

# Laboration 3: Piecewise linear approximations and the finite element method

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## Introduction

Differential equations are of vast interest in science and engineering since they provide mathematical models to a wide range of real world phenomena, such as heat transfer, electromagnetic waves, and quantum mechanics. Hence, the solutions of these equations can be used to gain insight about the world around us. Unfortunately solutions to differential equations can rarely be expressed by closed formulas and we must therefore use numerical approximations. The finite element method is a general technique for computing numerical (i.e., approximate) solutions to differential equations. In this computer session we shall study piecewise linear approximations and derive and implement a finite element method for the boundary value problem

$$-u'' = f, \quad a < x < b, \quad (1)$$

$$u(a) = u(b) = 0, \quad (2)$$

where  $u$  is the sought solution and  $f$  a given function.

## Weak or Variational Form

A finite element method is always derived from the weak or variational formulation of the problem at hand. To this end, let us define the vector space

$$H_0^1 = \{v : \int_a^b v(x)^2 + (v'(x))^2 dx < \infty, v(a) = v(b) = 0\}. \quad (3)$$

Multiplying  $f = -u''$  by a function  $v \in H_0^1$  and integrating by parts gives

$$\int_a^b f v dx = \int_a^b -u'' v \quad (4)$$

$$= -[u' v]_a^b + \int_a^b u' v' dx \quad (5)$$

$$= -u'(b)v(b) + u'(a)v(a) + \int_a^b u' v' dx. \quad (6)$$

Since  $u(a) = u(b) = 0$  the boundary terms drop out and we are left with

$$\int_a^b f v dx = \int_a^b u' v' dx. \quad (7)$$

Hence, the weak or variational form of (1) reads: Find  $u \in H_0^1$ , such that

$$\int_a^b u' v' dx = \int_a^b f v dx, \quad (8)$$

for all  $v \in H_0^1$ .

## Finite Element Approximation

The idea of the finite element method is to look for a solution approximation  $u_h$  in a finite dimensional subspace  $V_h$  of  $H_0^1$  typically consisting of piecewise polynomials. For simplicity, we will only consider the case with piecewise linear polynomials.

Let  $V_h$  be the space of all continuous piecewise linear functions, which vanish at the end points  $a$  and  $b$ , on a partition  $a = x_0 < x_1 < x_2 < \dots < x_N = b$  of the interval  $a \leq x \leq b$  into  $N$  subintervals of equal length  $h$ . Moreover let  $\{\varphi_j\}$  be the set of hat basis functions of  $V_h$  associated with the  $N - 1$  nodes  $x_j$ ,  $j = 1, 2, \dots, N - 1$ , such that

$$\varphi_i(x_j) = \begin{cases} 1, & \text{if } i = j, \\ 0, & \text{if } i \neq j. \end{cases} \quad (9)$$

Note especially that there are no hat functions  $\varphi_0$  and  $\varphi_N$  since the functions of  $V_h$  must vanish at the end points  $x_0$  and  $x_N$ . Otherwise  $V_h$  would not be a subspace of  $H_0^1$ .

The finite element approximation of (8) thus reads: Find  $u_h \in V_h$  such that

$$\int_a^b u_h' v' dx = \int_a^b f v dx, \quad (10)$$

for all  $v \in V_h$ .

It can be shown that (10) is equivalent to the  $N - 1$  equations

$$\int_a^b u_h' \varphi_i' dx = \int_a^b f \varphi_i dx, \quad i = 1, 2, \dots, N - 1, \quad (11)$$

because if (10) is satisfied for each basis function  $\varphi_j$  separately then it is also satisfied for any linear combination of them, that is, any arbitrary function  $v \in V_h$ .

Expanding  $u_h$  as a linear combination of hat functions we make the ansatz

$$u_h = \sum_{j=1}^{N-1} \xi_j \varphi_j(x), \quad (12)$$

where  $\xi_j$ ,  $j = 1, 2, \dots, N - 1$  are  $N - 1$  coefficients, the nodal values of  $u_h$ , to be determined.

