



Graphics

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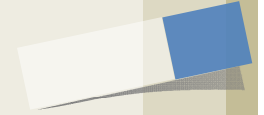
Many slides from Edward Angel and Dave Shreine

Many examples are from <https://webglfundamentals.org/>

Quick Review of WebGL



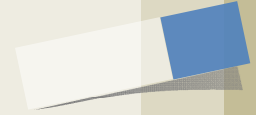
Program Execution



- ❑ WebGL runs within the browser
 - ❑ complex interaction among the operating system, the window system, the browser and your code (HTML and JS)
- ❑ Simple model
 - ❑ Start with HTML file
 - ❑ files read in asynchronously
 - ❑ start with onload function
 - ❑ event driven input



Coordinate Systems



- ❑ The units in **points** are determined by the application and are called *object*, *world*, *model* or *problem coordinates*
- ❑ Viewing specifications usually are also in object coordinates
- ❑ Eventually pixels will be produced in *window coordinates*
- ❑ WebGL also uses some internal representations that usually are not visible to the application but are important in the shaders
- ❑ Most important is *clip coordinates*

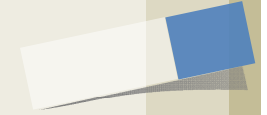


Coordinate Systems and Shaders

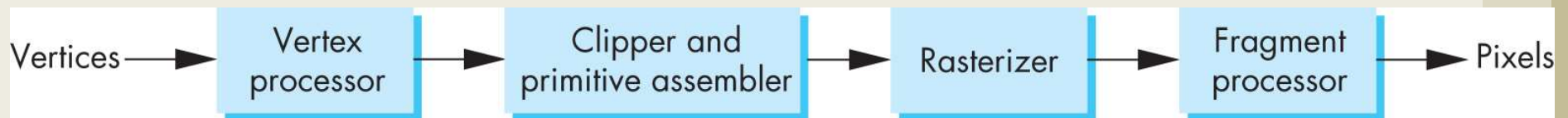
- ❑ Vertex shader must output in clip coordinates
- ❑ Input to fragment shader from rasterizer is in window coordinates
- ❑ Application can provide vertex data in any coordinate system but shader must eventually produce **gl_Position** in clip coordinates
- ❑ Simple example uses clip coordinates



Modern OpenGL

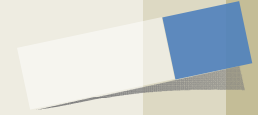


- ❑ Performance is achieved by using GPU rather than CPU
- ❑ **Control GPU through programs called shaders**
- ❑ **Application's job is to send data to GPU**
- ❑ GPU does all rendering





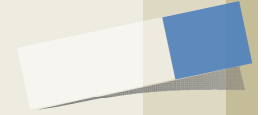
Immediate Mode Graphics



- ❑ Geometry specified by vertices
 - ❑ Locations in space(2 or 3 dimensional)
 - ❑ Points, lines, circles, polygons, curves, surfaces
- ❑ Immediate mode
 - ❑ Each time a vertex is specified in application, its location is sent to the GPU
 - ❑ Old style uses **glVertex**
 - ❑ **Creates bottleneck between CPU and GPU**
 - ❑ Removed from OpenGL 3.1 and OpenGL ES 2.0



Retained Mode Graphics



- ❑ Put all vertex attribute data in array
- ❑ Send array to GPU to be rendered immediately
- ❑ Almost OK but problem is we would have to send array over each time we need another render of it
- ❑ **Better to send array over and store on GPU for multiple renderings**

Programming with WebGL: More GLSL

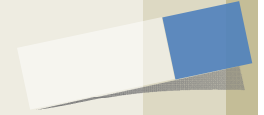


Linking Shaders with Application

- ❑ Read shaders
- ❑ Compile shaders
- ❑ Create a program object
- ❑ Link everything together
- ❑ Link variables in application with variables in shaders
 - Vertex attributes
 - Uniform variables



Program Object



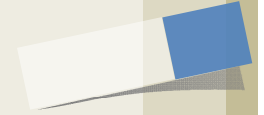
- ❑ **Container** for shaders
 - ▣ Can contain multiple shaders
 - ▣ Other GLSL functions

```
var program = gl.createProgram();
```

```
gl.attachShader( program, vertShdr );  
gl.attachShader( program, fragShdr );  
gl.linkProgram( program );
```



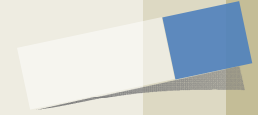
Reading a Shader



- ❑ Shaders are added to the program object and compiled
- ❑ Usual method of passing a shader is as a null-terminated string using the function
- ❑ `gl.shaderSource(fragShdr, fragElem.text);`
- ❑ If shader is in HTML file, we can get it into application by `getElementById` method
- ❑ If the shader is in a file, we can write a reader to convert the file to a string



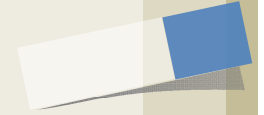
Adding a Vertex Shader



```
var vertShdr;  
var vertElem =  
    document.getElementById( vertexShaderId );  
  
vertShdr = gl.createShader( gl.VERTEX_SHADER );  
  
gl.shaderSource( vertShdr, vertElem.text );  
gl.compileShader( vertShdr );  
  
// after program object created  
gl.attachShader( program, vertShdr );
```



