Urban Informatics

Fall 2018

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@fedhere





Recap:

- Good practices with data: falsifiability, reproducibility
- Basic data retrieving and munging: APIs, Data formats
- SQL
- Basic statistics: distributions and their moments
- Hypothesis testing: *p*-value, statistical significance
- Statistical and Systematic errors
- Visualizations
- Geospatial analysis
- OLS
- Goodness of fit tests
- Likelihood







models with parameters that are "learned" from the data





models with parameters that are "learned" from the data parameters that are optimized based on the data





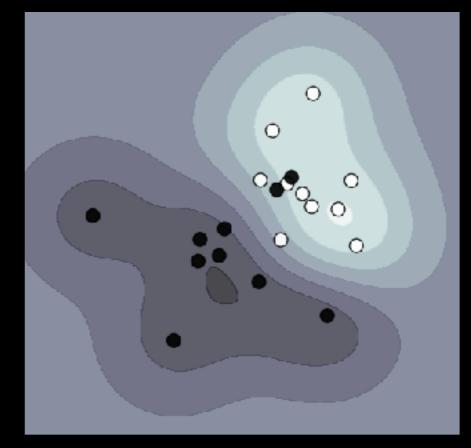
algorithms that can learn from and make predictions on data.





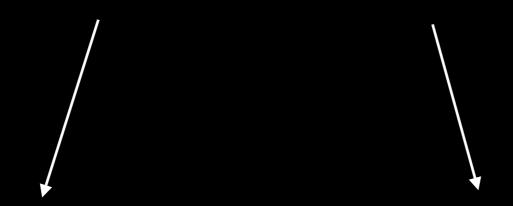
algorithms that can learn from and make predictions on data.

supervised learning extract features and create models that allow prediction where the correct answer is known for a subset of the data





algorithms that can learn from and make predictions on data.



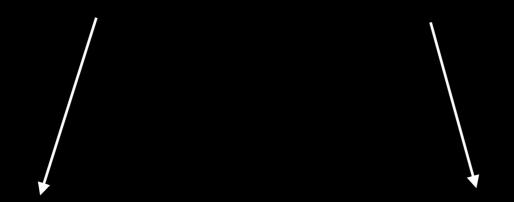
supervised learning extract features and create models that allow prediction where the correct answer is known for a subset of the data

unsupervised learning

identify features and create models that allow to understand structure in the data



algorithms that can learn from and make predictions on data.



supervised learning

unsupervised learning

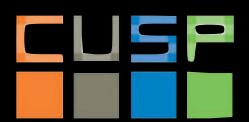
classification

prediction

understanding structure

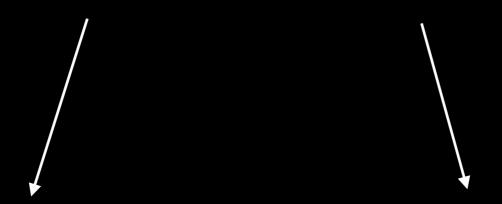
organizing + compressing data

(classification, feature learing)



XI: Clustering

algorithms that can learn from and make predictions on data.



supervised learning

classification

prediction

LR, SVM

CART

DL

unsupervised learning

understanding structure

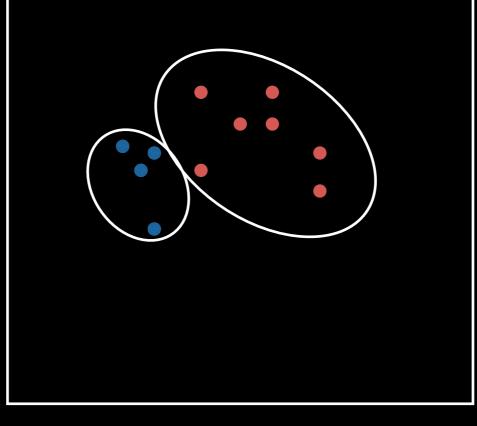
organizing + compressing data

(classification, feature learing)

CLUSTERING

XI: Clustering

Supervised Learning



X

observed:

(x, y, color)

Partitioning methods: classifying (SVM, CART)

goal is to partition the space of observed variables to separate the space of unobserved (target variables)

target: (color)

X



observed:

(x, y)

goal is to partition the space of observed variables to separate the space of unobserved (target variables)

target: (color)

