

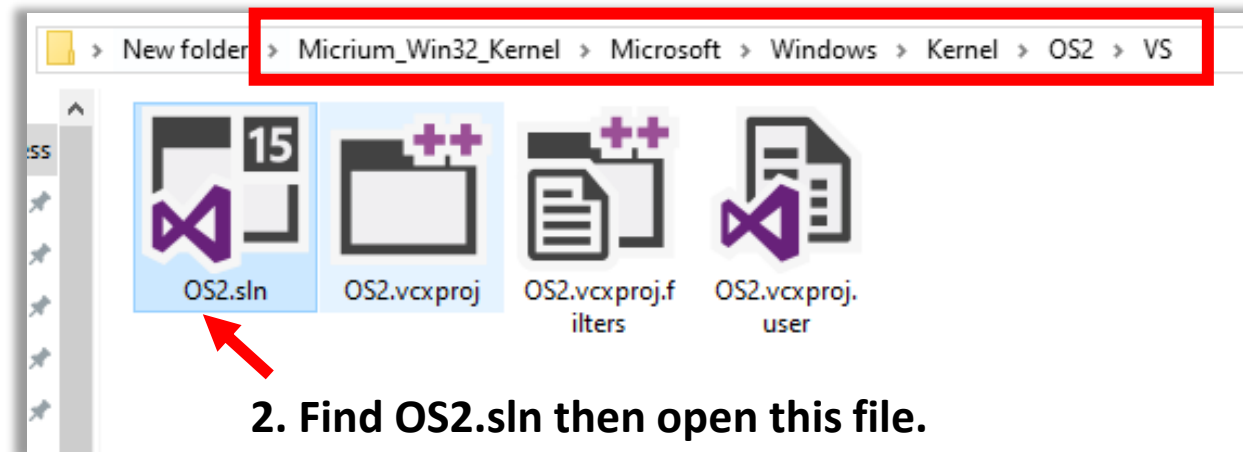
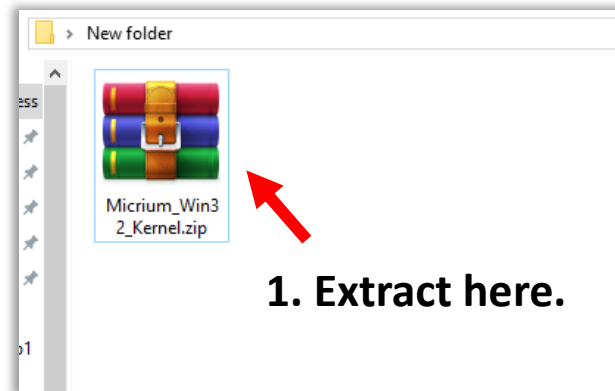
Run μ C/OS-II

2025/10/02

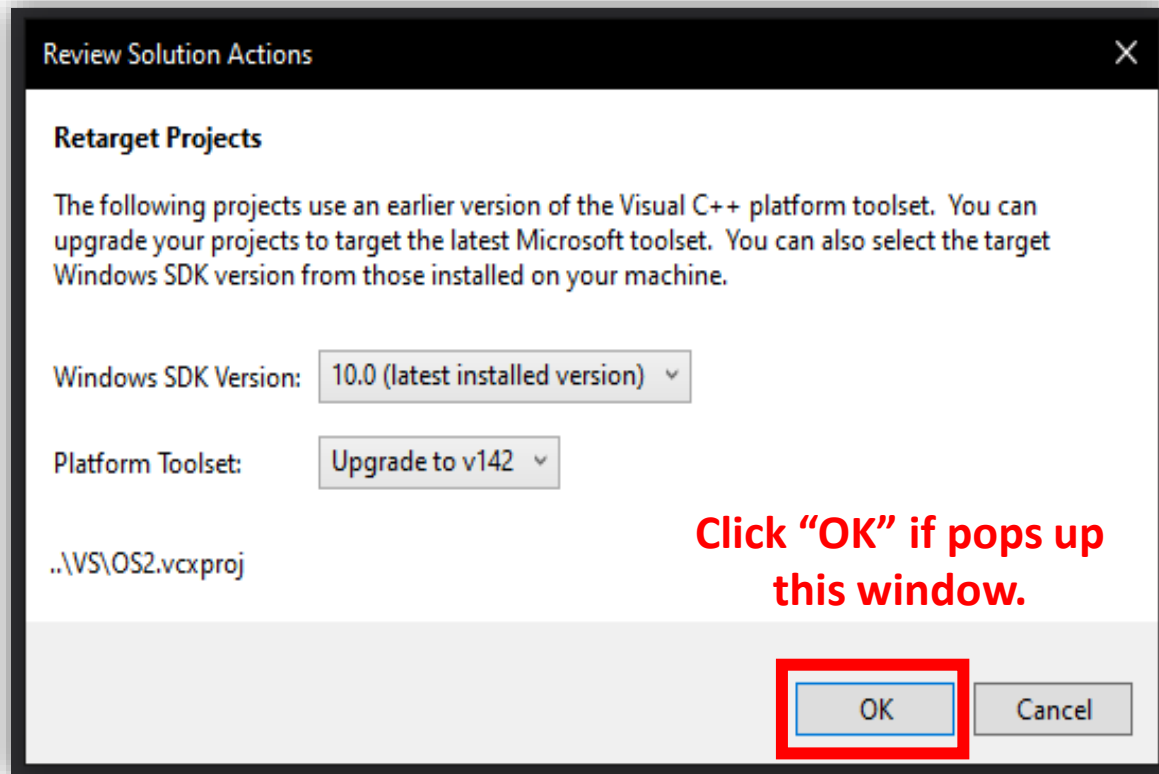
Outline

- Open example project
- Find μ C/OS-II source code
- Run example project
- Modify example project
- Create the initial tasks of HW1
- Debug mode

