_rank1 = s1 * np.outer(u1, v1)
```

```
# Compare original vs approximation
     reconstruction_error = np.linalg.norm(W_centered - W_rank1, "fro")
     original_norm = np.linalg.norm(W_centered, "fro")
     print(f"\nReconstruction quality:")
     print(f"Relative error: {reconstruction_error / original_norm * 100:.2f}%")
     print(f"Variance explained by rank-1: {S[0]**2 / np.sum(S**2) * 100:.1f}%")
     Singular values: [5.85901287e-01 4.30223612e-01 4.18119619e-01 3.58564503e-01
      8.28273849e-17]
     First singular value explains 41.3% of variance
     Reconstruction quality:
     Relative error: 76.63%
     Variance explained by rank-1: 41.3%
[85]: # -----
      # Plot the spatial and temporal components (1 pt)
     fig, ax = plt.subplot_mosaic(
         mosaic=[["Spatial", "Temporal"]], figsize=(10, 4), constrained_layout=True
     spatial_rf = u1.reshape(20, 15)
     time_lags = np.array(delta)
     ax["Spatial"].imshow(spatial_rf, cmap="RdBu_r", aspect="auto")
     ax["Spatial"].set_title("Spatial Component (u)")
     ax["Spatial"].set_xlabel("X position")
     ax["Spatial"].set_ylabel("Y position")
     ax["Spatial"].axis("off")
     ax["Temporal"].plot(time_lags, v1, "o-", linewidth=2, markersize=8)
     ax["Temporal"].set_title("Temporal Component (v)")
     ax["Temporal"].set_xlabel("Time lag (frames)")
     ax["Temporal"].set_ylabel("Amplitude")
     ax["Temporal"].grid(True, alpha=0.3)
     ax["Temporal"].axhline(y=0, color="k", linestyle="--", alpha=0.5)
     plt.tight_layout()
     plt.show()
     C:\Users\Julius\AppData\Local\Temp\ipykernel_18288\1958394392.py:21:
     UserWarning: The figure layout has changed to tight
       plt.tight_layout()
```



5 Task 4: Regularized receptive field

As you can see, maximum likelihood estimation of linear receptive fields can be quite noisy, if little data is available.

To improve on this, one can regularize the receptive field vector and a term to the cost function

$$C(w) = L(w) + \alpha ||w||_p^2$$

Here, the p indicates which norm of w is used: for p = 2, this is shrinks all coefficient equally to zero; for p = 1, it favors sparse solutions, a penality also known as lasso. Because the 1-norm is not smooth at zero, it is not as straightforward to implement "by hand".

Use a toolbox with an implementation of the lasso-penalization and fit the receptive field. Possibly, you will have to try different values of the regularization parameter α . Plot your estimates from above and the lasso-estimates. How do they differ? What happens when you increase or decrease alpha?

If you want to keep the Poisson noise model, you can use the implementation in pyglmnet. Otherwise, you can also resort to the linear model from sklearn which assumes Gaussian noise (which in my hands was much faster).

Grading: 3 pts

```
delta = [0, 1, 2, 3, 4]
alphas = np.logspace(-5, -2, 10)
# fit for each delay
print("Shape of alpha array", alphas.shape)
# 'c_binned' (binned spike counts, shape: num_frames) are defined from Task 2.
# For example, from previous cells:
var = io.loadmat("../data/nds cl 5 data.mat")
s_data = var["DN_stim"].reshape((300, 1500))
trigger times = var["DN triggertimes"].flatten()
s = s_data[:, 1 : len(trigger_times) + 1]
spike_times = var["DN_spiketimes"].flatten()
c_binned = np.histogram(spike_times, bins=trigger_times)[0]
num_pixels = s.shape[0]
num_frames = s.shape[1]
# Initialize w_hat_qlm to store the receptive fields
w_hat_glm = np.zeros((num_pixels, len(delta), len(alphas)))
# fit for each delay and each alpha
for alpha idx, alpha reg strength in enumerate(alphas):
   print(f"Fitting for regularization strength (lambda) = {alpha_reg_strength:.

