

CS 291A: Deep Learning for NLP

Neural Networks: Recurrent Neural Networks

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Slides adapted from Y. V. Chen.

Project Proposals

1. I should have given you either oral feedback or written feedback.
2. If not, please come to my office hour today after the class.

Questions about Google Cloud Credits

1. If you are requesting Google Cloud Credits, please email our reader Ke Ni ke00@ucsb.edu.
2. Not a hard requirement. You don't have to use Google Cloud. For example, AWS also offers student credits, and you can register yourself.
3. But you are strongly encouraged to use GPU instead of CPU for your projects.

Homework 1

Due date: a week from now.

Homework assignments must be done independently, not in a team.

Note that CodaLab uses UTC, so please refer to the handout for PT.

Two models to implement:

- Word2Vec (SkipGram)
- Glove

Use your UCSB umail address to register CodaLab:

Or we could not locate your submission.

The scoreboard is anonymous, and you can use your teamname as your nickname.

Don't be afraid of tensors

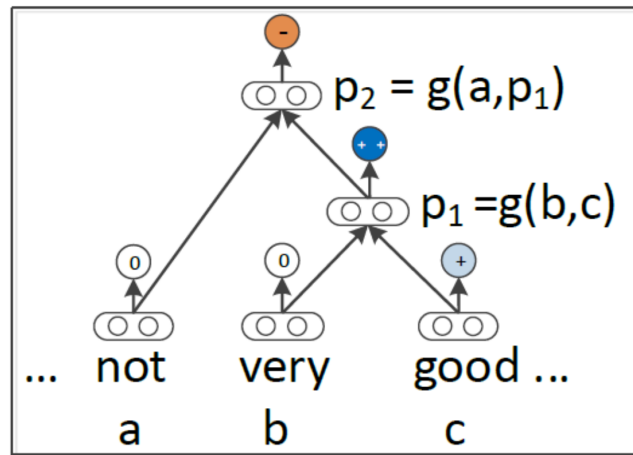
- It's just a generalization of vector, and matrix.
- A rank-3 tensor is basically a set of matrices.
- So, let's look at neural tensor network again.

Review: Recursive Neural Tensor Network

$$v_p = \sigma\left(W \begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix} + b\right)$$

Idea: allow more interactions of vectors

$$v_p = \sigma\left(\begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix}^T V_{c_1, c_2} \begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix} + W \begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix} + b\right)$$



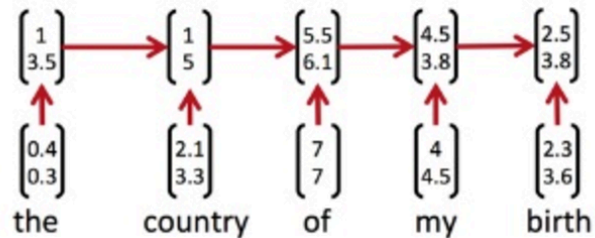
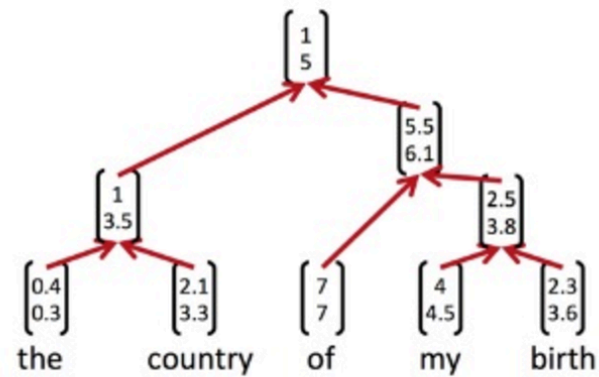
Slices of Tensor Layer Standard Layer

$$p = f \left(\left(\begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix}^T V_{c_1, c_2} \begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix} + W \begin{bmatrix} v_{c_1} \\ v_{c_2} \end{bmatrix} + b \right) \right)$$

$$p = f \left(\begin{bmatrix} b \\ c \end{bmatrix}^T V^{[1:2]} \begin{bmatrix} b \\ c \end{bmatrix} + W \begin{bmatrix} b \\ c \end{bmatrix} \right)$$

The diagram shows the internal structure of the tensor layer. It consists of two main parts: 'Slices of Tensor Layer' and 'Standard Layer'. The 'Slices of Tensor Layer' part is enclosed in a dashed box and shows two horizontal capsules (representing v_{c_1} and v_{c_2}) interacting with a grid of colored dots (representing the tensor V_{c_1, c_2}). The 'Standard Layer' part shows a single horizontal capsule (representing W) interacting with a vertical capsule (representing b). The output of the tensor layer is added to the output of the standard layer, and the result is passed through a function f to produce the final vector p .

Recursive vs. Recurrent



Review

Word Vector

Word2Vec Variants

Skip-gram: predicting surrounding words given the target word (Mikolov+, 2013)

$$p(w_{t-m}, \dots w_{t-1}, w_{t+1}, \dots, w_{t+m} \mid w_t)$$

CBOW (continuous bag-of-words): predicting the target word given the surrounding words (Mikolov+, 2013)

$$p(w_t \mid w_{t-m}, \dots w_{t-1}, w_{t+1}, \dots, w_{t+m})$$

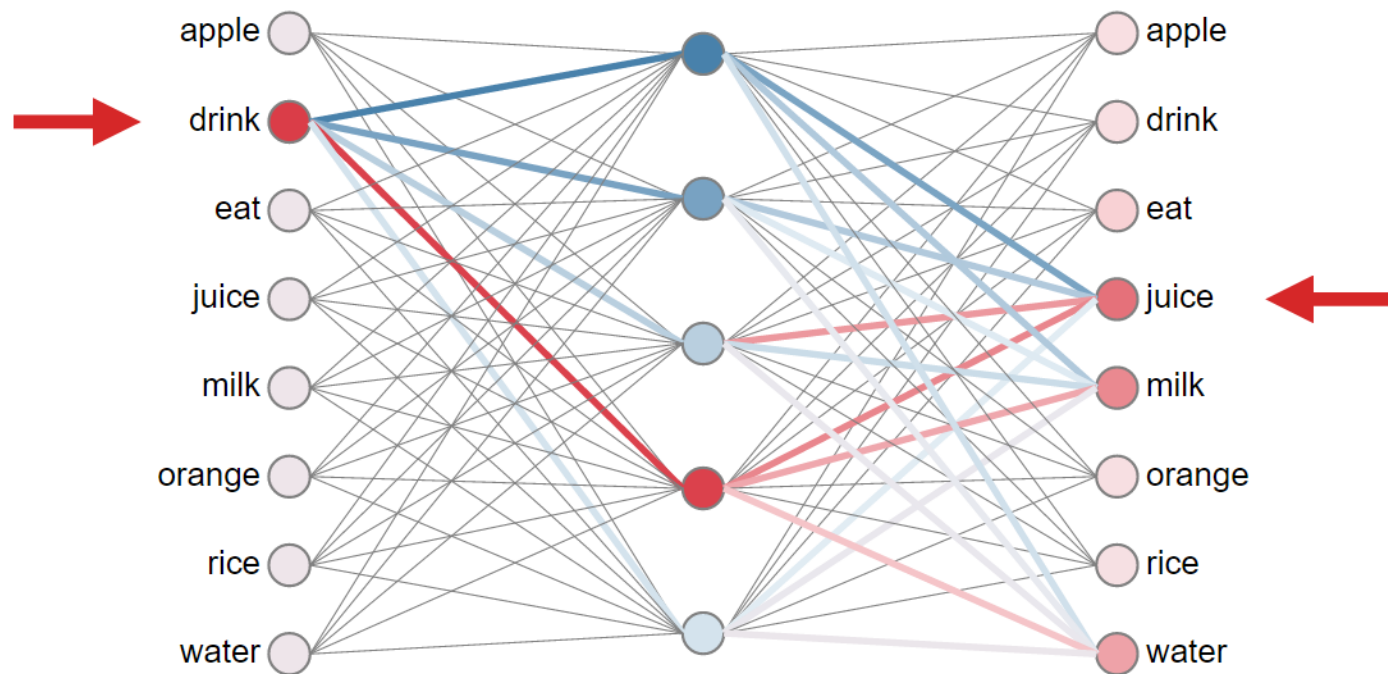
LM (Language modeling): predicting the next words given the proceeding contexts (Mikolov+, 2013)

$$p(w_{t+1} \mid w_t)$$

Word2Vec LM

Goal: predicting the next words given the proceeding contexts

$$p(w_{t+1} \mid w_t)$$



Outline

Language Modeling

- N-gram Language Model
- Feed-Forward Neural Language Model
- Recurrent Neural Network Language Model (RNNLM)

Recurrent Neural Network

- Definition
- Training via Backpropagation through Time (BPTT)
- Training Issue

Applications

- Sequential Input
- Sequential Output
 - Aligned Sequential Pairs (Tagging)
 - Unaligned Sequential Pairs (Seq2Seq/Encoder-Decoder)

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Language Modeling

Goal: estimate the probability of a word sequence

$$P(w_1, \dots, w_m)$$

Example task: determinate whether a sequence is grammatical or makes more sense



recognize speech
or
wreck a nice beach

If $P(\text{recognize speech})$
 $> P(\text{wreck a nice beach})$

Output =
“recognize speech”

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N-Gram Language Modeling

Goal: estimate the probability of a word sequence

$$P(w_1, \dots, w_m)$$

N-gram language model

- Probability is conditioned on a window of $(n-1)$ previous words

$$P(w_1, \dots, w_m) = \prod_{i=1}^m P(w_i \mid w_1, \dots, w_{i-1}) \approx \prod_{i=1}^m P(w_i \mid w_{i-(n-1)}, \dots, w_{i-1})$$

- Estimate the probability based on the training data

$$P(\text{beach} \mid \text{nice}) = \frac{C(\text{nice beach})}{C(\text{nice})}$$

Count of “nice beach” in the training data

Count of “nice” in the training data

Issue: some sequences may not appear in the training data

N-Gram Language Modeling

Training data:

- The dog ran
- The cat jumped

$$P(\text{jumped} \mid \text{dog}) = \cancel{0} \text{ } 0.0001$$

$$P(\text{ran} \mid \text{cat}) = \cancel{0} \text{ } 0.0001$$

give some small probability
→ smoothing

- The probability is not accurate.
- The phenomenon happens because we cannot collect all the possible text in the world as training data.