X



observed:

(x, y)

goal is to partition the space of observed variables to separate the space of unobserved (target variables)

 X_0

target: (color)

observed: (x, y)



if $x>x_0 =>$ ball is red

goal is to partition the space of observed variables to separate the space of unobserved (target variables)

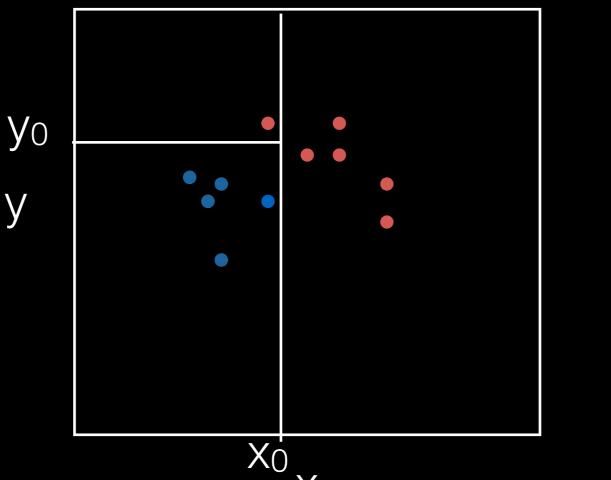
target: (color)

observed:

(x, y)



goal is to partition the space of observed variables to separate the space of unobserved (target variables)



(x, y)

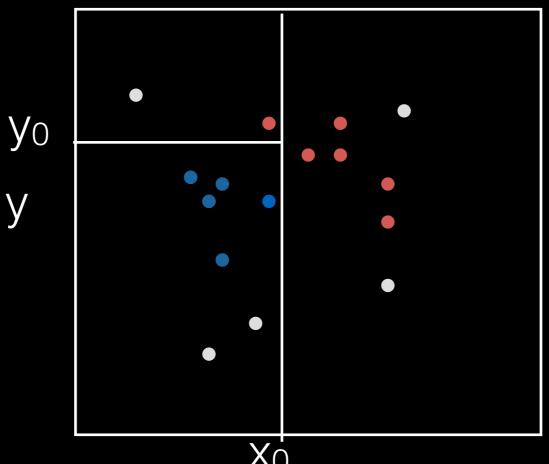
observed:

if $x>x_0$ or $y>y_0=>$ ball is red

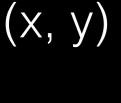
target:

(color)

goal is to partition the space of observed variables to separate the space of unobserved (target variables)



target: (color)

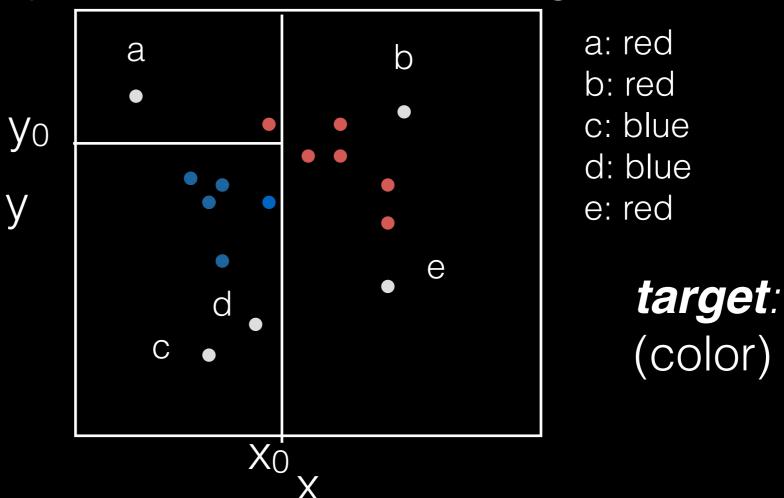


observed:



if $x>x_0$ or $y>y_0=>$ ball is red

goal is to partition the space of observed variables to separate the space of unobserved (target variables)





observed:

(x, y)

if $x>x_0$ or $y>y_0=>$ ball is red

Decision Trees



The good

- Non-Parametric
- White-box: can be easily interpreted
- Works with any feature type and mixed feature types
- Works with missing data
- Robust to outliers

The bad

- High variability (-> use ensamble methods)
- Tendency to overfit
- (not as easily interpretable after all...)



