

# Continuum Mechanics (B)

## Session 01: Stress analysis

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## Body and Surface Forces, Stress

When a body is subjected to external loads (加载)

- induced internal deformation
- induced internal forces

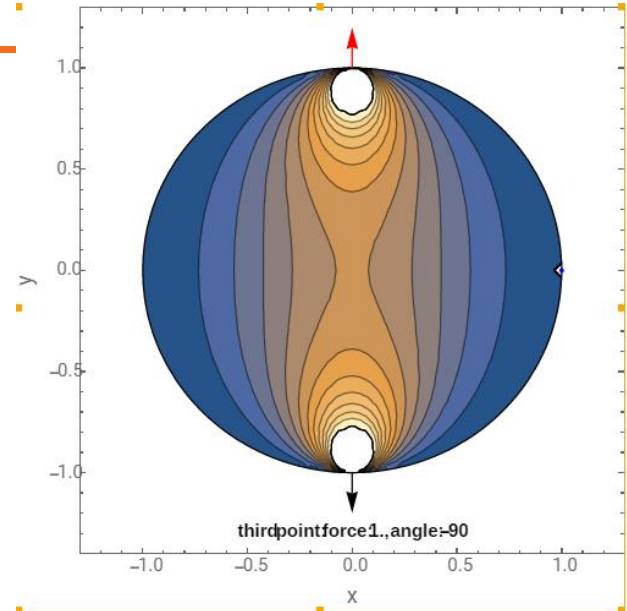
### External forces (loads):

- **Body force  $F$ :** associated with body mass
  - gravitational, magnetic and inertia forces
  - distributed through the whole volume of the body
  - unit:  $N/m^3$ 
    - force per unit volume
- **Surface forces:** induced by physical contact
  - red and black arrows in the right figure

**Internal force** is forces across an imaginary plane inside a body.

Internal force must be surface forces.

Point out the external forces applied to the honey.



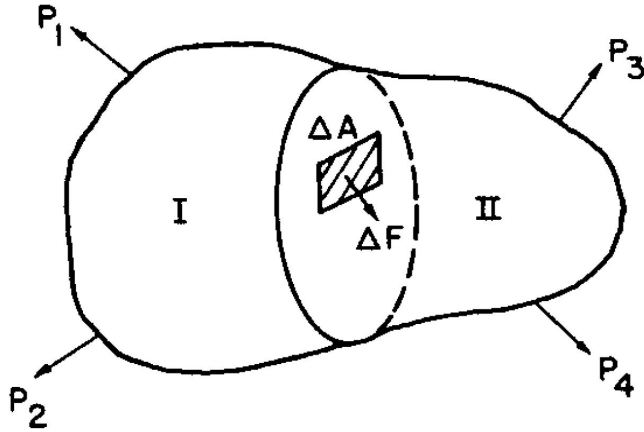
stress ( $\tau_{\max}$ ) distribution in a circular plate with concentrated loadings

(<https://demonstrations.wolfram.com/StressDistributionInACircularPlateWithConcentratedRadialLoad/>)

## Body and Surface Forces, Stress

Free body (隔离体): A body that is singled out from other bodies for the purposes of dynamic or static analysis, usually associated with free body diagram (受力分析图).

Consider a body subjected to external forces  $P_1$ - $P_4$ .

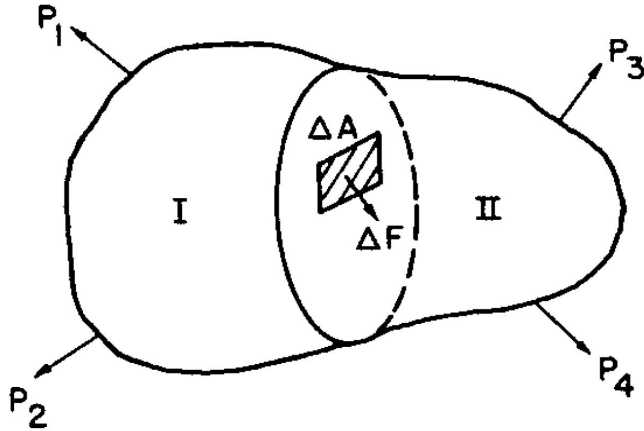


Consider the force applied by part II to **free body** (隔离体) part I through an imaginary plane  $\Delta A$  is  $\Delta F$

- $\Delta F$  is induced by external forces
- $\Delta F$  is surface force
- $\Delta F$  is external force to part I but is actually internal force for the whole body.

## Body and Surface Forces, Stress

Consider a body subjected to external forces P1-P4.



Free body (隔离体): A body that is singled out from other bodies for the purposes of dynamic or static analysis, usually associated with free body diagram (受力分析图).