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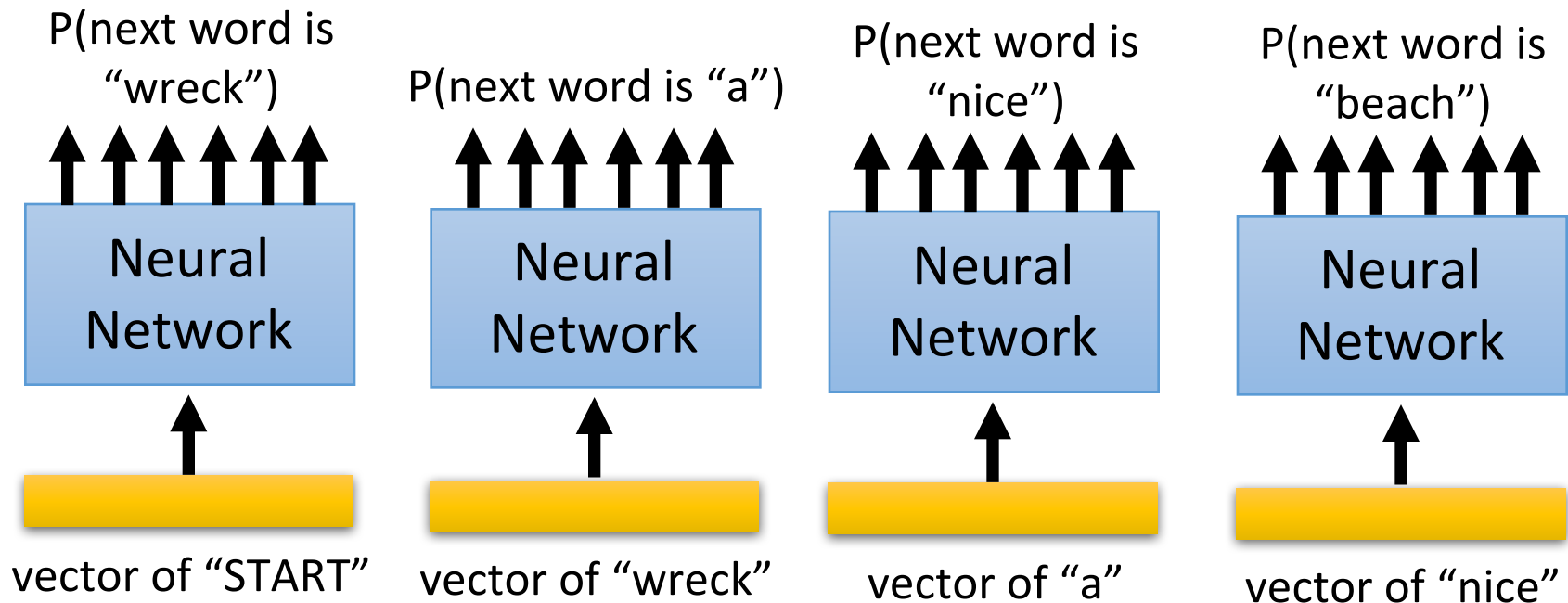
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Neural Language Modeling

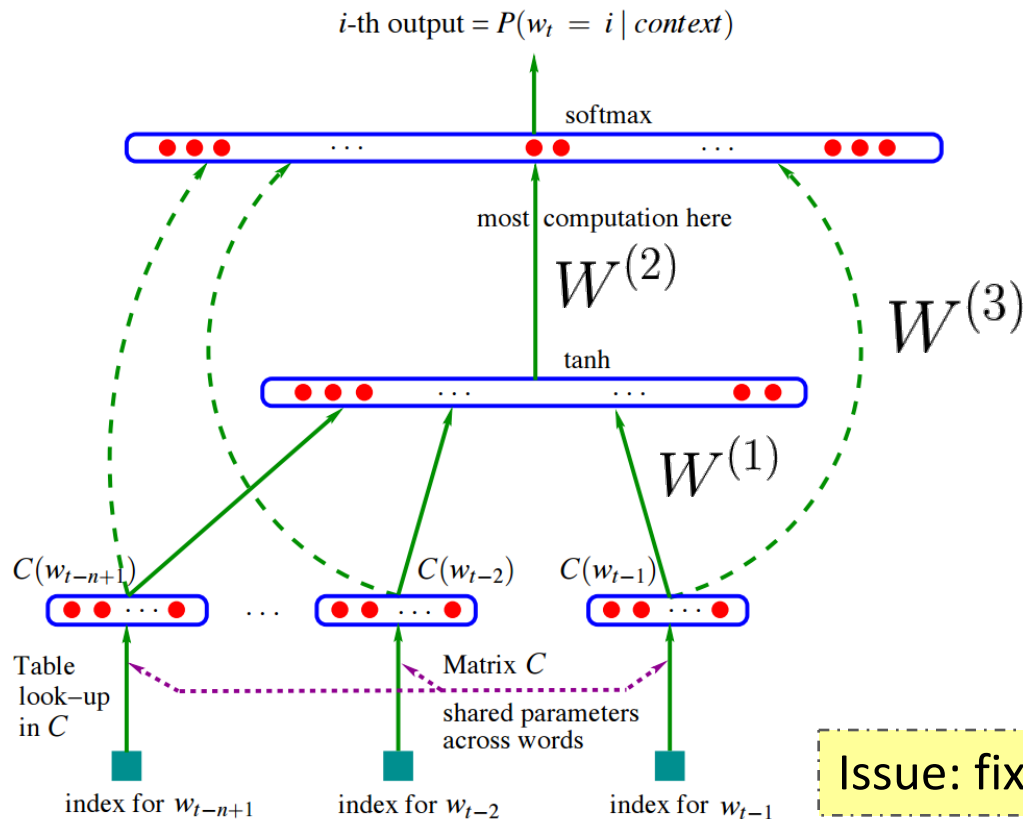
Idea: estimate $P(w_i \mid w_{i-(n-1)}, \dots, w_{i-1})$ not from count, but from the NN prediction

$$P(\text{"wreck a nice beach"}) = P(\text{wreck} \mid \text{START})P(a \mid \text{wreck})P(\text{nice} \mid a)P(\text{beach} \mid \text{nice})$$



Neural Language Modeling

$$\hat{y} = \text{softmax}(W^{(2)}\sigma(W^{(1)}x + b^{(1)}) + W^{(3)}x + b^{(3)})$$



Probability distribution of the next word

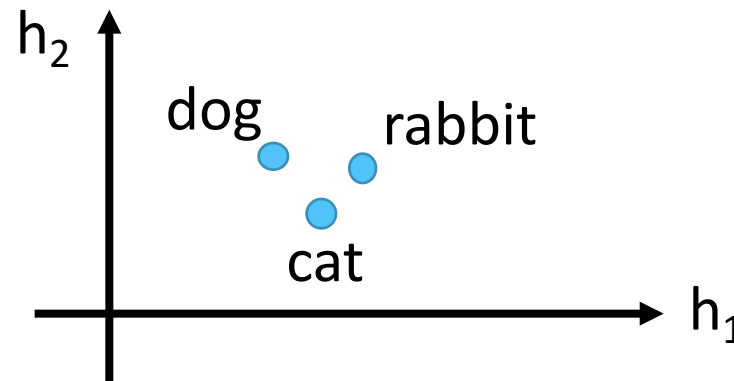


context vector

Issue: fixed context window for conditioning

Neural Language Modeling

The input layer (or hidden layer) of the related words are close



- If $P(\text{jump} | \text{dog})$ is large, $P(\text{jump} | \text{cat})$ increase accordingly (even there is not "... cat jump ..." in the data)

Smoothing is automatically done

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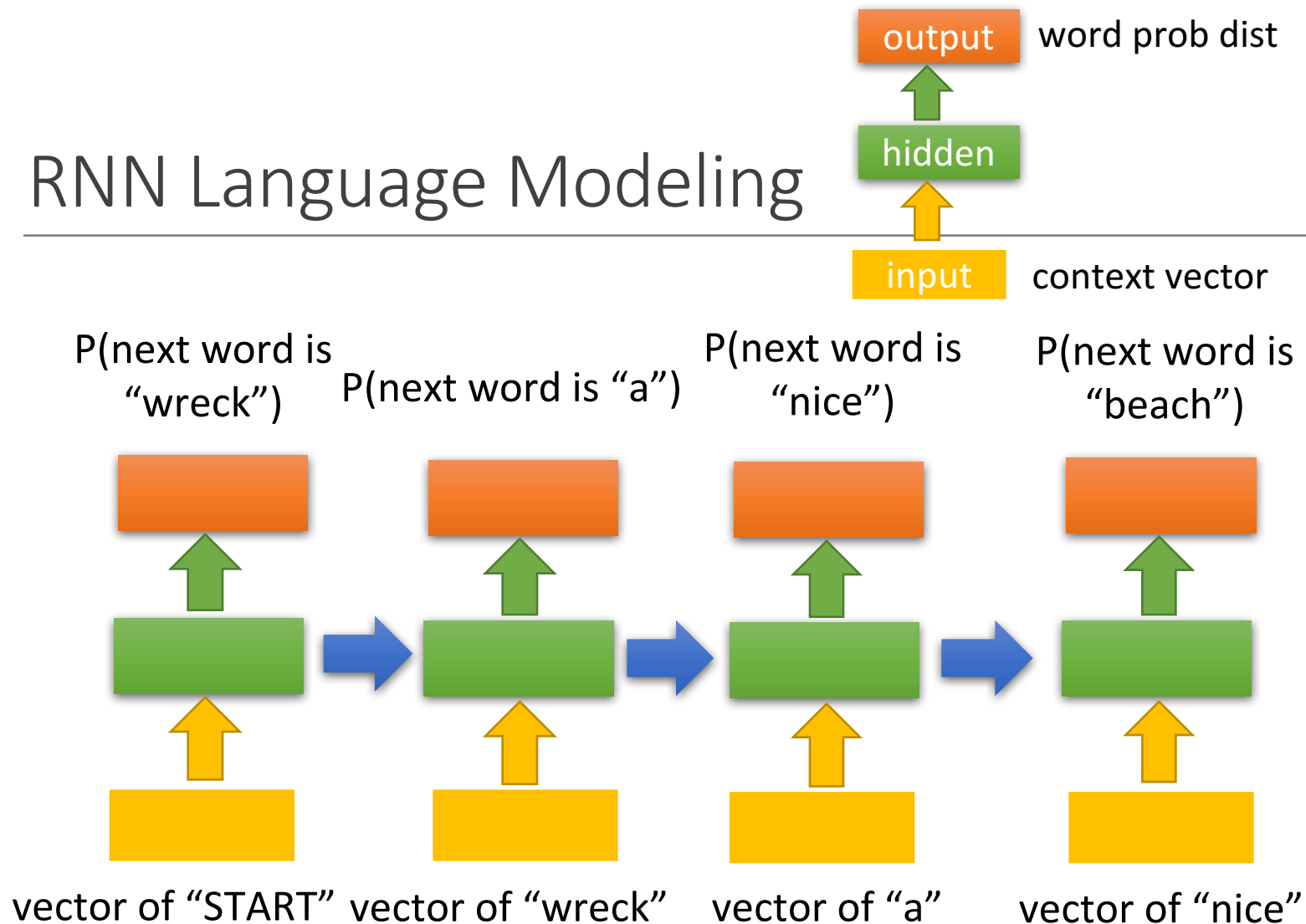
- Sequential Input
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Recurrent Neural Network

