


南方科技大学
SOUTHERN UNIVERSITY OF SCIENCE AND TECHNOLOGY

MAE5009
Continuum Mechanics B
Session 06: Energy Methods

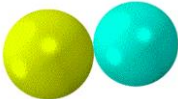
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Strain energy

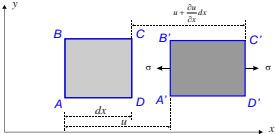
- Strain energy: the energy absorbed in the body due to external work

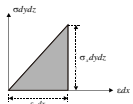


$$dU = \int_{\sigma=0}^{\sigma=\sigma_x} -\sigma dydz \cdot du + \int_{\sigma=0}^{\sigma=\sigma_x} \sigma dydz \cdot d\left(u + \frac{\partial u}{\partial x} dx\right)$$
$$= \int_{\sigma=0}^{\sigma=\sigma_x} \sigma d\left(\frac{\partial u}{\partial x}\right) dx dy dz$$
$$= \int_{\sigma=0}^{\sigma=\sigma_x} \sigma d\epsilon_x dx dy dz = \int_{\sigma=0}^{\sigma=\sigma_x} \sigma \frac{d\sigma}{E} dx dy dz$$
$$= \frac{\sigma_x^2}{2E} dx dy dz$$

Normal strain energy density:

$$U_0 = \frac{\sigma_x^2}{2E} = \frac{1}{2} \sigma_x \epsilon_x = \frac{1}{2} E \epsilon_x^2$$





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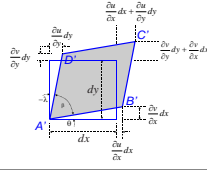
Strain energy

Shear strain energy:

$$dU = \frac{1}{2} \left(\tau_{xy} dydz \right) \left(\frac{\partial v}{\partial x} dx \right) + \frac{1}{2} \left(\tau_{yx} dx dz \right) \left(\frac{\partial u}{\partial y} dy \right)$$
$$= \frac{1}{2} \tau_{xy} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) dx dy dz$$
$$= \frac{1}{2} \tau_{xy} \gamma_{xy} dx dy dz$$

Shear strain energy density:

$$U_0 = \frac{1}{2} \tau_{xy} \gamma_{xy} = \frac{1}{2G} \tau_{xy}^2$$
$$= \frac{1}{2} \tau_{xy} \epsilon_{xy} + \frac{1}{2} \tau_{yx} \epsilon_{yx}$$



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Strain energy

- Strain energy due to σ_x and σ_y :

$$U_0 = \frac{1}{2} \sigma_x \epsilon_x + \frac{1}{2} \sigma_y \epsilon_y$$

- Under a general stress condition:

$$U_0 = \frac{1}{2} (\sigma_x \epsilon_x + \sigma_y \epsilon_y + \sigma_z \epsilon_z + \tau_{xy} \gamma_{xy} + \tau_{yz} \gamma_{yz} + \tau_{zx} \gamma_{zx})$$

In terms of stress components:

$$U_0 = \frac{1}{2} \left(\frac{1}{E} (\sigma_x^2 + \sigma_y^2 + \sigma_z^2) - \frac{2\nu}{E} (\sigma_x \sigma_y + \sigma_x \sigma_z + \sigma_y \sigma_z) + \frac{1}{G} (\tau_{xy}^2 + \tau_{xz}^2 + \tau_{yz}^2) \right)$$

In terms of strain components:

$$U_0 = \frac{1}{2} (\lambda \epsilon^2 + 2G (\epsilon_x^2 + \epsilon_y^2 + \epsilon_z^2) + G (\gamma_{xy}^2 + \gamma_{yz}^2 + \gamma_{zx}^2))$$

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Strain energy

- The derivative of U_0 with respect to any stress component is equal to the corresponding strain component, and the reverse is true:

$$\frac{\partial U_0 (\sigma_x, \sigma_y, \dots, \tau_{xz})}{\partial \sigma_x} = \epsilon_x \quad \frac{\partial U_0 (\epsilon_x, \epsilon_y, \dots, \gamma_{xz})}{\partial \epsilon_x} = \sigma_x$$

- The strain energy density is equal to the half of the dot product between the stress and strain vector:

$$U_0 = \frac{1}{2} (\sigma_x \epsilon_x + \sigma_y \epsilon_y + \sigma_z \epsilon_z + \tau_{xy} \gamma_{xy} + \tau_{yz} \gamma_{yz} + \tau_{zx} \gamma_{zx})$$
$$= \frac{1}{2} \text{vec} \begin{pmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \sigma_y & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_z \end{pmatrix} \cdot \text{vec} \begin{pmatrix} \epsilon_x & \epsilon_{xy} & \epsilon_{xz} \\ \epsilon_{yx} & \epsilon_y & \epsilon_{yz} \\ \epsilon_{zx} & \epsilon_{zy} & \epsilon_z \end{pmatrix}$$

where $\text{vec}()$ is a vectorization function which stacks all the columns of a matrix together and forms a vector

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