Open example project



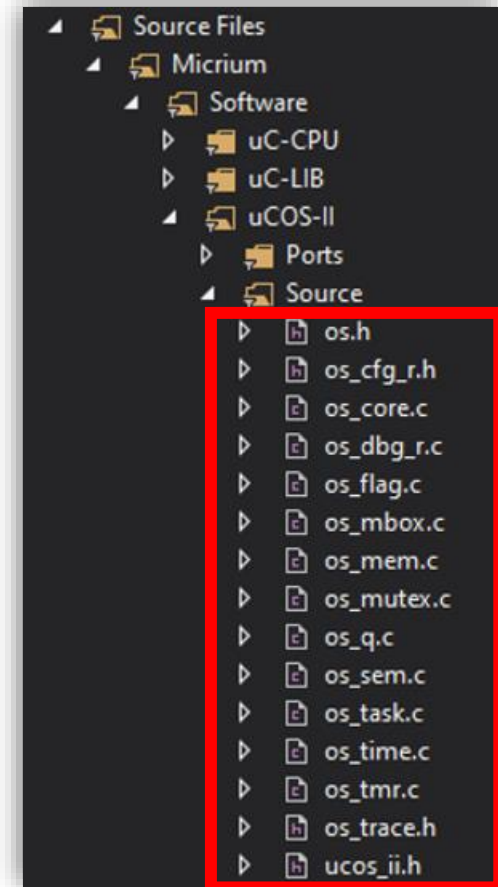
Open example project



Find μ C/OS-II source code

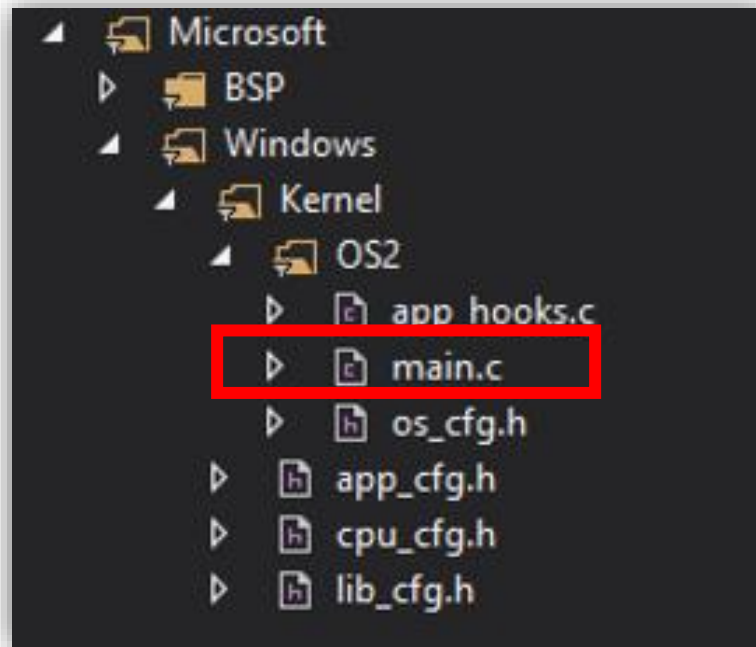
- Source code path:

Source Files\Micrium\Software\uCOSII\
Source



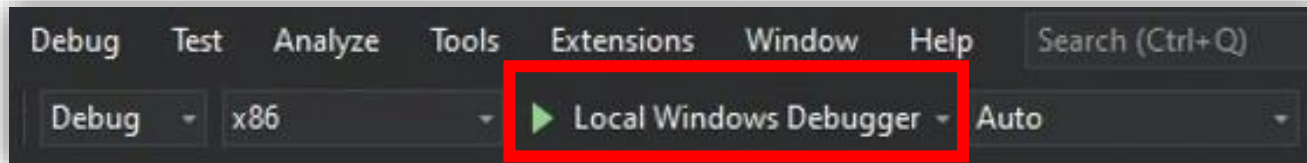
Find μ C/OS-II source code

- Main.c path: Microsoft\Windows\Kernel\OS2



Run example project

- Open `main.c` and then click “Local Windows Debugger” or press F5.



Run example project

- You can see the **tasks information** in command prompt if the project has been run successfully.

```
OSTick    created, Thread ID 24144
Task[ 63] created, Thread ID 10180
Task[ 62] created, Thread ID 24488
Task[ 61] created, Thread ID 14892
Task[  3] created, Thread ID 14728
Task[  3] 'Startup Task' Running
uCOS-III is Running...
Task[ 61] 'uC/OS-II Tmr' Running
Task[ 62] 'uC/OS-II Stat' Running
Task[ 63] 'uC/OS-II Idle' Running
Time: 100
Time: 200
Time: 300
Time: 400
Time: 500
```