Shader Reader

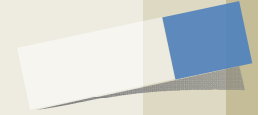


- ❑ Following code may be a security issue with some browsers if you try to run it locally
 - ▣ Cross Origin Request

```
function getShader(gl, shaderName, type) {  
    var shader = gl.createShader(type);  
    shaderScript = loadFileAJAX(shaderName);  
    if (!shaderScript) {  
        alert("Could not find shader source:  
            "+shaderName);  
    }  
}
```



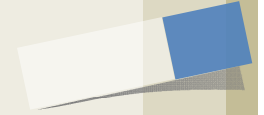
Precision Declaration



- ❑ In GLSL for WebGL we must specify desired precision in fragment shaders
 - ❑ artifact inherited from OpenGL ES
 - ❑ ES must run on very simple embedded devices that may not support 32-bit floating point
 - ❑ All implementations must support mediump
 - ❑ No default for float in fragment shader
- ❑ Can use preprocessor directives (`#ifdef`) to check if highp supported and, if not, default to mediump



Pass Through Fragment Shader



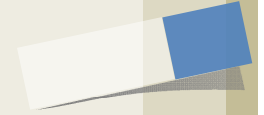
```
#ifdef GL_FRAGMENT_SHADER_PRECISION_HIGH
    precision highp float;
#else
    precision mediump float;
#endif

varying vec4 fcolor;
void main(void)
{
    gl_FragColor = fcolor;
}
```


Programming with WebGL: Three Dimensions



Objectives



- ❑ Develop a more sophisticated three-dimensional example
 - Sierpinski gasket: a fractal
- ❑ Introduce hidden-surface removal

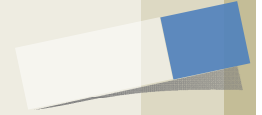


Three-dimensional Applications

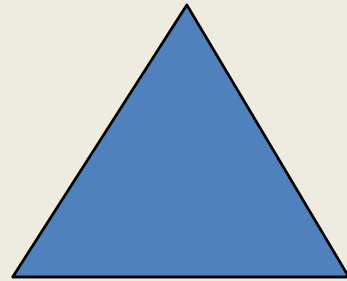
- ❑ In WebGL, two-dimensional applications are a special case of three-dimensional graphics
- ❑ Going to 3D
 - ❑ Not much changes
 - ❑ Use **vec3**, **gl.uniform3f**, ...
 - ❑ Have to worry about the order in which primitives are rendered or use hidden-surface removal



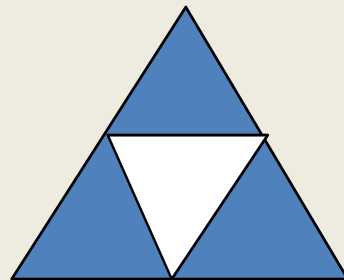
Sierpinski Gasket (2D)



- ❑ Start with a triangle



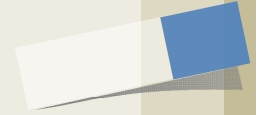
- ❑ Connect bisectors of sides and remove central triangle



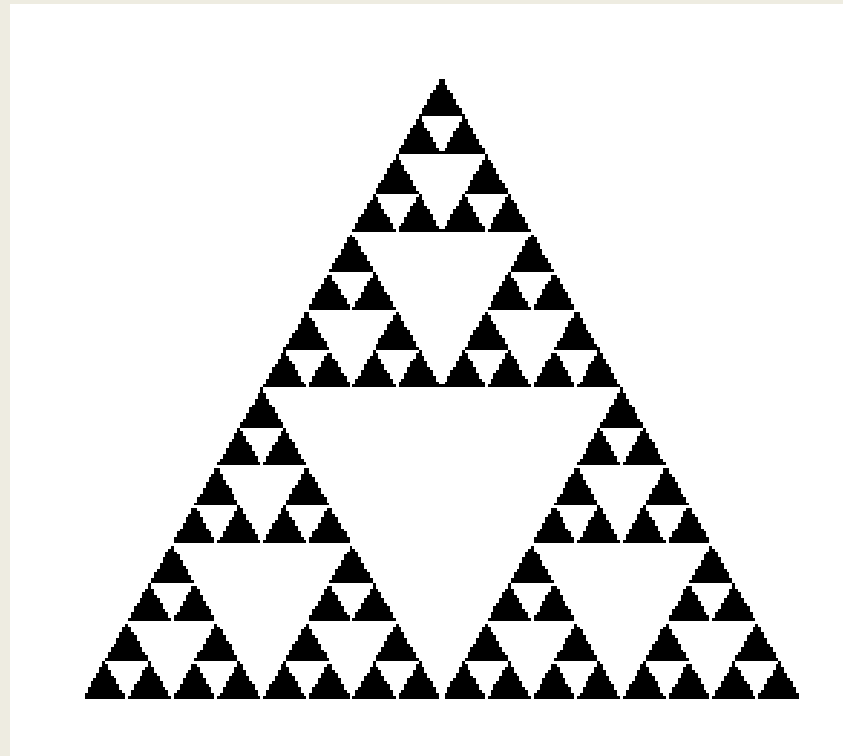
- ❑ Repeat



Example

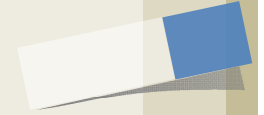


❑ Five subdivisions





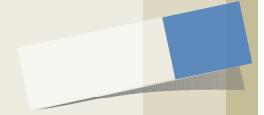
The gasket as a fractal



- ❑ Consider the filled area (black) and the perimeter (the length of all the lines around the filled triangles)
- ❑ As we continue subdividing
 - ❑ the area goes to zero
 - ❑ but the perimeter goes to infinity
- ❑ This is not an ordinary geometric object
 - ❑ It is neither two- nor three-dimensional
- ❑ It is a *fractal* (fractional dimension) object



