# Finding Short Peptide Substrates using Bayesian Active Learning

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We consider a Bayesian active learning problem arising in biochemistry, in which we wish to find a peptide that (1) has a certain expensive-to-ascertain biochemical property (it is a substrate for two protein-modifying enzymes, phosphopantetheinyltransferase and ACP hydrolase); and (2) is as short as possible. Finding such a peptide would allow tracking protein interactions with great ease, and would support a number of innovations in medicine, biochemistry, and materials science. However, such peptides are difficult to find, because the set of peptides is large, only a small fraction have the desired property, and ascertaining whether or not a peptide has the desired property requires performing a time-consuming laboratory experiment. We present a machine learning method for choosing which peptides to test to find such a peptide as quickly as possible. We prove theoretical bounds on its solution quality, demonstrate in simulation that it outperforms two natural benchmark methods, and then describe how it was used in practice to find a peptide with the desired property that is shorter than the shortest previously known. While our method was developed for this specific application in biochemistry, it can also be used in other Bayesian active learning problems in which we wish to find an exemplar whose expensive-to-obtain binary label is positive, and for which a secondary easy-to-evaluate cost objective is as small as possible.

# 1. Introduction

In this paper, we use machine learning to address a specific instance of a problem common in medicine, materials science, chemistry, and other physical sciences. In this class of problems, we wish to find a molecule with a particular biological or chemical property. While we have historical data on related molecules or related properties that can support predictive modeling, the only way that we can determine with certainty whether a particular molecule has the property of interest (in colloquial language, "is a hit") is to synthesize and test it in a time-consuming laboratory experiment. Success is hampered by the enormous search space, and the limits imposed by experimental cost on the number of molecules that can be tested. Within this context, we wish to use

mathematical methods to recommend which experiments to perform, so as to reliably find a hit within a given experimental budget. Common examples include drug discovery, in which we wish to find a molecule that can be effective in treating a particular disease, and materials discovery, in which we wish to find a molecule that has a particular material property.

The instance of this problem that we consider in detail in this paper comes from biochemistry: we wish to find a peptide that is (1) as short as possible; and (2) is a substrate for two protein-modifying enzymes, phosphopantetheinyltransferase (PPTase) and ACP hydrolase (AcpH). These protein-modifying enzymes can be used to attach and detach arbitrary molecules to their substrates. In particular, we can use PPTase to attach a fluorescent "tag" or "label" to peptides that we would discover that are substrates for both enzymes, allowing us to track the peptide, starting from a time of our choosing. We can then use AcpH to remove the fluorescent tag at a time of our choosing. If this peptide were short, then it could be inserted into a protein or peptide-based catalytic complex of our choosing without disrupting its activity, allowing monitoring of biological and catalytic systems. This monitoring tool would have a number of applications in medicine, biology, and materials science.

Finding such a peptide is challenging, because the number of peptides is large, and only a small fraction of them are substrates for both enzymes (i.e., are "hits"). A peptide is a string of amino acids, of which 20 occur in nature, so there are  $20^n$  peptides of length n. The typical length of the peptides under consideration is 15 amino acids long, and the number of peptides with length 15 is  $20^{15} \approx 3.3 \times 10^{19}$ . Of these, we estimate that approximately 1 in  $10^4$  is a substrate. We can test peptides in batches of size approximately 300, and each batch requires approximately one week of work, several thousand dollars in materials, and access to an expensive shared machine on which time can be reserved for a batch of experiments approximately once every two months. If we were to test peptides of length 15 uniformly at random, then we would need to test  $n = \log(1/2)/\log(1-10^{-4}) \approx 6931$  peptides to ensure a probability of 1/2 of finding at least one hit, which would in turn require 23 batches of experiments, and roughly four years' time.

To address this challenge, we formulate this problem as a Bayesian active learning problem. We first develop a Bayesian classification method, which combines Naive Bayes, a prior distribution encoding knowledge from domain experts, and training data from naturally occurring and longer peptide substrates, to predict whether a short peptide is a hit. We then use the joint probability distributed over unobserved labels ("hit" or "miss") of all peptides created by this classification method within a combinatorial optimization framework to find a *set* of peptides to test that, when taken together, are most likely to produce a hit. We provide a theoretical performance guarantee on the quality of the resulting set of peptides to test, and using simulation, we show that this combination of prediction and optimization provides robust results that are better than a more

naive use of the predictive model that considers only marginal probabilities, and a benchmark method of truncating and mutating known hits at random. We then describe laboratory results in which this method was used to discover peptide substrates that are shorter than the shortest previously known (cite YBBR paper).