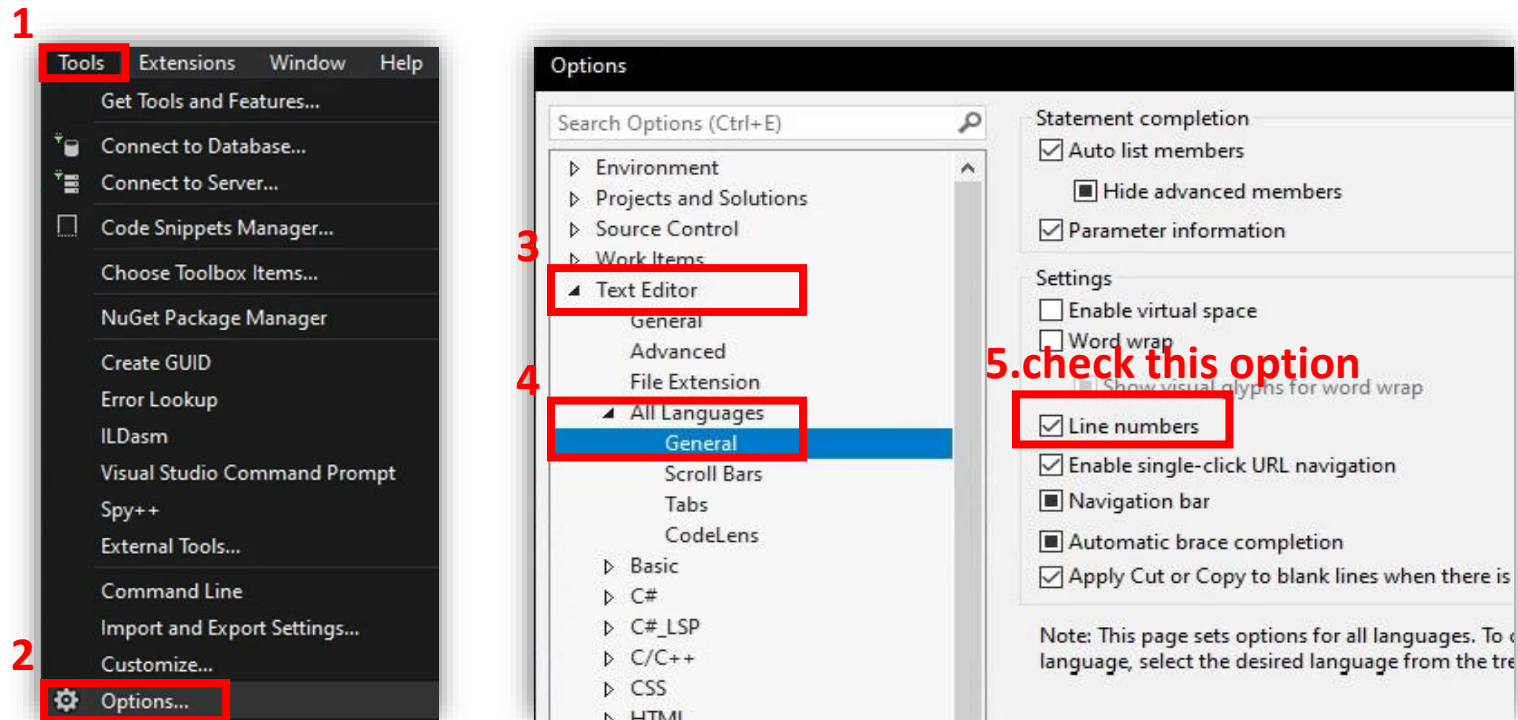

Modify example project

- You need to disable two tasks and messages **before submitting your project.**

```
OSTick    created, Thread ID  452
Task[ 63] created, Thread ID 10768
Task[ 62] created, Thread ID  1548
Task[ 61] created, Thread ID 10696
Task[  3] created, Thread ID 17848
Task[  3] 'Startup Task' Running
uCOS-III is Running...
Task[ 61] 'uC/OS-II Tmr' Running
Task[ 62] 'uC/OS-II Stat' Running
Task[ 63] 'uC/OS-II Idle' Running
Time: 100
Time: 200
Time: 300
Time: 401
Time: 501
Time: 601
Time: 701
```

Modify example project

- First, open the line numbers.



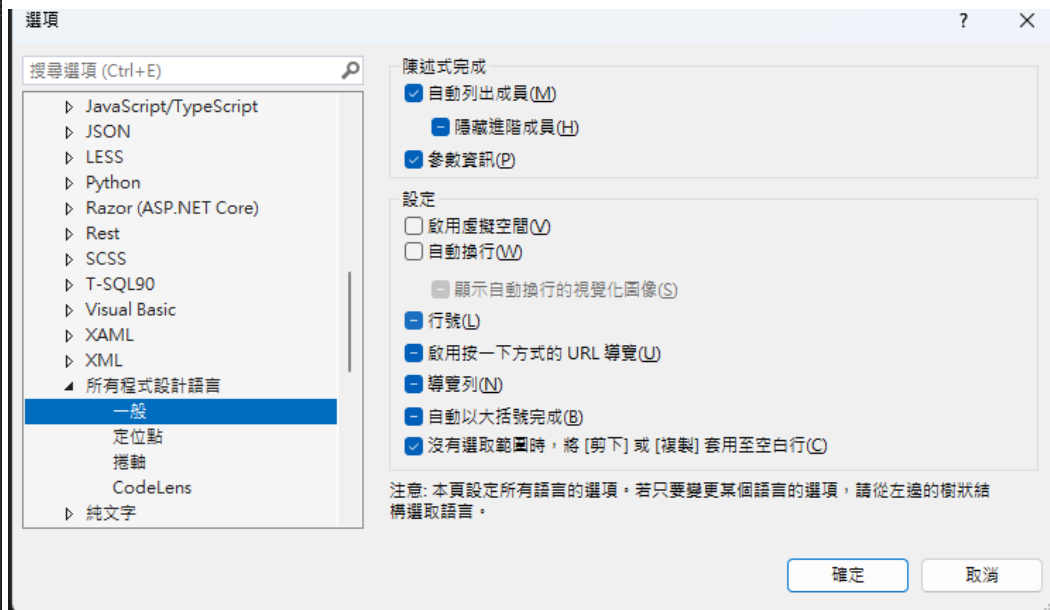
Modify example project

- First, open the line numbers.

