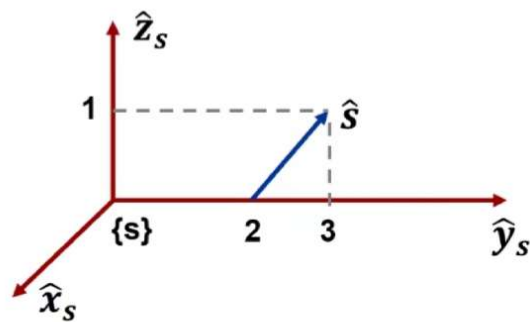


Quiz # 2



$\{b\}$ -frame is initially aligned with $\{s\}$ -frame, i.e. $T_{sb}(0) = I$.

Starting from $t = 0$, $\{b\}$ -frame rotates about \hat{s} with speed $\dot{\theta} = 3$

- 1) Find the screw axis in twist form $S = (\omega, v)$ (expressed in $\{s\}$)
- 2) What is $T_{sb}(t)$? (expression in terms of the screw axis is fine)

Quiz 2:

$$(1) \quad \hat{s} = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad q = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} \quad h=0 \quad \dot{\theta}=3$$

$$\begin{bmatrix} w \\ v \end{bmatrix} = V = S \cdot \dot{\theta} = \begin{bmatrix} \hat{s} \\ h \cdot \hat{s} - \hat{s} \times q \end{bmatrix} \cdot \dot{\theta} = \begin{bmatrix} 0 \\ \frac{3}{\sqrt{2}} \\ \frac{3}{\sqrt{2}} \\ 3\sqrt{2} \\ 0 \\ 0 \end{bmatrix} ; \quad S = \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ \sqrt{2} \\ 0 \\ 0 \end{bmatrix}$$

$$12) \quad T_{sb}(t) = e^{[s] \cdot \dot{\theta} t} \cdot T_{sb}(0) = e^{[V] \cdot t} \cdot T_{sb}(0)$$

$$\text{where } [s] = \begin{bmatrix} [w] & v \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \sqrt{2} \\ \frac{1}{\sqrt{2}} & 0 & 0 & 0 \\ -\frac{1}{\sqrt{2}} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$T_{sb}(0) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$27) \quad T_{sb}(t) = e^{[s] \cdot 3t} \cdot T_{sb}(0)$$