This paper builds on a number of recently developed methods for optimal search, all of which aim to effectively collect information so as to make the best decisions under uncertainty. In this setting, they need to trade off the reward by sampling (i.e. exploitation) and the cost by acquiring this information (i.e. exploration). For example, in drug discovery, people search for a chemical derivative of the base molecule that best treats disease. To achieve this goal, they choose molecules to test to maximize the expected quality of the best compound discovered (Negoescu et al. 2011). Since the budget for testing is limited, they need to test the most informative and high quality molecules. To address this problem, Jones & Schonlau proposed Expected Improvement algorithm to sample points sequentially (Jones et al. 1998). Ginsbourger used constant liar heuristic to extend Expected Improvement algorithm to parallel setting (Ginsbourger et al. 2008). There are quite a few papers about parallel sampling in active learning research community (Chen et al. 2013, Hoi et al. 2006b,a), but they only aim to maximize information gain (i.e. pure exploration).

In section 2, we provide a formal model of our problem. In section 3, we state the Bayesian classification model used for the problem. In section 4, we provide the formulation of the proposed optimization algorithm, prove its performance guarantee, and summarize the algorithm in pseudo code. In section 5, we use available real data to validate our statistical model, compare the performance of our proposed optimization method against other methods, and show progress of this biochemical application using our method.

## 2. Problem Formulation

We now formalize and generalize our problem as an active learning problem, which includes but is not limited to our application.

Let E be a generic search space of exemplars. In our application, E is the search space of peptide candidates. Each element  $x \in E$  has an unknown binary label  $y(x) = \{0,1\}$ . In our application, y(x) is 1 if x is a hit, i.e., is a substrate for both enzymes, and 0 if not. A known deterministic function f(x) measures the cost or disutility associated with x. In our application, f(x) is the length of the peptide, as longer peptides interfere more with the system being monitored. Our goal is to perform experiments so as to find x with a positive label and a cost f(x) that is as small as possible.

To obtain labels of exemplars, we can do a batch of experiments, which evaluates the labels for a subset  $S \subseteq E$ . The cardinality of S is constrained by some K (i.e.  $|S| \le K$ ), modeling our budget for performing experiments. We measure the quality of S by

$$f^*(S) = \min_{x \in S: y(x) = 1} f(x), \tag{1}$$

where we assume  $\min \emptyset = \infty$ .  $f^*(S)$  measures the smallest cost function for positive labeled elements in the set S, and in our motivating application, that means the shortest length of desired peptides in the set of peptides to test.

Let b be a target value and we wish to find  $S \subseteq E$  such that  $f^*(S)$  is better than b. In our motivating application, we let b be the length of the shortest previously known desired peptide. Since  $f^*(S)$  is an unknown random variable, we consider the following two probabilistic measures:

Probability of Improvement: 
$$P^*(S) = \mathbb{P}(f^*(S) < b)$$
  
Expected Improvement:  $EI(S) = \mathbb{E}[(b - f^*(S))^+]$  (2)

Given constraint on the cardinality of S, we wish to find S that maximizes one of these two measures. Let g(S) be either  $P^*(S)$  or EI(S), and we can write our goal as

$$\max_{S \subseteq E: |S| \le K} g(S). \tag{3}$$

## 3. Statistical model

We use Naive Bayes as the classification method, which, despite the name, has performed quite well in many cases. Let  $X = (X_1, ..., X_n)$  be an instance with n features and Y be its label. By Bayes's Rule, we have:

$$\mathbb{P}(Y=y|X=x) = \frac{\mathbb{P}(X=x|Y=y)\mathbb{P}(Y=y)}{\mathbb{P}(X=x)} = \frac{\mathbb{P}(X=x|Y=y)\mathbb{P}(Y=y)}{\sum_{y'}\mathbb{P}(X=x|Y=y')\mathbb{P}(Y=y')}$$

The Naive Bayes classifier assumes that the presence or absence of a particular feature is unrelated to the presence or absence of any other feature, given the class variable, i.e.

$$\mathbb{P}(Y = y | X = x) = \frac{\prod_{j=1}^{n} \mathbb{P}(X_j = x_j | Y = y) \mathbb{P}(Y = y)}{\sum_{y'} \prod_{j=1}^{n} \mathbb{P}(X_j = x_j | Y = y) \mathbb{P}(Y = y)}$$

In our motivation application, we have a set of peptides, each with length less than or equal to L. Each peptide is a sequence of amino acids. We use a reduced alphabet for amino-acids, i.e., we group them into K groups. For each peptide, let  $A_i$  be the amino acid on position j, and let  $X_i$  be the class of this amino acid. For a specific enzyme, let Y(x) = 1 if peptide x is a substrate for that enzyme and 0 if not.