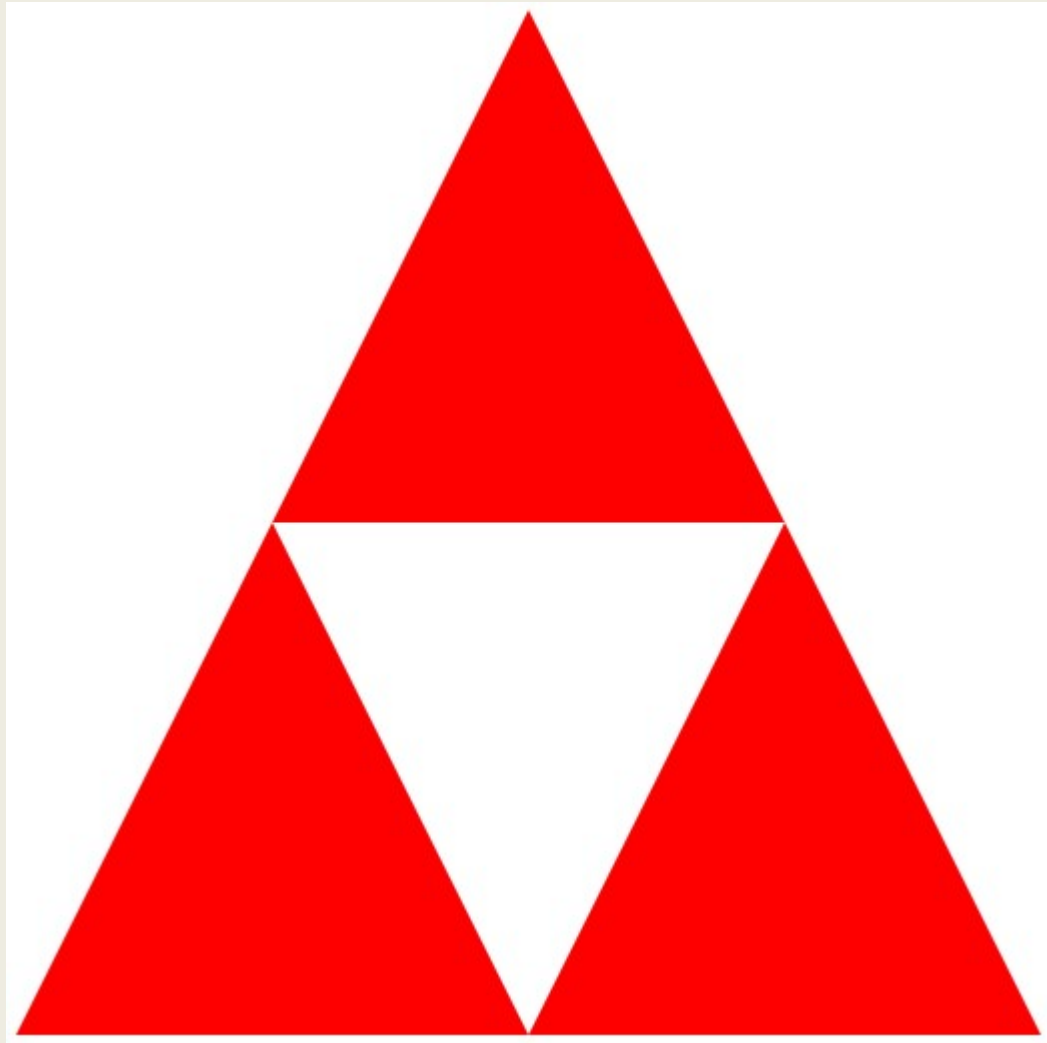
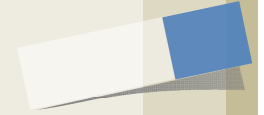
Gasket Program



- ❑ HTML file
 - ❑ Same as in other examples
 - ❑ Pass through vertex shader
 - ❑ Fragment shader sets color
 - ❑ Read in JS file

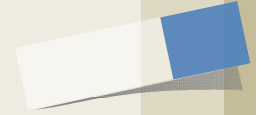


`gasket2.html`





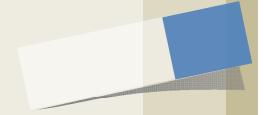
Gasket Program (gasket2.js)



```
var points = [];  
var NumTimesToSubdivide = 1;  
  
/* initial triangle */  
  
var vertices = [  
    vec2( -1, -1 ),  
    vec2(  0,  1 ),  
    vec2(  1, -1 )  
];  
  
divideTriangle( vertices[0], vertices[1],  
                vertices[2], NumTimesToSubdivide );
```



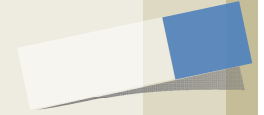
Draw one triangle



```
/* display one triangle */  
  
function triangle( a, b, c ){  
    points.push( a, b, c );  
}
```



Triangle Subdivision



```
function divideTriangle( a, b, c, count ){
```

```
    // check for end of recursion
    if ( count === 0 ) {
        triangle( a, b, c );
    }
```

```
    else {
```

```
        //bisect the sides
```

```
        var ab = mix( a, b, 0.5 );
```

```
        var ac = mix( a, c, 0.5 );
```

```
        var bc = mix( b, c, 0.5 );
```

```
        --count;
```

```
        // three new triangles
```

```
        divideTriangle( a, ab, ac, count-1 );
```

```
        divideTriangle( c, ac, bc, count-1 );
```

```
        divideTriangle( b, bc, ab, count-1 );
```

```
    }
```

```
}
```

```
/* display one triangle */
```

