

1.

a)

$$R = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 7 & 5 & 0 \\ 1 & 0 & 0 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 6 & 4 & 2 \end{pmatrix}, A = (1, 5, 2, 0)$$

b)

$$\begin{array}{cccccc} & P_0 & & P_2 & & P_1 & & P_3 & & P_4 \\ A = (1, 5, 2, 0) & \Rightarrow & (1, 5, 3, 2) & \Rightarrow & (2, 8, 8, 6) & \Rightarrow & (3, 8, 8, 6) & \Rightarrow & (3, 14, 11, 8) & \Rightarrow & (3, 14, 12, 12) \end{array}$$

c)

Sol)

If granted, the snap shot will be change to

$$R = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 3 & 3 & 0 \\ 1 & 0 & 0 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 6 & 4 & 2 \end{pmatrix}, C = \begin{pmatrix} 0 & 0 & 1 & 2 \\ 1 & 4 & 2 & 0 \\ 1 & 3 & 5 & 4 \\ 0 & 6 & 3 & 2 \\ 0 & 0 & 1 & 4 \end{pmatrix}, A = (1 \ 1 \ 0 \ 0)$$

$$\begin{array}{cccccc} & P_0 & & P_2 & & P_1 & & P_3 & & P_4 \\ A = (1, 1, 0, 0) & \Rightarrow & (1, 1, 1, 2) & \Rightarrow & (2, 4, 6, 6) & \Rightarrow & (3, 8, 8, 6) & \Rightarrow & (3, 14, 11, 8) & \Rightarrow & (3, 14, 12, 12) \end{array}$$

2.

a.

- Maximum virtual address space = $2^{32} = 2^{22} \times 2^{10} = 2^{22} \text{ KB}$
- \therefore Maximum # of pages per a process = virtual space / a page size = $2^{22} / 4 = 2^{20}$ pages .
- Maximum size of page table per a process = number of page \times one entry size
 $= 2^{20} \times 64 \text{ bits} = (2^{20} \times 64) / 8 \text{ Byte} = 2^{20} \times 8 \text{ byte} = \mathbf{8 \text{ MB}}$

b.

- need calculate the number of page frame
of page frame = size of RAM / size of page
 $= 8\text{GB} / 4\text{KB} = 8 \times 2^{30} / 4 \times 2^{10} = 2^{21} \text{ page frames}$
 $\therefore \mathbf{21 \text{ bits for page frame number.}}$

3.

a.

A multilevel page table reduces the number of actual pages of the page table that need to be in memory because of its hierarchic structure. In fact, in a program with lots of instruction and data locality, we only need the **top level page table (one page)**, one instruction page, and one data page.

b.

- Since page size = 16KB = 2^{14} , 14 bit for offset. That leaves 24 bits for the page fields.
- Since each entry is 4 bytes, one page can hold $2^{14} / 4 = 2^{12}$ page table entries and therefore requires 12 bits to index one page. So allocating 12 bits for each of the page fields will address all 2^{38} bytes.
- 12 + 12 + 14

4.

a.

- Mutual exclusion
- Hold-and Wait
- No preemption
- Circular wait

b.

- Ignore
- Detection and recovery
- Avoidance with dynamic allocation
- By attacking one of necessary deadlock condition

c.

Sol) a segment is a logical entity.

- If the segments are large, to keep them in the physical memory might be wasting memory space.
- If a segment's virtual space is larger than physical space, it is not even possible to keep them in the physical memory.

5.

a.

Size of bit-map = $2 \times 2^{10} \times 2^{16}$ Byte = $2 \times 2^{10} \times 2^{16} \times 8$ Bit = 2^{30} bit.

