EECS 351 Project A Report

Goal

Design and draw two different 3D parts which have two or more sequential, moving joints.

User-guide

Open the html file, there are one sequential rectangles, which models the posture of swimming, and a planet system, where three small balls spin around a big ball.

- 1. Press buttons on the web page to change the rotating speed or make the graphic stop.
- 2. Use mouse to drag the graphic to observe graphic with different view.
- 3. Stop the graphic quickly through press "Space" on the keyboard.

Result

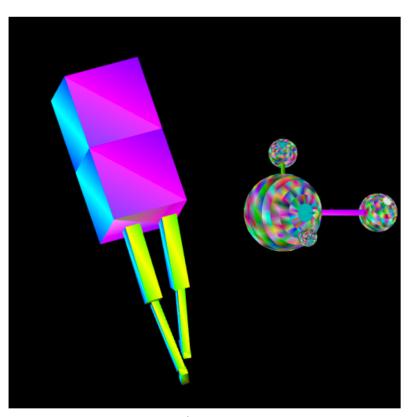


Figure 1

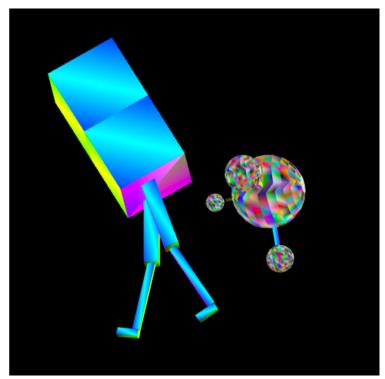


Figure 2

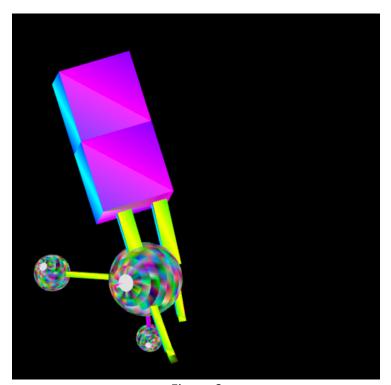


Figure 3

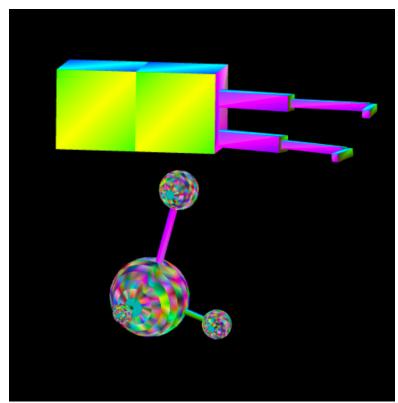


Figure 4

Sketch of program's scene-graph

```
modelMatrix.scale(1,1,-1);
// modelMatrix.rotate(15, 0, 1, 0);
// modelMatrix.rotate(-15, 1, 0, 0);
var dist = Math.sqrt(xMdragTot*xMdragTot + yMdragTot*yMdragTot);
// why add 0.001? avoids divide-by-zero in next statement
// in cases where user didn't drag the mouse.)
modelMatrix.rotate(dist*120.0, -yMdragTot+0.0001, xMdragTot+0.0001, 0.0);
modelMatrix.rotate(Angle_sphere, 0, 1, 0);
modelMatrix.scale(0.3, 0.015, 0.015);
modelMatrix.translate(0.8, 0, 0);
modelMatrix.rotate(0, 0, 0, 1); // Spin on XY diagonal axis
modelMatrix.translate(-1, -1, -1);
gl.uniformMatrix4fv(u_ModelMatrix, false, modelMatrix.elements);
gl.drawArrays(gl.TRIANGLES, recStart,36);
modelMatrix.scale(1,1,-1);
// modelMatrix.rotate(15, 0, 0, 1);
// modelMatrix.rotate(15, 0, 1, 0);
// modelMatrix.rotate(-15, 1, 0, 0);
var dist = Math.sqrt(xMdragTot*xMdragTot + yMdragTot*yMdragTot);
// // why add 0.001? avoids divide-by-zero in next statement
// in cases where user didn't drag the mouse.)
modelMatrix.rotate(dist*120.0, -yMdragTot+0.0001, xMdragTot+0.0001, 0.0);
modelMatrix.rotate(Angle_sphere - 90, -1, 0, 0);
```

Figure 5