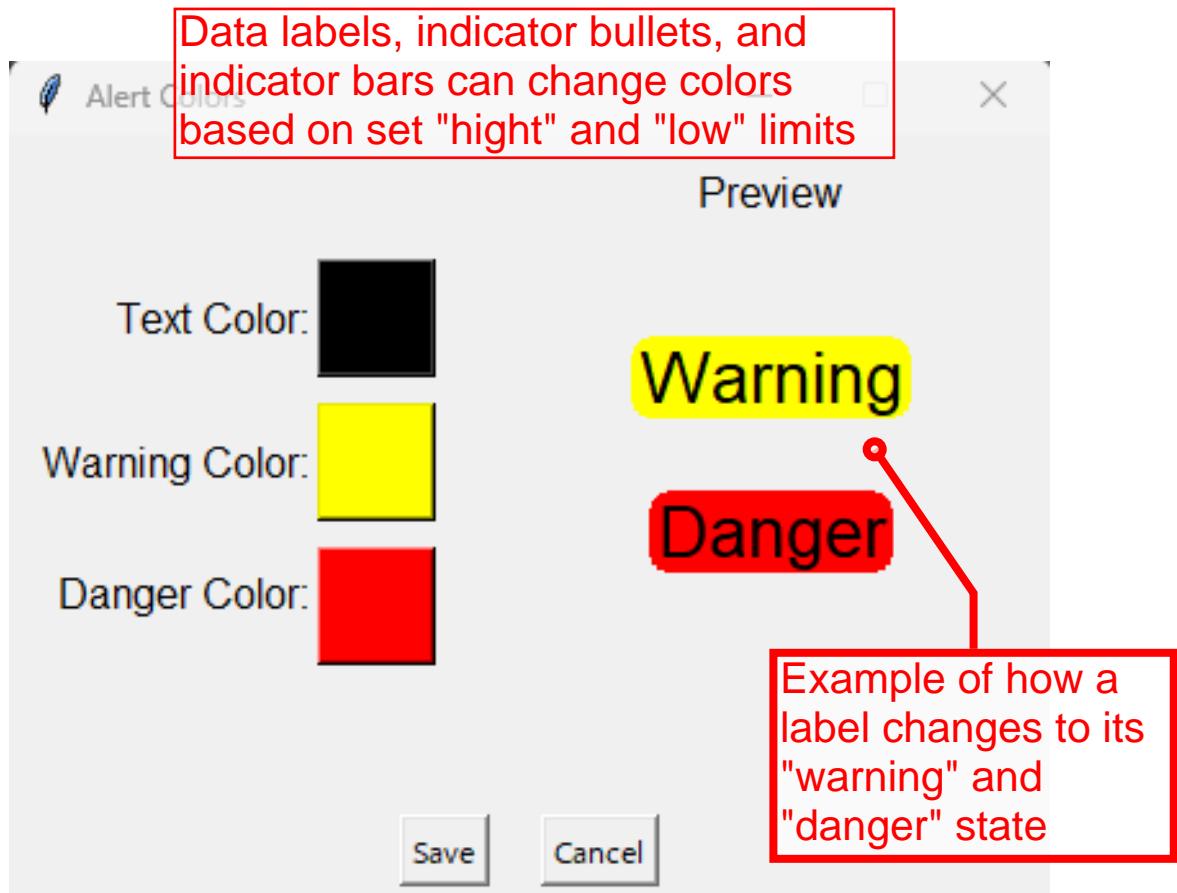
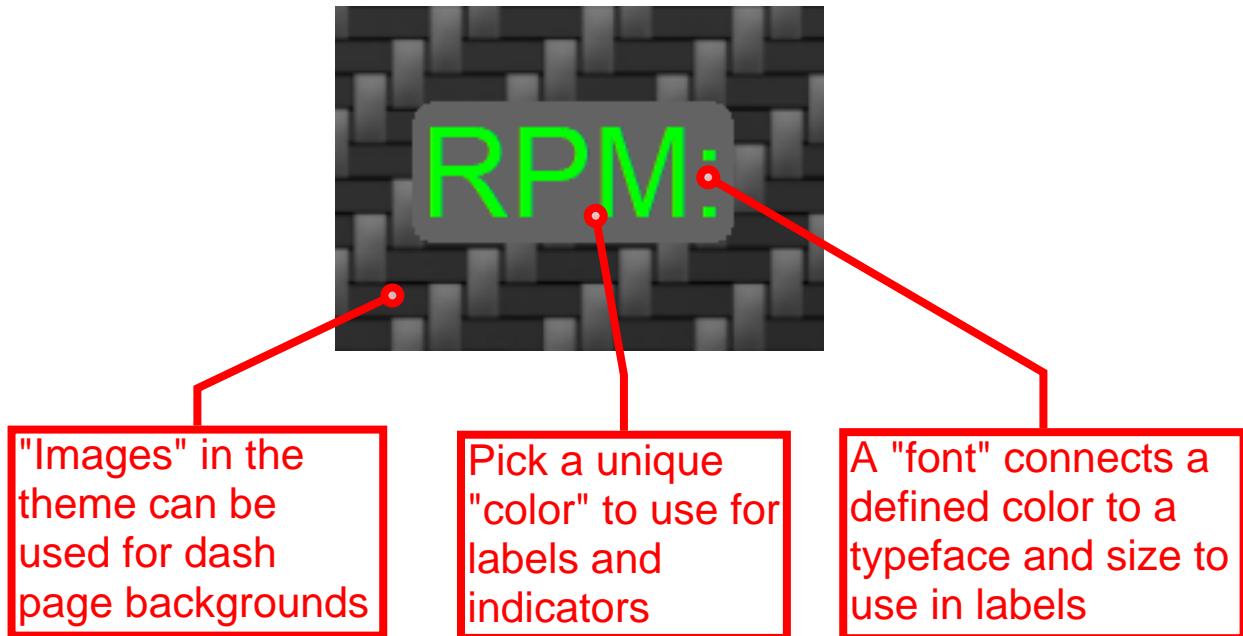


Theme information



Data Channels

The image shows two software windows related to CAN data channels:

- CAN data Channels** window:
 - Contains a list of CAN channels with their addresses:
 - RPM:0x63
 - ECT:0x43
 - WBO2:0x73
 - OILP:0x44
 - MAP:0x45
 - LOBM:0x2B
 - HIBM:0x27
 - Buttons: Add Channel, Edit Channel, Delete Channel.
- CAN channel Values** window:
 - Fields:
 - Channel Name: RPM
 - PID (in HEX): 0x63
 - Extended Frame:
 - DLC (expected frames): 2
 - RTR (Remote Req):
 - RTR Frequency (in ms): 17
 - Target Frames: 1,2
 - Calc Scalar: 256/4
 - Calc Offset: 0
 - Buttons: Save Channel, Cancel.

Annotations with red circles and arrows point to specific fields in the second window:

- Annotation 1: Points to the "Add Channel" button in the first window. Description: Define multiple data channels to use. CAN or OBD2 are accepted.
- Annotation 2: Points to the "PID (in HEX)" field. Description: Data Address.
- Annotation 3: Points to the "DLC (expected frames)" field. Description: Number of Frames.
- Annotation 4: Points to the "RTR (Remote Req)" checkbox. Description: Enable remote request -or- passively listen.
- Annotation 5: Points to the "Target Frames" field. Description: Build the equation to calculate a value.
- Annotation 6: Points to the "Calc Scalar" field. Description: Scalar and offset accepted in decimal or fractional format.