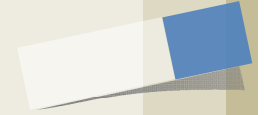
```
function triangle( a, b, c ){
```

```
    points.push( a, b, c );
```

```
}
```



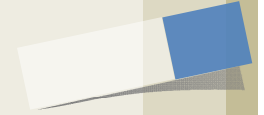
init()



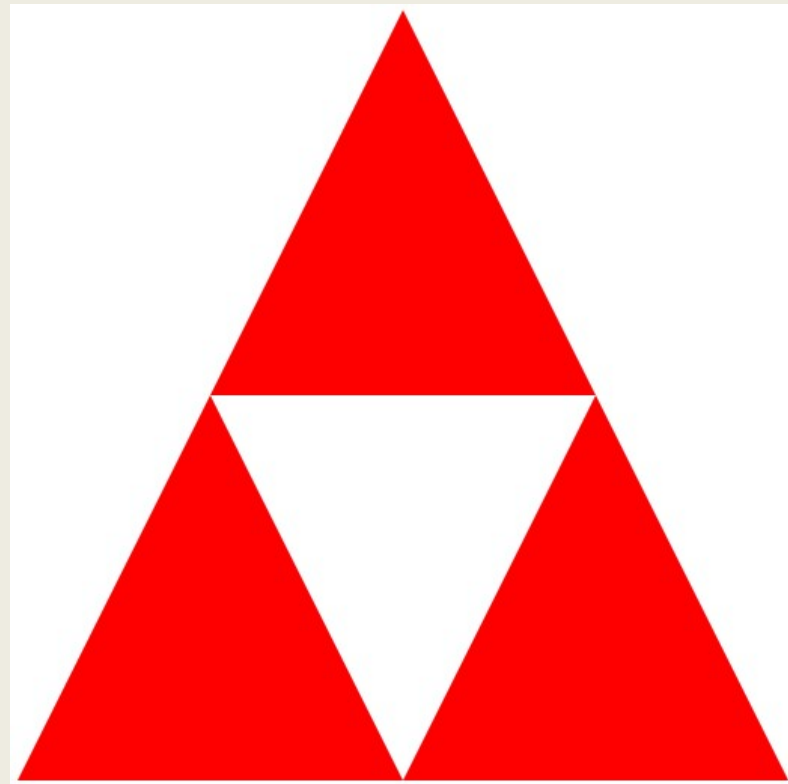
```
var program = initShaders( gl, "vertex-shader",  
    "fragment-shader" );  
gl.useProgram( program );  
var bufferId = gl.createBuffer();  
gl.bindBuffer( gl.ARRAY_BUFFER, bufferId );  
gl.bufferData( gl.ARRAY_BUFFER, flatten(points),  
    gl.STATIC_DRAW );  
  
var vPosition = gl.getAttributeLocation( program,  
    "vPosition" );  
gl.vertexAttribPointer( vPosition, 2, gl.FLOAT, false,  
    0, 0 );  
gl.enableVertexAttribArray( vPosition );  
render();
```



Render Function



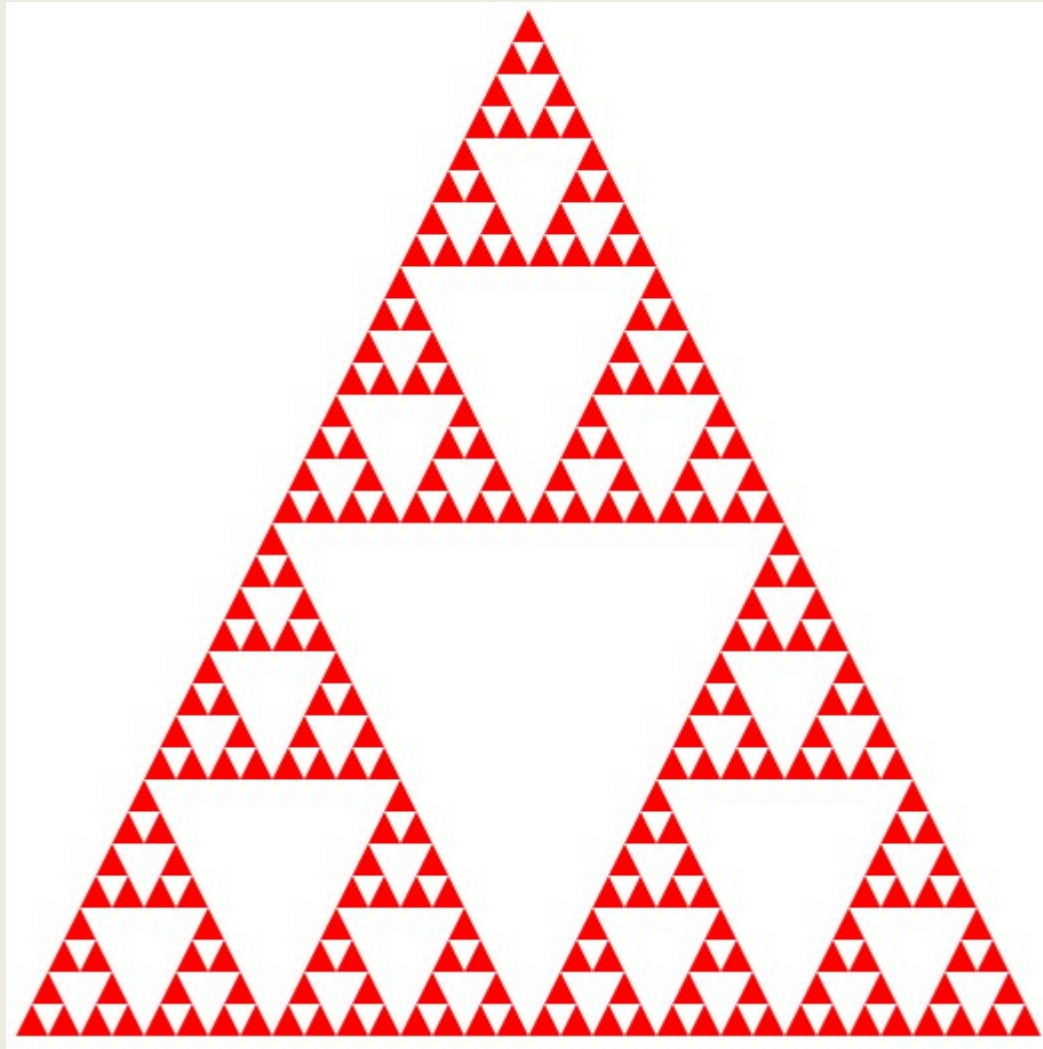
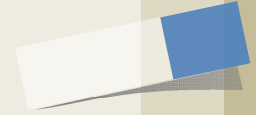
```
function render(){  
    gl.clear( gl.COLOR_BUFFER_BIT );  
    gl.drawArrays( gl.TRIANGLES, 0, points.length );  
}
```