4f}")
   for delay_idx, d_val in enumerate(delta):
        # Prepare data for the current delay d_val
        # Number of samples available for this delay
       n_samples_for_delay = num_frames - d_val
        if n_samples_for_delay <= 0: # This check is fine</pre>
            print(
                f" Skipping delay {d_val} for lambda {alpha_reg_strength:.4f}_

due to insufficient data points ({n_samples_for_delay})."

            w_hat_glm[:, delay_idx, alpha_idx] = np.nan # Or fill with zeros
            continue
       y_fit = c_binned[d_val : num_frames + 1] # Spike counts for the_
 ⇔current delay
        # X_{fit} needs to match the length of y_{fit}.
       X_fit = s[:, 0 : n_samples_for_delay - 1].T
        if (
```

```
X_{fit.shape}[0] == 0
        ): # Safequard, should be caught by n_samples_for_delay check
            print(
                 f" Skipping delay {d_val} for lambda {alpha_reg_strength:.4f}_\( \)
 →as X_fit is empty."
             w_hat_glm[:, delay_idx, alpha_idx] = np.nan
             continue
        print(f" Fitting for delay {d_val}... (Using {X_fit.shape[0]}_L
  ⇔samples)")
         # Initialize and fit the GLM model (Lasso regression)
        model = GLM(
            distr="poisson",
             alpha=1.0,
            reg_lambda=alpha_reg_strength,
             solver="cdfast",
            max_iter=300,
            tol=1e-4,
            verbose=True,
        ) # Set to True for convergence messages from pyglmnet
        try:
            model.fit(X_fit, y_fit)
             # model.beta contains the fitted coefficients (weights) excluding
  \hookrightarrow intercept
             w_hat_glm[:, delay_idx, alpha_idx] = model.beta_
        except Exception as e:
            print(
                 f" Error fitting GLM for lambda {alpha_reg_strength:.2f},__

