

## MAE5009: Continuum Mechanics B

### Assignment 04: Formulation of Problems in Elasticity

**Due November 9, 2020**

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1. Verify the following equations for plane strain problems with constant  $f_x$  and  $f_y$ :

$$(a) \quad \frac{\partial}{\partial y} \nabla^2 u = \frac{\partial}{\partial x} \nabla^2 v$$

**Solution:**

According to the displacement formation of the solution of plane strain problems, we can know:

$$\begin{aligned} G \nabla^2 u + (\lambda + G) \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + f_x &= 0 \\ G \nabla^2 v + (\lambda + G) \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + f_y &= 0 \end{aligned}$$

Then:

$$\begin{aligned} G \frac{\partial}{\partial y} \nabla^2 u &= -(\lambda + G) \frac{\partial^2}{\partial x \partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \\ G \frac{\partial}{\partial x} \nabla^2 v &= -(\lambda + G) \frac{\partial^2}{\partial x \partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \end{aligned}$$

Thus:

$$\frac{\partial}{\partial y} \nabla^2 u = \frac{\partial}{\partial x} \nabla^2 v = -\frac{(\lambda + G)}{G} \frac{\partial^2}{\partial x \partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$$

$$(b) \quad \frac{\partial}{\partial x} \nabla^2 u + \frac{\partial}{\partial y} \nabla^2 v = 0$$

**Solution:**

According to (a),

$$\begin{aligned} \nabla^2 u &= -\frac{(\lambda + G)}{G} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - \frac{f_x}{G} \\ \nabla^2 v &= -\frac{(\lambda + G)}{G} \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - \frac{f_y}{G} \end{aligned}$$

Then:

$$\begin{aligned} \frac{\partial}{\partial x} \nabla^2 u &= -\frac{(\lambda + G)}{G} \frac{\partial^2}{\partial x^2} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \\ \frac{\partial}{\partial y} \nabla^2 v &= -\frac{(\lambda + G)}{G} \frac{\partial^2}{\partial y^2} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \end{aligned}$$

And:

$$\frac{\partial}{\partial x} \nabla^2 u + \frac{\partial}{\partial y} \nabla^2 v = -\frac{(\lambda + G)}{G} \left( \frac{\partial}{\partial x} \nabla^2 u + \frac{\partial}{\partial y} \nabla^2 v \right)$$

$$\frac{(\lambda + 2G)}{G} \left( \frac{\partial}{\partial x} \nabla^2 u + \frac{\partial}{\partial y} \nabla^2 v \right) = 0$$

Since  $\frac{(\lambda+2G)}{G}$  is not zero, we can prove

$$\frac{\partial}{\partial x} \nabla^2 u + \frac{\partial}{\partial y} \nabla^2 v = 0$$

(c)  $\nabla^4 u = \nabla^4 v = 0$ , where  $\nabla^4 = \nabla^2(\nabla^2)$ .

**Solution:**

$$\nabla^4 u = \nabla^2(\nabla^2 u) = \frac{\partial^2}{\partial x^2} \nabla^2 u + \frac{\partial^2}{\partial y^2} \nabla^2 u$$

$$\nabla^4 v = \nabla^2(\nabla^2 v) = \frac{\partial^2}{\partial x^2} \nabla^2 v + \frac{\partial^2}{\partial y^2} \nabla^2 v$$

According to (a),  $\frac{\partial}{\partial y} \nabla^2 u = \frac{\partial}{\partial x} \nabla^2 v$ , then  $\frac{\partial^2}{\partial y^2} \nabla^2 u = \frac{\partial^2}{\partial x \partial y} \nabla^2 v$ ,  $\frac{\partial^2}{\partial x^2} \nabla^2 v = \frac{\partial^2}{\partial x \partial y} \nabla^2 u$ .

According to (b),  $\frac{\partial}{\partial x} \nabla^2 u = -\frac{\partial}{\partial y} \nabla^2 v$ , then  $\frac{\partial^2}{\partial x^2} \nabla^2 u = -\frac{\partial^2}{\partial x \partial y} \nabla^2 v$ ,  $\frac{\partial^2}{\partial y^2} \nabla^2 v = -\frac{\partial^2}{\partial x \partial y} \nabla^2 u$ .

Thus,

$$\begin{aligned} \nabla^4 u &= \nabla^2(\nabla^2 u) = \frac{\partial^2}{\partial x^2} \nabla^2 u + \frac{\partial^2}{\partial y^2} \nabla^2 u = -\frac{\partial^2}{\partial x \partial y} \nabla^2 v + \frac{\partial^2}{\partial x \partial y} \nabla^2 v = 0 \\ \nabla^4 v &= \nabla^2(\nabla^2 v) = \frac{\partial^2}{\partial x^2} \nabla^2 v + \frac{\partial^2}{\partial y^2} \nabla^2 v = \frac{\partial^2}{\partial x \partial y} \nabla^2 u - \frac{\partial^2}{\partial x \partial y} \nabla^2 u = 0 \\ \nabla^4 u &= \nabla^4 v = 0 \end{aligned}$$

2. A bar of constant mass density  $\rho$  hangs under its own weight and is supported by the uniform stress  $\sigma_0$  as shown in the figure. Assume that the stresses  $\sigma_x$ ,  $\sigma_y$ ,  $\tau_{xy}$ ,  $\tau_{xz}$  and  $\tau_{yz}$  are all zero,

(a) based on the above assumption, reduce 15 governing equations to seven equations in terms of  $\sigma_z$ ,  $\varepsilon_x$ ,  $\varepsilon_y$ ,  $\varepsilon_z$ ,  $u$ ,  $v$  and  $w$ .