Idea: condition the neural network on all previous words and tie the weights at each time step

Assumption: temporal information matters

RNN Language Modeling



Idea: pass the information from the previous hidden layer to leverage all contexts

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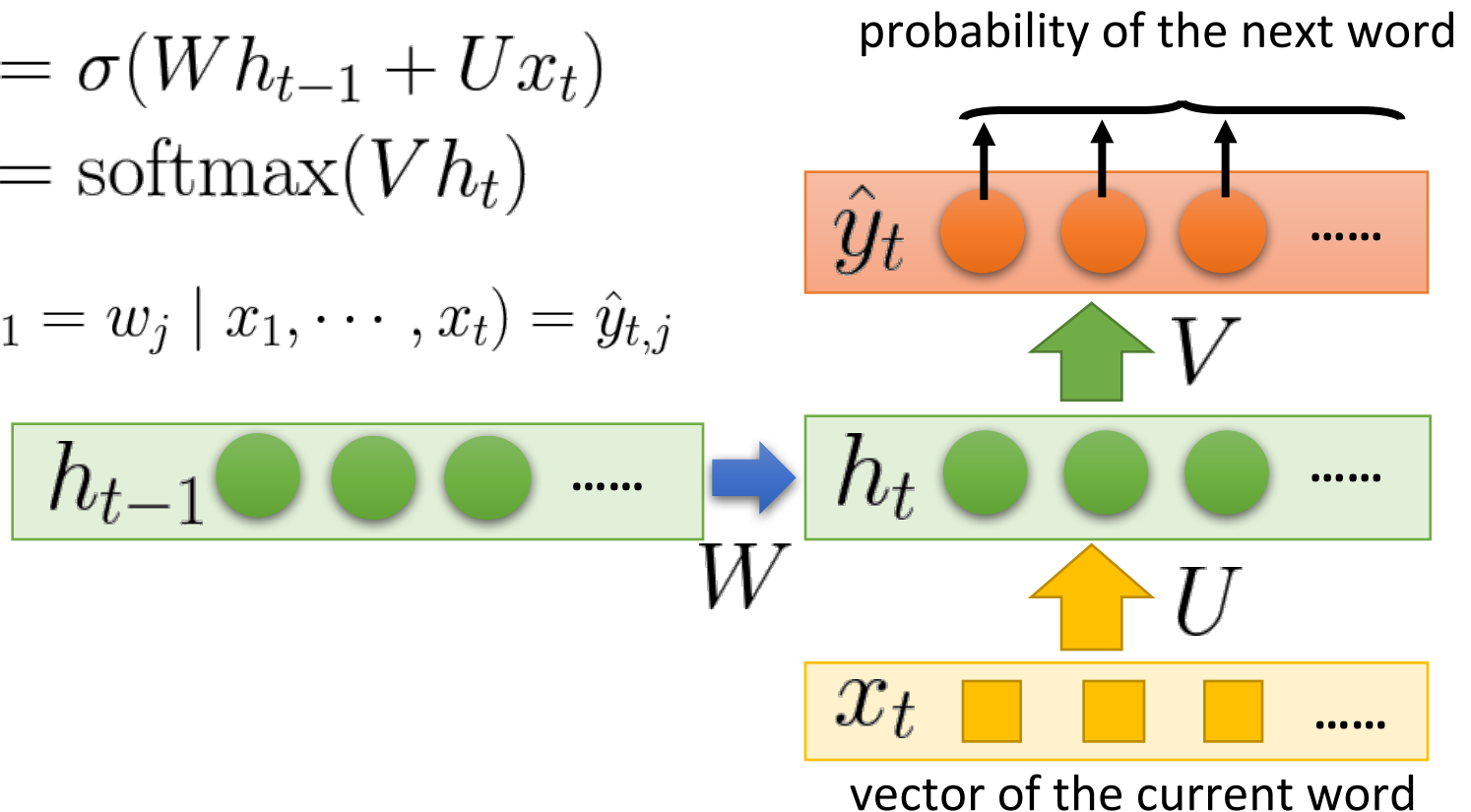
RNNLM Formulation

At each time step,

$$h_t = \sigma(W h_{t-1} + U x_t)$$

$$\hat{y}_t = \text{softmax}(V h_t)$$

$$P(x_{t+1} = w_j \mid x_1, \dots, x_t) = \hat{y}_{t,j}$$



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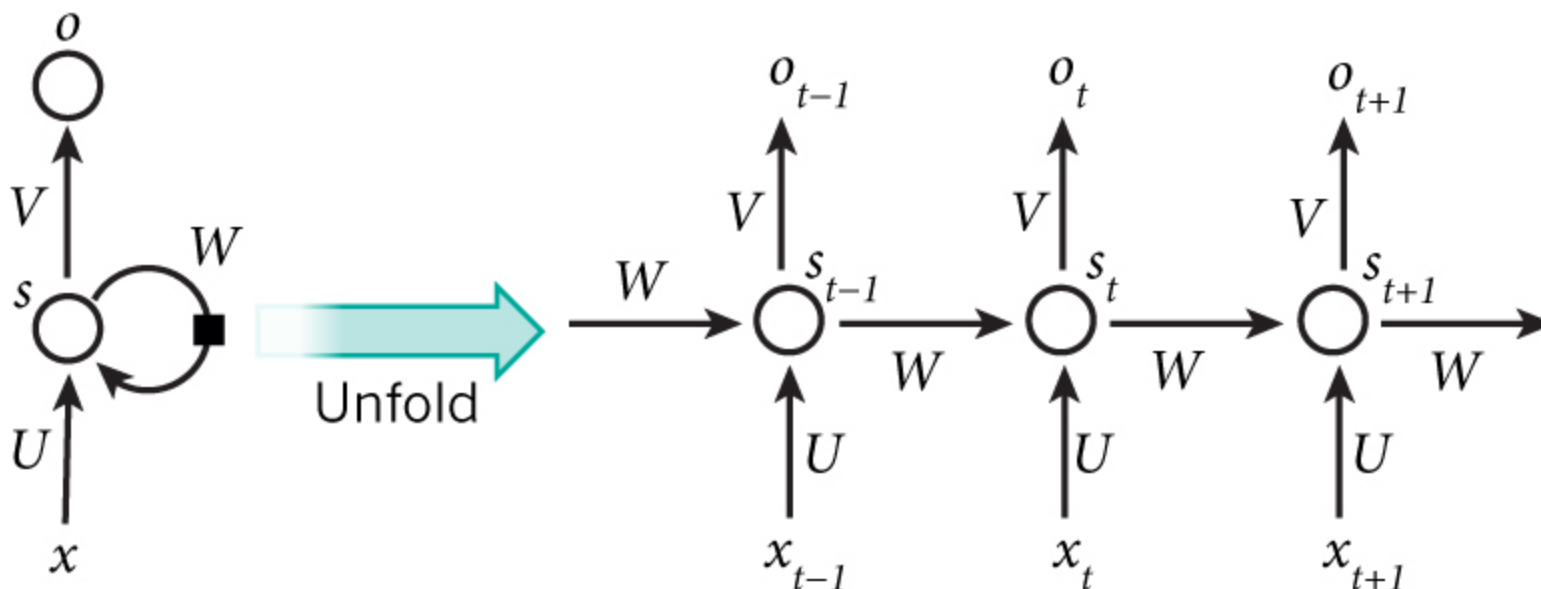
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Recurrent Neural Network Definition