delay {d_val}: {e}

             w_hat_glm[:, delay_idx, alpha_idx] = np.nan # Store NaNs if_
 ⇔fitting fails
print("\nFitting complete.")
# w_hat_qlm now contains the estimated receptive fields.
# Shape of w_hat_glm: (num_pixels, len(delta), len(alphas))
Lambda: 0.0000
INFO:pyglmnet:Lambda: 0.0000
Shape of alpha array (10,)
Fitting for regularization strength (lambda) = 0.0000
  Fitting for delay 0... (Using 1488 samples)
c:\Users\Julius\AppData\Local\Programs\Python\Python310\lib\site-
```

packages\pyglmnet\pyglmnet.py:863: UserWarning: Reached max number of iterations without convergence. warnings.warn(Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 1... (Using 1487 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 2... (Using 1486 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 3... (Using 1485 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 4... (Using 1484 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for regularization strength (lambda) = 0.0000 Fitting for delay 0... (Using 1488 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 1... (Using 1487 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 2... (Using 1486 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 3... (Using 1485 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for delay 4... (Using 1484 samples) Lambda: 0.0000 INFO:pyglmnet:Lambda: 0.0000 Fitting for regularization strength (lambda) = 0.0000 Fitting for delay 0... (Using 1488 samples)

Lambda: 0.0000

INFO:pyglmnet:Lambda: 0.0000

Fitting for delay 1... (Using 1487 samples)

Lambda: 0.0000

INFO:pyglmnet:Lambda: 0.0000

Fitting for delay 2... (Using 1486 samples)

Lambda: 0.0000

INFO:pyglmnet:Lambda: 0.0000

Fitting for delay 3... (Using 1485 samples)

Lambda: 0.0000

INFO:pyglmnet:Lambda: 0.0000

Fitting for delay 4... (Using 1484 samples)

Lambda: 0.0001

INFO:pyglmnet:Lambda: 0.0001

Fitting for regularization strength (lambda) = 0.0001 Fitting for delay 0... (Using 1488 samples)

Lambda: 0.0001

INFO:pyglmnet:Lambda: 0.0001

Fitting for delay 1... (Using 1487 samples)

Lambda: 0.0001

INFO:pyglmnet:Lambda: 0.0001

Fitting for delay 2... (Using 1486 samples)

Lambda: 0.0001

INFO:pyglmnet:Lambda: 0.0001

Fitting for delay 3... (Using 1485 samples)

Lambda: 0.0001

INFO:pyglmnet:Lambda: 0.0001

Fitting for delay 4... (Using 1484 samples)

Lambda: 0.0002

INFO:pyglmnet:Lambda: 0.0002

Fitting for regularization strength (lambda) = 0.0002

Fitting for delay 0... (Using 1488 samples)

Lambda: 0.0002

INFO:pyglmnet:Lambda: 0.0002

Fitting for delay 1... (Using 1487 samples)

Lambda: 0.0002

INFO:pyglmnet:Lambda: 0.0002

Fitting for delay 2... (Using 1486 samples)

Lambda: 0.0002

INFO:pyglmnet:Lambda: 0.0002

Fitting for delay 3... (Using 1485 samples)

Lambda: 0.0002

INFO:pyglmnet:Lambda: 0.0002

Fitting for delay 4... (Using 1484 samples)

Lambda: 0.0005

INFO:pyglmnet:Lambda: 0.0005

Fitting for regularization strength (lambda) = 0.0005

Fitting for delay 0... (Using 1488 samples)

Lambda: 0.0005

INFO:pyglmnet:Lambda: 0.0005

Fitting for delay 1... (Using 1487 samples)

Lambda: 0.0005

INFO:pyglmnet:Lambda: 0.0005

Fitting for delay 2... (Using 1486 samples)

Lambda: 0.0005

INFO:pyglmnet:Lambda: 0.0005

Fitting for delay 3... (Using 1485 samples)

Parameter update tolerance. Converged in 281 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 281 iterations

Lambda: 0.0005

INFO:pyglmnet:Lambda: 0.0005

Fitting for delay 4... (Using 1484 samples)

Lambda: 0.0010

INFO:pyglmnet:Lambda: 0.0010

Fitting for regularization strength (lambda) = 0.0010

Fitting for delay 0... (Using 1488 samples)

Lambda: 0.0010