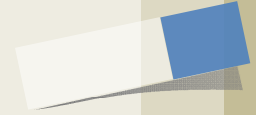
gasket2.html

```
var NumTimesToSubdivide = 5;
```

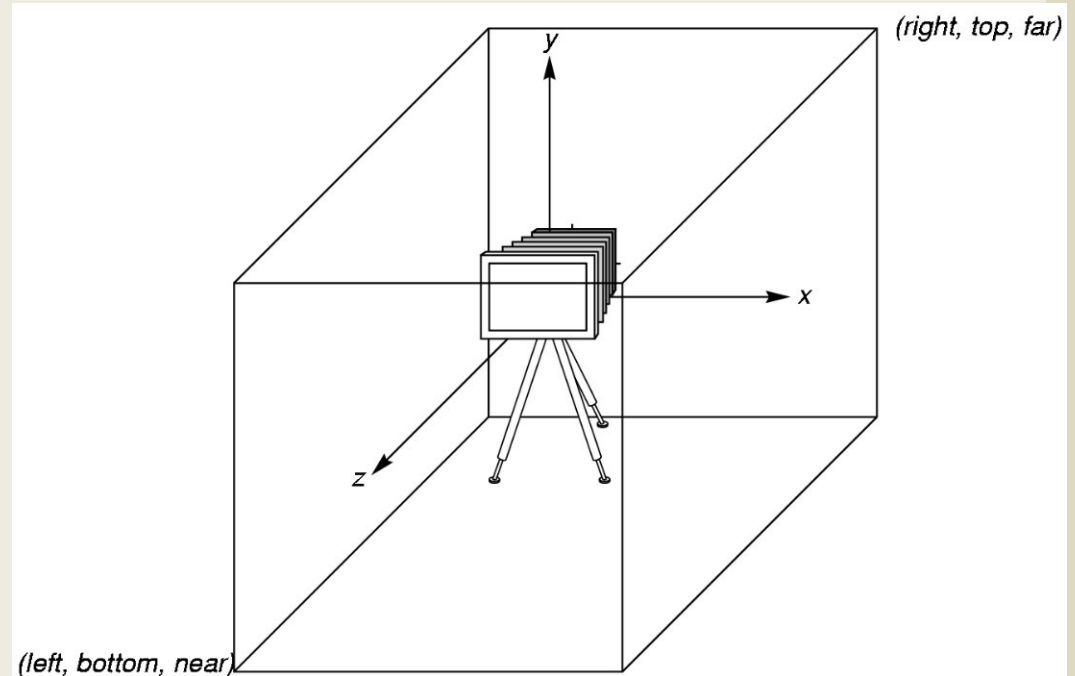




WebGL Camera



- ❑ WebGL places a camera at the origin in object space pointing in the negative z direction
- ❑ The default viewing volume is a box centered at the origin with sides of length 2





The Orthographic Viewing

$$(x, y, z) \rightarrow (x, y, 0)$$

- ❑ The simplest and OpenGL's **default view** is the orthographic projection.
 - ❑ Unlike a real camera, the orthographic projection can include objects behind the camera. Thus, because the plane $z = 0$ is located between -1 and 1 , the two-dimensional plane intersects the viewing volume.
 - ❑ We discuss this projection and others in detail in Chapter 4.