$$s_t = \sigma(W s_{t-1} + U x_t) \quad \sigma(\cdot): \text{tanh, ReLU}$$

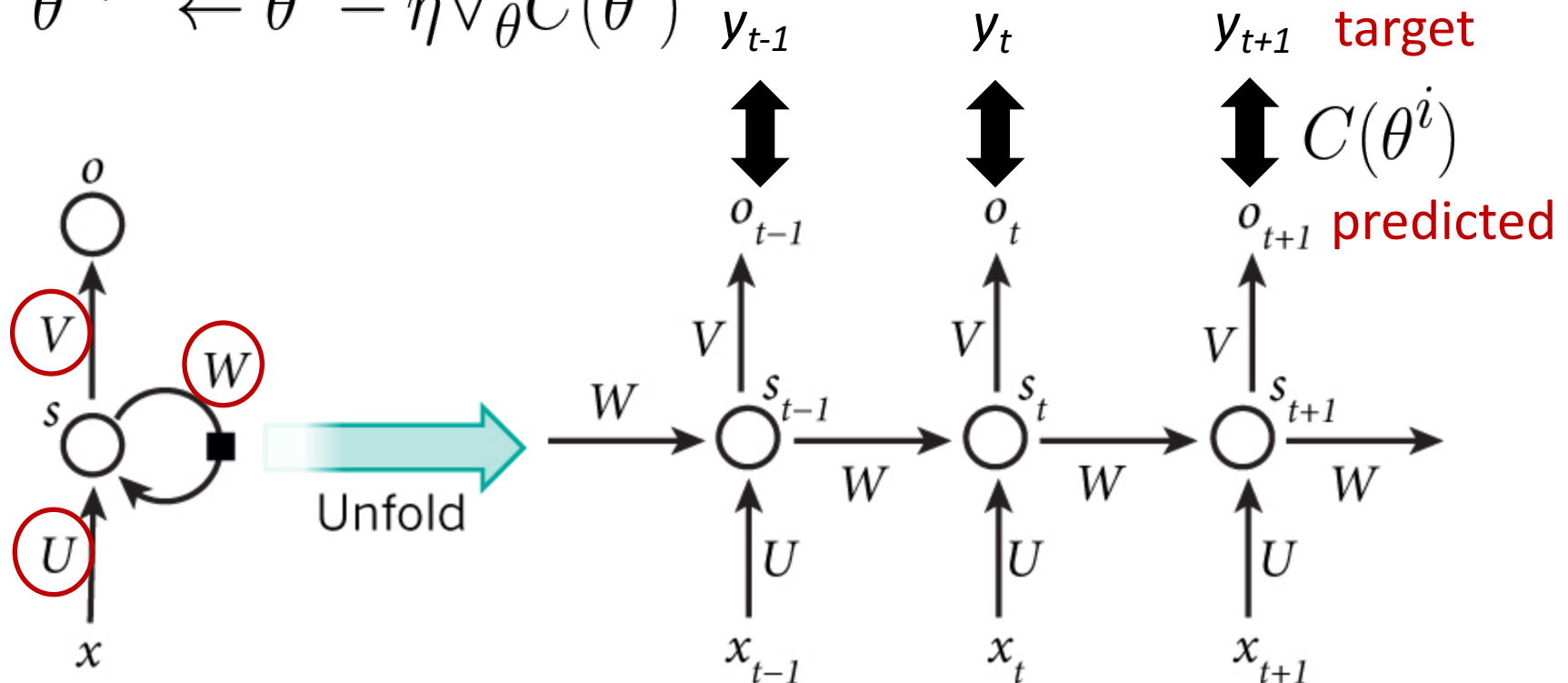
$$o_t = \text{softmax}(V s_t)$$



Model Training

All model parameters $\theta = \{U, V, W\}$ can be updated by

$$\theta^{i+1} \leftarrow \theta^i - \eta \nabla_{\theta} C(\theta^i)$$



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In-class exercise:

Derive the delta rule for backpropagation

$y_j = \sigma(z_j)$, $z_j = \sum x_i w_{ji}$, t_j : ground truth.
The quadratic error is defined as:

$$E = \sum_j \frac{1}{2} (t_j - y_j)^2$$

What is $\frac{\partial E}{\partial w_{ji}}$?

(Hint: use chain rule twice)

Derive the delta rule for backpropagation.

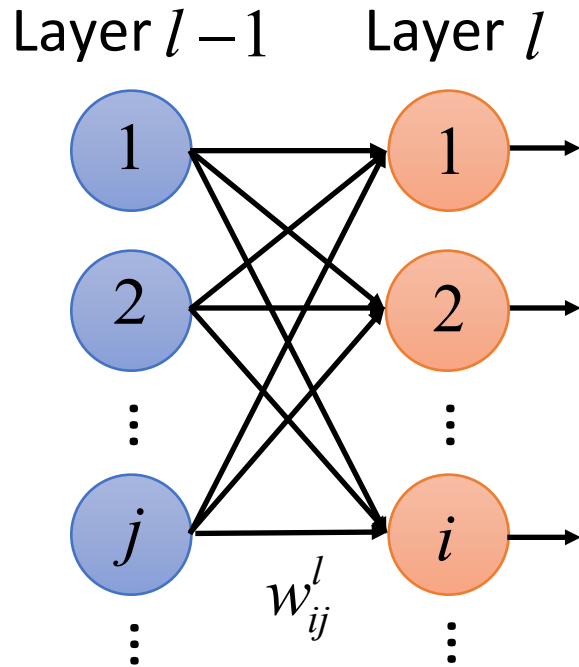
$$\begin{aligned}\frac{\partial E}{\partial w_{ji}} &= \frac{\partial \left(\frac{1}{2} (t_j - y_j)^2 \right)}{\partial w_{ji}} \\ &= \frac{\partial \left(\frac{1}{2} (t_j - y_j)^2 \right)}{\partial y_j} \frac{\partial y_j}{\partial w_{ji}} \\ &= - (t_j - y_j) \frac{\partial y_j}{\partial w_{ji}} \\ &= - (t_j - y_j) \frac{\partial y_j}{\partial z_j} \frac{\partial z_j}{\partial w_{ji}} \\ &= - (t_j - y_j) \sigma'(z_j) \frac{\partial z_j}{\partial w_{ji}} \\ &= - (t_j - y_j) \sigma'(z_j) \frac{\partial (\sum_k x_k w_{jk})}{\partial w_{ji}}\end{aligned}$$

$$\frac{\partial x_i w_{ji}}{\partial w_{ji}} = x_i$$

$$\frac{\partial E}{\partial w_{ji}} = - (t_j - y_j) \sigma'(z_j) x_i$$

Backpropagation

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \frac{\partial C(\theta)}{\partial z_i^l} \frac{\partial z_i^l}{\partial w_{ij}^l}$$



δ_i^l Error signal

Backward Pass

$$\begin{aligned} \delta^L &= \sigma'(z^L) \odot \nabla C(y) \\ \delta^{L-1} &= \sigma'(z^{L-1}) \odot (W^L)^T \delta^L \\ &\vdots \\ \delta^l &= \sigma'(z^l) \odot (W^{l+1})^T \delta^{l+1} \\ &\vdots \end{aligned}$$

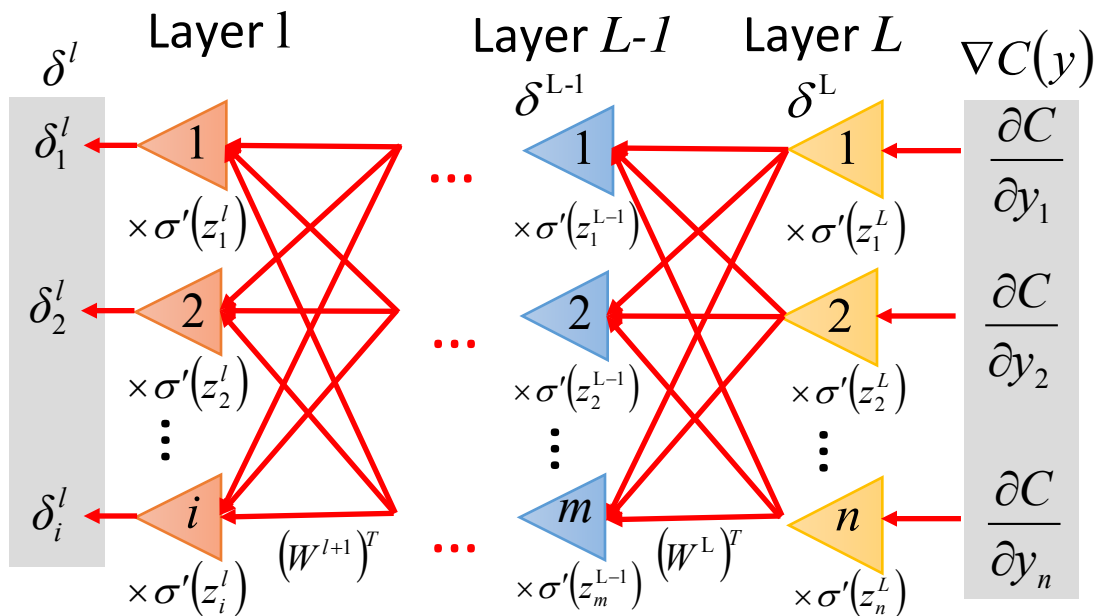
$$\begin{cases} a_j^{l-1} & l > 1 \\ x_j & l = 1 \end{cases}$$

Forward Pass

$$\begin{aligned} z^1 &= W^1 x + b^1 \\ a^1 &= \sigma(z^1) \\ &\vdots \\ z^l &= W^l a^{l-1} + b^l \\ a^l &= \sigma(z^l) \\ &\vdots \end{aligned}$$

Backpropagation

$$\frac{\partial C(\theta)}{\partial w_{ij}^l} = \boxed{\frac{\partial C(\theta)}{\partial z_i^l}} \frac{\partial z_i^l}{\partial w_{ij}^l}$$