Substituting (12) into (10) yields

$$\sum_{j=1}^{N-1} \xi_j \int_a^b \varphi_j' \varphi_i' dx = \int_a^b f \varphi_i dx \quad i = 1, 2, \dots, N - 1, \quad (13)$$

which is a  $(N - 1) \times (N - 1)$  system of equations for  $\xi_j$ . In matrix form we write

$$A\xi = b, \quad (14)$$

where  $A$  is a  $(N - 1) \times (N - 1)$  matrix, the so-called stiffness matrix, with entries

$$A_{i,j} = \int_b^a \varphi'_i(x) \varphi'_j(x) dx, \quad i, j = 1, 2, \dots, N - 1, \quad (15)$$

$\xi = (\xi_1, \xi_2, \dots, \xi_{N-1})^T$  is a  $(N - 1)$  vector containing the unknown coefficients  $\xi_j$ ,  $j = 1, 2, \dots, N - 1$ , and  $b$  is a  $(N - 1)$  vector, the so-called load vector, with entries

$$b_i = \int_a^b f(x) \varphi_i(x) dx, \quad i = 1, 2, \dots, N - 1. \quad (16)$$

## Computer Implementation

The explicit expression for a hat function  $\varphi_i(x)$  is given by

$$\varphi_i(x) = \begin{cases} (x - x_{i-1})/h, & \text{if } x_{i-1} \leq x \leq x_i, \\ (x_{i+1} - x)/h, & \text{if } x_i \leq x \leq x_{i+1}, \\ 0, & \text{otherwise.} \end{cases} \quad (17)$$

Hence the derivative  $\varphi'_i$  is either  $+1/h$ ,  $-1/h$ , or 0 depending on the interval.

Using (17) it is straightforward to calculate the entries of the stiffness matrix. For  $|i - j| > 1$ , we have  $A_{i,j} = 0$ , since  $\varphi_i$  and  $\varphi_j$  lack overlapping support. However, if  $i = j$ , then

$$\int_a^b \varphi_i'^2 dx = \int_{x_{i-1}}^{x_i} \varphi_i'^2 dx + \int_{x_i}^{x_{i+1}} \varphi_i'^2 dx \quad (18)$$

$$= \int_{x_i}^{x_{i+1}} \frac{1}{h^2} dx + \int_{x_i}^{x_{i+1}} \frac{(-1)^2}{h^2} dx = \frac{2}{h}. \quad (19)$$

where we have used that  $x_i - x_{i-1} = x_{i+1} - x_i = h$ . Further, if  $j = i + 1$ ,

then

$$A_{i,i+1} = \int_a^b \varphi'_i \varphi'_{i+1} dx = \int_{x_i}^{x_{i+1}} \varphi'_i \varphi'_{i+1} dx \quad (20)$$

$$= \int_{x_i}^{x_{i+1}} \frac{(-1)}{h} \cdot \frac{1}{h} dx = -\frac{1}{h}. \quad (21)$$

Changing  $i$  to  $i - 1$  we also have  $A_{i-1,i} = -1/h$ .

Thus the stiffness matrix looks like:

$$A = \frac{1}{h} \begin{bmatrix} 2 & -1 & & & \\ -1 & 2 & -1 & & \\ & -1 & 2 & -1 & \\ & & \ddots & \ddots & \ddots \\ & & & -1 & 2 & -1 \\ & & & & -1 & 2 \end{bmatrix}. \quad (22)$$

The entries  $b_i$  of the load vector must often be evaluated using quadrature, since they involve the function  $f$  which can be hard to integrate analytically. For example, using the trapezoidal rule one obtains the approximate load vector entries

$$b_i = \int_a^b f \varphi_i dx = \int_{x_{i-1}}^{x_{i+1}} f \varphi_i dx \approx f(x_i)h. \quad (23)$$

**Assembly.** From a computational point it is advantageous to rewrite (14) as

$$\frac{1}{h} \begin{bmatrix} 10^6 & -1 & & & \\ -1 & 2 & -1 & & \\ & -1 & 2 & -1 & \\ & & \ddots & \ddots & \ddots \\ & & & -1 & 2 & -1 \\ & & & & -1 & 10^6 \end{bmatrix} \begin{bmatrix} \xi_0 \\ \xi_1 \\ \xi_2 \\ \vdots \\ \xi_{N-1} \\ \xi_N \end{bmatrix} = h \begin{bmatrix} f(x_0) \\ f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{N-1}) \\ f(x_N) \end{bmatrix}, \quad (24)$$

that is, to extend the original  $(N - 1) \times (N - 1)$  system of equations into a new  $(N + 1) \times (N + 1)$  system of equations by adding additional equations

for the nodal values  $\xi_0 = u_h(x_0)$  and  $\xi_N = u_h(x_N)$ . Recalling the boundary conditions  $u(a) = u(b) = 0$  it is clear that we want  $\xi_0 = \xi_N = 0$ . This is accomplished by setting the diagonal entries  $A_{0,0}$  and  $A_{N+1,N+1}$  to a big number, say  $10^6$ . The entries  $b_0$  and  $b_N$  of the extended load vector are superfluous and can be chosen arbitrarily.