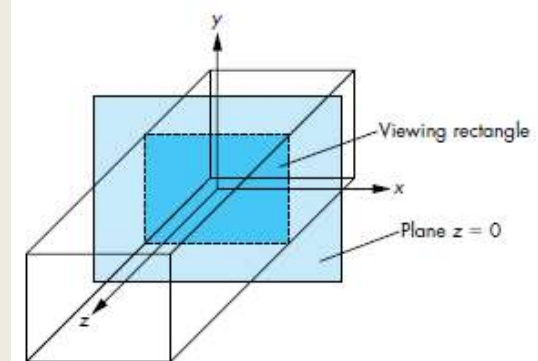
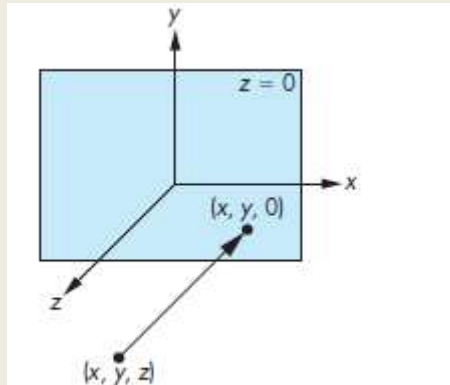
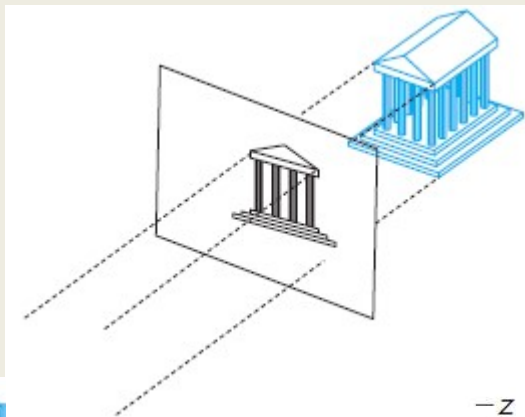
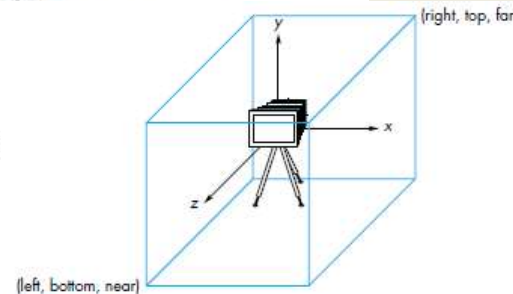
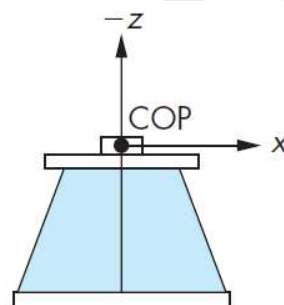


FIGURE 2.34 Viewing volume.



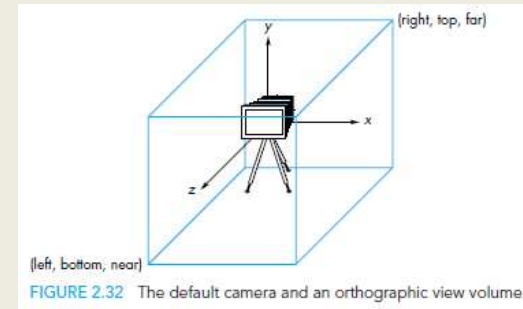
(left, bottom, near)
FIGURE 2.32 The default camera and an orthographic view volume.



Moving to 3D

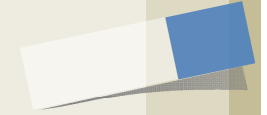
- ❑ We can easily make the program three-dimensional by using three dimensional points and starting with a tetrahedron

```
var vertices = [  
    vec3( 0.0000, 0.0000, -1.0000 ),  
    vec3( 0.0000, 0.9428, 0.3333 ),  
    vec3( -0.8165, -0.4714, 0.3333 ),  
    vec3( 0.8165, -0.4714, 0.3333 )  
];  
subdivide each face
```

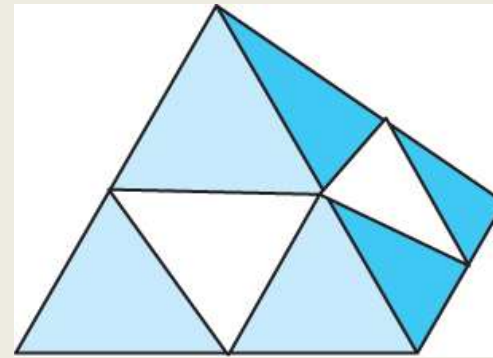
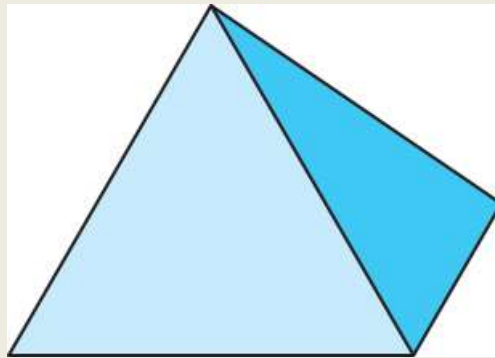