There are 2^{30} blocks

Total disk size = $2^{30} \times 2 \times 2^{10} = 2^{41}$ Byte = 2 TB

b.

sol) # of block information per block = (block size / bit used for a block #) – 1
 $= 8 \times 2 \times 2^{10} / 32 \text{ bit} = 2^9 - 1 = 512 - 1 = 511$
 total # block number = 511×2^{20}
 total disk size = $511 \times 2^{20} \times 2 \times 2^{10} = 511 \times 2^{31} \text{ Byte} = \text{about } 2^9 \times 2^{31} \text{ Byte} = 1 \text{ TB}.$

6.

- a. files are cached in the RAM when it is opened.
- b.
 - In LSF, each i-node is not at a fixed location; they are written to the log.
 - LFS uses a data structure called an **i-node map** to maintain the current location of each i-node.
 - Opening a file consists of using the map to locate the i-node for the file.

7.

- a) Page 3
- b) Page 0
- c) Page 0
- d) Page 1

8.

Sol) since 1 block is 2KB, and 4 Byte per block address, it can save $2 \times 2^{10} / 4 = 2^9 = 512$ block information

Total = $512 + 10 = 522$ block information.

Since a block size is 2KB, largest file will be $2\text{KB} \times 522 = 1044 \text{ KB}$

9.

- a.

Total Overhead(P) = Average page table size + the wasted memory in th last page of process

$$= \frac{S}{P} \times E + \frac{P}{2}$$

b.

$$\text{Overhead}(P) = -\frac{SE}{P^2} + \frac{1}{2} = 0$$

$P = \sqrt{2SE}$: optimal page size

10.

a.

Sol) 1 block = $2 \times 2^{10} \times 8 = 16384 \text{ bit}$, $16384 / 32 = 512 - 1 = 511$ block numbers /block
 $128 \text{ GB} = (128 \times 2^{30}) / (2 \times 2^{10}) = 2^{26} \text{ blocks (number of blocks in 128 GB)}$
 Needs $(2^{26}) / 511 = 131328.5 = 131229 \text{ blocks}$

b.

Sol) $128 \text{ GB} = (128 \times 2^{30}) / (2 \times 2^{10}) = 2^{26}$ blocks (number of blocks in 128 GB)

System need one bit per block, the bit map size is 2^{26} bits.

$2^{26} \text{ bits} = (2^{26}) / 8 = 2^{23} \text{ Byte}$

Since each block size is 2KB, need $(2^{23}) / (2 \times 2^{10}) = 4096$ blocks to save free block information.

c.

- Since this system use 32bit disk block number, this system support 2^{32} blocks
- Maximum disk size = $2^{32} \times 2 \times 2^{10} \text{ Byte} = 8 \times 2^{40} = 8 \text{ TB}$

11.

- Maintains an internal array M that keep track of the state of memory.
- M has as many as virtual memory pages n.
- Top m entries contain all the pages currently in the memory (page frames).
- Bottom $n - m$ entries contains all the pages that have been referenced once but have been page out and are not currently in memory

12.

- Phase 1** : begins at the starting directory and examines all the entries in it. For each modified file, its i-node is marked in the bitmap. Each directory is also marked and recursively inspected.
- Phase 2**: unmarking any directories that have no modified files or directories in them or under them.
- Phase 3**: all marked directory is dumped
- Phase 4**: all marked files is dumped

13. (5 pt.)

a)

P₃

A=(2,1,0,0) -> (2,2,2,0) Deadlock

b)

P₁P₃P₂P₄P₅

A=(0,0,0) → (0,1,0) → (3,1,3) → (5,1,3) → (7,2,4) → (7,2,6)

14.

Sol) In LINUX system, size of a block and number of blocks information are saved in super block in the partition. Since used block information for a file is saved in it's i-node, we can get used blocks information by scanning all i-nodes.

```
Create new bitmap (size of bit = number of block from super block)
  Reset (set as 0)
For each i-node do
  For each entry of i-node do
    Set bitmap to 1 (based on used block information)
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15.

Solution 1)

Attacking hold and wait,
starvation

Solution 2)

Attacking circular wait,
If a process need two resource at a same time, this solution have problem