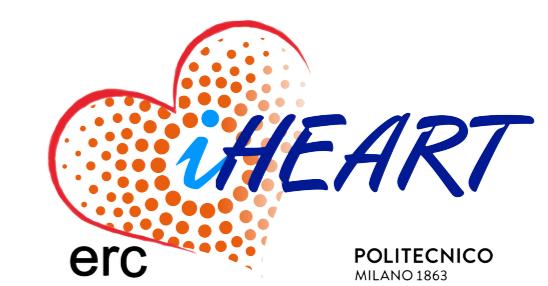


# Deep learning-based reduced order models for real-time approximation of nonlinear time-dependent parametrized PDEs

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## Abstract

Conventional linear reduced order modeling techniques, such as, e.g., the reduced basis method, may incur in severe limitations when dealing with nonlinear time-dependent parametrized PDEs, featuring coherent structures that propagate over time such as transport, wave, or convection-dominated phenomena. In this work, we propose a new, nonlinear approach relying on deep learning (DL) algorithms to obtain accurate and efficient reduced order models (ROMs), whose dimensionality matches the number of system parameters.

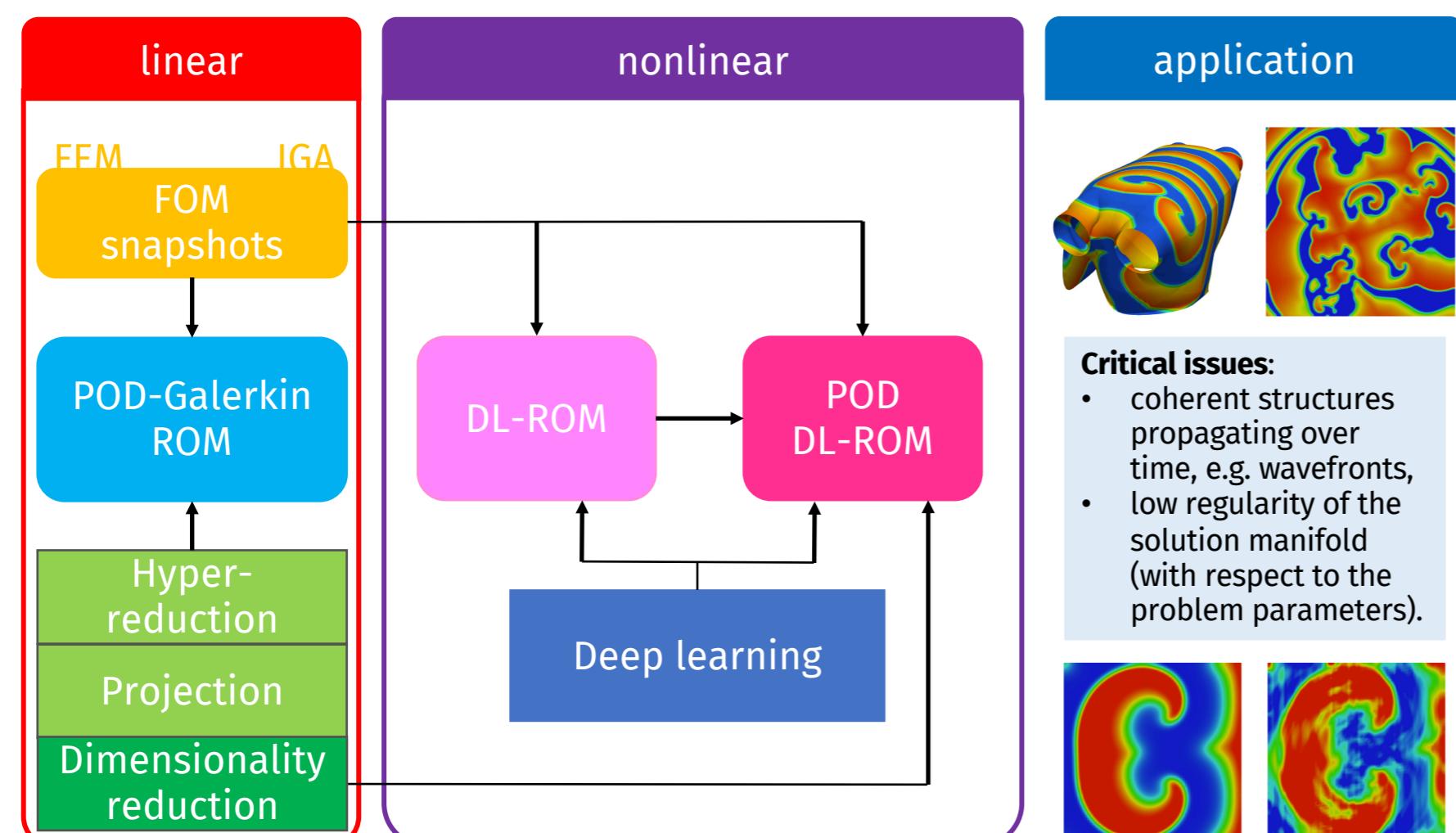
## Introduction

Given  $\mu \in \mathcal{P}$ , we aim at solving the initial value problem

$$\begin{cases} \dot{\mathbf{u}}_h(t; \mu) = \mathbf{f}(t, \mathbf{u}_h(t; \mu); \mu) & t \in (0, T), \\ \mathbf{u}_h(0; \mu) = \mathbf{u}_0(\mu), \end{cases} \quad (1)$$