The **stress** at a point is defined as the limitation of force/area

$$\mathbf{p} = \lim_{\Delta A \rightarrow 0} \frac{\Delta \mathbf{F}}{\Delta A} = \frac{d\mathbf{F}}{dA}$$

The stress  $\mathbf{p}$  on the plane  $\Delta A$  is a vector (**stress vector**) and  $\mathbf{p}$  is parallel to  $\Delta \mathbf{F}$

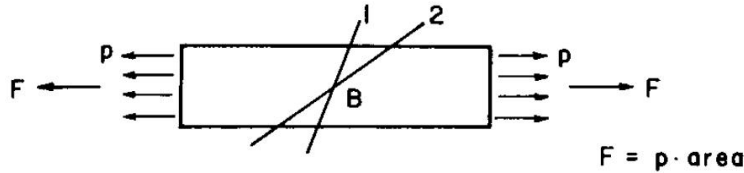
Q: Is the stress vector  $\mathbf{p}$  in the direction normal to the surface  $\Delta A$ ?

To fully determine stress vector on a point, we need to know:

- Magnitude, Orientation
- the plane on which stress acts

## Body and Surface Forces, Stress

Consider the internal forces at point B due to external force  $\mathbf{F}$



The stress vector at point B differs for plane 1 ( $\mathbf{p}_1$ ) and plane 2 ( $\mathbf{p}_2$ ), **why?**

The stress vector varies for each plane across point B.

The **stress state** at a point: the set of stress vector acting on the infinitesimal area elements surrounding the point in all possible directions.

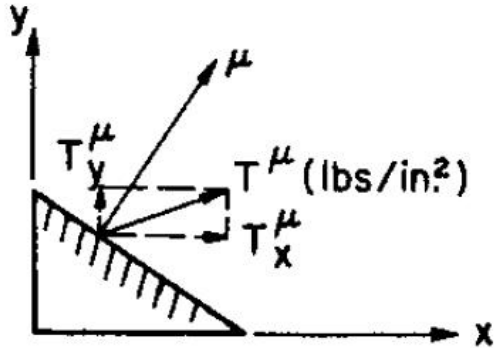
Stress state at point B is a 2nd-order tensor:

- Stress vector on any plane through a given point can be determined if we know the stress on any two planes passing through the point (in two-dimensional case).
- Check the direction for stress vectors  $\mathbf{p}_1$  and  $\mathbf{p}_2$
- Compare the magnitude of the stress vectors  $\mathbf{p}_1$ ,  $\mathbf{p}_2$ , and  $\mathbf{p}$

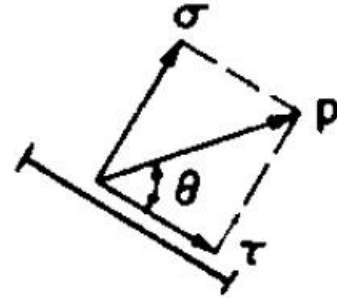
## Body and Surface Forces, Stress

We can designate (表示) the stress vector in two ways in a coordinate

- the  $x$ ,  $y$ , and  $z$  components
- the normal and tangential (shearing) components



The stress  $T^\mu$  is expressed in the  $x$ , and  $y$  components, outward normal of the plane  $\mu$  defines the plane

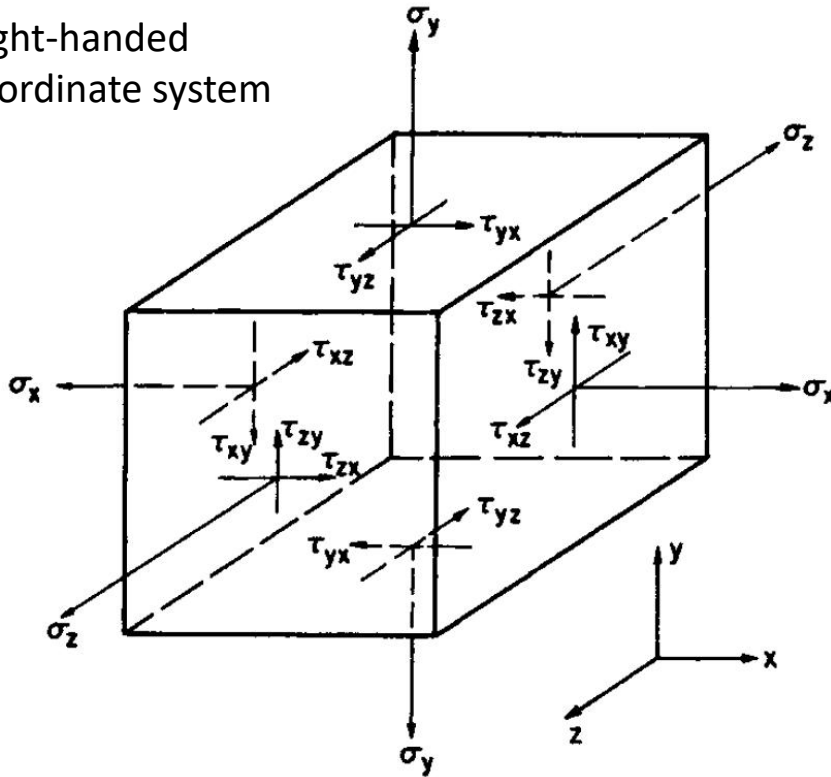


The internal stress  $p$  is expressed in normal ( $\sigma$ ) and shear ( $\tau$ ) components.