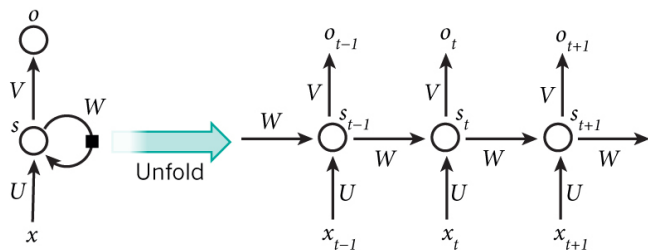
δ_i^l Error signal

Backward Pass

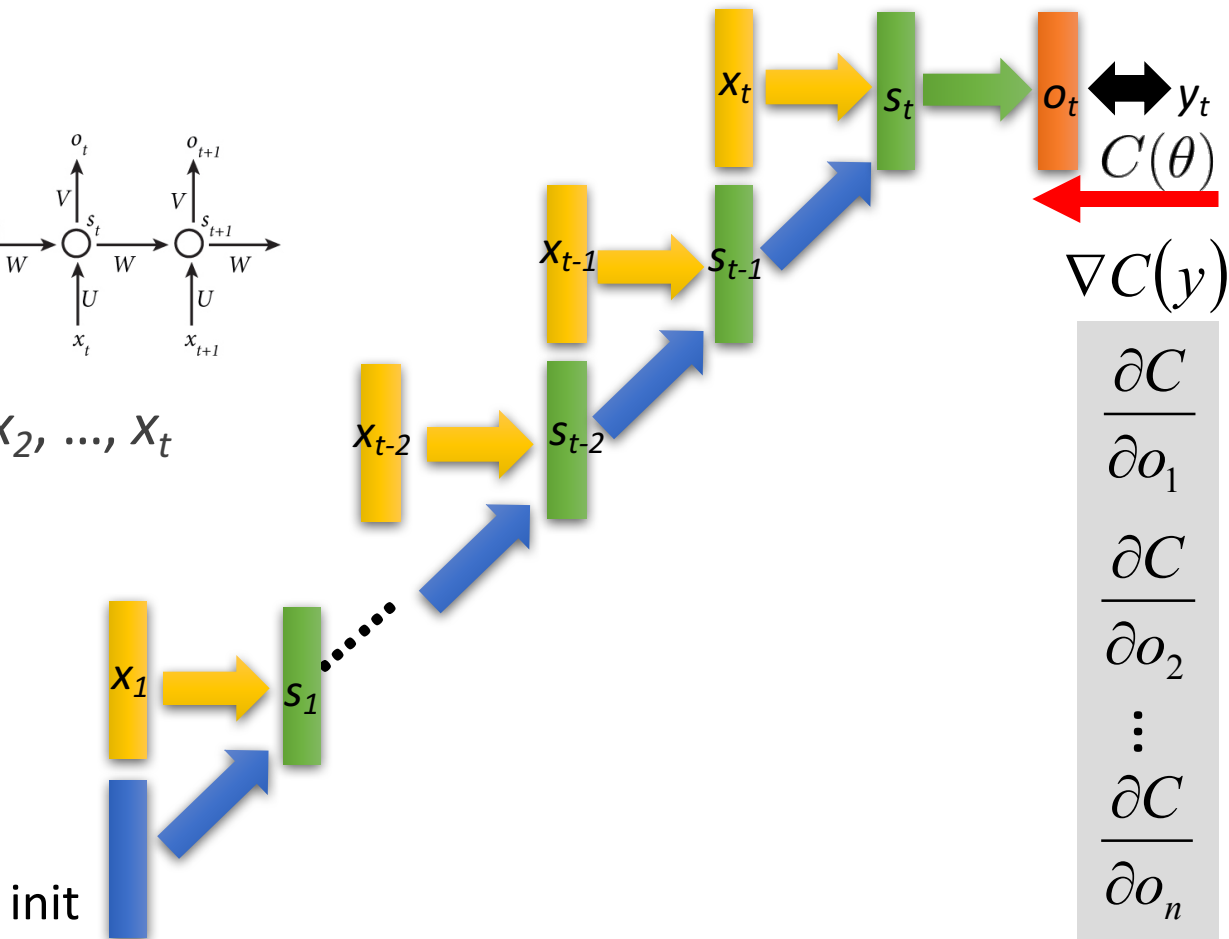
$$\begin{aligned} \delta^L &= \sigma'(z^L) \odot \nabla C(y) \\ \delta^{L-1} &= \sigma'(z^{L-1}) \odot (W^L)^T \delta^L \\ &\vdots \\ \delta^l &= \sigma'(z^l) \odot (W^{l+1})^T \delta^{l+1} \\ &\vdots \end{aligned}$$

Backpropagation through Time (BPTT)

Unfold

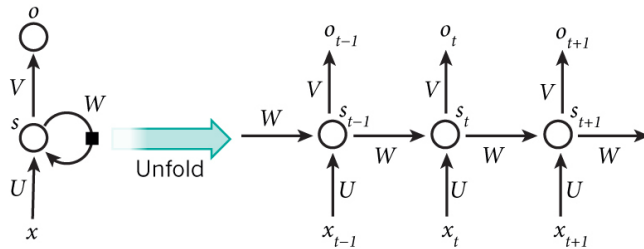


- Input: $\text{init}, x_1, x_2, \dots, x_t$
- Output: o_t
- Target: y_t

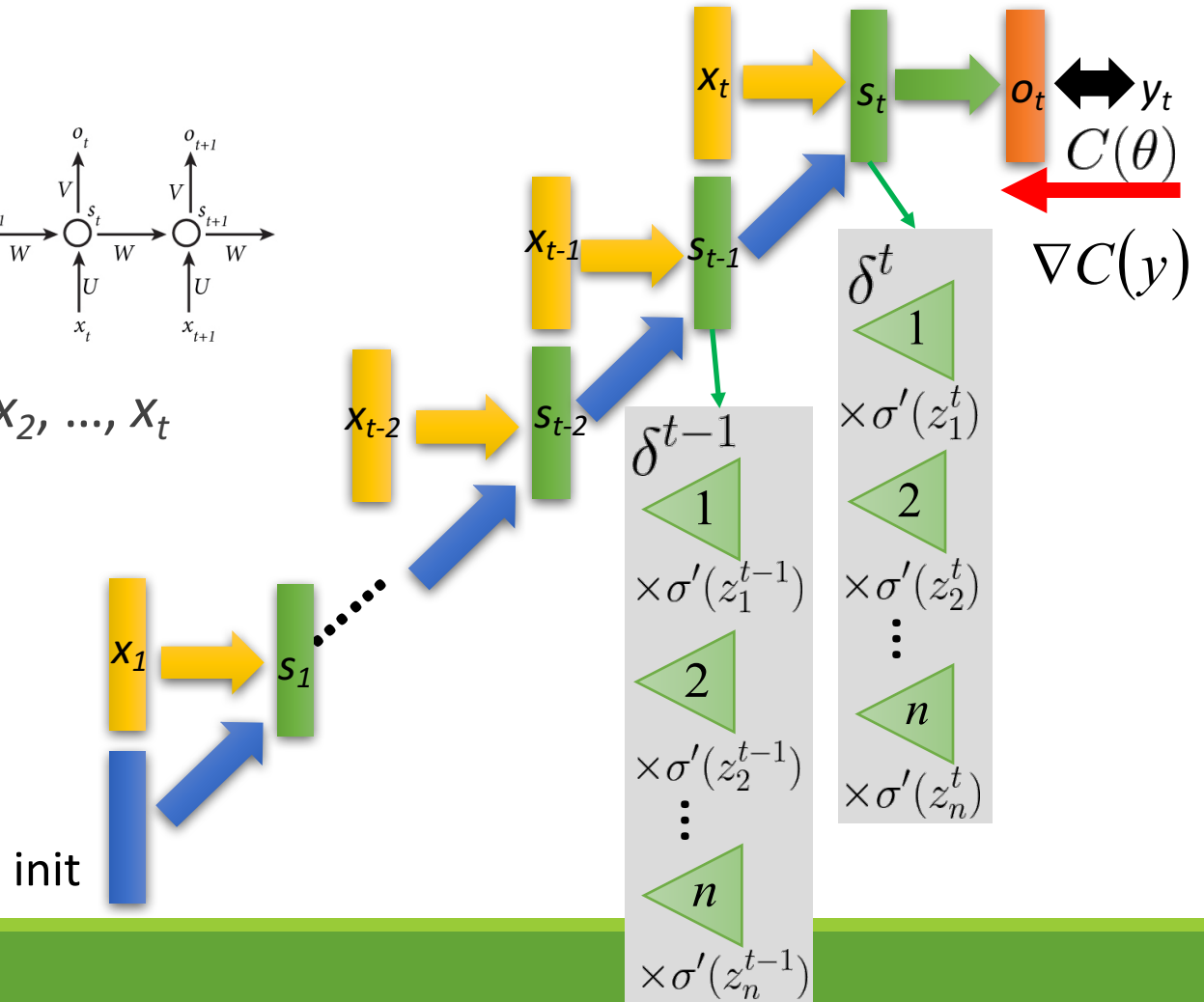


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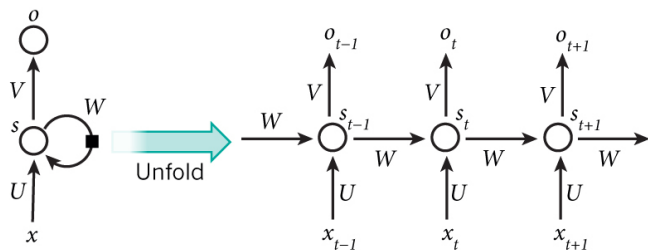


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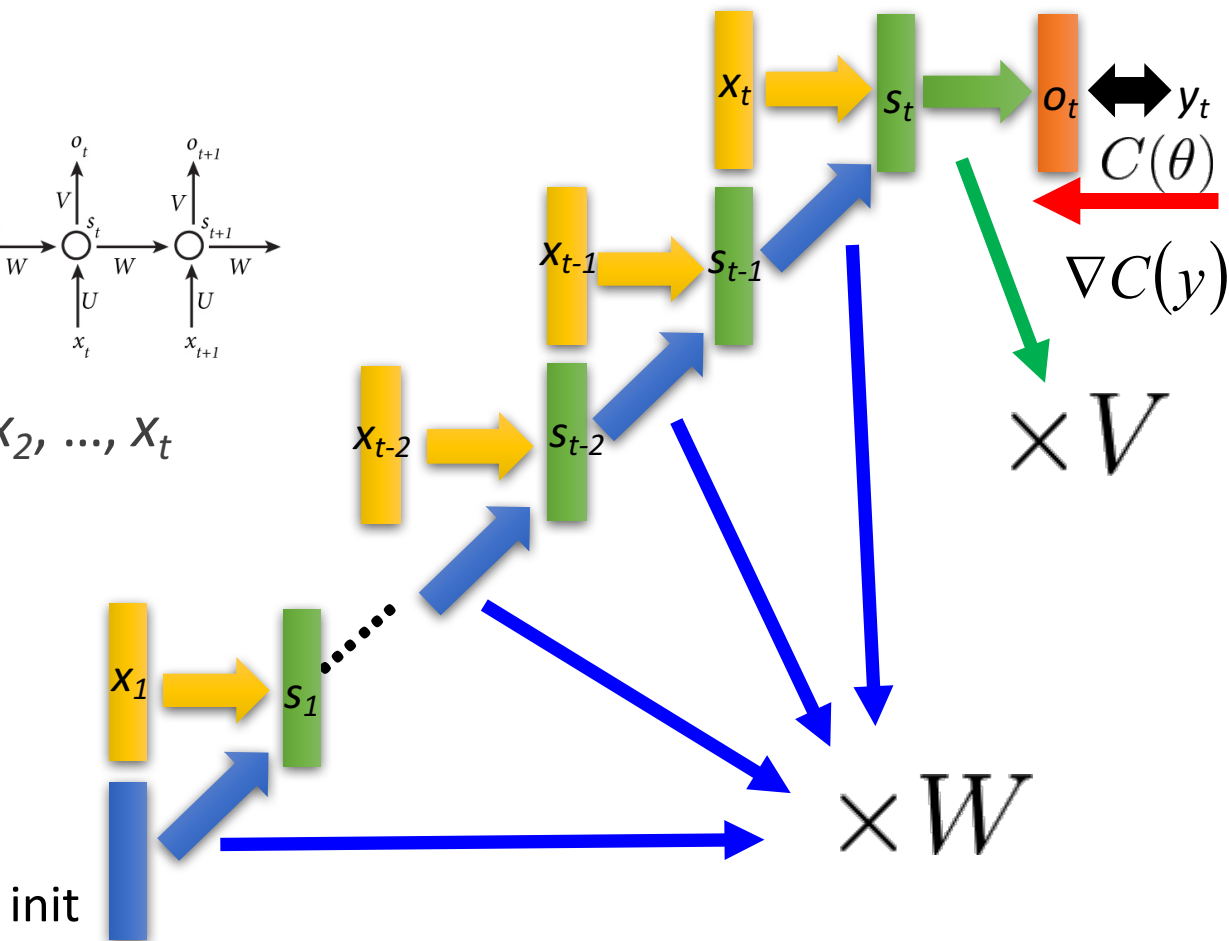