**Solution:**

For the stress-strain relations:

$$\sigma_x = 2G\varepsilon_x + \lambda(\varepsilon_x + \varepsilon_y + \varepsilon_z) = 0$$

$$\sigma_y = 2G\varepsilon_y + \lambda(\varepsilon_x + \varepsilon_y + \varepsilon_z) = 0$$

$$\sigma_z = 2G\varepsilon_z + \lambda(\varepsilon_x + \varepsilon_y + \varepsilon_z) = E\varepsilon_z$$

We can get  $\varepsilon_x = \varepsilon_y = -\nu\varepsilon_z$ ,  $\gamma_{xy} = \gamma_{xz} = \gamma_{yz} = 0$ .

According to the equilibrium equations:

$$\begin{aligned} f_x &= f_y = 0 \\ \frac{\partial \sigma_z}{\partial z} + f_z &= 0 \end{aligned}$$

For the strain-displacement relations:

$$\varepsilon_x = \varepsilon_y = -\nu \varepsilon_z = \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} = -\nu \frac{\partial w}{\partial z}$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0, \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} = 0 \text{ and } \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} = 0.$$

(b) integrate the equilibrium equation to show that  $\sigma_z = \rho g z$  where  $g$  is the acceleration due to gravity. Also show that the prescribed boundary conditions are satisfied by this solution

**Solution:**

Let the cross-section area be  $A$ , the force equilibrium for any  $z$  should be satisfied.

$$\sigma_z A - mg = 0$$

Then  $mg = \rho g V = \rho g Az$  and  $\sigma_z A - \rho g Az = 0$ , we can prove:

$$\sigma_z = \rho g z$$

When  $z = l$ ,  $\sigma_z = \rho g l = \sigma_0$ . When  $z = 0$ ,  $\sigma_z = 0$ .

(c) find  $\varepsilon_x$ ,  $\varepsilon_y$ ,  $\varepsilon_z$  from the generalized Hooke's law

**Solution:**

$$\sigma_x = 2G\varepsilon_x + \lambda(\varepsilon_x + \varepsilon_y + \varepsilon_z) = 0$$

$$\sigma_y = 2G\varepsilon_y + \lambda(\varepsilon_x + \varepsilon_y + \varepsilon_z) = 0$$

We can get  $\varepsilon_x = \varepsilon_y = -\nu \varepsilon_z$ , then

$$\sigma_z = 2G\varepsilon_z + \lambda(\varepsilon_x + \varepsilon_y + \varepsilon_z) = E\varepsilon_z$$

$$\text{So } \varepsilon_z = \frac{\rho g z}{E}, \varepsilon_x = \varepsilon_y = -\nu \varepsilon_z = -\nu \frac{\rho g z}{E}.$$

(d) if the displacement and rotation components are zero at the point  $(0,0,l)$ , determine the displacement component  $u$  and  $v$

**Solution:**

According to (a) (b) and (c),  $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} = -\frac{\nu \rho g z}{E}$ ,  $\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0$ , then we can make assumptions that

$$u = -\frac{\nu \rho g z}{E} x + C_1(y, z), v = -\frac{\nu \rho g z}{E} y + C_2(x, z), w = \frac{\rho g}{2E} z^2 + C_3(x, y)$$

Since the displacement and rotation components are zero at point  $(0,0,l)$ , we can get

$$C_1(y, z)|_{(0,l)} = 0, C_2(x, z)|_{(0,l)} = 0, C_3(x, y)|_{(0,0)} = -\frac{\rho g}{2E} l^2$$

$$\frac{\partial u}{\partial y} = \frac{\partial C_1(y, z)}{\partial y}|_{(0,l)} = 0, \frac{\partial v}{\partial x} = \frac{\partial C_2(x, z)}{\partial x}|_{(0,l)} = 0$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = \frac{\partial C_1(y, z)}{\partial y} + \frac{\partial C_2(x, z)}{\partial x} = 0$$

According to  $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$  and  $\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0$ , we know that

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 v}{\partial x \partial y}, \frac{\partial^2 u}{\partial y^2} = -\frac{\partial^2 v}{\partial x \partial y}$$

Because  $\frac{\partial^2 u}{\partial x^2} = 0$ , then  $\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 C_1(y,z)}{\partial y^2} = -\frac{\partial^2 u}{\partial x^2} = 0$ . The  $\frac{\partial C_1(y,z)}{\partial y}$  is not a function of

y. With the same way,  $\frac{\partial C_2(x,z)}{\partial x}$  is not a function of x.

