

Homework 5.

$$1. (a) A_{dev}^T = \frac{1}{3}(tr\bar{A})\bar{I}, B_{dev} = \bar{B} - \frac{1}{3}tr(\bar{B})\bar{I}$$

$$A_{dev}^T B_{dev} = \frac{1}{3}(tr\bar{A})\bar{B} - \frac{1}{9}tr(\bar{A})tr(\bar{B})\bar{I}$$

$$\begin{aligned} A_{dev} \cdot B_{dev} &= tr(A_{dev}^T B_{dev}) = tr\left[\frac{1}{3}(tr\bar{A})\bar{B} - \frac{1}{9}tr(\bar{A})tr(\bar{B})\bar{I}\right] \\ &= \frac{1}{3}tr(\bar{A})tr(\bar{B}) - \frac{1}{3}tr(\bar{A})tr(\bar{B}) = 0 \end{aligned}$$

$$(b) \bar{A}_{dev}^T = \bar{A}^T - \frac{1}{3}tr(\bar{A})\bar{I}, B_{dev} = \bar{B} - \frac{1}{3}tr(\bar{B})\bar{I}$$

$$A_{dev}^T B_{dev} = \bar{A}^T \bar{B} - \frac{1}{3}tr(\bar{A})\bar{B} - \frac{1}{3}tr(\bar{B})\bar{A} + \frac{1}{9}tr(\bar{A})tr(\bar{B})\bar{I}$$

$$tr(A_{dev}^T B_{dev}) = tr(\bar{A}^T \bar{B}) - \frac{1}{3}tr(\bar{A})tr(\bar{B}) - \frac{1}{3}tr(\bar{A})tr(\bar{B}) + \frac{1}{9}tr(\bar{A})tr(\bar{B})$$

$$\text{So, right} = tr(\bar{A}^T \bar{B}) = \bar{A} \cdot \bar{B}$$

$$(c) W = \frac{1}{2}\bar{e} = (\bar{e}^T \bar{e}) = \frac{1}{2}C_{ijkl}e_{ij}e_{kl}$$

$$= \frac{1}{2}[\lambda\delta_{ij}\delta_{kl} + m(\delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk})]e_{ij}e_{kl}$$

$$= \frac{1}{2}\lambda e_{ii}e_{jj} + \frac{1}{2}m(e_{ij})^2 + \frac{1}{2}m(e_{ij})^2$$

$$= \frac{1}{2}\lambda[tr(\bar{e})]^2 + m\bar{e} \cdot \bar{e}$$

$$= \left(\frac{\lambda}{2} + \frac{m}{3}\right)(tr\bar{e})^2 + m(\bar{e}_{dev})^2$$

$$(d) \lambda = \frac{VE}{(1+V)(1-2V)}, m = \frac{E}{2(1+V)}$$

$$\frac{\lambda+m}{2+\lambda} = \frac{VE}{2(1+V)(1-2V)} + \frac{E}{6(1+V)} = \frac{(1+V-6V^2)E}{6(1+V)(1-2V)} > 0$$

$$\left| m = \frac{E}{2(1+V)} > 0 \right.$$

E represents the ratio of uniaxial stress to the uniaxial strain.

V represents the ratio of transverse strain to the axial strain.

so, $E > 0$, $1+V > 0$, that's $V > -1$

① When $1-2V > 0$, that's $V < \frac{1}{2}$, $1+V-6V^2 > 0$, that's $-\frac{1}{3} < V < \frac{1}{2}$

② when $1-2V < 0$, that's $V > \frac{1}{2}$, $1+V-6V^2 < 0$, that's $V > \frac{1}{2} \otimes V < \frac{1}{3}$

so, $V > -1$.

$$(e) \text{ As } \bar{\bar{\sigma}}_{\text{dev}} = \begin{bmatrix} \sigma_{11} - \frac{\text{tr}\bar{\bar{\sigma}}}{3} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} - \frac{\text{tr}\bar{\bar{\sigma}}}{3} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} - \frac{\text{tr}\bar{\bar{\sigma}}}{3} \end{bmatrix}$$

$$C_1 = \frac{1}{2} (\sigma_{11} + \sigma_{22} - \frac{2}{3} \text{tr}\bar{\bar{\sigma}}), C_2 = \frac{1}{2} (\sigma_{22} + \sigma_{33} - \frac{1}{3} \text{tr}\bar{\bar{\sigma}}), C_3 = \frac{1}{2} (\sigma_{11} + \sigma_{33} - \frac{2}{3} \text{tr}\bar{\bar{\sigma}})$$

$$R_1 = \frac{1}{2} (\sigma_{11} - \sigma_{22}), R_2 = \frac{1}{2} (\sigma_{22} - \sigma_{33}), R_3 = \frac{1}{2} (\sigma_{11} - \sigma_{33})$$