The system of equations (24) can be computed using the standard assembly technique. Thus the stiffness matrix is successively computed by looping over the elements, for each element adding the element stiffness matrix, viz.,

$$\frac{1}{h} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{1}{h} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \dots + \frac{1}{h} \begin{bmatrix} & & & \\ & & & \\ & & 1 & -1 \\ & -1 & 1 & \end{bmatrix}.$$

Each element matrix is found by performing the integration (15) over a single element.

A routine for assembling the stiffness matrix is listed below.

```
function A=my_stiffness_matrix_assembler(x)
%
% Returns the assembled stiffness matrix A.
% Input is a vector x of node coords.
%
N = length(x) - 1; % number of elements
A = zeros(N+1, N+1); % initialize stiffness matrix to zero
for i = 1:N % loop over elements
    h = x(i+1) - x(i); % element length
    n = [i i+1]; % nodes
    A(n,n) = A(n,n) + [1 -1; -1 1]/h; % assemble element stiffness
end
A(1,1) = 1.e+6; % adjust for BC
A(N+1,N+1) = 1.e+6;
```

The load vector is computed with the use of

```

function b = LoadAssembler1D(x,f)
% trapezoidal integration
n = length(x)-1;
b = zeros(n+1,1);
for i = 1:n
    h = x(i+1) - x(i);
    b(i) = b(i) + f(x(i))*h/2;
    b(i+1) = b(i+1) + f(x(i+1))*h/2;
end

```

Putting it all together we get the main routine:

```

function my_first_fem_solver()
a = 0 % left end point of interval
b = 1 % right
N = 5 % number of intervals
h = (b-a)/N % mesh size
x = a:h:b; % node coords
f = ... % define your function here
A=my_stiffness_matrix_assembler(x);
B=LoadAssembler1D(x,f);
xi = A\B; % solve system of equations
plot(x,xi) % plot solution

```

**Problem 1.** Let  $I = [0, 1]$  and define a uniform mesh on  $I$ . Let  $V_h$  denote the space of all continuous piecewise linear functions on the uniform mesh.

- Write a matlab script `hatfun(x,xe,k)`, that computes the hat function  $\varphi_k(x)$ , where  $\mathbf{x}$  is a vector containing the  $n+1$  nodal points and  $\mathbf{x}_e$  the evaluation point. Then, plot  $\varphi_2(x)$  in partitions with  $n = 2, 5, 10$ .
- Compute the linear interpolant  $\pi f \in V_h$  of  $f(x) = x(1-x)$  by using your script `hatfun`. Hint: The interpolant is defined by (1.31) in the book.
- Write a new script `MassAssembler1D(x)` that computes the mass matrix, by studying the functionality of

`my_stiffness_matrix_assembler`. Compute the  $L^2$ -projection  $P_h f \in V_h$  of  $f(x) = x(1-x)$ . Hint: compare with the functions `L2projector1D` and `MassAssembler1D` given in the book.

- Download the file `LoadAssemblerS1D.m` from Cambro and study it. Modify your code, compare with the previous result and discuss findings.

**Problem 2.** Implement the finite element solver outlined above. Test your code by solving  $-u'' = 2$ ,  $0 < x < 1$ ,  $u(0) = u(1) = 0$ . Use uniform meshes with  $h = 1/2, 1/4, 1/16$  and  $1/256$ . Compare with the exact solution  $u(x) = x(1-x)$  using

- The maximum norm
- The  $L^2$ -norm
- The energy norm  $\|u\|_E^2 = \int_a^b u'(x)^2 dx$

Hint: Show that  $\|u - u_h\|_E^2 = \|u'\|^2 - \|u_h'\|^2$ , where  $u$  is the exact solution and  $u_h$  is the finite element approximation.

**Problem 3.** Modify your code so that it can handle the inhomogeneous boundary condition  $u(1) = u_1$ . Test your code by solving  $-u'' = 0$ ,  $0 < x < 1$ ,  $u(0) = 0$ ,  $u(1) = 7$ .