Actor-Based Distributed Systems

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Class Logistics

- During our meeting we will use Ray Framework
- Install all required components
 - pip install -U "ray[default]"
 - <u>https://docs.ray.io/en/latest/ray-overview/installation.html</u>

Important pip install ray is not enough !!!

Notes on REST API

- The most common security issues:
 - Shadow API
 - Deprecated API
 - Unauthorized API



API calls make up a massive 71% of all web traffic

Widespread API usage is expanding the attack surface for bad actors. These threats make it critical for organizations to understand the risks and complexities of APIs and the importance of API Security.

Class Logistics

- Laboratory classes during week 25.3-5.4
 - There is no meeting on Wednesday 3.4
- We will use desktops from Computer Networks Laboratory
 - Select Ubuntu image
- Preliminary plan homework assignment
 - Elastic schedule on week 25-29.4

Class Logistics

- Laboratory grading
 - Showing up => 1 pt
 - UPEL task upload => 1 pt
 - Hard work on lab meeting => 2 pt
 - You need to show me logs of your tasks execution on Ray Dashboard
 - Extra activity, labs improvement => 1 pt

 Mathematical model of concurrent computation proposed by Carl Hewitt in 1973

Session 8 Formalisms for Artificial Intelligence

A Universal Modular <u>ACTOR</u> Formalism for Artificial Intelligence Carl Hewitt Peter Bishop Richard Steiger

This paper proposes a modular ACTOR architecture and definitional method for artificial intelligence that is conceptually based on a single kind of object: actors [or, if you will, virtual processors, activation frames, or streams]. The formalism makes no presuppositions about the representation of primitive data structures and control structures. Such structures can be programmed, micro-coded, or hard wired in a uniform modular fashion. In fact it is impossible to determine whether a given object is "really" represented as a list, a vector, a hash table, a function, or a process. The architecture will efficiently run the coming generation of PLANNER-like artificial intelligence languages including those requiring a high degree of parallelism. The efficiency is gained without loss of programming generality because it only makes certain actors more efficient; it does not change their behavioral characteristics. The architecture is general with respect to control structure and does not have or need goto, interrupt, or semaphore primitives. The formalism achieves the goals that the disallowed constructs are intended to achieve by other more structured methods.

PLANNER Progress

- The actor is an object that encapsulates state and behavior
- Originated from
 - Smalltalk, Petri Nets, Channels ...
 - More details on theory in attached document
- More recent
 - Scheme made them concrete
 - Erlang made them useful
 - Akka made them cool
 - Ray makes them easy

- Primitives for concurrency/parallelism
- Can exchange messages between each-other
- When an actor receives a message it can:
 - Send a finite number of messages to other actors
 - Create a finite number of new actors
 - Modify its interval behavior on receiving messages

- Messages between actors are always sent asynchronously
- No requirement on order of message arrival
- Queuing and dequeuing of messages in an actor mailbox are atomic operations
- Fire and Forgot approach, no race conditions anymore

Origins

- Originated on UC Berkeley
- Group led by Ion Stoica:
 - Apache Messos, Apache Spark (Databricks),
 Apache Alluxio (Alluxio)
 - Ray is managed by Anyscale

Ray: A Distributed Framework for Emerging AI Applications

Philipp Moritz*, Robert Nishihara*, Stephanie Wang, Alexey Tumanov, Richard Liaw, Eric Liang, Melih Elibol, Zongheng Yang, William Paul, Michael I. Jordan, Ion Stoica University of California, Berkeley