Since  $\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = 0$ , then  $\frac{\partial C_1(y,z)}{\partial y} = -\frac{\partial C_2(x,z)}{\partial x} = f_1(z)$

$$\frac{\partial C_1(y,z)}{\partial y} \Big|_{(0,l)} = 0$$

$$f_1(z) \Big|_{z=l} = 0$$

Then  $C_1(y,z) = f_1(z)y, C_2(x,z) = -f_1(z)x$

$$u = -\frac{\nu \rho g}{E} xz + f_1(z)y, v = -\frac{\nu \rho g}{E} yz - f_1(z)x$$

With the same way about  $u$  and  $w$ ,  $\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial z^2} = \frac{\partial^2 f_1(z)}{\partial z^2} y = 0$

Then  $\frac{\partial^2 f_1(z)}{\partial z^2} = 0$  and  $\frac{\partial f_1(z)}{\partial z} = A_1$ , where  $A_1$  is a constant.

So  $f_1(z) = A_1 z - A_1 l$  for the boundary condition that  $f_1(z) \Big|_{z=l} = 0$

Since:

$$\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} = \left(-\frac{\nu \rho g}{E} x + A_1 y\right) + \frac{\partial C_3(x,y)}{\partial x} = 0, C_3(x,y) = \frac{\nu \rho g}{2E} x^2 - A_1 xy + f_2(y)$$

$$\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} = \left(-\frac{\nu \rho g}{E} y - A_1 x\right) + \frac{\partial C_3(x,y)}{\partial y} = 0, C_3(x,y) = \frac{\nu \rho g}{2E} y^2 + A_1 xy + f_3(x)$$

The boundary condition  $C_3(x,y) \Big|_{(0,0)} = -\frac{\rho g}{2E} l^2$

Then  $A_1 = 0, f_1(z) = 0, f_2(y) = \frac{\nu \rho g}{2E} y^2 - \frac{\rho g}{2E} l^2, f_3(x) = \frac{\nu \rho g}{2E} x^2 - \frac{\rho g}{2E} l^2$

$$C_3(x,y) = \frac{\nu \rho g}{2E} x^2 + \frac{\nu \rho g}{2E} y^2 - \frac{\rho g}{2E} l^2$$

$$u = -\frac{\nu \rho g}{E} xz, v = -\frac{\nu \rho g}{E} yz$$

(e) prove that  $w = \frac{\rho g}{2E} (z^2 + \nu x^2 + \nu y^2 - l^2)$

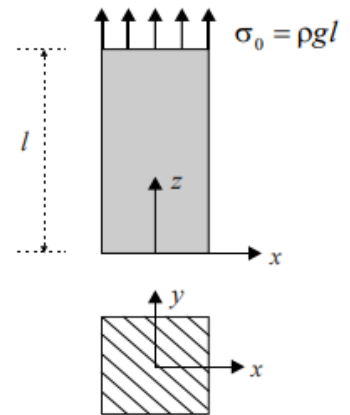
**Solution:**

According to (d),

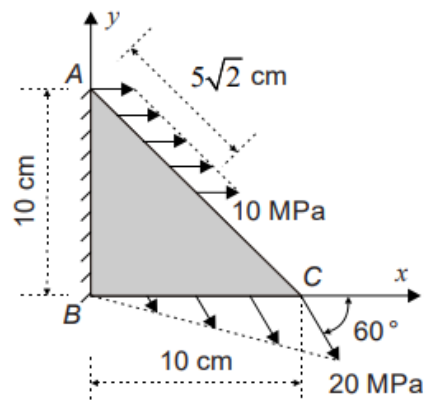
$$C_3(x,y) = \frac{\nu \rho g}{2E} x^2 + \frac{\nu \rho g}{2E} y^2 - \frac{\rho g}{2E} l^2$$

Then

$$w = \frac{\rho g}{2E} z^2 + C_3(x,y) = \frac{\rho g}{2E} z^2 + \frac{\nu \rho g}{2E} x^2 + \frac{\nu \rho g}{2E} y^2 - \frac{\rho g}{2E} l^2 = \frac{\rho g}{2E} (z^2 + \nu x^2 + \nu y^2 - l^2)$$



3. Express the boundary conditions for the following plate subjected to plate strain condition. The surface forces are functions of  $x$  and  $y$  only.



**Solution:**

Surface  $f(x, y)$ , for plane strain problem  $\varepsilon_z = \gamma_{xz} = \gamma_{yz} = 0$

The boundary conditions:

$$\varepsilon_x = \varepsilon_y = 0, \quad x = 0$$

AB :

$$\begin{cases} \sigma_x = 2x \cos(60^\circ), y = 0, 0 \leq x \leq 10 \\ \sigma_y = -2x \sin(60^\circ), y = 0, 0 \leq x \leq 10 \\ \sigma_x = 10 \text{ MPa}, 0 \leq x \leq 5, y = 10 - x \\ \sigma_y = 0 \text{ MPa}, 0 \leq x \leq 5, y = 10 - x \\ \sigma_x = 0 \text{ MPa}, 5 < x < 10, y = 10 - x \\ \sigma_y = 0 \text{ MPa}, 5 \leq x < 10, y = 10 - x \end{cases}$$