- **Normal stress:** the component of stress perpendicular to the plane on which it acts.
- **shear stress:** the component of stress which lies in the plane.

# Body and Surface Forces, Stress

Right-handed  
coordinate system



Three-Dimensional State of Stress at an element

Let's give some conventions in this book:

A plane is designated by the direction of its outward normal

The right-hand face of the element in the left figure is called the x plane; the left-hand face the negative x plane.

**Sign conventions in this course:**

on positive surfaces: stress acting in positive coordinate directions are positive  
on negative surfaces: stress acting in negative coordinate directions are positive.

shear stress:

$$\tau_{xy}, \tau_{xz}, \tau_{yx}, \tau_{yz}, \tau_{zx}, \tau_{zy}$$

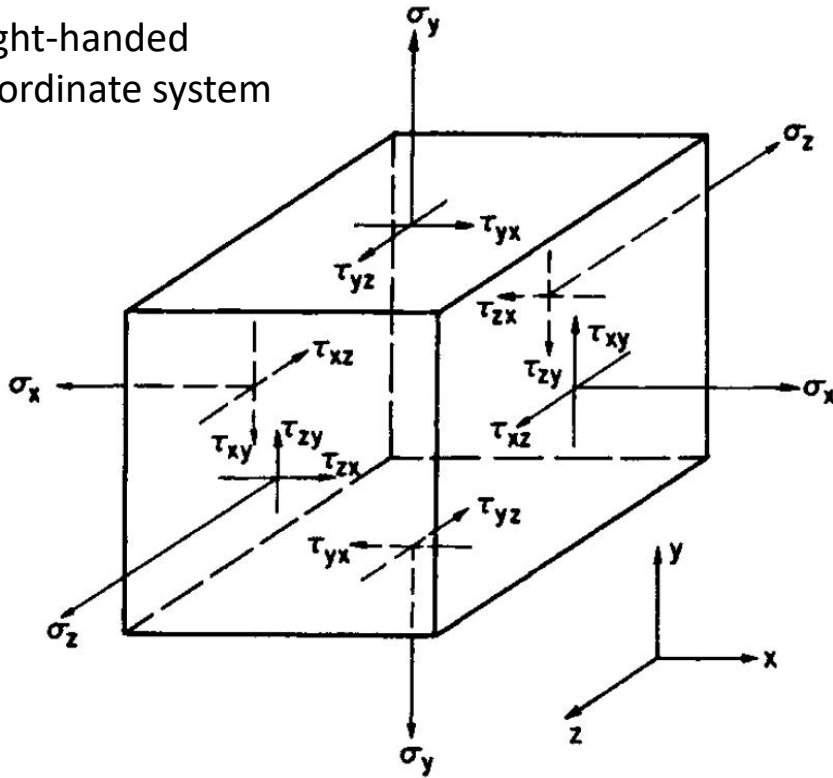
normal stress:

$$\sigma_{xx} (\sigma_x), \sigma_{yy} (\sigma_y), \sigma_{zz} (\sigma_z)$$



# Body and Surface Forces, Stress

Right-handed  
coordinate system



Three-Dimensional State of Stress at an element

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A plane is designated by the direction of its outward normal

The right-hand face of the element in the left figure is called the  $x$  plane; the left-hand face the negative  $x$  plane.

## Sign conventions in this course:

on positive surfaces: stress acting in positive coordinate directions are positive  
on negative surfaces: stress acting in negative coordinate directions are positive.

- Extension stress is positive and compression negative
- Opposite directions for shear stress on positive and negative planes.

# Review

- External vs internal force; Body force vs surface force
- **stress vector** at a point
  - Force per unit area at a single point ( $\text{Pa} = \text{N/m}^2$ )
  - magnitude, direction, **on which plane the stress vector acts on**
- Stress state at a point
  - stress vectors for all the planes through the point
- Right-handed coordinate systems, sign conventions
- decomposition of the stress vector  **$p$** 
  - normal stress  $\sigma$  and shear stresses  $\tau$
  - along x, y, z axes ( $p_x, p_y$ )
  - meaning of  $\tau_{xy}, \tau_{yz}, \sigma_x$