1



2

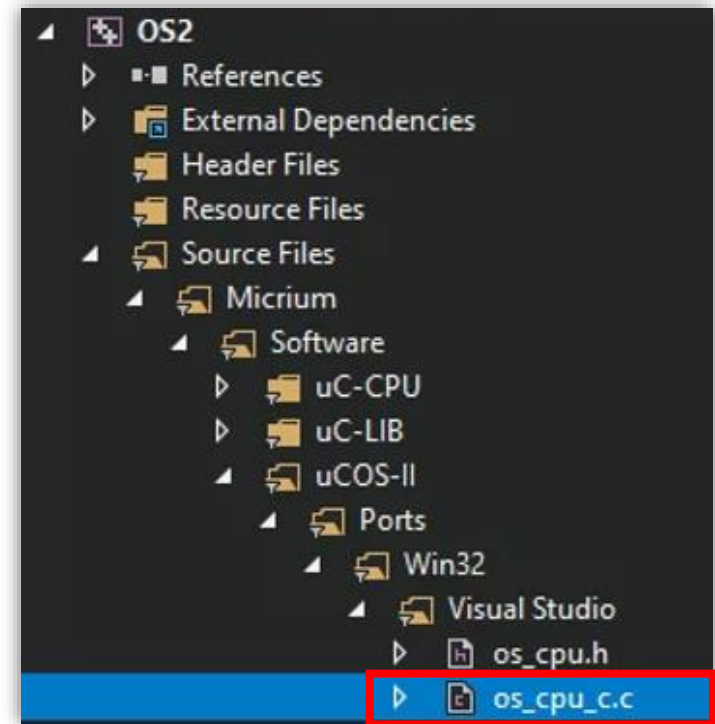


Modify example project

- Find **os_cpu.c.c** and then open it.

- os_cpu.c.c path:

Micrium\Software\uCOSII\Ports\
Win32\Visual Studio



Modify example project

- Comment out the 1237th line.

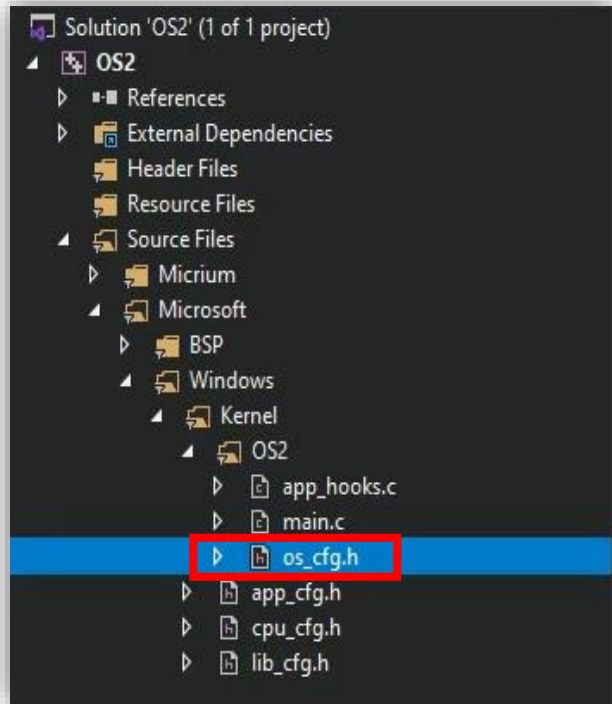
```
1236  #if (OS_MSG_TRACE > 0u)
1237  OS_Printf("Task[%3.1d] '%s' Running\n", p_tcb->OSTCBPrio, p_tcb->OSTCBTaskName);
1238  #endif
```



```
1236  #if (OS_MSG_TRACE > 0u)
1237  //OS_Printf("Task[%3.1d] '%s' Running\n", p_tcb->OSTCBPrio, p_tcb->OSTCBTaskName);
1238  #endif
```

Modify example project

- Next, find **os_cfg.h** and then open it.



- **os_cfg.h** path:
Micrium_Win32_Kernel\
Microsoft\Windows\Kernel\OS2

Modify example project

- Go to the 71th line and 139th line and then **DISABLE** them.

```
70  #define OS_TASK_REG_TBL_SIZE      1u  /* Size of task variables array (#of INT32U entries)
71  #define OS_TASK_STAT_EN Task[62]  1u  /* Enable (1) or Disable(0) the statistics task
72  #define OS_TASK_STAT_STK_CHK_EN  1u  /* Check task stacks from statistic task
```

```
138  /* ----- TIMER MANAGEMENT -----
139  #define OS_TMR_EN Task[61]  1u  /* Enable (1) or Disable (0) code generation for TIMERS
140  #define OS_TMR_CFG_MAX      16u  /* Maximum number of timers
```



```
70  #define OS_TASK_REG_TBL_SIZE      1u  /* Size of task variables array (#of INT32U entries)
71  #define OS_TASK_STAT_EN           0u  /* Enable (1) or Disable(0) the statistics task
72  #define OS_TASK_STAT_STK_CHK_EN  1u  /* Check task stacks from statistic task
```

```
138  /* ----- TIMER MANAGEMENT ----- *
139  #define OS_TMR_EN           0u  /* Enable (1) or Disable (0) code generation for TIMERS *
140  #define OS_TMR_CFG_MAX      16u  /* Maximum number of timers *
```