Origins

The next generation of AI infrastructure is being built and scaled on Ray





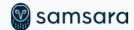




















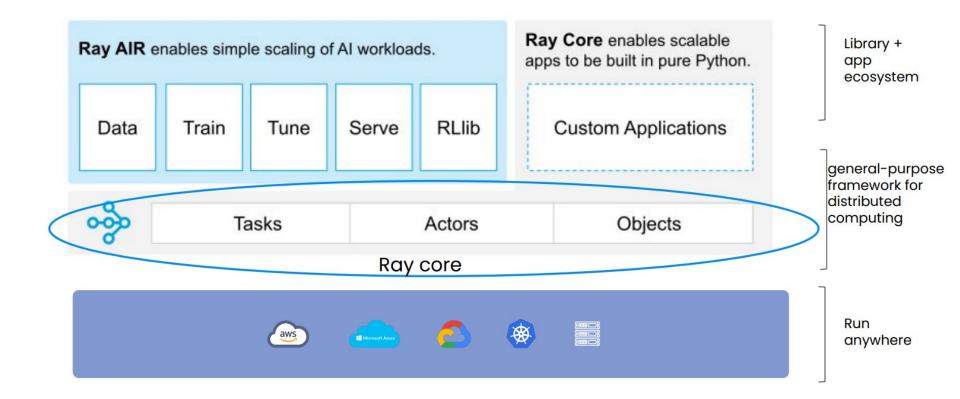
Perplexity AI: How We Built the World's Best LLM-Powered Search Engine in 6 Months, w/ Less Than \$4M

Anyscale • 18K views • 5 months ago

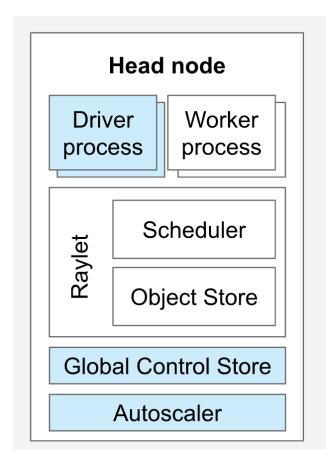
The FAST Compute Model

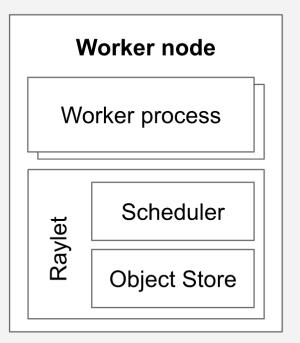
- Futures: references to objects
- Actors: remote class instances (objects)
- Shared in-memory distributed object store
- Tasks: remote functions

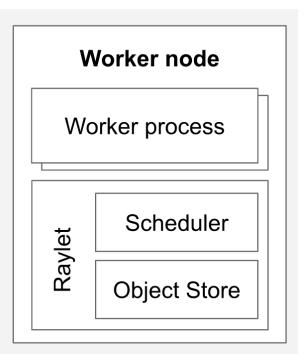
What is Ray?



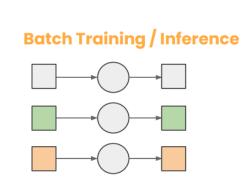
What is Ray?

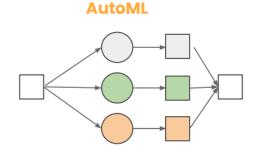


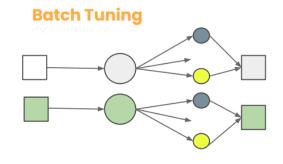




Scaling patterns







Different data / Same function

Compute

Data

Same data / Different function

Different data / Same function

What is Ray?

Python → Ray APIs

object



Node

```
Task
                                                                                 Distributed
 def f(x):
                                                    @ray.remote
                                                                                                        f()
                                                    def f(x):
    # do something with x:
                                                                                                        Node
                                                                                                                            Node
   y= ...
                                                       # do something with x:
   return y
                                                      y= ...
                                                       return y
                                                      @ray.remote
 class Cls():
                                                                                 Distributed
                                                      class Cls():
   def __init__(self,
                                                                                                                            Cls()
                                                                                                        Cls
                                                        def
                                Actor
                                                                                                                    •••
 x):
                                                      __init__(self, x):
                                                                                                        Node
                                                                                                                            Node
   def f(self, a):
                                                        def f(self, a):
   def g(self, a):
                                                        def g(self, a):
import numpy as np
                            Distributed
a= np.arange(1, 10e6)
                                                       import numpy as np
                                                                                   Distributed
b = a * 2
                            immutable
                                                       a = np.arange(1, 10e6)
                                                       obj a = ray.put(a)
                                                                                                                      •••
```

b = ray.get(obj a) * 2

Node

Task API

```
Node 1
                                                                                                Node 2
@ray.remote
def read_array(file):
    # read ndarray "a"
    # from "file"
                                                                                                  file
      return a
                                                                         (read_array
@ray.remote
def add(a, b):
      return np.add(a, b)
id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
                                                                    Return id1 (future) immediately,
sum = ray.get(id)
                                                                    before read_array() finishes
```

