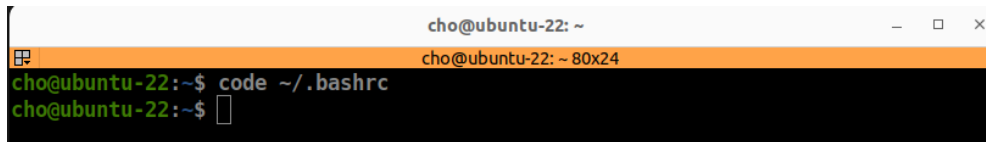


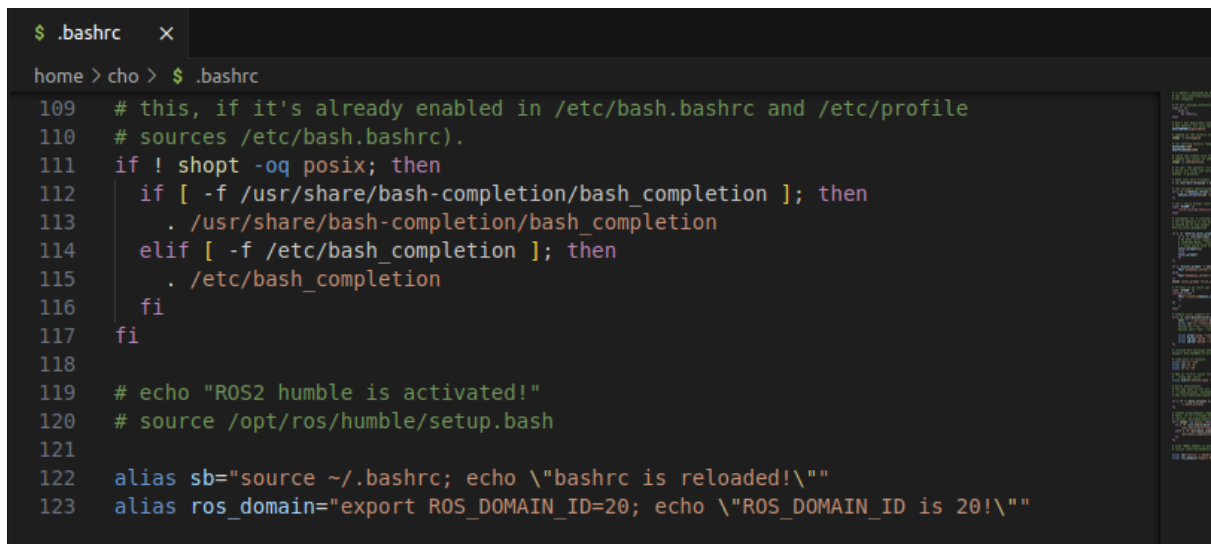
bashrc

[1] code ~/.bashrc (VScode를 깔았다는 전제)



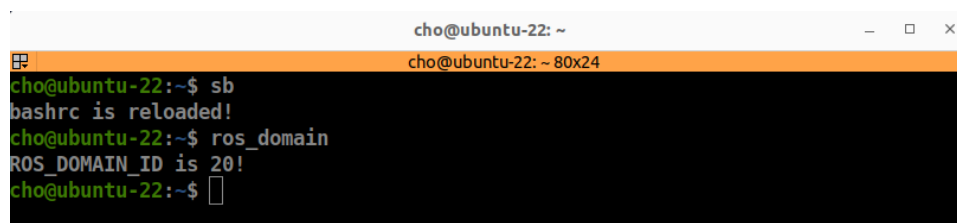
```
cho@ubuntu-22: ~  
cho@ubuntu-22:~$ code ~/.bashrc  
cho@ubuntu-22:~$
```

[2] 가장 밑으로 스크롤 내린 후, 122번, 123번과 같이 작성 후 저장



```
109 # this, if it's already enabled in /etc/bash.bashrc and /etc/profile  
110 # sources /etc/bash.bashrc).  
111 if ! shopt -oq posix; then  
112     if [ -f /usr/share/bash-completion/bash_completion ]; then  
113         . /usr/share/bash-completion/bash_completion  
114     elif [ -f /etc/bash_completion ]; then  
115         . /etc/bash_completion  
116     fi  
117 fi  
118  
119 # echo "ROS2 humble is activated!"  
120 # source /opt/ros/humble/setup.bash  
121  
122 alias sb="source ~/.bashrc; echo \"bashrc is reloaded!\""  
123 alias ros_domain="export ROS_DOMAIN_ID=20; echo \"ROS_DOMAIN_ID is 20!\""
```

[3] 터미널 열어서 sb, ros_domain을 치면 아래와 같이 설정되는걸 확인



```
cho@ubuntu-22:~$ sb  
bashrc is reloaded!  
cho@ubuntu-22:~$ ros_domain  
ROS_DOMAIN_ID is 20!  
cho@ubuntu-22:~$
```