Modify example project

- Finally, **rerun this project** and you can see the modified tasks information.

```
OSTick    created, Thread ID 17868
Task[ 63] created, Thread ID 18020
Task[  3] created, Thread ID 18740
uCOS-III is Running...
Time: 100
Time: 200
Time: 300
Time: 400
Time: 500
Time: 600
Time: 700
Time: 800
Time: 900
Time: 1000
Time: 1100
Time: 1200
```


Modify example project

- Go to `os_cfg.h` and then set 1 tick in 1 second.

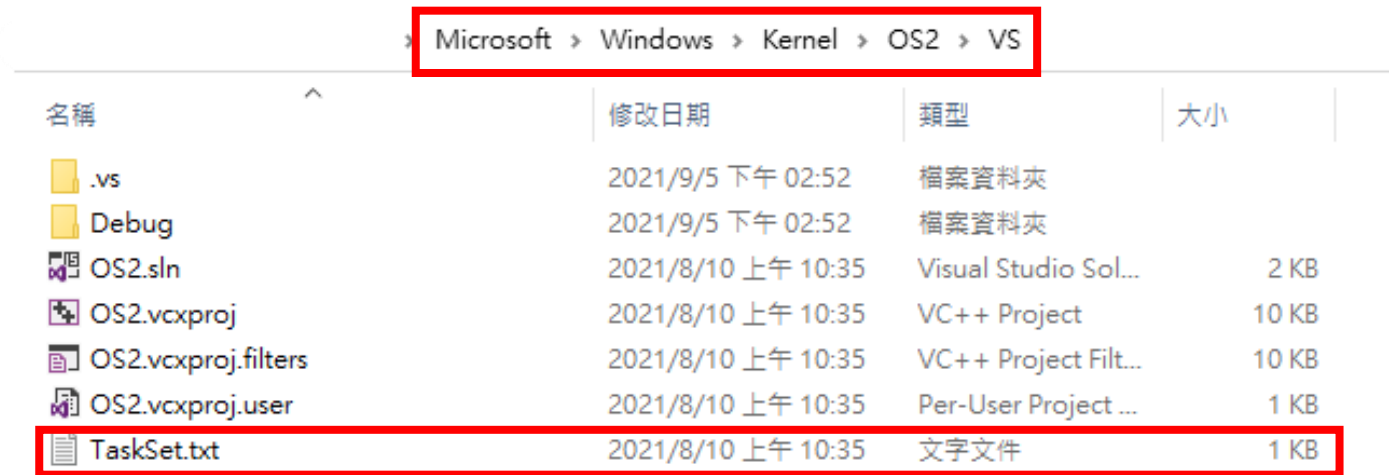
```
49  
50 #define OS_TICK_STEP_EN      1u  /* Enable tick stepping feature for uC/OS-View  
51 #define OS_TICKS_PER_SEC    100u /* Set the number of ticks in one second  
52
```



```
50 #define OS_TICK_STEP_EN      1u  /* Enable tick stepping feature for uC/OS-View  
51 #define OS_TICKS_PER_SEC    1u  /* Set the number of ticks in one second  
52  
53 #define OS_TLS_TBL_SIZE      0u  /* Size of Thread-Local Storage Table
```

Create the initial tasks of HW1

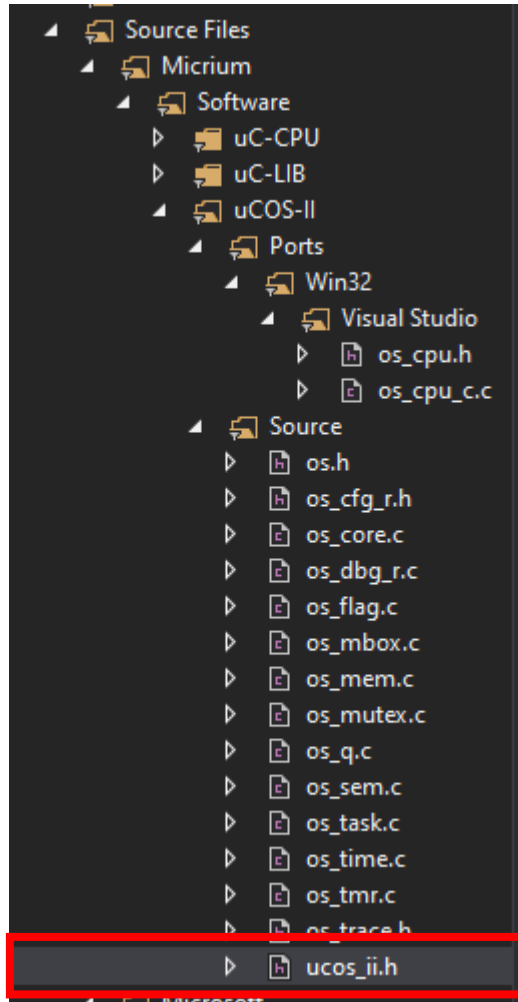
- Download input TaskSet.txt from Moodle.
- Move the file to the path
Micrium_Win32_Kernel\Microsoft\Windows\Kernel\OS2