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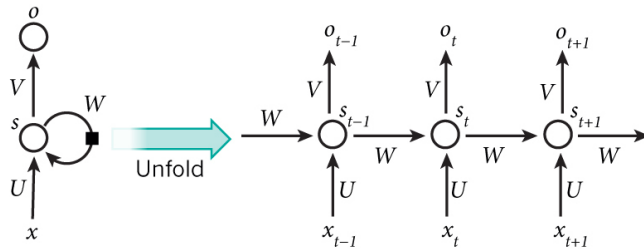


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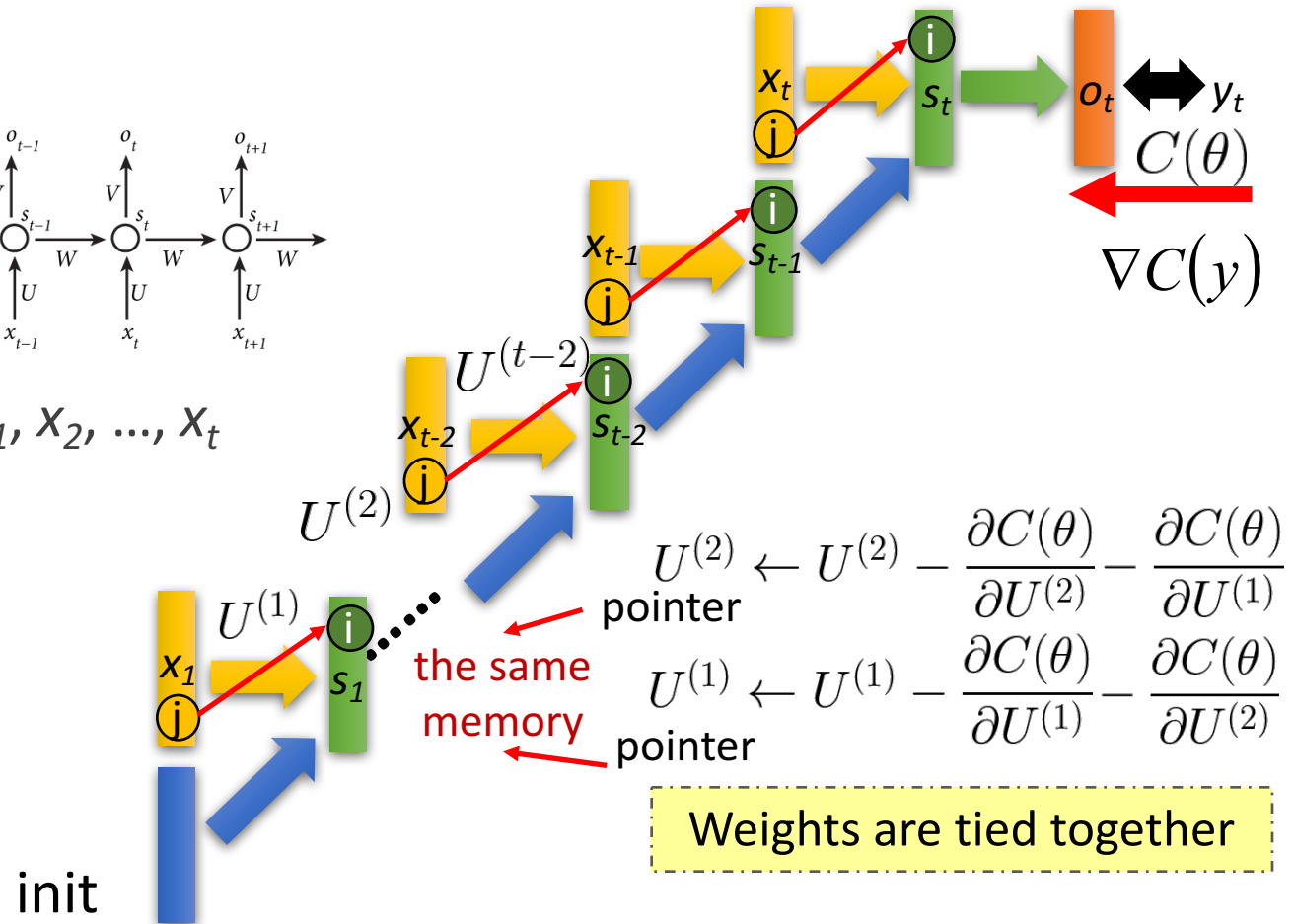


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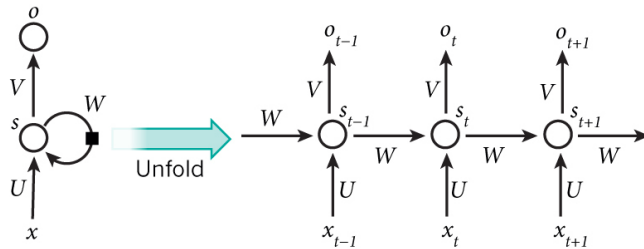


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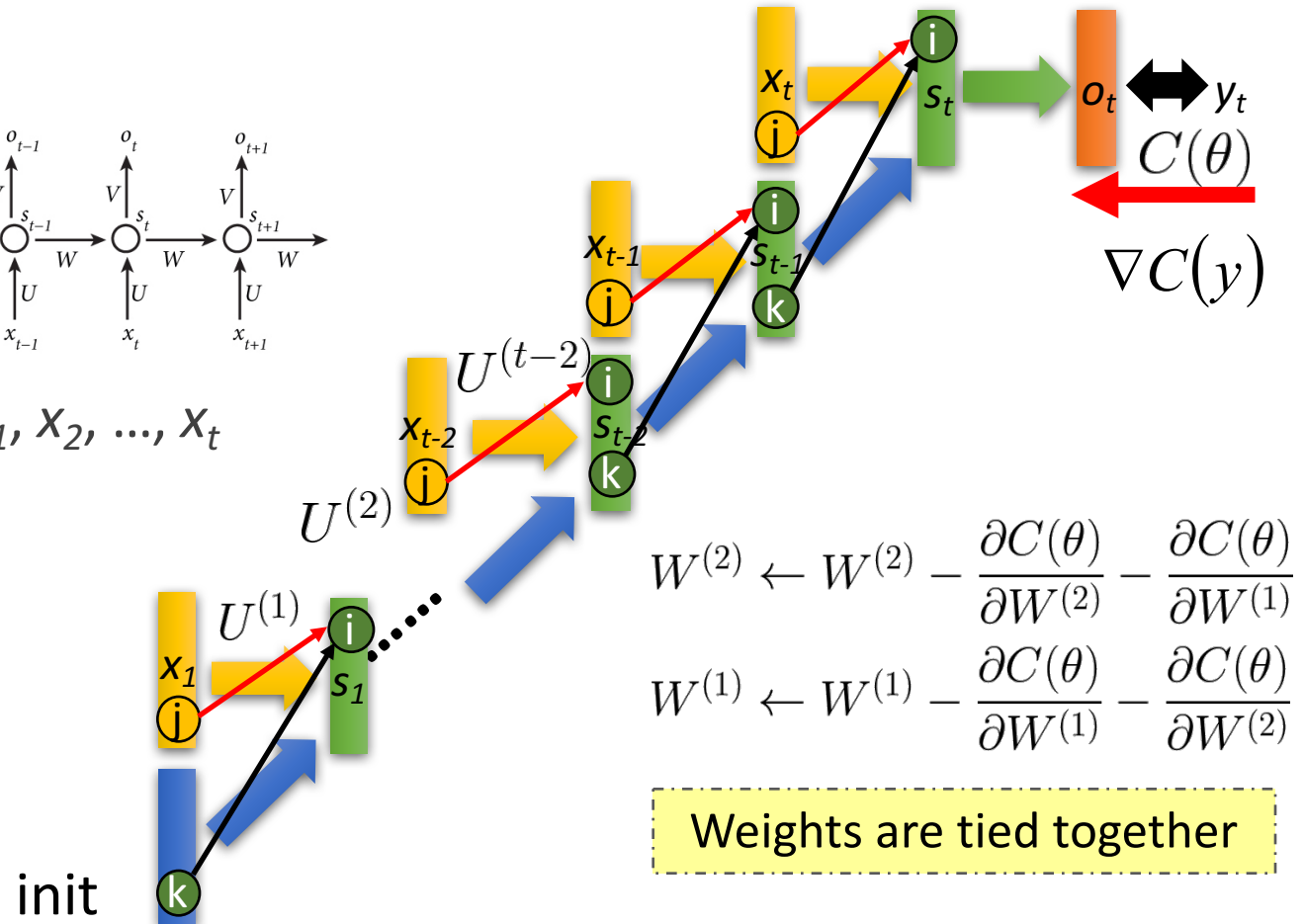