3D Gasket



- ❑ We can subdivide each of the four faces

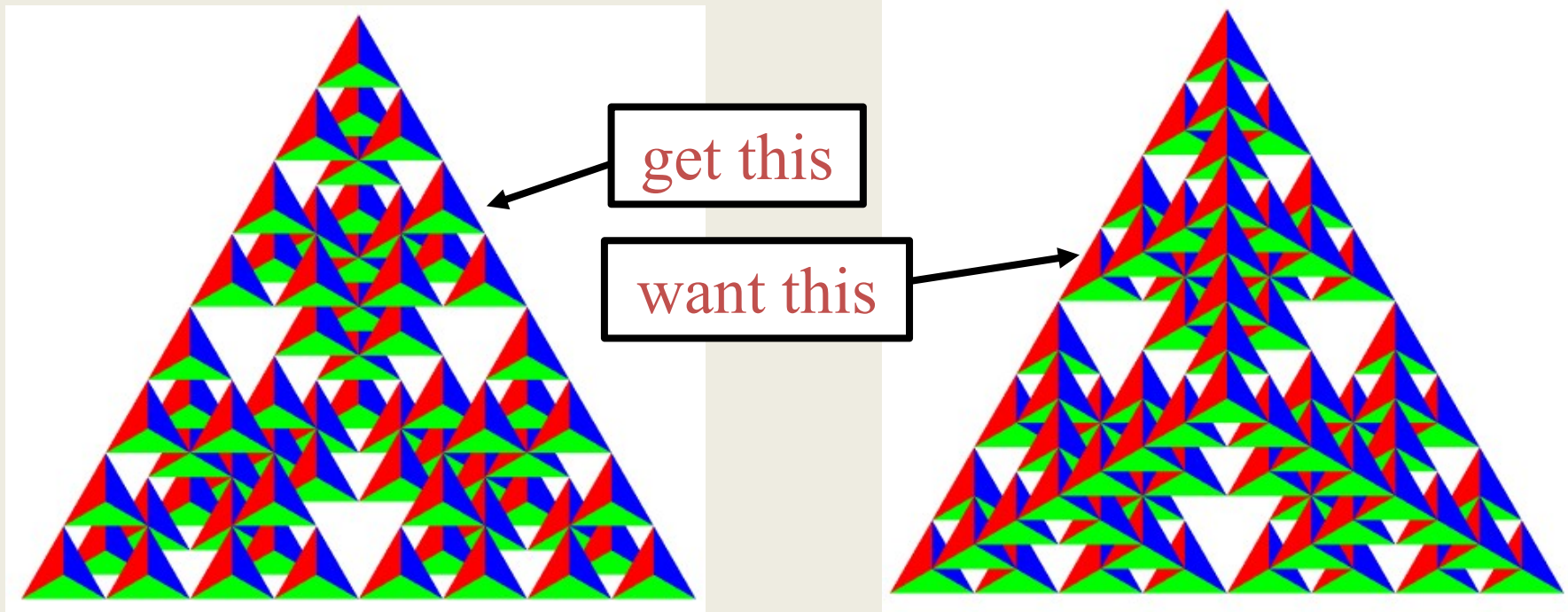


- ❑ Appears as if we remove a solid tetrahedron from the center leaving four smaller tetrahedra
- ❑ Code almost identical to 2D example



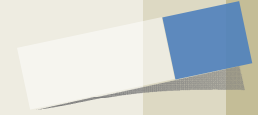
Almost Correct

- ❑ Because the triangles are drawn in the order they are specified in the program, the front triangles are not always rendered in front of triangles behind them.

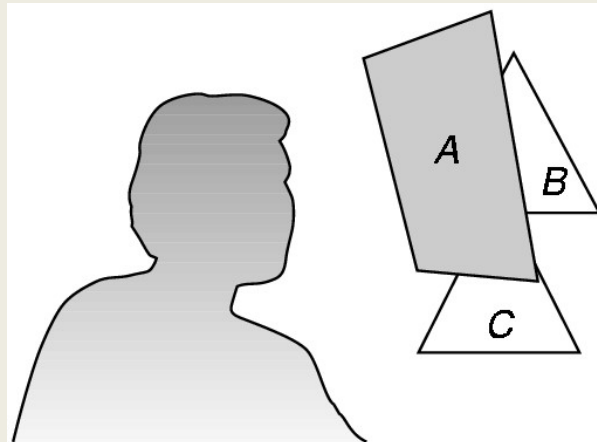




Hidden-Surface Removal



- ❑ We want to see only those surfaces in front of other surfaces
- ❑ OpenGL uses a *hidden-surface* method called the z-buffer algorithm that saves depth information as objects are rendered so that only the front objects appear in the image



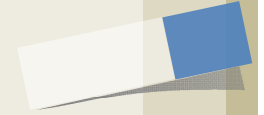


Using the z-buffer algorithm

- ❑ The algorithm uses an extra buffer, the z-buffer, to store depth information as geometry travels down the pipeline
- ❑ Depth buffer is required to be available in WebGL
- ❑ It must be
 - ▣ Enabled
 - ▣ `gl.enable(gl.DEPTH_TEST)`
 - ▣ Cleared in for each render
 - ▣ `gl.clear(gl.COLOR_BUFFER_BIT | gl.DEPTH_BUFFER_BIT)`