We let  $\theta_{y,j}(k) = \mathbb{P}(X_i = k | Y(X) = y)$ , for each j = 1, ..., L, k = 1, ..., K and  $y \in \{0, 1\}$ . We further assume some known prior distribution  $\mathbb{P}(Y(x) = y)$ ,  $y \in \{0, 1\}$ . Let  $\theta$  be the full set of parameters  $\theta_{y,j}(k)$ , for j = 1, ..., L, k = 1, ..., K and  $y \in \{0, 1\}$ . Then, given an unlabeled peptide, we can calculate its probability being a substrate as:

$$\mathbb{P}(Y(x) = 1 | \theta) = \frac{\mathbb{P}(Y(x) = 1) \prod_{j} \theta_{1,j}(x_j)}{\left[\mathbb{P}(Y(x) = 1) \prod_{j} \theta_{1,j}(x_j)\right] + \left[\mathbb{P}(Y(x) = 0) \prod_{j} \theta_{0,j}(x_j)\right]}$$
(4)

We estimate the parameters  $\theta_{y,j}(k)$  using Bayesian inference. We assume for each  $j=1,\ldots,L$ ,  $y \in \{0,1\}$ , the vector  $\theta_{y,j} \sim \text{Dirichlet}(\alpha_{y,j}(1),\ldots,\alpha_{y,j}(K))$ . A good initial choice for the parameter vector  $\alpha_{y,j} = (\alpha_{y,j}(1),\ldots,\alpha_{y,j}(6))$  can be choosing  $\alpha_{y,j}(k)$  to be constant across k, and y, and to only depend upon j. Since amino acids further from the serine are less likely to have a strong influence on its activity, we choose this value to be 1 in the positions next to the serine and to increase as j moves further.

We further assume two hyper parameters  $\gamma_0$  and  $\gamma_1$  that characterize the distribution for y = 0 and y = 1 respectively. Then, with the prior distribution and hyper parameters, our posterior distribution is also Dirichlet. In particular, it is Dirichlet $(\alpha_{y,j}(1) + \gamma_y N_{y,j}(1), \dots, \alpha_{y,j}(K) + \gamma_y N_{y,j}(K))$ , where  $N_{y,j}(k)$  counts how many peptides x in the training data with Y(x) = y had  $x_j = k$ . That is, it counts how many peptides had amino acid j in class j.

# 4. Optimization Algorithm

(3) is a combinatorial optimization problem with huge feasible region. This problem is considered NP-hard and yet there is no known algorithm that solves it quickly. We propose an approximation algorithm, which solves (3) using greedy heuristic, that is, starting with the empty set  $S = \emptyset$ , iteratively find element e such that

$$\underset{e \in E \setminus S}{\arg \max} g(S \cup \{e\}), \tag{5}$$

and incorporate it into S until |S| = K for some chosen K. This approach reduces the size of search space dramatically from  $|E|^{|S|}$  down to  $|E| \times |S|$ , and we prove that if objective function g is either  $P^*$  or EI, the proposed greedy algorithm is guaranteed to be near-optimal with a lower bound. Additionally, we show that under the statistical model described in section 3, we can formulate (5) as Mixed-Integer Nonlinear Programming (MINLP) and solve it efficiently using a off-the-shelf MINLP solver.

## 4.1. Lower bound of greedy algorithm

In this subsection, we show that when the objective function g in (5) is either  $P^*$  or EI, the proposed greedy algorithm has performance guarantee. The result is stated in the following:

THEOREM 1. If objective function is probability of improvement (i.e  $P^*(S)$ ) or expected improvement (i.e EI(S)), the greedy algorithm is guaranteed to achieve a factor  $(1-1/e)(\approx 63\%)$  of the optimal value.

We prove the theorem using the following three lemmas. Lemma 1 is a result from the analysis of greedy heuristic in combinatorial optimization by Nemhauser, which provides lower bound of greedy heuristic given that objective function satisfies certain conditions. Lemma 2 and 3 show P\* and EI are the objective functions that satisfy conditions stated in Lemma 1, and thus greedy algorithm has a lower bound.

LEMMA 1. Nemhauser et al. (1978) If F(S) is submodular, nondecreasing and  $F(\emptyset) = 0$ , the greedy heuristic always produces a solution whose value is at least  $1 - [(K-1)/K]^K$  times the optimal value, where  $|S| \leq K$ . This bound can be achieved for each K and has a limiting value of 1 - 1/e, where e is the base of the natural logarithm.

LEMMA 2. Probability of improvement  $P^*(S)$  is submodular, nondecreasing and  $P^*(\emptyset) = 0$ .

LEMMA 3. Expected improvement EI(S) is submodular, nondecreasing and  $EI(\emptyset) = 0$ .