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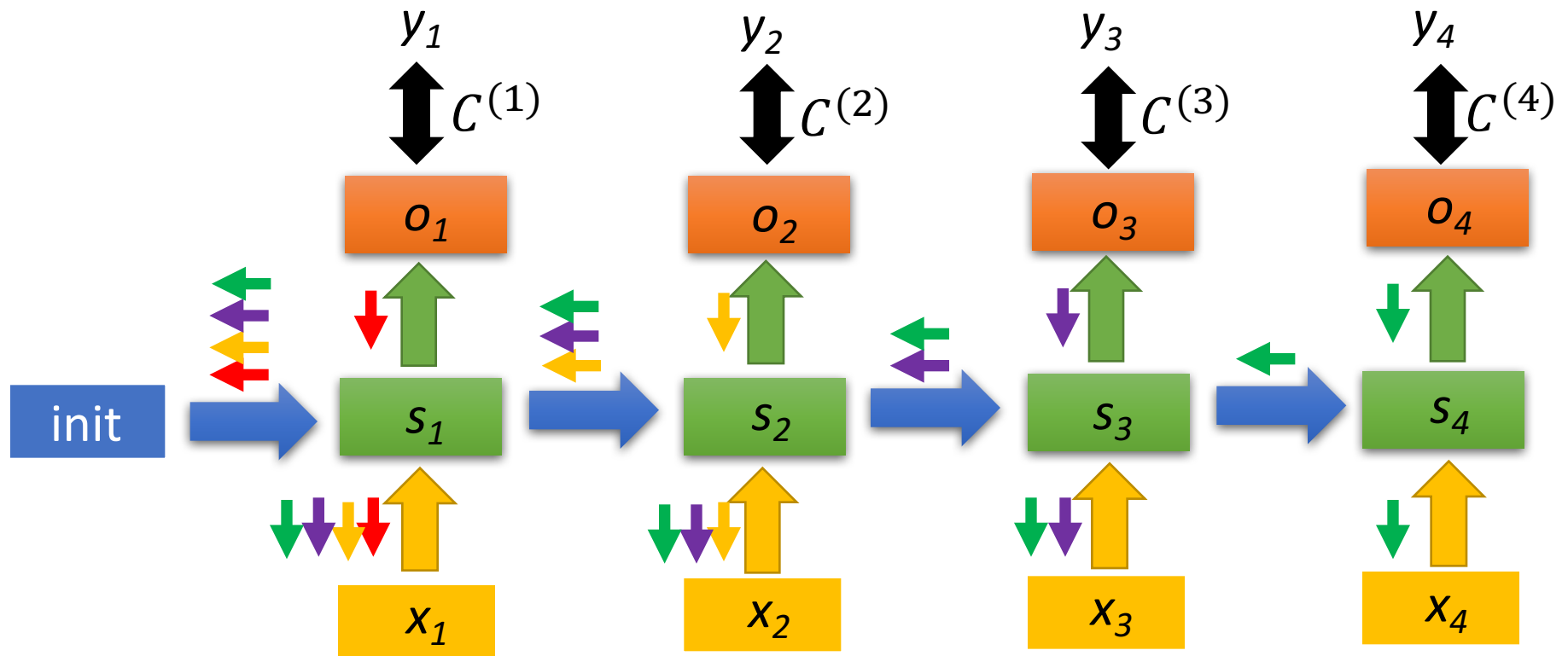
- Input: $\text{init}, x_1, x_2, \dots, x_t$
- Output: o_t
- Target: y_t



BPTT

Forward Pass: Compute $s_1, s_2, s_3, s_4 \dots$

Backward Pass:
 \rightarrow For $C^{(4)}$ \leftarrow For $C^{(3)}$
 \rightarrow For $C^{(2)}$ \leftarrow For $C^{(1)}$



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RNN Training Issue

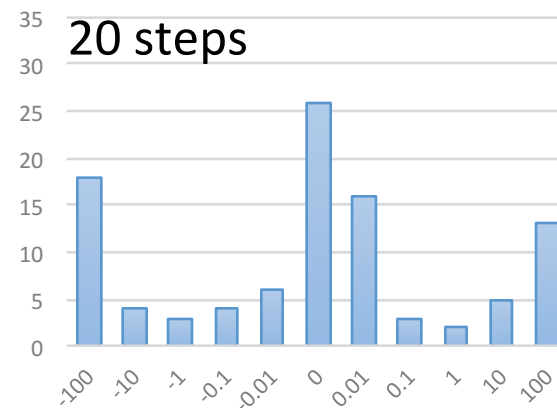
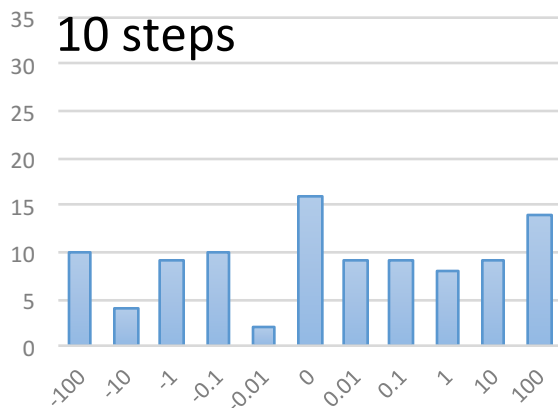
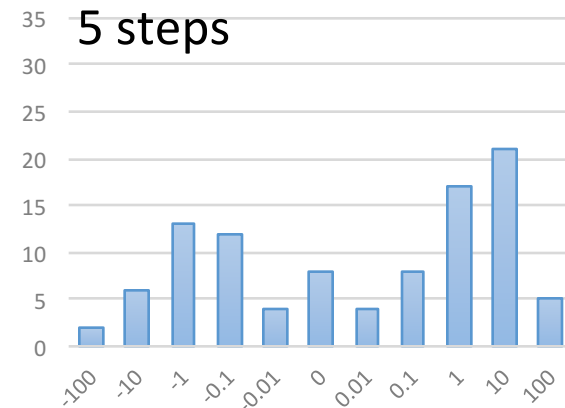
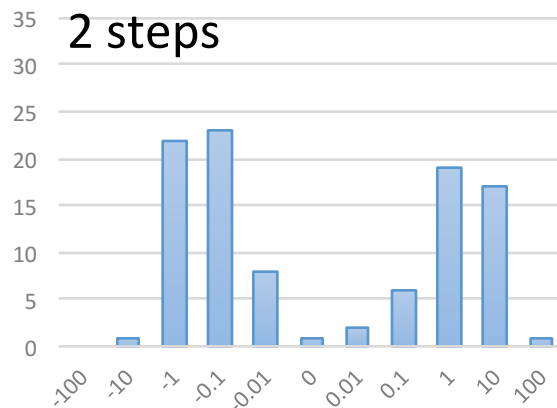
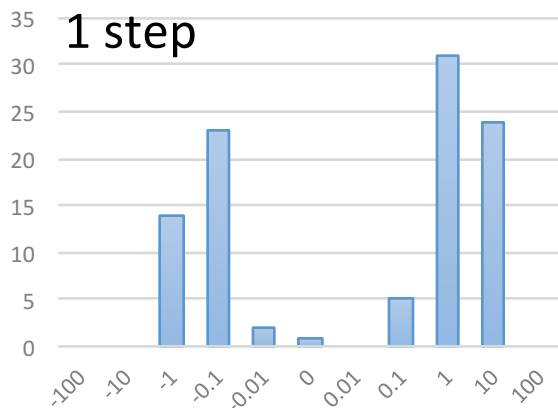
The gradient is a product of Jacobian matrices, each associated with a step in the forward computation

Multiply the same matrix at each time step during backprop

$$\delta^l = \sigma'(z^l) \odot (W^{l+1})^T \delta^{l+1}$$

The gradient becomes very small or very large quickly
→ **vanishing or exploding gradient**

Vanishing/Exploding Gradient Example



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How to Frame the Learning Problem?

The learning algorithm f is to map the input domain X into the output domain Y

$$f : X \rightarrow Y$$

Input domain: word, word sequence, audio signal, click logs

Output domain: single label, sequence tags, tree structure, probability distribution

Network design should leverage input and output domain properties

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Input Domain – Sequence Modeling

Idea: aggregate the meaning from all words into a vector

Method:

- Basic combination: average, sum
- Neural combination:
 - ✓ Recursive neural network (RvNN)
 - ✓ Recurrent neural network (RNN)
 - ✓ Convolutional neural network (CNN)

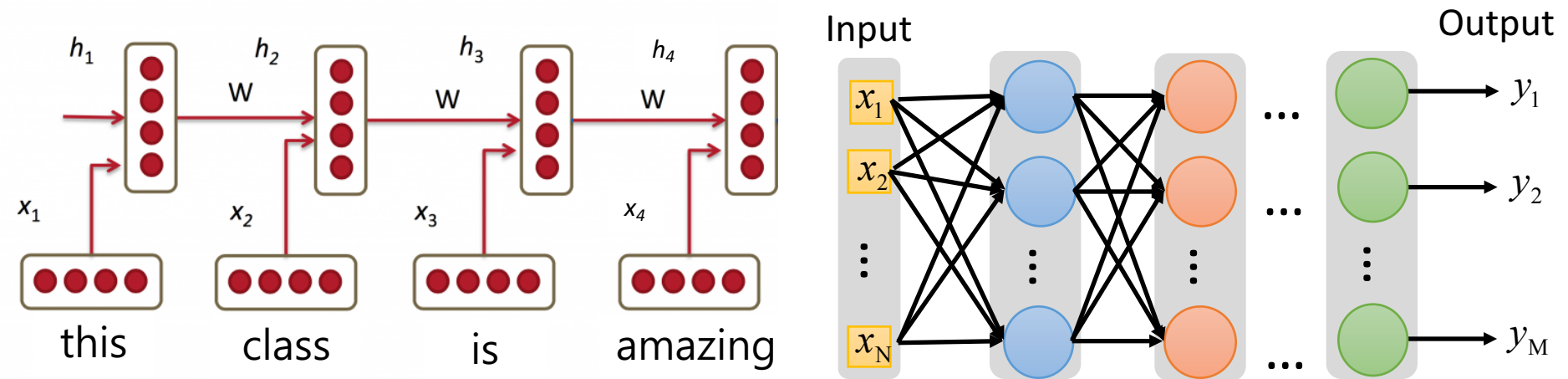
| | N -dim |
|---------|-----------------------------------|
| this | $[0.2 \ 0.6 \ 0.3 \ \dots \ 0.4]$ |
| class | $[0.9 \ 0.8 \ 0.1 \ \dots \ 0.1]$ |
| is | $[0.1 \ 0.3 \ 0.1 \ \dots \ 0.7]$ |
| amazing | $[0.5 \ 0.0 \ 0.6 \ \dots \ 0.4]$ |

How to compute $\vec{x} = [x_1 \ x_2 \ x_3 \ \dots \ x_N]$

Sentiment Analysis

Encode the sequential input into a vector using RNN

$$\vec{x} = [x_1 \ x_2 \ x_3 \ \cdots \ x_N]$$



RNN considers temporal information to learn sentence vectors as the input of classification tasks

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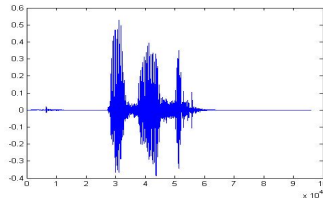
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Output Domain – Sequence Prediction

POS Tagging

“this class is amazing” → This/NT class/NN is/VBZ
amazing/JJ.

