



Run params:
 number: 3
 gain_ini: 0.03
 gain: 0.03
 delta_cmd_ini: 0.002
 delta_cmd: 0.002
 regularization: left_right_ave
 regularization_rate: 0.25
 n_iterations: 100
 comment: dynamic gain
 actuator_mask: None

Metric params:
 method1: R2Integral
 method2: None
 weights_method12: (1, 0)
 weights_fwhm_xy: (0.5, 0.5)
 r2_integration_radius: 40.0
 normalize_brightness: True
 roi_size: (100, 100, 1)
 tracking: mass
 peak_estimate: max

Left view metric:
 weights_metric12(1, 0)

Right view metric:
 weights_metric12(1, 0)

