



CS32: Introduction to Computer Science II **Discussion Week 8**

Junheng Hao, Arabelle Siahaan May 24, 2019

Announcements



- Homework 4 is due 11PM next Tuesday, May 28. (@A@)
- How do you feel about midterm 2?

Outline Today



- Sorting (cont'd)
- Tree (Part 1)
- Homework 4 Guidelines

SortingIntroduction



Most important algorithm ever!

Methods:

- Selection sort
- Bubble sort
- Insertion sort
- Merge sort
- Quick sort

Focus on:

- 1. Steps for each sorting algorithm
- 2. Runtime complexity for worst cases, best cases and average cases
- 3. Space complexity
- 4. How about additional assumptions, such as the array is "almost sorted" / "reversed" arrays

Selection sort



Steps:

- 4 3 1 5 2
- **1** 3 4 5 2
- **1** | **2** | 4 | 5 | 3
- **1 2 3** 5 4
- 1 2 3 4 5

Idea: Find the smallest item in the unsorted portion and place it in the front.

Runtime complexity:

Average: $O(n^2)$

Worst: $O(n^2)$

Best: $O(n^2)$

Space complexity: O(1)

Insertion sort



Steps:

- **4 3 1 5 2**
- **3 4 1** 5 2
- **1 3 4 5** 2
- 1 3 4 5 2
- 1 2 3 4 5

Idea: Pick one from the unsorted part and place it in the right position.

Runtime complexity:

Average: $O(n^2)$

Worst: $O(n^2)$

Best: O(n)

Space complexity: O(1)

Bubble sort



Steps:

4 3 1 5 2

3 4 1 5 2

3 1 4 5 2

3 1 4 2 5

1 3 2 4 5

1 2 3 4 5

Idea: Well, just "bubble" as its name

Runtime complexity:

Average: $O(n^2)$

Worst: $O(n^2)$

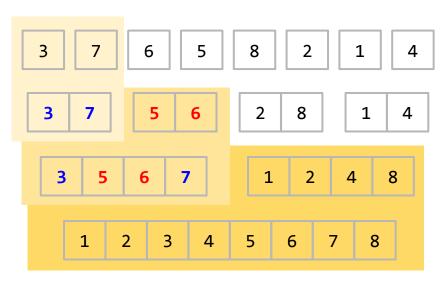
Best: O(n)

Space complexity: O(1)

Merge sort



Steps:



Idea: Divide and conquer

Runtime complexity:

Average: $O(n \log n)$

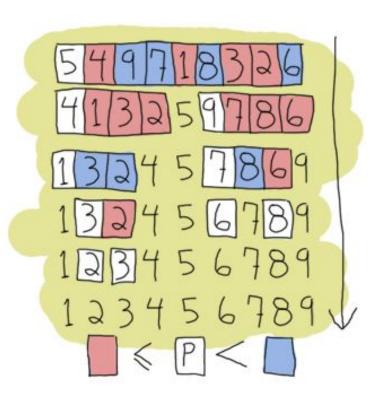
Worst: $O(n \log n)$

Best: $O(n \log n)$

Space complexity: O(n)

SortingQuicksort





Idea: Set a pivot. Numbers less then pivot are placed to front while other to end.

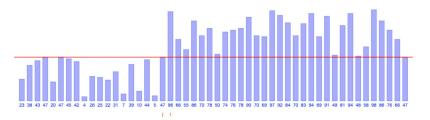
Runtime complexity:

Average: $O(n \log n)$

Worst: $O(n^2)$

Best: $O(n \log n)$

Space complexity: $O(\log n)$



Other methods and complexity?



- O(n log n) is faster than $O(n^2) \rightarrow Merge$ sort is more efficient than selection, insertion and bubble sort in runtime.
- O(n log n) is best average complexity that a general sorting algorithm can achieve.
- With more information about the data provided, you can sometimes sort things almost linearly.