Speech Recognition



→ “how are you?”

Machine Translation

“How are you doing today?” → “你好嗎?”

The output can be viewed as a sequence of classification

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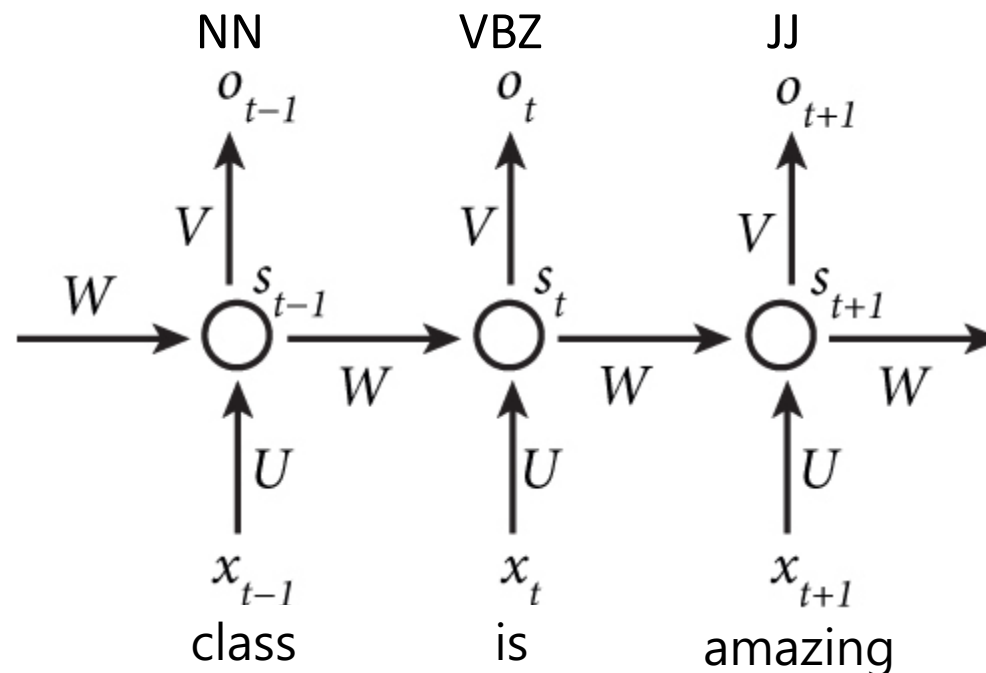
Applications

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POS Tagging

Tag a word at each timestamp

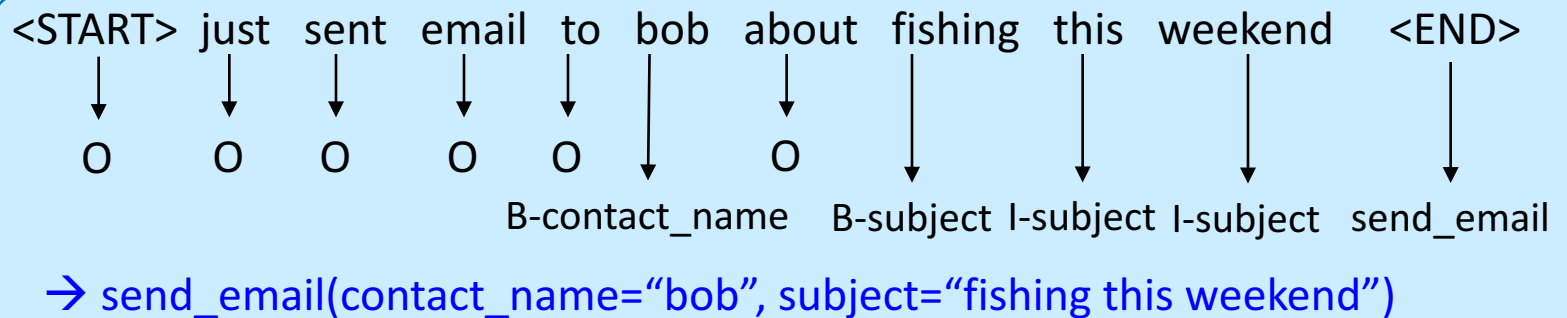
- Input: word sequence
- Output: corresponding POS tag sequence



Natural Language Understanding (NLU)

Tag a word at each timestamp

- Input: word sequence
- Output: IOB-format slot tag and intent tag



Temporal orders for input and output are the same

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Language Modeling

- N-gram Language Model
- Feed-Forward Neural Language Model
- Recurrent Neural Network Language Model (RNNLM)

Recurrent Neural Network

- Definition
- Training via Backpropagation through Time (BPTT)
- Training Issue

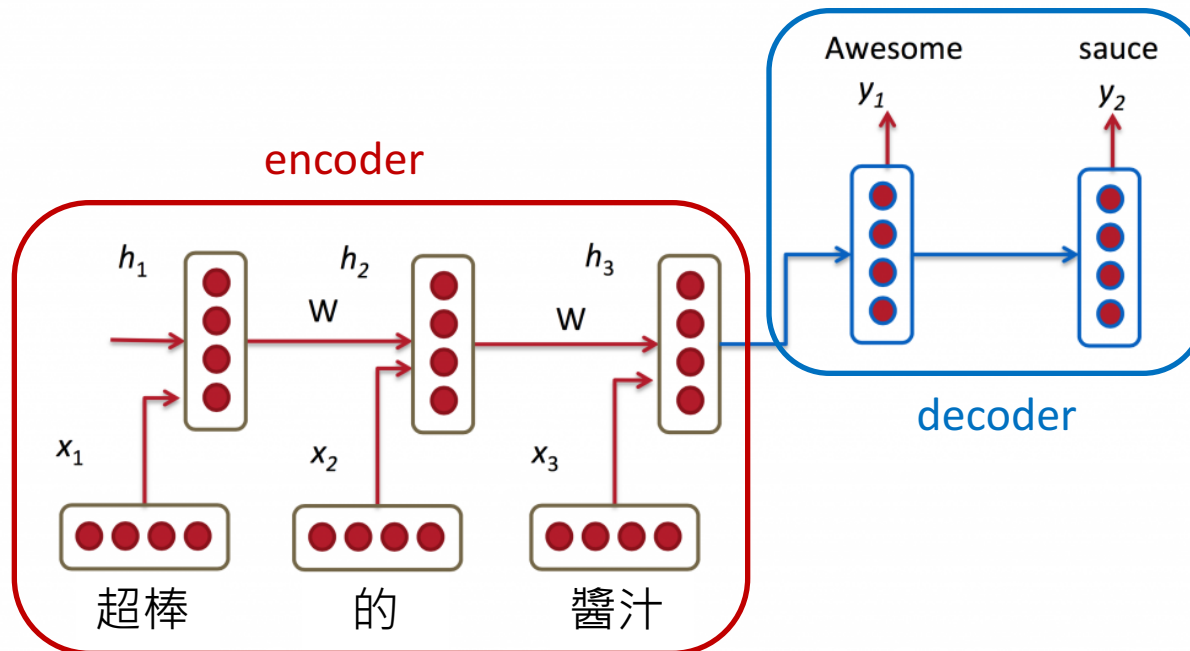
Applications

- Sequential Input
- Sequential Output
 - Aligned Sequential Pairs (Tagging)
 - **Unaligned Sequential Pairs (Seq2Seq/Encoder-Decoder)**

Machine Translation

Cascade two RNNs, one for encoding and one for decoding

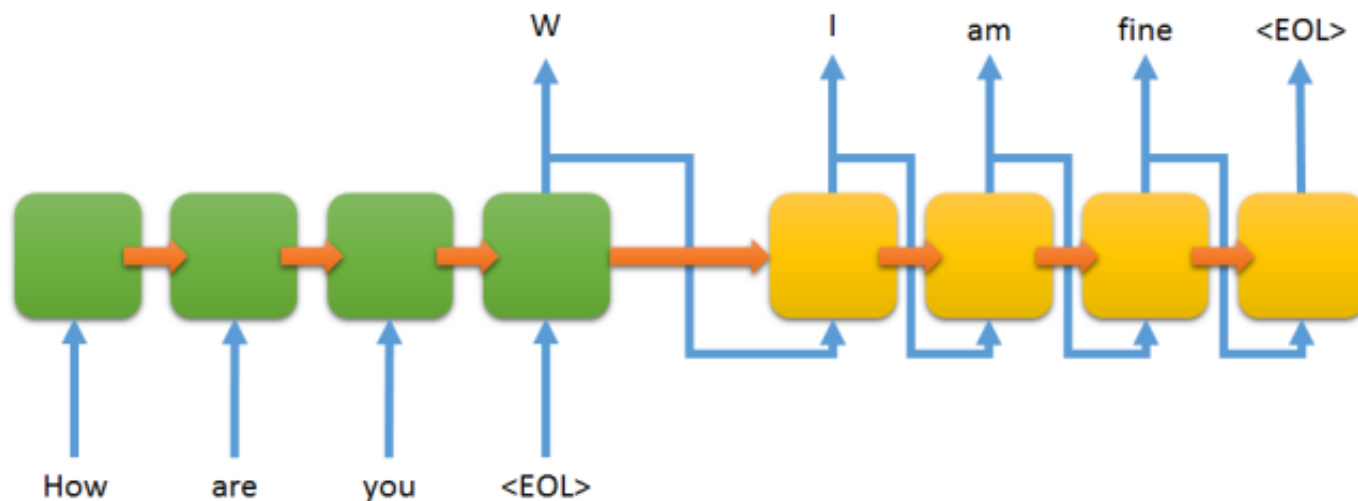
- Input: word sequences in the source language
- Output: word sequences in the target language



Chit-Chat Dialogue Modeling

Cascade two RNNs, one for encoding and one for decoding

- Input: word sequences in the question
- Output: word sequences in the response



Temporal ordering for input and output may be different

Concluding Remarks

Language Modeling

- RNNLM

Recurrent Neural Networks

- Definition

$$s_t = \sigma(W s_{t-1} + U x_t)$$

$$o_t = \text{softmax}(V s_t)$$

- Backpropagation through Time (BPTT)
- Vanishing/Exploding Gradient

Applications

- Sequential Input: Sequence-Level Embedding
- Sequential Output: Tagging / Seq2Seq (Encoder-Decoder)