INFO:pyglmnet:Lambda: 0.0010

Fitting for delay 1... (Using 1487 samples)

Parameter update tolerance. Converged in 269 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 269 iterations

Lambda: 0.0010

INFO:pyglmnet:Lambda: 0.0010

Fitting for delay 2... (Using 1486 samples)

Parameter update tolerance. Converged in 249 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 249 iterations

Lambda: 0.0010

INFO:pyglmnet:Lambda: 0.0010

Fitting for delay 3... (Using 1485 samples)

Parameter update tolerance. Converged in 276 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 276 iterations

Lambda: 0.0010

INFO:pyglmnet:Lambda: 0.0010

Fitting for delay 4... (Using 1484 samples)

Parameter update tolerance. Converged in 293 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 293 iterations

Lambda: 0.0022

INFO:pyglmnet:Lambda: 0.0022

Fitting for regularization strength (lambda) = 0.0022

Fitting for delay 0... (Using 1488 samples)

Parameter update tolerance. Converged in 210 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 210 iterations

Lambda: 0.0022

INFO:pyglmnet:Lambda: 0.0022

Fitting for delay 1... (Using 1487 samples)

Parameter update tolerance. Converged in 229 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 229 iterations

Lambda: 0.0022

INFO:pyglmnet:Lambda: 0.0022

Fitting for delay 2... (Using 1486 samples)

Parameter update tolerance. Converged in 240 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 240 iterations

Lambda: 0.0022

INFO:pyglmnet:Lambda: 0.0022

Fitting for delay 3... (Using 1485 samples)

Parameter update tolerance. Converged in 218 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 218 iterations

Lambda: 0.0022

INFO:pyglmnet:Lambda: 0.0022

Fitting for delay 4... (Using 1484 samples)

Parameter update tolerance. Converged in 195 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 195 iterations

Lambda: 0.0046

INFO:pyglmnet:Lambda: 0.0046

Fitting for regularization strength (lambda) = 0.0046 Fitting for delay 0... (Using 1488 samples)

Parameter update tolerance. Converged in 165 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 165 iterations

Lambda: 0.0046

INFO:pyglmnet:Lambda: 0.0046

Fitting for delay 1... (Using 1487 samples)

Parameter update tolerance. Converged in 146 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 146 iterations

Lambda: 0.0046

INFO:pyglmnet:Lambda: 0.0046

Fitting for delay 2... (Using 1486 samples)

Parameter update tolerance. Converged in 121 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 121 iterations

Lambda: 0.0046

INFO:pyglmnet:Lambda: 0.0046

Fitting for delay 3... (Using 1485 samples)

Parameter update tolerance. Converged in 169 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 169 iterations

Lambda: 0.0046

INFO:pyglmnet:Lambda: 0.0046

Fitting for delay 4... (Using 1484 samples)

Parameter update tolerance. Converged in 137 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 137 iterations

Lambda: 0.0100

INFO:pyglmnet:Lambda: 0.0100

Fitting for regularization strength (lambda) = 0.0100

Fitting for delay 0... (Using 1488 samples)

Parameter update tolerance. Converged in 87 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 87 iterations

Lambda: 0.0100

INFO:pyglmnet:Lambda: 0.0100

Fitting for delay 1... (Using 1487 samples)

Parameter update tolerance. Converged in 86 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 86 iterations

Lambda: 0.0100

INFO:pyglmnet:Lambda: 0.0100

Fitting for delay 2... (Using 1486 samples)

Parameter update tolerance. Converged in 70 iterations

INFO:pyglmnet: Parameter update tolerance. Converged in 70 iterations