Proof of Theorem 1. From Lemma 2 and 3, we know that  $P^*$  and EI are submodular, nondecreasing and their measure of the empty set is 0. From Lemma 1, we conclude that if the objective function g in (5) is  $P^*$  or EI, the greedy algorithm is guaranteed to achieve a factor of (1-1/e) of the optimal value.  $\square$ 

Proof of Lemma 2. First we show  $P^*(\emptyset) = 0$ .

$$P^*(\emptyset) = \mathbb{P}(f^*(\emptyset) < b) = \mathbb{P}(\infty < b) = 0.$$

To show  $P^*(S)$  is nondecreasing, let  $A \subseteq B \subseteq E$  where E is a finite set, then

$$\begin{split} \mathbf{P}^*(B) &= \mathbb{P}(f^*(B) < b) \\ &= \mathbb{P}(f^*(B) < b | f^*(A) \ge b) \mathbb{P}(f^*(A) \ge b) + \mathbb{P}(f^*(B) < b | f^*(A) < b) \mathbb{P}(f^*(A) < b) \\ &= \mathbb{P}(f^*(B) < b | f^*(A) \ge b) \mathbb{P}(f^*(A) \ge b) + \mathbb{P}(f^*(A) < b) \\ &\ge \mathbb{P}(f^*(A) < b) \\ &= \mathbf{P}^*(A) \end{split}$$

Lastly, we want to show  $P^*(S)$  is submodular. For  $e \in E \setminus B$ ,

$$\begin{split} & \mathbb{P}^*(A \cup \{e\}) - \mathbb{P}^*(A) \\ & = \mathbb{P}(f^*(A \cup \{e\}) < b) - \mathbb{P}(f^*(A) < b) \\ & = \mathbb{P}(f^*(A \cup \{e\}) < b|f^*(A) < b)\mathbb{P}(f^*(A) < b) + \mathbb{P}(f^*(A \cup \{e\}) < b|f^*(A) \ge b)\mathbb{P}(f^*(A) \ge b) - \mathbb{P}(f^*(A) \le b) - \mathbb{P}(f^*(A) \le b) \\ & = \mathbb{P}(f^*(A) < b) + \mathbb{P}(f^*(A \cup \{e\}) < b|f^*(A) \ge b)\mathbb{P}(f^*(A) \ge b) - \mathbb{P}(f^*(A) < b) \\ & = \mathbb{P}(f^*(A \cup \{e\}) < b|f^*(A) \ge b)\mathbb{P}(f^*(A) \ge b) \\ & = \mathbb{P}(f(e) < b, y(e) = 1 | f^*(A) \ge b)\mathbb{P}(f^*(A) \ge b) \\ & = \mathbb{P}(f(e) < b, y(e) = 1, f^*(A) \ge b) \end{split}$$

Using similar argument,

$$\begin{split} & \mathbf{P}^*(B \cup \{e\}) - \mathbf{P}^*(B) \\ & = \mathbb{P}(f(e) < b, y(e) = 1, f^*(B) \ge b) \\ & = \mathbb{P}(f(e) < b, y(e) = 1, f^*(A) \ge b, f^*(B \backslash A) \ge b) \end{split}$$

Therefore,  $P^*(A \cup \{e\}) - P^*(A) \ge P^*(B \cup \{e\}) - P^*(B)$ , thus  $P^*(S)$  is submodular.  $\square$  *Proof of Lemma 3.* First we show  $EI(\emptyset) = 0$ .

$$EI(\emptyset) = \mathbb{E}[(b - f^*(\emptyset))^+] = \mathbb{E}[0] = 0.$$

To show  $\mathrm{EI}(S)$  is nondecreasing, let  $A\subseteq B\subseteq E$  where E is a finite set. Since  $f^*(B)\leq f^*(A)$ ,  $b-f^*(B)\geq b-f^*(A)$ , and  $(b-f^*(B))^+\geq (b-f^*(A))^+$ , therefore,  $\mathbb{E}[(b-f^*(B))^+]\geq \mathbb{E}[(b-f^*(A))^+]$ . Lastly, we want to show  $\mathrm{P}^*(S)$  is submodular. For  $e\in E\backslash B$ , consider  $\mathbb{E}[(b-f^*(A\cup\{e\}))^+]-\mathbb{E}[(b-f^*(A))^+]$ . We can write

$$(b - f^*(A \cup \{e\}))^+ = \begin{cases} (b - f^*(A))^+ & \text{if } y(e) = 0\\ (b - \min\{f(e), f^*(A)\})^+ & \text{if } y(e) = 1 \end{cases}$$