Question: What is the complexity of these sorting algorithms if you know the array is **reversed**? What if the array is **almost already sorted**?

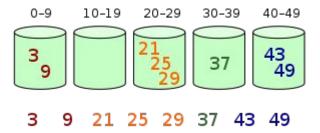


Other methods and complexity?



There are many other sorting methods:

- Shell sort (shell 1959, Knuth 1973, Ciura 2001)
- Quicksort 3-way
- Heap sort
- Bucket sort



Why sorting is important?



Sorting is the most important and basic algorithm. Many other real-world problems are somewhat based on sorting, including:

Sorting Algorithms Animations: https://www.toptal.com/developers/sorting-algorithms
Other good demos:

https://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html http://sorting.at/





Question: How about get the *K-th* largest numbers in one array?

<u>Leetcode question #215</u>

Hint:

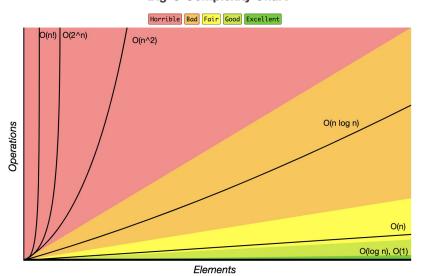
- 1. How to find the k-th largest numbers by merge sort and quicksort (or other sort methods)? What are the average and worst complexity?
- 2. What data structures is good to use?

Big-O Notation

Big-O Complexity Chart



Big-O Complexity Chart



Array Sorting Algorithms

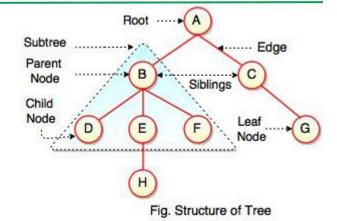
Algorithm	Time Complexity			Space Complexity
	Best	Average	Worst	Worst
Quicksort	$\Omega(n \log(n))$	$\theta(n \log(n))$	0(n^2)	0(log(n))
<u>Mergesort</u>	$\Omega(n \log(n))$	$\theta(n \log(n))$	0(n log(n))	0(n)
Timsort	$\Omega(n)$	$\theta(n \log(n))$	0(n log(n))	0(n)
<u>Heapsort</u>	$\Omega(n \log(n))$	$\theta(n \log(n))$	0(n log(n))	0(1)
Bubble Sort	$\Omega(n)$	θ(n^2)	0(n^2)	0(1)
Insertion Sort	$\Omega(n)$	θ(n^2)	0(n^2)	0(1)
Selection Sort	Ω(n^2)	θ(n^2)	0(n^2)	0(1)
Tree Sort	$\Omega(n \log(n))$	$\theta(n \log(n))$	0(n^2)	0(n)
Shell Sort	$\Omega(n \log(n))$	$\theta(n(\log(n))^2)$	0(n(log(n))^2)	0(1)
Bucket Sort	$\Omega(n+k)$	$\theta(n+k)$	0(n^2)	0(n)
Radix Sort	$\Omega(nk)$	Θ(nk)	0(nk)	0(n+k)
Counting Sort	$\Omega(n+k)$	$\theta(n+k)$	0(n+k)	0(k)
Cubesort	$\Omega(n)$	$\theta(n \log(n))$	0(n log(n))	0(n)

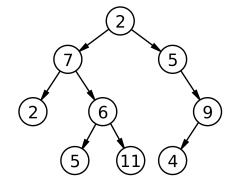
Tree

Definition



- Terms: Node/edge, root node, leaf node, parent and child node, subtree, levels (height/depth).
- Features: No loop, no shared children
- Question: How many edges should there be in a tree with n nodes?
- Binary tree: no node has more than two children.
- Question: How many nodes can a binary tree of height h have? → Full binary tree