Microsoft > Windows > Kernel > OS2 > VS				
名稱	修改日期	類型	大小	
.vs	2021/9/5 下午 02:52	檔案資料夾		
Debug	2021/9/5 下午 02:52	檔案資料夾		
OS2.sln	2021/8/10 上午 10:35	Visual Studio Sol...	2 KB	
OS2.vcxproj	2021/8/10 上午 10:35	VC++ Project	10 KB	
OS2.vcxproj.filters	2021/8/10 上午 10:35	VC++ Project Filt...	10 KB	
OS2.vcxproj.user	2021/8/10 上午 10:35	Per-User Project ...	1 KB	
TaskSet.txt	2021/8/10 上午 10:35	文字文件	1 KB	

Create the initial tasks of HW1

- Go to `ucos_ii.h`



- `ucos_ii.h` path:
Micrium_Win32_Kernel\Micrium
\Software\uCOS-II\Source

Create the initial tasks of HW1

- Then, include <string.h> and add some parameter structure in ucos_ii.h

```
58  /*read file*/  
59  #include <string.h>
```

```
67  /*End time for the simulation*/  
68  #define SYSTEM_END_TIME 30  
69  
70  /*Input File*/  
71  FILE* fp;  
72  #define INPUT_FILE_NAME "./TaskSet.txt"  
73  #define OUTPUT_FILE_NAME "./Output.txt"  
74  #define MAX 20           //Task maximum number  
75  #define INFO 4           //information of task  
76  /*Input File*/  
77  
78  /*Output file*/  
79  FILE* Output_fp;  
80  errno_t Output_err;  
81  /*Output file*/
```

Notice:
Please make sure filenames are same as the figure.

Hints:
Parameters may be modified by different project

Create the initial tasks of HW1

- Then, include <string.h> and add some parameter structure in ucos_ii.h

```
83  /*Task structure */
84  typedef struct task_para_set {
85      INT16U TaskID;
86      INT16U TaskArriveTime;
87      INT16U TaskExecutionTime;
88      INT16U TaskPeriodic;
89      INT16U TaskNumber;
90      INT16U TaskPriority;
91  }task_para_set;
92
93  int TASK_NUMBER;
94  OS_STK** Task_STK;
95  task_para_set TaskParameter[OS_MAX_TASKS];
```

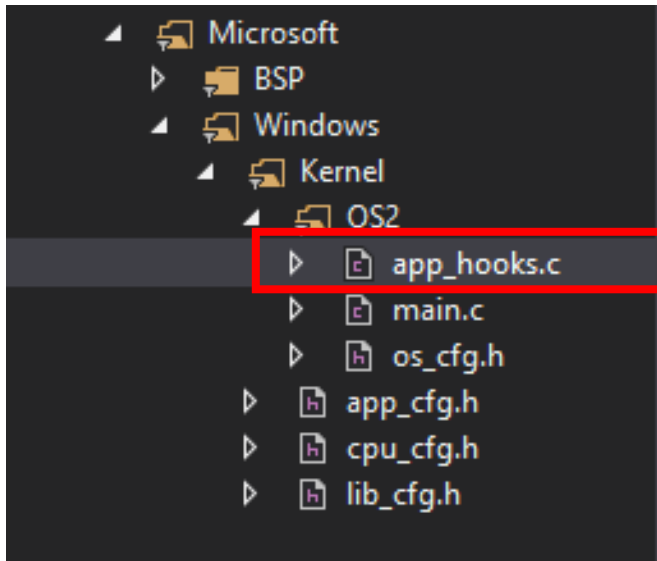
Create the initial tasks of HW1

- Then, include <string.h> and add some parameter structure in ucos_ii.h

```
1477 void      App_TaskReturnHook  (OS_TCB      *ptcb);
1478
1479 void      App_TaskStatHook    (void);
1480
1481 #if OS_TASK_SW_HOOK_EN > 0u
1482 void      App_TaskSwHook      (void);
1483 #endif
1484
1485 void      App_TCBInitHook      (OS_TCB      *ptcb);
1486
1487 #if OS_TIME_TICK_HOOK_EN > 0u
1488 void      App_TimeTickHook     (void);
1489 #endif
1490
1491 void      OutFileInit(void);
1492 void      InputFile(void);
1493 #endif
1494
1495 /*
1496 *****
1497 *                                     FUNCTION PROTOTYPES
1498 *
1499 * IMPORTANT: These prototypes MUST be placed in OS_CPU.H
1500 *****
1501 */
1502
1503 #if 0
1504 void      OSStartHighRdy      (void);
1505 void      OSIntCtxSw          (void);
1506 void      OSCtxSw             (void);
1507 #endif
1508
1509
```

Create the initial tasks of HW1

- Go to `app_hooks.c` and then add two functions.