Then

$$\begin{split} & \mathbb{E}[(b-f^*(A\cup\{e\}))^+] - \mathbb{E}[(b-f^*(A))^+] \\ &= \mathbb{P}(y(e)=1)\mathbb{E}[(b-\min\{f(e),f^*(A)\})^+ - (b-f^*(A))^+ | y(e)=1] \\ &= \mathbb{P}(y(e)=1)\mathbb{P}(f(e) < f^*(A)|y(e)=1)\mathbb{E}[(b-e)^+ - (b-f^*(A))^+ | y(e)=1, f(e) < f^*(A)] \\ &= \mathbb{E}[\mathbbm{1}_{y(e)=1,f(e) < f^*(A)}((b-e)^+ - (b-f^*(A))^+)] \end{split}$$

Since  $f^*(A) \ge f^*(B)$ ,  $\mathbb{1}_{y(e)=1,f(e)< f^*(A)}((b-e)^+ - (b-f^*(A))^+)) \ge \mathbb{1}_{y(e)=1,f(e)< f^*(B)}((b-e)^+ - (b-f^*(B))^+)$ , thus

$$\mathrm{EI}(A \cup \{e\}) - \mathrm{EI}(A) \geq \mathrm{EI}(B \cup \{e\}) - \mathrm{EI}(B)$$

EI(S) is submodular.  $\square$ 

## 4.2. Probability of Improvement

We first show in Proposition 1 that (5) can be written into the form in which the objective function can be easily calculated using any statistical classifier. This is the general form of greedy algorithm for optimization over probability of improvement and can be used with any underlying statistical model. In addition, we show that, using the Naive Bayes classifier proposed in section 3, we can further formulate (5) as a MINLP, which can be solved efficiently using an off-the-shelf MINLP solver.

Proposition 1. If the objective function g is  $P^*$ , we can write (5) as

$$\underset{e \in E \setminus S, f(e) < b}{\operatorname{arg\,max}} \, \mathbb{P}(y(e) = 1 | y(x) = 0, \forall x \in S). \tag{6}$$

Proof of proposition 1.

$$\begin{split} \mathbf{P}^*(S \cup \{e\}) &= \mathbb{P}(f^*(S \cup \{e\}) < b) \\ &= \mathbb{P}(f^*(S) < b) + \mathbb{P}(f^*(S) \ge b) \mathbb{P}(f(e) < b, y(e) = 1 | f^*(S) \ge b), \end{split}$$

so (5) becomes

$$\max_{e \in E \setminus S} P^*(S \cup \{e\}) = \max_{e \in E \setminus S} \mathbb{P}(f(e) < b, y(e) = 1 | f^*(S) \ge b). \tag{7}$$

Note that when  $f(e) \ge b$ ,  $\mathbb{P}(f(e) < b, y(e) = 1 | f^*(S) \ge b) = 0$ , thus our algorithm will always propose e such that f(e) < b. Therefore, it is reasonable to assume that f(x) < b for  $\forall x \in S$ , and  $f^*(S) \ge b$  is equivalent to y(x) = 0 for  $\forall x \in S$ . Now we can write (7) as

$$\max_{e \in E \backslash S, f(e) < b} \mathbb{P}(y(e) = 1 \mid y(x) = 0, \forall x \in S). \quad \Box$$

In our motivating application, we use the Naive Bayes model described in section 3, and we want to formulate (6) as a MINLP. First write equation (4) as

$$\mathbb{P}(Y(x) = 1 | \theta) = \frac{\prod_{j} \eta_{j}(x_{j})}{\prod_{j} \eta_{j}(x_{j}) + \frac{\mathbb{P}(Y(x) = 0)}{\mathbb{P}(Y(x) = 1)}},$$
(8)

where

$$\eta_j(x_j) = \frac{\theta_{1,j}(x_j)}{\theta_{0,j}(x_j)} \text{ for } \forall j \in \{1,\dots,L\}.$$

Then we can write equation (6) as

$$\underset{e \in E \setminus S, f(e) < b}{\operatorname{arg max}} \frac{\prod_{j} \eta_{j}(e_{j})}{\prod_{j} \eta_{j}(e_{j}) + \frac{\mathbb{P}(Y(e) = 0)}{\mathbb{P}(Y(e) = 1)}},\tag{9}$$

where

$$\eta_j(e_j) = \frac{\mathbb{P}(e_j|Y(e)=1,Y(x)=0,\forall x\in S)}{\mathbb{P}(e_j|Y(e)=0,Y(x)=0,\forall x\in S)}.$$

Now we can formulate equation (9) as a MINLP.

$$\max \frac{\prod_{j} \Sigma_{k} x_{j}(k) \eta_{j}(k)}{\prod_{j} \Sigma_{k} x_{j}(k) \eta_{j}(k) + \frac{\mathbb{P}(Y(x)=0)}{\mathbb{P}(Y(x)=1)}}$$
s.t  $k \in \{1, \dots, K\}$ 

$$x_{j}(k) \in \{0, 1\}$$

$$\Sigma_{k} x_{j}(k) = 1,$$

$$(10)$$

where

$$x_j(k) = \begin{cases} 1 & \text{if } e_j = k \\ 0 & \text{else.} \end{cases}$$

We summarize the algorithm in Algorithm 1.