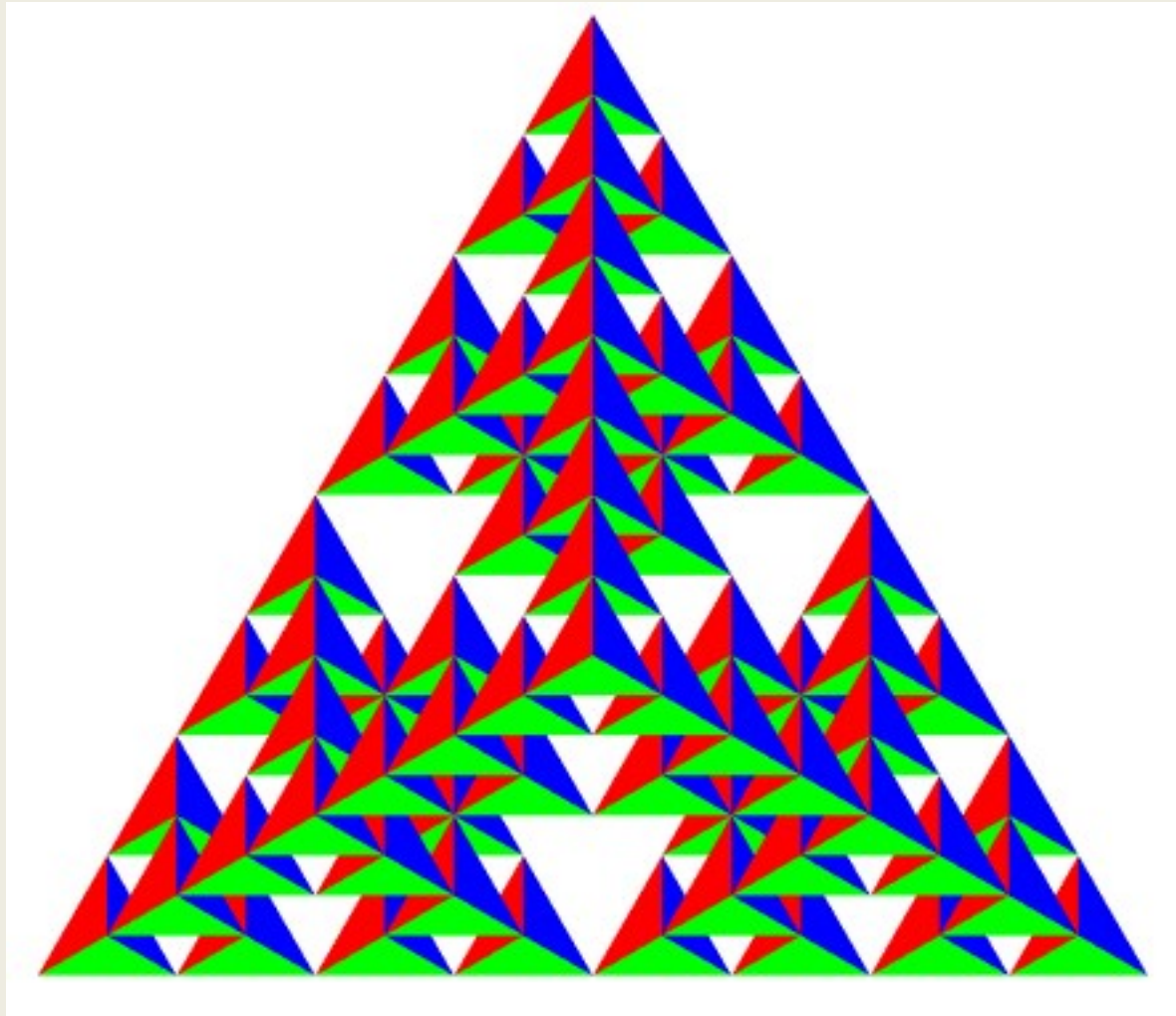


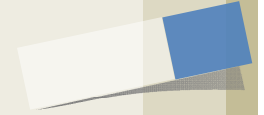
Surface vs Volume Subdivision



- ❑ In our example, we divided the surface of each face
- ❑ We could also divide the volume using the same midpoints
- ❑ The midpoints define four smaller tetrahedrons, one for each vertex
- ❑ Keeping only these tetrahedrons removes a *volume* in the middle
- ❑ See text for code

Volume Subdivision(gasket4.html)

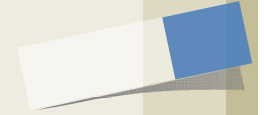




(Optional) Polygon + α



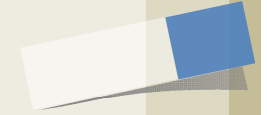
Polygon Testing



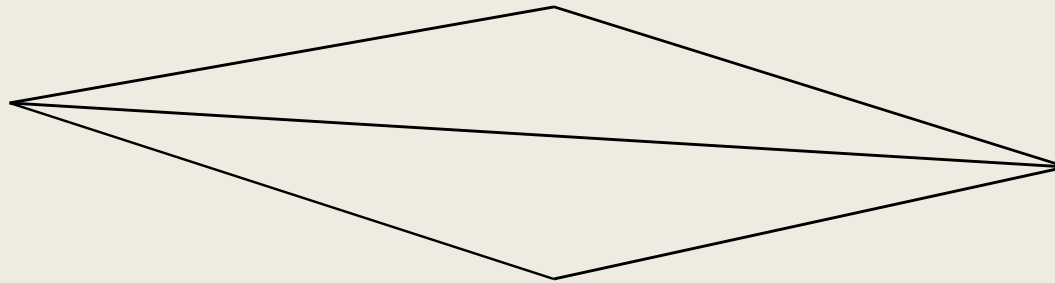
- ❑ Conceptually simple to test for simplicity and convexity
- ❑ Time consuming
- ❑ Earlier versions assumed both and left testing to the application
- ❑ Present version only renders triangles
- ❑ Need algorithm to triangulate an arbitrary polygon



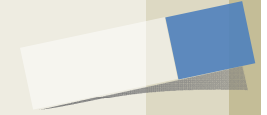
Good and Bad Triangles



- ❑ Long thin triangles render badly



- ❑ Equilateral triangles render well
- ❑ Maximize minimum angle
- ❑ Delaunay triangulation for unstructured points



Recursive Division

- Find leftmost vertex and split