where  $\mathcal{P} \subset \mathbb{R}^{n_\mu}$  is a bounded and closed set.

**Reduced order modeling** aims at replacing the FOM (1) by a model showing a much lower complexity but still able to express the physical features of the problem at hand.



## Deep learning-based reduced order models

The POD-DL-ROM approximation  $\tilde{\mathbf{u}}_h(t; \mu, \theta_{DF}, \theta_D)$  of the FOM solution  $\mathbf{u}_h(t; \mu)$  is given by

$$\tilde{\mathbf{u}}_h(t; \mu, \theta_{DF}, \theta_D) = \mathbf{V}\tilde{\mathbf{u}}_N(t; \mu, \theta_{DF}, \theta_D),$$

where  $\tilde{\mathbf{u}}_N(t; \mu, \theta_{DF}, \theta_D) = \mathbf{f}_N^D(\phi_n^{DF}(t; \mu, \theta_{DF}); \theta_D)$ .

- To describe the reduced dynamics on the nonlinear trial manifold  $\tilde{\mathcal{S}}_N^n$ , the intrinsic coordinates of the approximation  $\tilde{\mathbf{u}}_N$  are defined as

$$\mathbf{u}_n(t; \mu) = \phi_n^{DF}(t; \mu, \theta_{DF}),$$

where  $\phi_n(\cdot, \cdot, \theta_{DF}) : [0, T] \times \mathbb{R}^{n_\mu+1} \rightarrow \mathbb{R}^n$  is a *deep feedforward neural network*;