```
Lambda: 0.0100
INFO:pyglmnet:Lambda: 0.0100
Fitting for delay 3... (Using 1485 samples)

Parameter update tolerance. Converged in 72 iterations
INFO:pyglmnet: Parameter update tolerance. Converged in 72 iterations
Lambda: 0.0100
INFO:pyglmnet:Lambda: 0.0100

Fitting for delay 4... (Using 1484 samples)

Parameter update tolerance. Converged in 88 iterations
INFO:pyglmnet: Parameter update tolerance. Converged in 88 iterations
```

Fitting complete.

```
[90]: # -----
      # plot the estimated receptive fields (1 pt)
     # show the number of values that are neither zero nor NaN
     print(
         f"Number of non-NaN and non-zero values in w_hat_glm: {np.count_nonzero(~np.
      ⇔isnan(w_hat_glm))}"
     fig, ax = plt.subplots(
         len(alphas), len(delta), sharex=True, sharey=True, figsize=(10, 20)
     )
     # Correctly calculate vmin and vmax for consistent and symmetric color scaling
      →across all subplots
     if np.all(np.isnan(w hat glm)):
         # Handle case where all w_hat_glm values are NaN (e.g., if fitting failed
      ⇔everywhere)
         vmin_val = -1.0
         vmax_val = 1.0
     else:
         abs_max_val = np.nanmax(np.abs(w_hat_glm)) # Max absolute value, ignoring_
         if abs_max_val == 0 or np.isnan(
             abs_max_val
         ): # Handles all zeros or if somehow still NaN
             vmin_val = -1.0 # Default if data is all zero or problematic
             vmax val = 1.0
         else:
             vmin_val = -abs_max_val
             vmax_val = abs_max_val
```

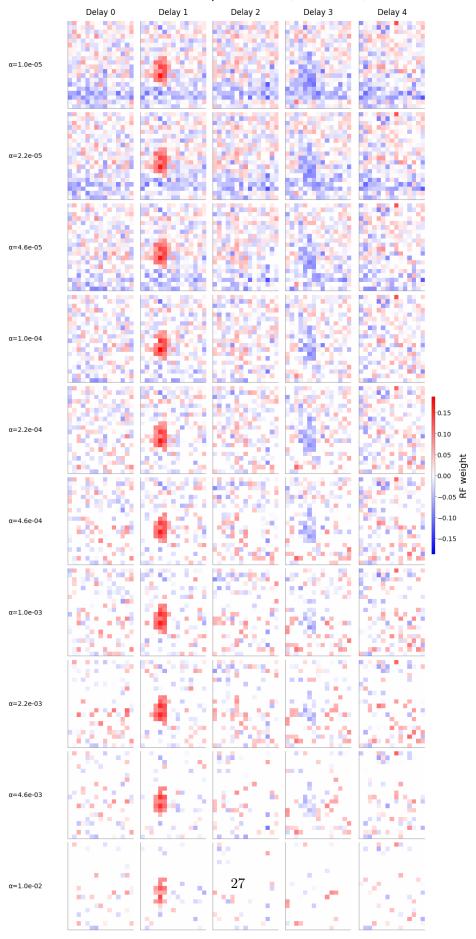
```
for alpha_idx, alpha_reg_strength in enumerate(alphas):
    for delay_idx, d_val in enumerate(delta):
        # Plot the estimated receptive field
        rf_to_plot = w_hat_glm[:, delay_idx, alpha_idx].reshape(20, 15)
        if np.all(np.isnan(rf_to_plot)):
            # Handle cases where a specific RF is all NaN (e.g., skipped during_
 \hookrightarrow fitting)
            # You could plot a placeholder or leave it blank
            ax[alpha_idx, delay_idx].text(
                0.5,
                0.5,
                "NaN".
                ha="center",
                va="center",
                transform=ax[alpha_idx, delay_idx].transAxes,
            im = None # No image object to use for colorbar later if this is -
 ⇔the last one
        else:
            im = ax[alpha_idx, delay_idx].imshow(
               rf_to_plot,
                vmin=vmin_val, # Use vmin for lower color scale limit
                vmax=vmax_val, # Use vmax for upper color scale limit
                cmap="bwr",
                interpolation="nearest", # Often better for pixelated data
            )
        if alpha_idx == 0: # Titles for the top row
            ax[alpha_idx, delay_idx].set_title(f"Delay {d_val}", y=1.05)
        if delay idx == 0: # Y-labels for the first column
            ax[alpha_idx, delay_idx].set_ylabel(
                f" ={alpha reg strength:.1e}",
                rotation=0,
                ha="right",
                va="center",
                labelpad=40,
        ax[alpha_idx, delay_idx].set_xticks([])
        ax[alpha_idx, delay_idx].set_yticks([])
# Add colorbar
# Make sure 'im' is from a successfully plotted image
if im is not None: # Check if 'im' was assigned
    cbar = fig.colorbar(
        im, ax=ax[:, -1].ravel().tolist(), fraction=0.046, pad=0.1, aspect=50
```

```
) # Adjust aspect for colorbar
   cbar.set_label("RF weight", fontsize=14)
else:
   print("Warning: No valid image was plotted to create a colorbar from.")

fig.suptitle("Estimated Receptive Fields (Lasso GLM)", fontsize=20, y=1.02)
# plt.tight_layout(rect=[0, 0, 1, 0.96]) # Adjust rect if using suptitle
plt.show()
```

Number of non-NaN and non-zero values in w_hat_glm: 15000

Estimated Receptive Fields (Lasso GLM)



The lasso-penalization effectively increases the cost of large coefficients in the receptive field and thus leads to a more robust estimate. The regularization parameter α controls the strength of this penalty.

When you increase α , the coefficients in the receptive field are shrunk more towards zero (as seen in the bottom rows), leading to a sparser solution. If you decrease α , the coefficients are less penalized, and the receptive field can take larger values, potentially leading to overfitting/higher variance in the estimate.

5.1 Bonus Task (Optional): Spike Triggered Average

Instead of the Maximum Likelihood implementation above, estimate the receptive field using the spike triggered average. Use it to increase the temporal resolution of your receptive field estimate. Perform the SVD analysis for your STA-based receptive field and plot the spatial and temporal kernel as in Task 3.

Questions: 1. Explain how / why you chose a specific time delta. 2. Reconsider what you know about STA. Is it suitable to use STA for this data? Why/why not? What are the (dis-)advantages of using the MLE based method from above?

Grading: 1 BONUS Point.

BONUS Points do not count for this individual coding lab, but sum up to 5% of your overall coding lab grade. There are 4 BONUS points across all coding labs.