前一个摩尔圆是后一个摩尔圆向右平移 $\frac{1}{3} \text{tr}\bar{\bar{\sigma}}$ 的结果.

$$(2) (a) \bar{\bar{\sigma}} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix} = \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \sigma_3 \\ \sigma_4 \\ \sigma_5 \\ \sigma_6 \end{bmatrix} = \{ \sigma_i \}$$

$$\bar{\bar{e}} = \begin{bmatrix} e_{11} & e_{12} & e_{13} \\ e_{21} & e_{22} & e_{23} \\ e_{31} & e_{23} & e_{33} \end{bmatrix} = \begin{bmatrix} e_{11} \\ e_{22} \\ e_{33} \\ e_{23} \\ e_{13} \\ e_{12} \end{bmatrix} = \begin{bmatrix} e_1 \\ e_2 \\ e_3 \\ e_4 \\ e_5 \\ e_6 \end{bmatrix} = \{ e_i \}$$

$$(b) C_{ijkl} = C_{ij}. \text{ As } C_{ijkl} = C_{kl}e_i e_j, \text{ so } C_{ij} = C_{jj}.$$

$$(c) \bar{\bar{\sigma}} \cdot \bar{\bar{e}} = e_{ij} \sigma_{ij} = \sigma_{11} e_1.$$

$$3. ① \text{ when } v=0, \lambda = \frac{VE}{(1+v)(1-2v)} = 0, G = \frac{E}{2(1+v)} = \frac{E}{2}, k = \frac{E}{3(1+2v)} = \frac{E}{3}$$

$$② \text{ when } v=0.3, \lambda = 0.58E, G = 0.38E, k = 0.83E$$

$$③ \text{ when } v=0.5, \lambda = \infty, G = \frac{E}{2}, k = \infty$$

$v=0.5$ 对应的情况是：无论用多大的力都无法让该物体产生形变。

$$(4) (a) \bar{\bar{e}} = \frac{1+\nu}{E} \bar{\bar{f}} = \frac{\nu}{E} \text{tr}(\bar{\bar{f}}) \bar{\bar{I}}$$

① simple tension. $\bar{\bar{e}} = \begin{bmatrix} 0.002 & 0 & 0 \\ 0 & -0.007 & 0 \\ 0 & 0 & -0.007 \end{bmatrix}$

② pure shear. $\bar{\bar{e}} = \begin{bmatrix} 0 & 0.0015 & 0 \\ 0.0015 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

③ hydrostatic compression. $\bar{\bar{e}} = \begin{bmatrix} 0.0023 & 0 & 0 \\ 0 & 0.0023 & 0 \\ 0 & 0 & 0.0023 \end{bmatrix}$

(b) ① simple tension. $\bar{\bar{e}} = \begin{bmatrix} 0.0014 & 0 & 0 \\ 0 & -0.0004 & 0 \\ 0 & 0 & -0.0004 \end{bmatrix}$

② pure shear. $\bar{\bar{e}} = \begin{bmatrix} 0 & 0.0009 & 0 \\ 0.0009 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

③ hydrostatic compression. $\bar{\bar{e}} = \begin{bmatrix} -0.001 & 0 & 0 \\ 0 & -0.001 & 0 \\ 0 & 0 & -0.001 \end{bmatrix}$

(c) ① simple tension, $\bar{\bar{e}} = \begin{bmatrix} 7.895 & 0 & 0 \\ 0 & -3.940 & 0 \\ 0 & 0 & -3.940 \end{bmatrix}$

② pure shear, $\bar{\bar{e}} = \begin{bmatrix} 0 & 1.5226 & 0 \\ 1.5226 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