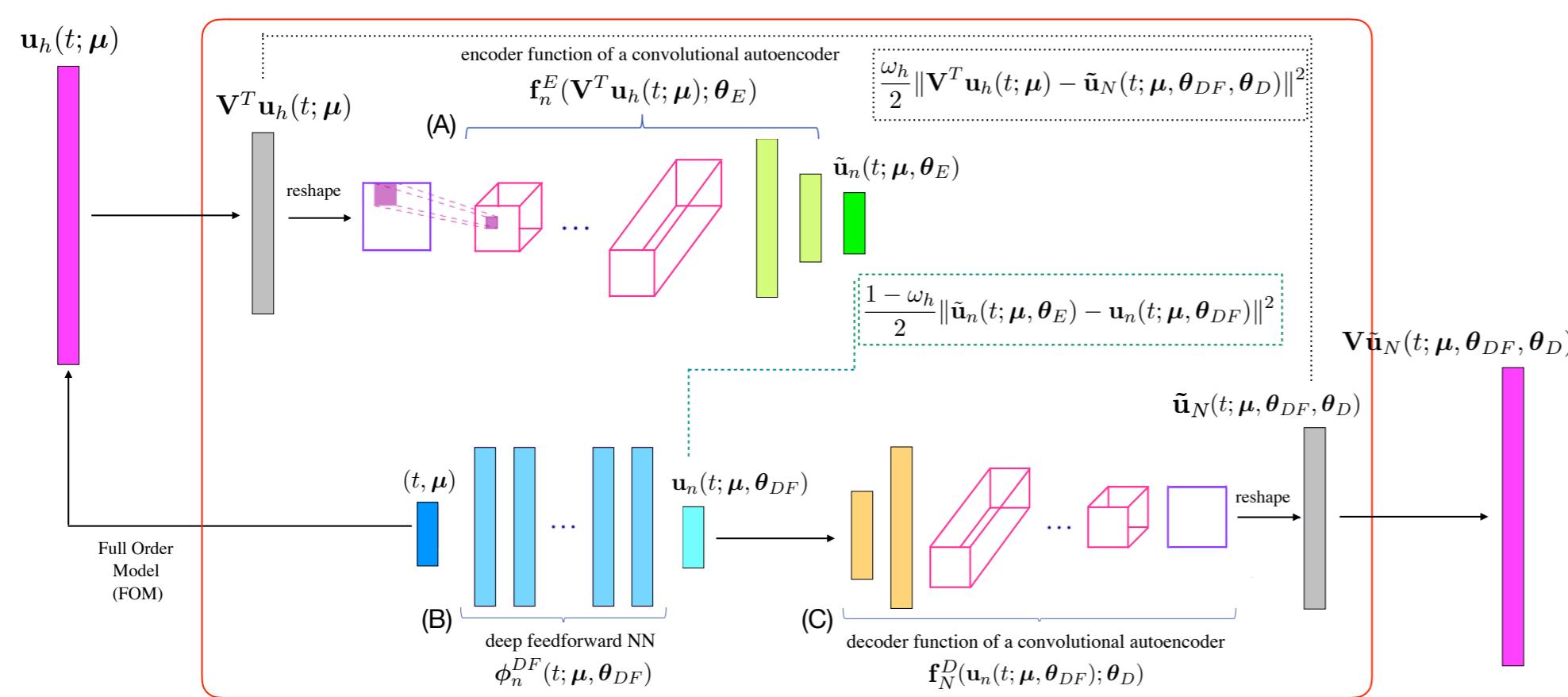
- to model the reduced nonlinear trial manifold  $\tilde{\mathcal{S}}_N^n$ , we employ the decoder function of a *convolutional autoencoder*, that is,

$$\tilde{\mathcal{S}}_N^n = \{\mathbf{f}_N^D(\phi_n^{DF}(t; \mu, \theta_{DF}); \theta_D) \mid \mathbf{u}_n(t; \mu, \theta_{DF}) \in \mathbb{R}^n, t \in [0, T], \mu \in \mathcal{P} \subset \mathbb{R}^{n_\mu}\},$$

where  $\mathbf{f}_N^D(\cdot; \theta_D) : \mathbb{R}^n \rightarrow \mathbb{R}^N$ .

Computing the ROM approximation consists in solving an optimization problem (in the variable  $\theta$ ) where the **per-example loss function** is given by

$$\mathcal{L}(t^k, \mu_i; \theta) = \frac{\omega_h}{2} \|\mathbf{V}^T \mathbf{u}_h(t^k; \mu_i) - \tilde{\mathbf{u}}_N(t^k; \mu_i, \theta_{DF}, \theta_D)\|^2 + \frac{1 - \omega_h}{2} \|\tilde{\mathbf{u}}_N(t^k; \mu_i, \theta_E) - \mathbf{u}_n(t^k; \mu_i, \theta_{DF})\|^2$$