Task API

```
@ray.remote
def read_array(file):
    # read ndarray "a"
    # from "file"
    return a

@ray.remote
def add(a, b):
    return np.add(a, b)

id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id)
Node 1

File

Pread_array

read_array

id1

id2

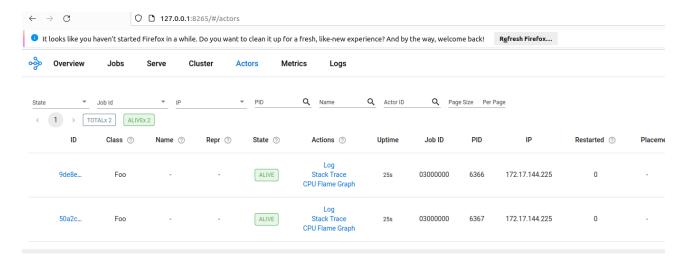
Dynamic task graph:
build at runtime
```

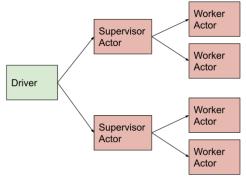
Task API

```
Node 1
                                                                                                      Node 2
@ray.remote
def read_array(file):
    # read ndarray "a"
    # from "file"
       return a
                                                                                 read array
                                                                                                        read_array
@ray.remote
def add(a, b):
                                                                                         id1
                                                                                                         id2
       return np.add(a, b)
                                                                                                            Node 3
id1 = read_array.remote(file1)
id2 = read_array.remote(file2)
id = add.remote(id1, id2)
sum = ray.get(id) ray.get() block until
                                                                                                  add
                                                                                                   id
                                       result available
```

- Start a node
 - ray start --head --port=6379
- Check the dashboard on :
 - http://127.0.0.1:8265/
- Copy notebook to folder and start jupyter service
 - jupyter notebook

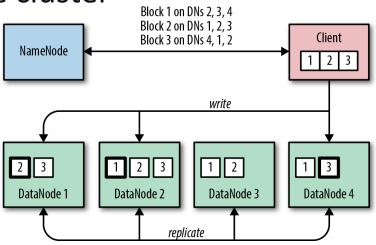
- Open and fill all the gaps in attached notebook
 - All important aspects of ray framework are covered
 - At the end there is main pi computation task
- Your dashboard should look like:





- Implement a distributed artifacts storage system:
 - there is one name node and x storage node (all actors)
 - execute it in a separate script in the system terminal/console
 - name node distributes artifacts to storage nodes in chunks/blocks and keeps track of them
 - there are few copies of chunks in the system to improve high availability and speed (similarly as in HDFS)
 - randomly, data storage nodes can fail; the name node keeps track of all chunks and manages the copies (everything should be consistent)
 - provide a list operation of the most important data (e.g. where chunks/blocks are stored)

- User can perform the following operations from the interactive shell prompt
 - Artifact consist of name and content (stored as string)
 - upload by providing a new artifact
 - update the stored artifact content
 - user can delete artifacts present in the storage
 - user can get/download the artifacts from the storage
 - user can list the status of the cluster



- Verification tests:
 - upload an artifact, list the status
 - update an artifact, list the status
 - get an artifact, list the status
 - delete an artifact, list the status

Homework

- Tier 1 (4 pts)
 - Prepare and present all exercises from labs from Task1 => 4 pts
- Tier 2 (6-8 pts)
 - Prepare implementation of the Task 2 from lab
 - Present demo solution and test scenarios => 7 pts
 - Add some additional advanced functionality, select anything from items not discussed on labs (https://docs.ray.io/en/latest/ray-core/actors.html) => 8 pts
 - Add distribution of environment (e.g. execute it on cluster based on K8s, docker ...) => 9 pts

Homework

- Tier 3 (9 pts)
 - Prepare sample project with other Ray modules
 - Select 3 different modules
 - Prepare tests form your solution
 - Present how you move it from regular implementation to demo on ray
 - Execute them on top of distributed environment(+ 1 pt = 10 total)