a single tree



Application:
a robot to predict
surviving the
Titanic (Kaggle)

features:

gender ticket class age

target variable:

survival (y/n)



Ns: survived

Nd: died

Application:
a robot to predict
surviving the
Titanic (Kaggle)

gender (binary)

M

Ns=93 Nd=360

features:

purity 79%

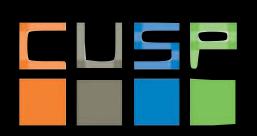
gender 79/75%

ticket class

age

target variable:

survival (y/n)



Ns=197 Nd=64 purity 75%

Application:
a robot to predict
surviving the
Titanic (Kaggle)

class (categorical)

1st

Ns=471 Nd=242

features: purity 66%

gender 79/75% ticket class 66/44% age

target variable:

survival (y/n)

\2nd,3rd Ns=335 Nd=378 purity 44%

Application:
a robot to predict
surviving the
Titanic (Kaggle)

<6.5

Ns=500 Nd=214

features:

purity 30%

gender 79/75% ticket class 66/44% age 30/70%

target variable:

survival (y/n)



age (continuous)

>6.5 Ns=278 Nd=435

purity 70%

Application:
a robot to predict
surviving the
Titanic (Kaggle)

age (continuous)

M

Ns=93 Nd=360

features:

purity 79%

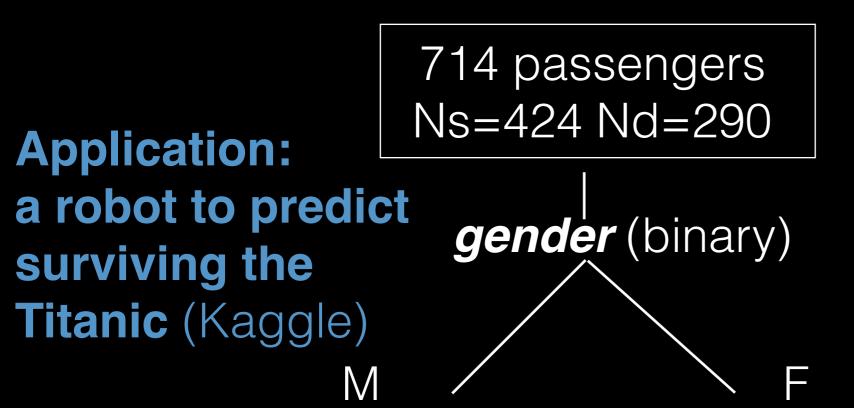
Ns=197 Nd=64 purity 75%

gender 79/75%

age 66/44% ticket class 30/70%

target variable:





Ns=197 Nd=64

purity 75%

Ns=93 Nd=360

features: purity 79%

gender 79/75%

target variable:



Application:
a robot to predict
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gender (binary)

M

Ns=93 Nd=360

features: purity 79%

Ns=197 Nd=64 purity 75%

gender 79/75%

age: M 74/67% F 96/40%

ticket class: M 40/15% F 96/65%

target variable:



Application:
a robot to predict
surviving the
Titanic (Kaggle)

gender (binary)