- `app_hooks.c` path:
Micrium_Win32_Kernel\Microsoft\Windows\Kernel\OS2

Create the initial tasks of HW1

- Then, add two functions in `app_hooks.c`

```
91 void OutFileInit() {
92     /*Clear the file*/
93     if ((Output_err = fopen_s(&Output_fp, OUTPUT_FILE_NAME, "w")) == 0)
94         fclose(Output_fp);
95     else
96         printf("Error to clear output file");
97 }
```

```
99 void InputFile() {
100     /*
101      * Read File
102      * Task Information:
103      * Task_ID ArriveTime ExecutionTime Periodic
104      */
105     errno_t err;
106     if ((err = fopen_s(&fp, INPUT_FILE_NAME, "r")) == 0)        /*task set 1-4*/
107     {
108         printf("The file 'TaskSet.txt' was opened\n");
109     }
110     else
111     {
112         printf("The file 'TaskSet.txt' was not opened\n");
113     }
114
115     char str[MAX];
116     char* ptr;
117     char* pTmp = NULL;
118     int TaskInfo[INFO], i, j = 0;
119     TASK_NUMBER = 0;
```


Create the initial tasks of HW1

- Then, add two functions in `app_hooks.c`

```
120 while (!feof(fp))
121 {
122     i = 0;
123     memset(str, 0, sizeof(str));
124     fgets(str, sizeof(str) - 1, fp);
125     ptr = strtok_s(str, " ", &pTmp);
126     while (ptr != NULL)
127     {
128         TaskInfo[i] = atoi(ptr);
129         ptr = strtok_s(NULL, " ", &pTmp);
130         /*printf("Info: %d\n", task_inf[i]);*/
131         if (i == 0) {
132             TASK_NUMBER++;
133             TaskParameter[j].TaskID = TASK_NUMBER;
134         }
135         else if (i == 1)
136             TaskParameter[j].TaskArriveTime = TaskInfo[i];
137         else if (i == 2) {
138             TaskParameter[j].TaskExecutionTime = TaskInfo[i];
139         }
140         else if (i == 3)
141             TaskParameter[j].TaskPeriodic = TaskInfo[i];
142
143         i++;
144     }
145
146     /*Initial Priority*/
147     TaskParameter[j].TaskPriority = j; //just an example
148
149     j++;
150 }
151 fclose(fp);
152 /*read file*/
153 }
```

Notice:
Here has a space in
strotok_s function

Hints:
Initial priority can be
fixed when use
different scheduling.

Create the initial tasks of HW1

- You need to declare the task **stack size** and as **GLOBAL** variables in main.c.

```
51  /*
52  ****
53  *                                LOCAL GLOBAL VARIABLES
54  ****
55  */
56
57  #define TASK_STACKSIZE          2048
58
```

Create the initial tasks of HW1

- Initial the output file and read the input file in main function.
- Create Stack Size for every task in main function.

```
99      /*Initialize Output File*/
100     OutFileInit();
101
102     /*Input File*/
103     InputFile();
```

```
105     /*Dynamic Create the Stack size*/
106     Task_STK = malloc(TASK_NUMBER * sizeof(int*));
107
108     /* for each pointer, allocate storage for an array of ints */
109     int n;
110     for (n = 0; n < TASK_NUMBER; n++) {
111         Task_STK[n] = malloc(TASK_STACKSIZE * sizeof(int));
112     }
```

Create the initial tasks of HW1

- Declare and define task function.

```
65 static void task1(void* p_arg);  
66 static void task2(void* p_arg);  
67
```

```
141  
142 void task1(void* p_arg) {  
143     task_para_set* task_data;  
144     task_data = p_arg;  
145     while (1)  
146     {  
147         printf("Tick: %d, Hello from task%d\n", OSTime, task_data->TaskID);  
148         OSTimeDly(task_data->TaskPeriodic);  
149     }  
150 }  
151  
152 void task2(void* p_arg) {  
153     task_para_set* task_data;  
154     task_data = p_arg;  
155     while (1)  
156     {  
157         printf("Tick: %d, Hello from task%d\n", OSTime, task_data->TaskID);  
158         OSTimeDly(task_data->TaskPeriodic);  
159     }  
160 }
```

Create the initial tasks of HW1

- Add this part when you print the output information.
- Then, you can write the output in Output.txt.

```
printf("Tick: %d, Hello from task%d\n", OSTime, task_data->TaskID);
```



```
printf("Tick: %d, Hello from task%d\n", OSTime, task_data->TaskID);  
if ((Output_err = fopen_s(&Output_fp, "./Output.txt", "a")) == 0)  
{  
    fprintf(Output_fp, "Tick: %d, Hello from task%d\n", OSTime, task_data->TaskID);  
    fclose(Output_fp);  
}
```

Output.txt - 記事本

檔案(F) 編輯(E) 格式(O) 檢視(V)

```
Tick: 0, Hello from task1  
Tick: 0, Hello from task2  
Tick: 3, Hello from task1  
Tick: 6, Hello from task1  
Tick: 6, Hello from task2  
Tick: 9, Hello from task1  
Tick: 12, Hello from task1  
Tick: 12, Hello from task2  
Tick: 15, Hello from task1  
Tick: 18, Hello from task1  
Tick: 18, Hello from task2  
Tick: 21, Hello from task1  
Tick: 24, Hello from task1  
Tick: 24, Hello from task2  
Tick: 27, Hello from task1  
Tick: 30, Hello from task1  
Tick: 30, Hello from task2
```

Create the initial tasks of HW1

- Call *OSTaskCreateExt(...)* in main function to create a new task.

```
114  /*Creat Task Set*/
115  OSTaskCreateExt(task1,                                /* Create the task1 */
116      &TaskParameter[0],
117      &Task_STK[0][TASK_STACKSIZE - 1],
118      TaskParameter[0].TaskPriority,
119      TaskParameter[0].TaskID,
120      &Task_STK[0][0],
121      TASK_STACKSIZE,
122      &TaskParameter[0],
123      (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR));
124
125  OSTaskCreateExt(task2,                                /* Create the task2 */
126      &TaskParameter[1],
127      &Task_STK[1][TASK_STACKSIZE - 1],
128      TaskParameter[1].TaskPriority,
129      TaskParameter[1].TaskID,
130      &Task_STK[1][0],
131      TASK_STACKSIZE,
132      &TaskParameter[1],
133      (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR));
```

You can find its definition by right-click its name.