Tree

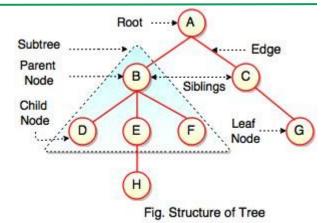
As a data structure

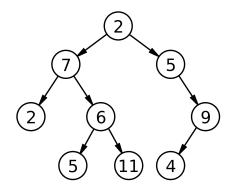


- Tree is a useful data structure!
- Basic functions: insert, remove, search, traverse
- How to traverse a tree?

```
struct Node{
  ItemType val;
  Node* leftChild;
  Node* rightChild;
} // a simple node
```

```
Class Tree{
public:
   // ???
private:
   // ???
}
```





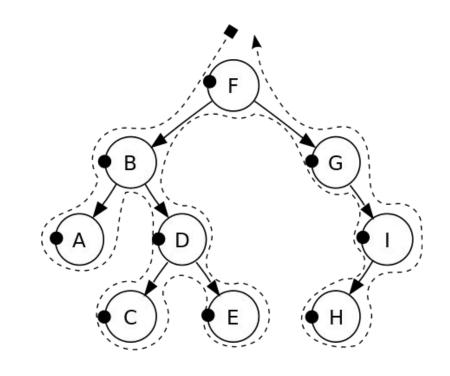
Tree Traversal: Pre-order

Three methods of tree traversal



```
void preorder(const Node* node)
{
  if (node == nullptr) return;
  cout << node->val << ",";
  preorder(node->left);
  preorder(node->right);
}
```

```
Pre-order output:
F, B, A, D, C, E, G, I, H
```



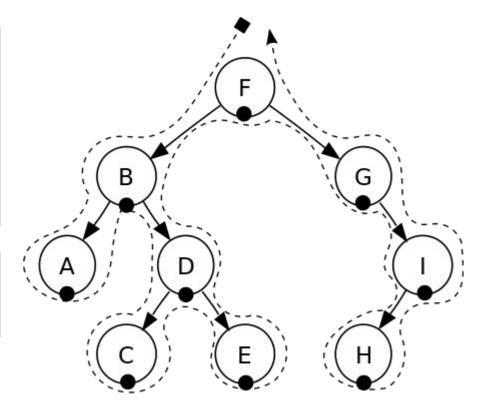
Tree Traversal: In-order

Three methods of tree traversal



```
void inorder(const Node* node)
{
  if (node == nullptr) return;
  inorder(node->left);
  cout << node->val << ",";
  inorder(node->right);
}
```

```
In-order output:
A,B,C,D,E,F,G,H,I
```



Tree Traversal: Post-order

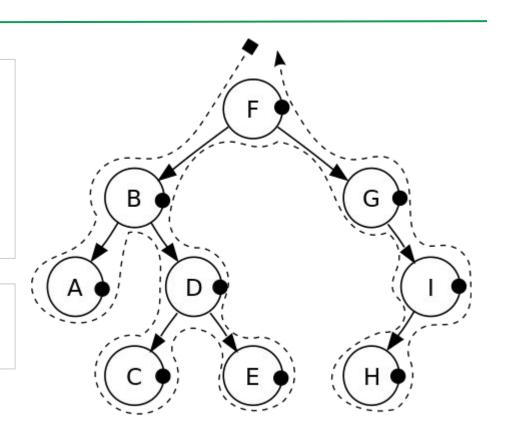


Three methods of tree traversal

```
void postorder(const Node* node)
{
  if (node == nullptr) return;
  postorder(node->left);
  postorder(node->right);
  cout << node->val << ",";
}</pre>
```

```
Post-order output:
```

A, C, E, D, B, H, I, G, F



Tree Traversal: Compare



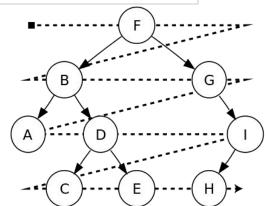
```
void preorder(const Node* node)
{
  if (node == nullptr) return;
  cout << node->val << ",";
  preorder(node->left);
  preorder(node->right);
}
```

```
void postorder(const Node* node)
{
  if (node == nullptr) return;
  postorder(node->left);
  postorder(node->right);
  cout << node->val << ",";
}</pre>
```

```
void inorder(const Node* node)
{
  if (node == nullptr) return;
  inorder(node->left);
  cout << node->val << ",";
  inorder(node->right);
}
```

Level-order or say breadth-first search!