# **Algorithm 1** (Probability of Improvement)

**Require:** Inputs M, J, K, data set D and prior distribution of  $\theta_v \sim Dirichlet(\alpha_v), y \in \{1, 0\}$ 

- 1:  $S \leftarrow \emptyset$
- 2: Calculate posterior distribution of  $\theta_1 \sim Dirichlet(\alpha_1 | \{x | x \in D, y(x) = 1\})$ .
- 3: for m = 1 to M do
- 4:  $COUNT \leftarrow 0$
- 5: Calculate posterior distribution of  $\theta_0 \sim Dirichlet(\alpha_0 | \{x | x \in D, y(x) = 0\} \cup S)$ .
- 6: **loop**
- 7: Sample  $\theta_1$  from  $Dirichlet(\boldsymbol{\alpha}_1|\{x|x\in D,y(x)=1\})$  and  $\theta_0$  from  $Dirichlet(\boldsymbol{\alpha}_0|\{x|x\in D,y(x)=0\}\cup S)$ .
- 8:  $\eta \leftarrow \frac{\theta_1}{\theta_0}$
- 9: Solve MINLP in equation (10) to find x.
- 10:  $COUNT \leftarrow COUNT + x$ .
- 11: **end loop**
- 12: for j = 1 to J do
- 13:  $e_j \leftarrow \underset{k \in \{1, \dots, K\}}{\operatorname{arg \, max}} COUNT_{kj}$
- 14: end for
- 15:  $S \leftarrow (S, e)$
- 16: **end for**

## 4.3. Expected Improvement

The formulation for the case of expected improvement is similar to that of probability of improvement, and for our motivating application, we can also formulate (5) as a MINLP.

Proposition 2. If the objective function g is EI, we can write (5) as

$$\underset{e \in E \setminus S}{\operatorname{arg\,max}} c_0 \mathbb{P}_0(e) (b - f(e))^+ + \sum_{i=1}^{|S|} c_i \mathbb{P}_i(e) (f(x_i) - f(e))^+, \tag{11}$$

where

$$\mathbb{P}_{0}(e) = \mathbb{P}(y(e) = 1 | y(x) = 0, \forall x \in S),$$

$$\mathbb{P}_{i}(e) = \mathbb{P}(y(e) = 1 | y(x_{i}) = 1, y(x_{i}) = 0, \forall j < i, x_{i}, x_{i} \in S),$$

and  $c_i(i = 0, ..., |S|)$  are known coefficients.

Proof of proposition 2. Since choosing e such that  $f(e) \ge b$  has no contribution to the objective function, by using similar argument as dealing with probability of improvement, we argue that f(x) < b for  $\forall x \in S$ . Thus

$$f^*(S)$$
  $\begin{cases} = \infty & \text{if } y(x) = 0 \text{ for } \forall x \in S, \\ < b & \text{else.} \end{cases}$ 

Now objective function we want to maximize becomes

$$\begin{split} & \mathbb{E}\left[(b-f^*(S\cup\{e\}))^+\right] \\ & = \mathbb{E}[(b-f(e))^+ \mathbb{1}_{f^*(S)=\infty,y(e)=1}] + \mathbb{E}[(b-f^*(S\cup\{e\}))^+ \mathbb{1}_{f^*(S)< b}] \\ & = \mathbb{E}[(b-f(e))^+ \mathbb{1}_{f^*(S)=\infty,y(e)=1}] + \mathbb{E}[(b-f^*(S))\mathbb{1}_{f^*(S)< b}] + \mathbb{E}[(f^*(S)-f(e))\mathbb{1}_{y(e)=1,f(e)< f^*(S)< b}]. \end{split}$$

so

$$\max_{e \in E \setminus S} \mathbb{E}\left[ (b - f^*(S \cup \{e\}))^+ \right], 
= \max_{e \in E \setminus S, f(e) < b} \mathbb{E}\left[ (b - f(e)) \mathbb{1}_{f^*(S) = \infty, y(e) = 1} \right] + \mathbb{E}\left[ (f^*(S) - f(e)) \mathbb{1}_{y(e) = 1, f(e) < f^*(S) < b} \right].$$
(12)