Hints:
Create the task in the for loop will be suitable next project.

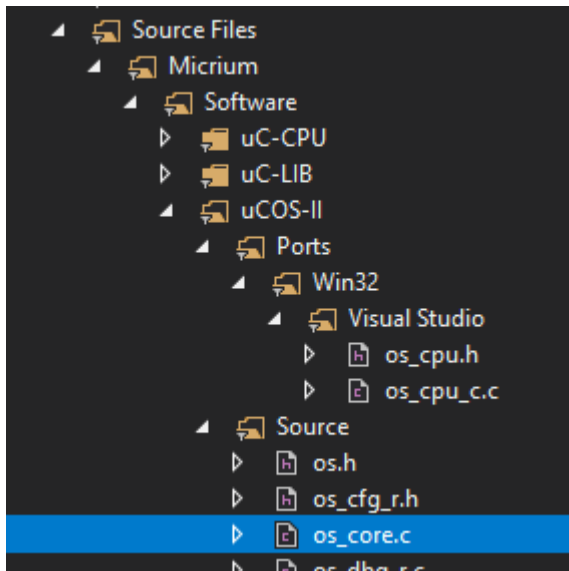
Create the initial tasks of HW1

- Comment out or delete “*create the startup task*” and “*OSTaskNameSet(...)*”

```
130  /*
131  OSTaskCreateExt( StartupTask,                      /* Create the startup task
132                  0,
133                  &StartupTaskStk[APP_CFG_STARTUP_TASK_STK_SIZE - 1u],
134                  APP_CFG_STARTUP_TASK_PRIO,
135                  APP_CFG_STARTUP_TASK_PRIO,
136                  &StartupTaskStk[0u],
137                  APP_CFG_STARTUP_TASK_STK_SIZE,
138                  0u,
139                  (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR));
140
141  #if OS_TASK_NAME_EN > 0u
142      OSTaskNameSet(      APP_CFG_STARTUP_TASK_PRIO,
143                      (INT8U *)"Startup Task",
144                      &os_err);
145  #endif
146  */
```

Create the initial tasks of HW1

- Open the file **os_core.c**
- Finally, add the system end time in the OSTimeTick()



- os_core.c path:
Micrium_Win32_Kernel\Micrium\
Software\uCOS-II\Source

OSTimeTick():

```
961      /*Setting the end time for the OS*/  
962      if (OSTimeGet() > SYSTEM_END_TIME) {  
963          OSRunning = OS_FALSE;  
964          exit(0);  
965      }  
966      /*Setting the end time for the OS*/
```

This function
will stop
project

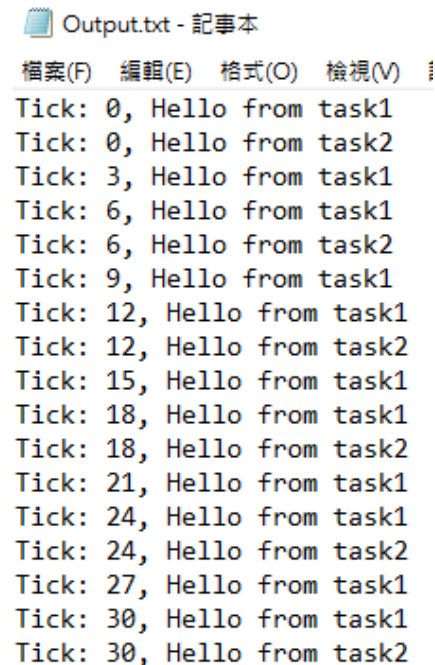
Create the initial tasks of HW1

- Then rerun this project, you can see two tasks information in command prompt.

```
OSTick    created, Thread ID 13816
Task[ 63] created, Thread ID  3592
The file 'TaskSet.txt' was opened
Task[  0] created, Thread ID  6108
Task[  1] created, Thread ID  1904
Tick: 0, Hello from task1
Tick: 0, Hello from task2
Tick: 3, Hello from task1
Tick: 6, Hello from task1
Tick: 6, Hello from task2
Tick: 9, Hello from task1
Tick: 12, Hello from task1
Tick: 12, Hello from task2
Tick: 15, Hello from task1
Tick: 18, Hello from task1
Tick: 18, Hello from task2
```

Create the initial tasks of HW1

- Please make sure the output formation is exactly same as the answer we provide.
- We will use our checker to see if the answer is correct or not in HW through the output of your project.



Output.txt - 記事本

檔案(F) 編輯(E) 格式(O) 檢視(V) ⋮

Tick: 0, Hello from task1
Tick: 0, Hello from task2
Tick: 3, Hello from task1
Tick: 6, Hello from task1
Tick: 6, Hello from task2
Tick: 9, Hello from task1
Tick: 12, Hello from task1
Tick: 12, Hello from task2
Tick: 15, Hello from task1
Tick: 18, Hello from task1
Tick: 18, Hello from task2
Tick: 21, Hello from task1
Tick: 24, Hello from task1
Tick: 24, Hello from task2
Tick: 27, Hello from task1
Tick: 30, Hello from task1
Tick: 30, Hello from task2

Now you can use this project to do HW1!

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