```
[88]: # compute the spike triggered average
      # Load data from Task 2
      var = io.loadmat("../data/nds_cl_5_data.mat")
      s_data = var["DN_stim"].reshape((300, 1500))
      trigger_times = var["DN_triggertimes"].flatten()
      spike_times = var["DN_spiketimes"].flatten()
      # Use the stimulus from earlier
      stim_data = s_data[:, 1 : len(trigger_times) + 1]
      # Create proper spike count bins
      c binned = np.zeros(len(trigger times))
      for i in range(len(trigger_times)):
          # Count spikes in each stimulus frame interval
          if i < len(trigger_times) - 1:</pre>
              spike_mask = (spike_times >= trigger_times[i]) & (
                   spike_times < trigger_times[i + 1]</pre>
              )
          else:
              spike_mask = (spike_times >= trigger_times[i]) & (
                   spike_times < trigger_times[i] + 0.1</pre>
```

```
c_binned[i] = np.sum(spike_mask)
num_pixels = stim_data.shape[0]
num_frames = stim_data.shape[1]
# Choose temporal window length for STA
T_window = 30 # frames before spike time
print(f"Computing STA for T = {T_window} frames...")
print(f"Stimulus shape: {stim data.shape}")
print(f"Spike counts shape: {c_binned.shape}")
print(f"Total spikes: {np.sum(c_binned)}")
# Compute overall stimulus mean (crucial for proper STA!)
stim_mean = np.mean(stim_data, axis=1, keepdims=True) # Shape: (num_pixels, 1)
print(f"Stimulus mean shape: {stim_mean.shape}")
# Initialize STA accumulator
sta_sum = np.zeros((num_pixels, T_window))
total_spikes = 0
# Compute STA
for t_spike in range(T_window, num_frames):
    if c_binned[t_spike] > 0: # Only consider time bins with spikes
        # Get stimulus window: T window frames ending at t spike
        start_idx = t_spike - T_window
        end idx = t spike
        stim_window = stim_data[:, start_idx:end_idx] # Shape: (num_pixels,_
 \hookrightarrow T_window)
        # Subtract mean from stimulus window
        stim_window_centered = stim_window - stim_mean
        # Add to STA, weighted by number of spikes
        sta_sum += stim_window_centered * c_binned[t_spike]
        total_spikes += c_binned[t_spike]
# Normalize by total number of spikes
if total_spikes > 0:
    sta = sta_sum / total_spikes
else:
    print("No spikes found!")
    sta = sta_sum
print(f"Total contributing spikes: {total_spikes}")
```