③ hydrostatic compression, $\bar{\bar{e}} = \begin{bmatrix} -0.5263 & 0 & 0 \\ 0 & -0.5263 & 0 \\ 0 & 0 & 0.5263 \end{bmatrix}$

$$(d) \bar{I} = \begin{bmatrix} 20 & 0 & 0 \\ 0 & 30 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \bar{e} = \begin{bmatrix} 5.46 \times 10^{-5} & 0 & 0 \\ 0 & 1.17 \times 10^{-5} & 0 \\ 0 & 0 & -7 \times 10^{-5} \end{bmatrix}$$

$$\text{change in } x\text{-axis: } 5.46 \times 10^{-5} \times 300 = 0.0164 \text{ mm}$$

$$\text{change in } y\text{-axis: } 1.17 \times 10^{-5} \times 200 = 0.00023 \text{ mm}$$

$$\text{change in } z\text{-axis: } -7 \times 10^{-5} \times 4 = -0.00028 \text{ mm}$$

$$(5) \nabla \cdot \bar{\sigma} + \vec{b} = \vec{0}, \text{ as } \vec{b} = 0, \text{ so } \nabla \cdot \bar{\sigma} = \vec{0}$$

$$(a) \nabla \cdot \bar{\sigma} = (\lambda + \mu) \nabla \cdot (\nabla \vec{u}) + \mu \nabla^2 \vec{u} = 0$$

$$\therefore \lambda + \mu > 0, \mu > 0, \text{ so } \nabla \cdot (\nabla \vec{u}) = 0, \nabla^2 \vec{u} = 0$$

$$\because \nabla \cdot \vec{u} = \frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} = e_1 + e_2 + e_3 = t \bar{e}$$

$$\therefore \nabla \cdot t \bar{e} = 0 \quad \therefore \nabla^2 t \bar{e} = 0.$$

$$(b) \because \nabla^2 \vec{u} = 0, \therefore \nabla^2 (\nabla^2 \vec{u}) = 0, \text{ so } \nabla^2 (\nabla^2 \vec{u}_i) = 0.$$

$$b. \nabla^2 \sigma_x + \frac{1}{\mu V} \frac{\partial^2 \sigma_x}{\partial x^2} = -2 \frac{\partial f_x}{\partial x} - \frac{V}{\mu V} \left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z} \right)$$

$$\nabla^2 \sigma_y + \frac{1}{\mu V} \frac{\partial^2 \sigma_y}{\partial y^2} = -2 \frac{\partial f_y}{\partial y} - \frac{V}{\mu V} \left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z} \right)$$

$$\nabla^2 \sigma_z + \frac{1}{\mu V} \frac{\partial^2 \sigma_z}{\partial z^2} = -2 \frac{\partial f_z}{\partial z} - \frac{V}{\mu V} \left(\frac{\partial f_x}{\partial x} + \frac{\partial f_y}{\partial y} + \frac{\partial f_z}{\partial z} \right)$$

$$\nabla^2 \tau_{yz} + \frac{1}{\mu V} \frac{\partial^2 \tau_{yz}}{\partial y \partial z} = - \left(\frac{\partial f_y}{\partial z} + \frac{\partial f_z}{\partial y} \right)$$

$$\nabla^2 \tau_{zx} + \frac{1}{\mu V} \frac{\partial^2 \tau_{zx}}{\partial z \partial x} = - \left(\frac{\partial f_x}{\partial z} + \frac{\partial f_z}{\partial x} \right)$$

$$\nabla^2 \tau_{xy} + \frac{1}{\mu V} \frac{\partial^2 \tau_{xy}}{\partial x \partial y} = - \left(\frac{\partial f_x}{\partial y} + \frac{\partial f_y}{\partial x} \right)$$

$$\sigma = I_1 = \sigma_x + \sigma_y + \sigma_z$$

$$f_x = - \frac{\partial \sigma_x}{\partial x} - \frac{\partial \tau_{xy}}{\partial y} - \frac{\partial \tau_{xz}}{\partial z}$$

$$f_y = - \frac{\partial \sigma_y}{\partial y} - \frac{\partial \tau_{xy}}{\partial x} - \frac{\partial \tau_{yz}}{\partial z}$$

$$f_z = - \frac{\partial \sigma_z}{\partial z} - \frac{\partial \tau_{xz}}{\partial x} - \frac{\partial \tau_{yz}}{\partial y}$$