For  $e \in E \setminus S$ , f(e) < b,

$$\mathbb{E}[(b-f(e))\mathbb{1}_{f^*(S)=\infty,y(e)=1}] = \mathbb{P}(y(e)=1,y(x)=0,\forall x \in S)(b-f(e)),$$

$$\mathbb{E}[(f^*(S)-f(e))\mathbb{1}_{y(e)=1,f(e)< f^*(S)< b}],$$

$$=\mathbb{E}[\mathbb{E}[(f^*(S)-f(e))\mathbb{1}_{y(e)=1,f(e)< f^*(S)< b}]|f^*(S)=l],$$

$$=\sum_{l \in L, f(e)< l} \mathbb{P}(y(e)=1|f^*(S)=l)(l-f(e))\mathbb{P}(f^*(S)=l),$$
(13)

where  $L = \{f(x) : x \in S\}$ . If we rank elements in S such that  $f(x_i) \leq f(x_j), \forall i < j, x_i, x_j \in S$ , we can write equation above as

$$\sum_{i=1}^{|S|} \mathbb{P}(y(e) = 1, y(x_i) = 1, y(x_j) = 0, \forall j < i, x_i, x_j \in S)(f(x_i) - f(e))^+. \tag{14}$$

Substitute (13) (14) into (12), and note that  $\mathbb{P}(y(e) = 1, \mathcal{F}(x_1, \dots, x_{|S|})) \propto \mathbb{P}(y(e) = 1 | \mathcal{F}(x_1, \dots, x_{|S|}))$  with known coefficient given S, we get (11) in proposition 2.  $\square$ 

Note that each term in the summation of (11) has a similar structure as (6). Let  $S = \{p^1, \dots, p^{|S|}\}$ , we can write (11) as a MINLP:

$$\max \quad \sum_{i=0}^{|S|} c_i \frac{\prod_j \sum_k x_j(k) \eta_j^i(k)}{\prod_j \sum_k x_j(k) \eta_j^i(k) + \frac{\mathbb{P}(Y(x)=0)}{\mathbb{P}(Y(x)=1)}} (f_i - f(e))^+$$
s.t  $k \in \{1, \dots, K\}$ 

$$x_j(k) \in \{0, 1\}$$

$$\sum_k x_j(k) = 1,$$

$$(15)$$

where

$$x_j(k) = \begin{cases} 1 & \text{if } e_j = k \\ 0 & \text{else,} \end{cases}$$
$$f_i = \begin{cases} b & \text{if } i = 0 \\ f(p^i) & \text{else,} \end{cases}$$

and  $c_i$ 's are known coefficients. We summarize it in Algorithm 2.

# **Algorithm 2** (Expected Improvement)

```
Require: Inputs M, J, K, data set D and prior distribution of \theta_u \sim Dirichlet(\alpha_u), y \in \{1, 0\}
  1: S \leftarrow \emptyset
 2: for m = 1 to M do
          COUNT \leftarrow 0
          if S is not empty then
 4:
             Sort elements in S as \{p^1, \ldots, p^{|S|}\} such that f(p^i) \leq f(p^j), \forall i < j.
          end if
 6:
          Calculate posterior distribution of \theta_1^0 \sim Dirichlet(\alpha_1 | \{x | x \in D, y(x) = 1\}) and \theta_0^0 \sim
          Dirichlet(\boldsymbol{\alpha}_0|\{x|x\in D,y(x)=0\}\cup S).
          for i = 1 to |S| do
 8:
             Calculate posterior distribution of \theta_1^i \sim Dirichlet(\boldsymbol{\alpha}_1 | \{x | x \in D, y(x) = 1\} \cup \{p^i\}) and \theta_0^i \sim Dirichlet(\boldsymbol{\alpha}_1 | \{x | x \in D, y(x) = 1\} \cup \{p^i\})
 9:
             Dirichlet(\alpha_0 | \{x | x \in D, y(x) = 0\} \cup \{p^j | j < i\}).
          end for
10:
          loop
11:
            \begin{array}{l} \textit{Sample} \,\, \theta_1^{i=0:|S|} \,\, \textit{and} \,\, \theta_0^{i=0:|S|} \,\, \textit{from posterior distribution.} \\ \eta^{i=0:|S|} \leftarrow \frac{\theta_1^{i=0:|S|}}{\theta_0^{i=0:|S|}} \end{array}
12:
13:
             Solve MINLP in equation (15) to find x.
14:
             COUNT \leftarrow COUNT + x.
15:
          end loop
16:
          for j = 1 to J do
17:
             e_i \leftarrow \operatorname{arg\,max} COUNT_{k_i}
18:
          end for
19:
          S \leftarrow (S, e)
20:
21: end for
```

## 5. Model Validation and Performance

In this section we validate our statistical model and evaluate the performance of our proposed optimization methods. For model validation, we use real experimental data as training data, and use the leave-one-out cross validation to produce receiver operating characteristic(ROC) curve. We show the plots in Section 5.1. To evaluate the performance of our proposed algorithm, we compare it with two methods introduced in Section 5.2, using either P\* or EI as performance metrics. We show the performance results in Section 5.3. In Section 5.4 we show that after performing two rounds of experiments using the proposed algorithm to generate peptide candidates, we successfully found more short peptides with desired property.