//Other ways?



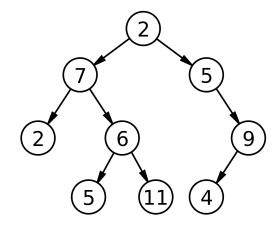
Tree





- It is easy and natural to apply recursion on trees!
- Pre-order / in-order / post-order are all recursive methods to traverse a tree.
- Question: How to calculate a height of a given tree?

```
int getTreeHeight(const Node* node)
  if (node == nullptr) return 0;
 int leftHeight = getTreeHeight(node->left);
 int rightHeight = getTreeHeight(node->right);
 if (leftHeight > rightHeight)
    return leftHeight + 1;
 else
    return rightHeight + 1;
```



Tree

Conclusions and applications



- Non-linear data structures unlike arrays or lists.
- Present hierarchy
- Optimized (like balanced) tree and variants can improve efficiency of search, sort and other typical problems.
- Other tree variants:
 - o B tree / B+ tree
 - Red-black tree
 - K-D Tree
 - Suffix Tree

```
file system
-----
    / <-- root
/
... home
    / \
ugrad course
/    / | \
... cs31 cs32 cs35L</pre>
```

Next week about tree



- Binary Search Tree
- Heap
- More interesting questions ...

6 5 3 1 8 7 2 4

Hints for Homework 4 - P1



```
template <typename T>
class S
 struct N
 N* f();
template <typename T>
typename S<T>::N* S<T>::f()
                                // OK
```

Note & Reminders:

- Only need to change (or add) a few lines if you decide to use template
 <typename ItemType>
- Put template <typename T> ahead of every function you declare outside the class statement.

Hints for Homework 4 - P2



```
#include "Sequence.h" // class template from
problem 1
     class Coord
       public:
         Coord(int r, int c) : m_r(r), m_c(c) {}
         Coord(): m r(0), m c(0) {}
         double r() const { return m r; }
         double c() const { return m c; }
       private:
         double m r;
         double m c;
     };
     int main()
         Sequence<int> si;
         si.insert(50);
                                      // OK
         Sequence<Coord> sc;
         sc.insert(0, Coord(50,20));
                                      // OK
         sc.insert(Coord(40,10));
                                      // error!
```

Note & Reminders:

Check the 1-argument insert()
 function and think about the operation
 which leads to error for Coord but not
 for int.

Hints for Homework 4 - P3, P4



```
// Problem 4

void listAll(const Domain* d, string path)
// two-parameter overload
{
    // You will write this code.
}

void listAll(const Domain* d)
// one-parameter overload
{
    if (d != nullptr)
        listAll(d, d->label());
}
```

Note & Reminders:

- (P3) Implement functions with remove() in STL.
- 2. (P4) Necessity for two-parameter overload of listAll() function. → What is the purpose of string path parameter?
- (P4) If the container is const, you must use a const_iterator to traverse an STL container.

Hints for Homework 4 - P5, 6, 7



Note & Reminders:

- 1. Only the highest order will be considered as your final answer.
- 2. Analysis implementation of **every** function in **every** step.





Break Time! (5 minutes)

Q&A

Group Exercises: Worksheet



- Exercise problems from Worksheet 7 (see "LA worksheet" tab in CS32 website). Answers will be posted next week.
- Questions for today:
 - \circ TBA

Question X



Content





Thank you!

Q&A