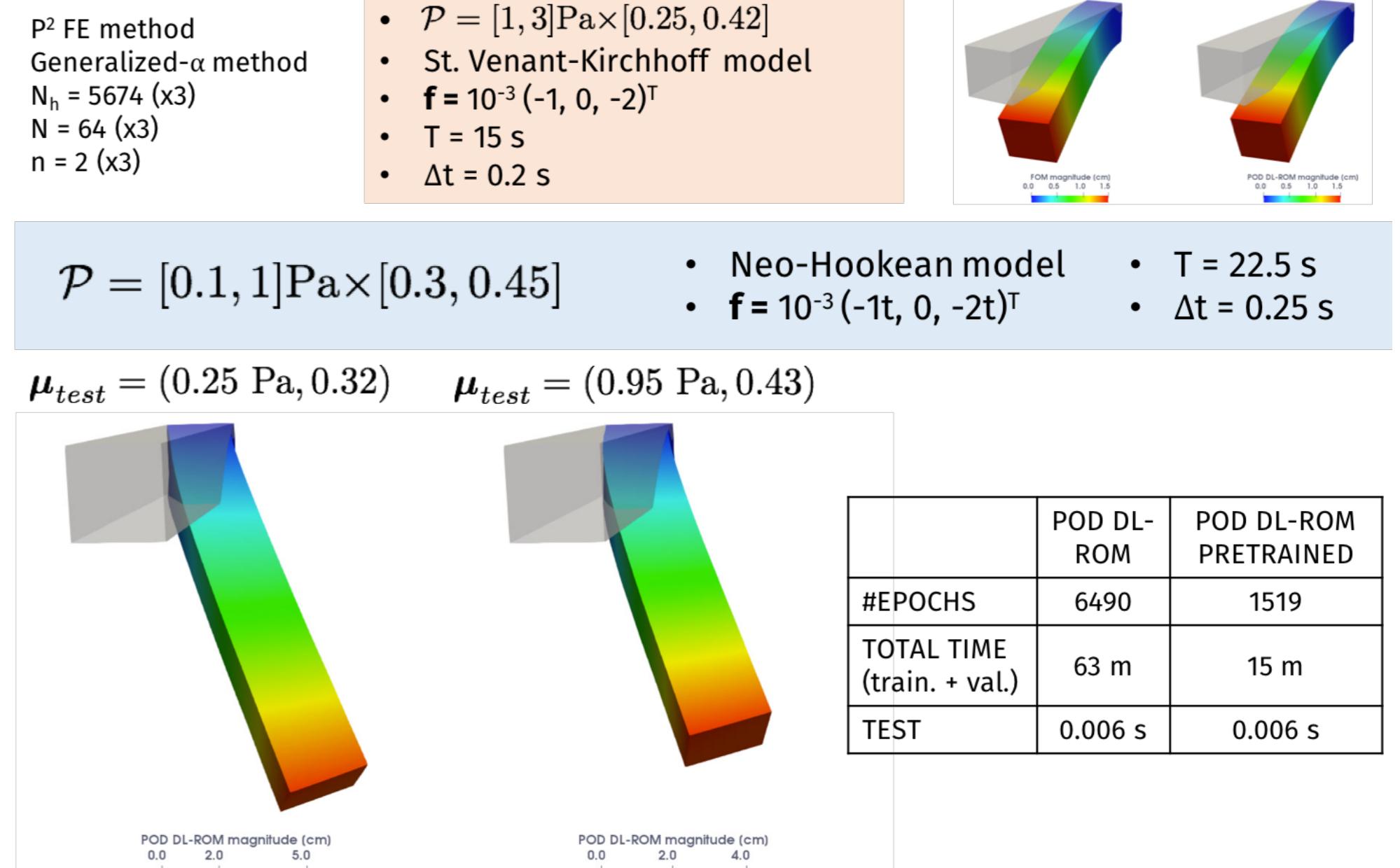


## Main features:

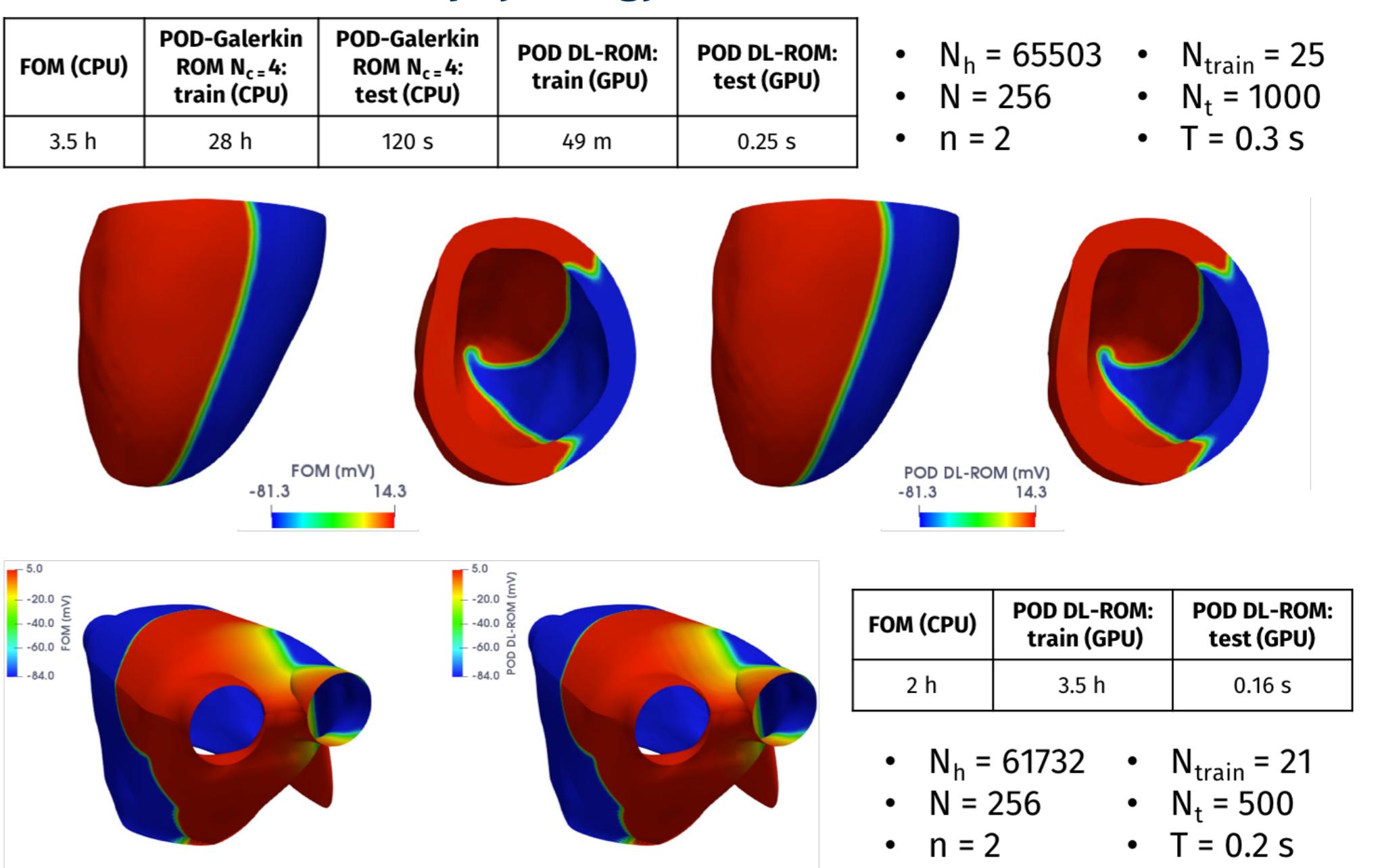
- POD-DL-ROMs learn, simultaneously, the **nonlinear trial manifold** and the **nonlinear reduced dynamics**;
- the POD-DL-ROM dimension is as close as possible to the **number of parameters** which the PDE solution depends upon;
- a prior dimensionality reduction, performed by means of **randomized POD**, and **pretraining** allow to drastically reduce training computational times.

## Numerical results

### Test 1: pretraining on 3D elastodynamics equations



### Test 2: cardiac electrophysiology on left ventricle and atrium



## References

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- <https://github.com/stefaniafresca/DL-ROM>

## Acknowledgements

With the support of the EU ERC-ADG - Advanced Grant iHEART Project ID: 740132.

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