## 5.1. Naive Bayes Classifier

Since our training data is expensive and highly skewed, we use the leave-one-out cross validation procedure to choose the optimal hyper parameters. For each setting of the hyper parameters, we obtain an receiver operating characteristic (ROC) curve using the result of the leave-one out procedure and choose the setting with highest AUC (area under curve).

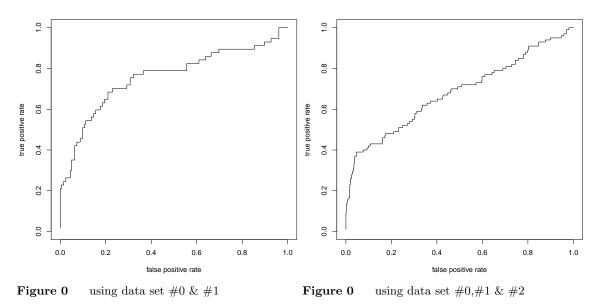


Figure 1 ROC curve using leave-one-out cross validation

In Figure 1, note ROC curve to the left is better than the one to the right. This is because data set #2 was generated by our algorithm based on the previous two data sets, and due to the exploration manner of our algorithm, data set #2 should lie in the region that is more challenging for the classifier. Thus it is reasonable that our classifier performs worse using all available data sets.

### 5.2. Comparison Methods

We compare our proposed algorithm to the two methods that our biochemist collaborators originally considered to use: one is a typical biological evoluation approach, that is, mutate known peptides with positive label, and take N peptide candidates with highest predicted probability being positive for testing. The other method is to use the trained classifier to predict probability being positive for all peptides in the library, and select N most probable ones for testing. We show their performance in Section 5.3.

## 5.3. Performance Comparison

The benchmark was performed on real experiment data. We use data set #0 and #1 to train the statistical model, and based on this model, we generate peptides for testing using our proposed algorithm and the other two comparison methods. Then we train the statistical model using data set #0, #1 and #2, and treat it as oracle to evaluate the performance of the methods.

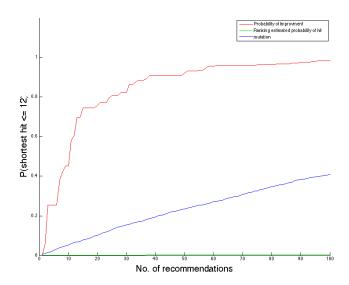


Figure 2 Benchmark of Probability of Improvement algorithm

In Figure 2 we show the benchmark using P\* as performance metric. We can see Probability of Improvement algorithm is significantly better than the other two methods. Part of the reason is that the Probability of Improvement algorithm is designed to make the best decisions under uncertainty and choose the best balance between exploitation and exploration. We can see the effect of uncertainty of the current model by noting that the ranking method performs the worst, because in this method it assumes the underlying statistical model is accurate and does pure exploitation.

We also plan to show the benchmark using EI as performance metric in the furture.

### 5.4. Progress on Real Experiments

Given the initial training data with size, we have performed two rounds of experiments using recommendations generated by Probability of Improvement algorithm. We show the histogram of length distribution of desired peptides found in Figure 3.

From the histogram we conclude that the usage of Probability of Improvement algorithm did a great job in finding short desired peptides.

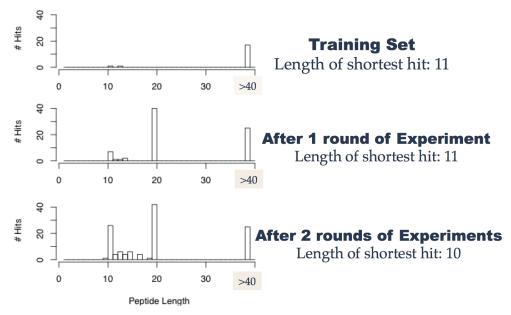


Figure 3 Length distribution of target peptides.

## 6. Conclusion

We proposed an optimal search algorithm based on greedy heuristic for solving the active learning problem motivated by a biochemistry problem, which is described in Section 2, and proved that the proposed algorithm guarantees to achieve at least a factor (1-1/e) of the optimal value. From benchmark results, we further showed that the proposed algorithm outperformed the other two heuristic search methods. In addition to theoretic results, We demonstrated effectiveness of our methods by applying them to the motivating problem, in which we have found a significant number of short peptides with desired property.

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