```
print(f"STA shape: {sta.shape}")
# Important: Subtract mean from STA before SVD (as mentioned in Task 3)
sta_mean_subtracted = sta - np.mean(sta, axis=1, keepdims=True)
# Perform SVD on the mean-subtracted STA
U, S, Vt = np.linalg.svd(sta_mean_subtracted, full_matrices=False)
print(f"SVD shapes: U={U.shape}, S={S.shape}, Vt={Vt.shape}")
# Plot results as in Task 3
fig, ax = plt.subplot_mosaic(
   mosaic=[["Spatial", "Temporal"]], figsize=(12, 6), constrained_layout=True
# Plot the first spatial component from SVD (reshaped to 20x15)
first_spatial_component = U[:, 0].reshape(20, 15)
spatial_vmax = np.max(np.abs(first_spatial_component))
im = ax["Spatial"].imshow(
   first_spatial_component,
   cmap="bwr",
   vmin=-spatial_vmax,
   vmax=spatial_vmax,
   interpolation="nearest",
)
ax["Spatial"].set_title("First Spatial Component (U)")
ax["Spatial"].set xlabel("Spatial X (15 pixels)")
ax["Spatial"].set_ylabel("Spatial Y (20 pixels)")
fig.colorbar(im, ax=ax["Spatial"], label="Weight")
# Plot the first temporal component
first_temporal_component = Vt[0, :]
# Time axis: negative values are frames before spike (0 is spike time)
time_lags = np.arange(-T_window, 0)
ax["Temporal"].plot(time_lags, first_temporal_component, "o-", markersize=3)
ax["Temporal"].set_title("First Temporal Component (V )")
ax["Temporal"].set_xlabel("Time Lag (frames before spike)")
ax["Temporal"].set_ylabel("Weight")
ax["Temporal"].grid(True)
ax["Temporal"].axvline(x=0, color="r", linestyle="--", alpha=0.5, label="Spike",
 →time")
ax["Temporal"].legend()
plt.show()
# Print diagnostics
print(f"\nSingular values (first 5): {S[:5]}")
```

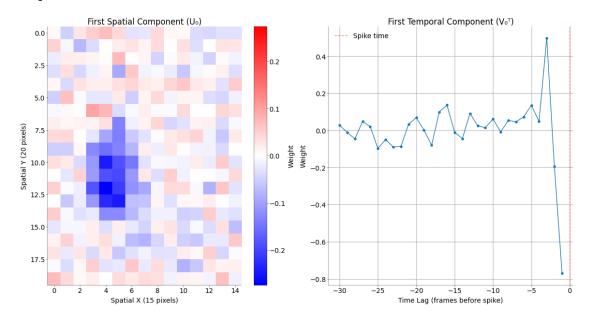
Computing STA for T = 30 frames... Stimulus shape: (300, 1489) Spike counts shape: (1489,)

Total spikes: 5493.0

Stimulus mean shape: (300, 1) Total contributing spikes: 5328.0

STA shape: (300, 30)

SVD shapes: U=(300, 30), S=(30,), Vt=(30, 30)



Singular values (first 5): [0.16674041 0.15200556 0.1299146 0.12124906 0.11830279]

Explained variance by first component: 9.6%

1. Time delta choice: We chose a time lag of 30 frames for the implementation of the STA. This is rough compromise between capturing as much temporal information as possible while still having a discernable receptive field in the spatial component (+ less computational cost). When we set the > 40 frames the spatial component would no longer the receptive field, but just a noisy 20×15 pixel image.

2. Suitability of STA for this data:

Advantages of STA: - Simple and robust: No optimization required, less prone to local minima - Model-free: Makes no assumptions about the nonlinearity - Fast computation: Direct calculation from spike-triggered stimuli - Interpretable: Directly shows average stimulus preceding spikes

Disadvantages of STA: - Assumes white noise stimulus: Requires uncorrelated stimulus for unbiased estimates - **Linear assumption:** Only captures linear components of the receptive field - **Low spike count sensitivity:** Requires many spikes for stable estimates - **No nonlinearity modeling:** Cannot account for the exponential nonlinearity in LNP models

Advantages of MLE method: - Accounts for nonlinearity: Explicitly models the exponential function in LNP - Optimal under model assumptions: Maximum likelihood is asymptotically efficient - Better with few spikes: Can work with lower spike counts due to model constraints - Principled uncertainty quantification: Provides confidence intervals

Disadvantages of MLE method: - **Model dependent**: Assumes specific LNP structure - **Optimization complexity**: Requires careful initialization and can get stuck in local minima - **Computational cost**: More expensive, especially with regularization - **Sensitive to model misspecification**: Poor performance if model assumptions are violated

Conclusion: For this binary white noise stimulus data, STA is quite suitable as it meets the white noise assumption. However, the MLE approach should theoretically perform better due to its explicit modeling of the Poisson spiking and exponential nonlinearity.