M

Ns=93 Nd=360

features: purity 79%

Ns=197 Nd=64 purity 75%

gender 79/75%

age: M 67/82% F 74/76%

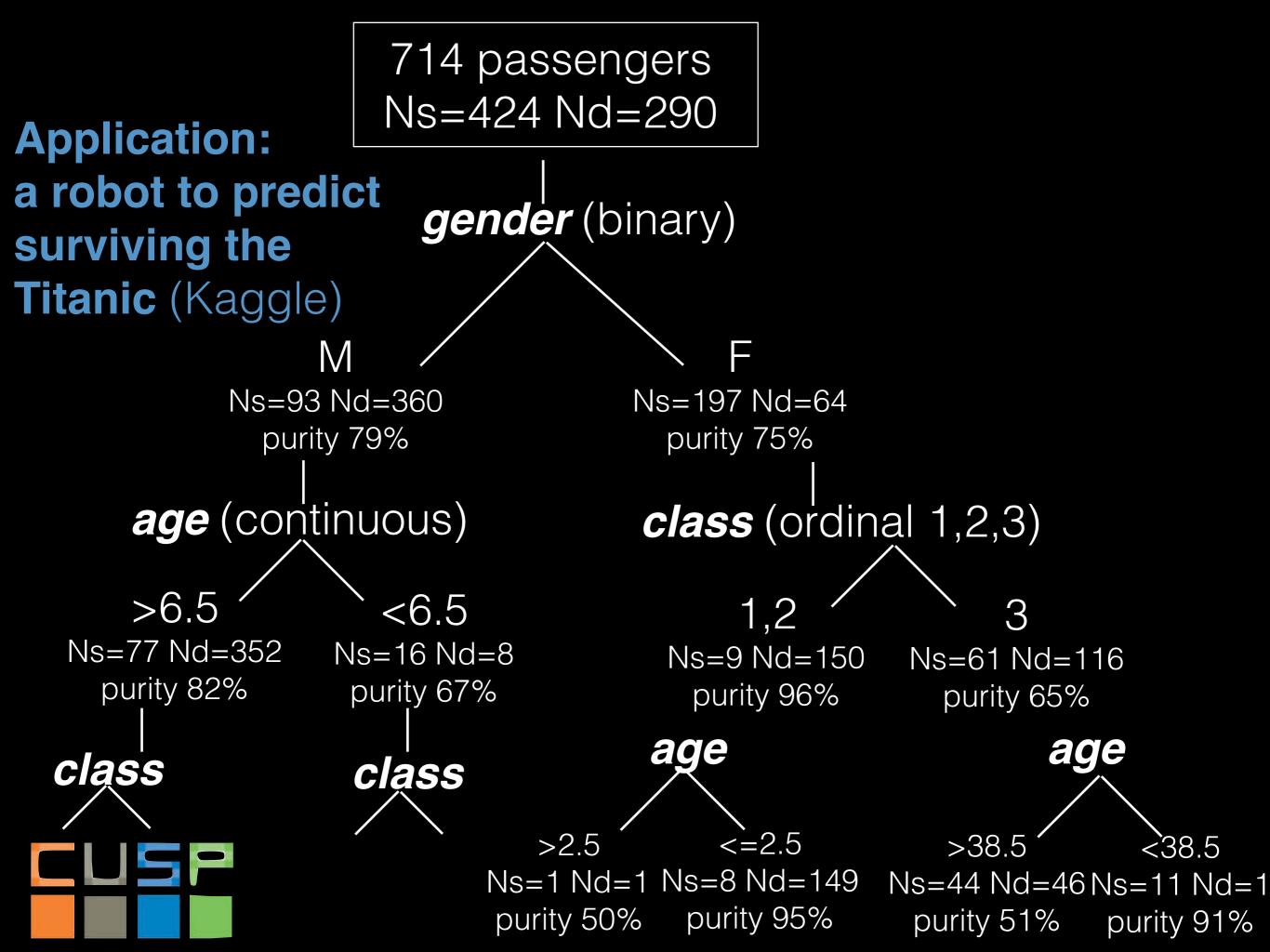
ticket class: M 40/15% F 96/65%

target variable:

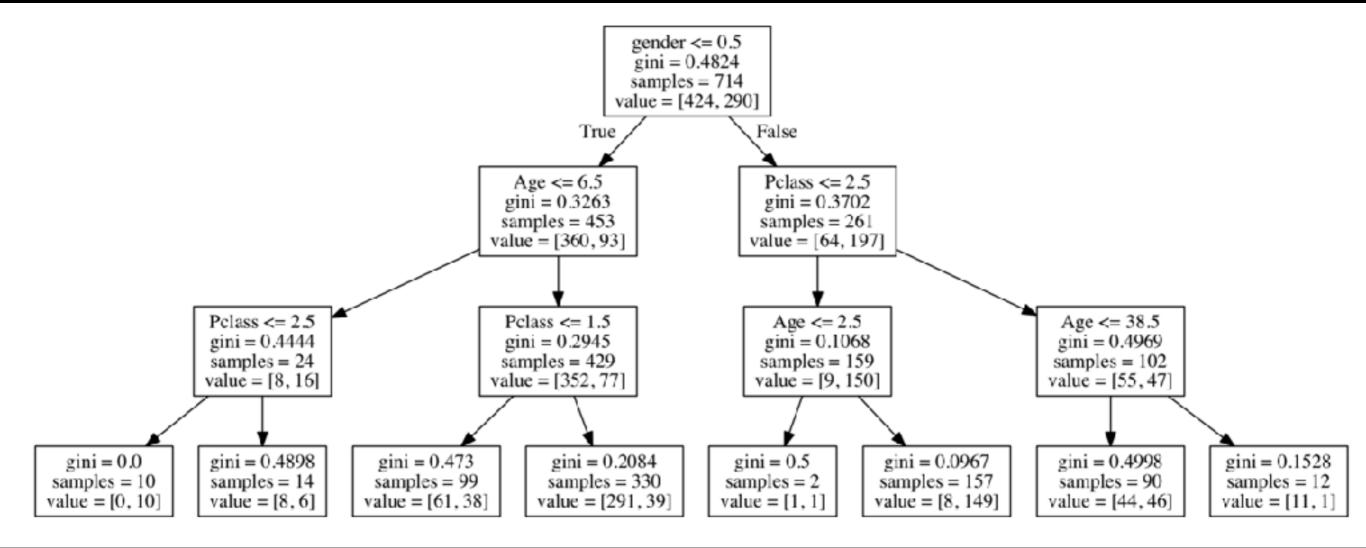


714 passengers Ns=424 Nd=290 **Application:** a robot to predict *gender* (binary) surviving the Titanic (Kaggle) M Ns=93 Nd=360 Ns=197 Nd=64 purity 79% purity 75% age (continuous) **class** (ordinal 1,2,3) >6.5 <6.5 2,3 Ns=77 Nd=352 Ns=16 Nd=8 Ns=82 Nd=3 Ns=114 Nd=62 purity 82% purity 67% purity 96% purity 65%



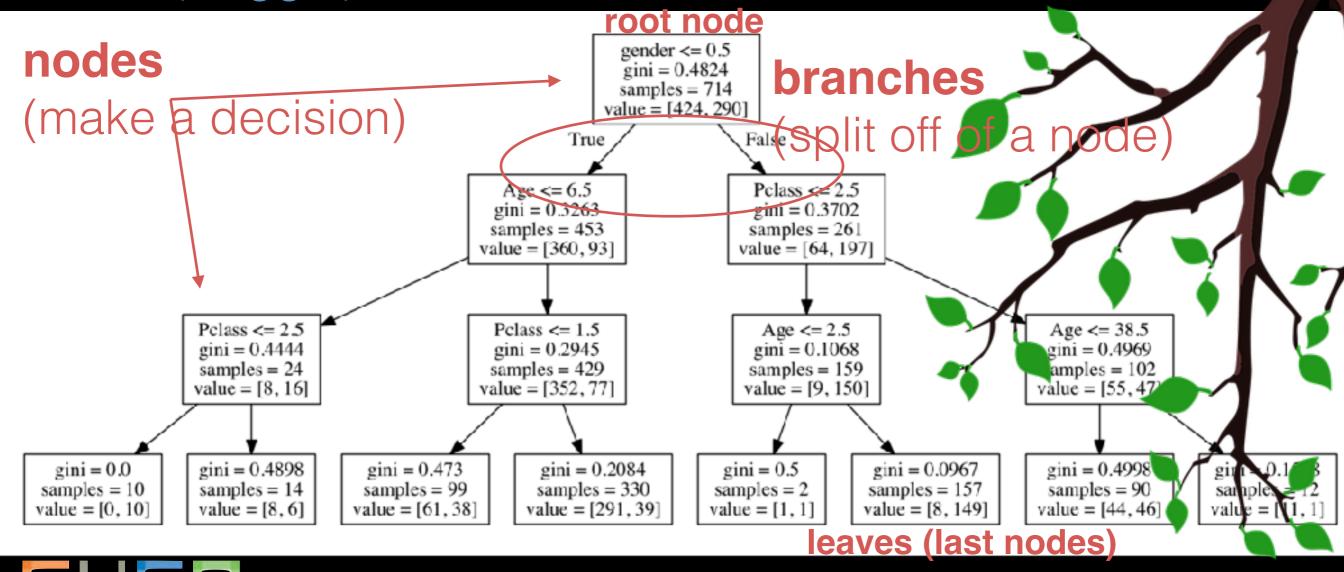


Application: a robot to predict surviving the Titanic (Kaggle)





Application: a robot to predict surviving the Titanic (Kaggle)

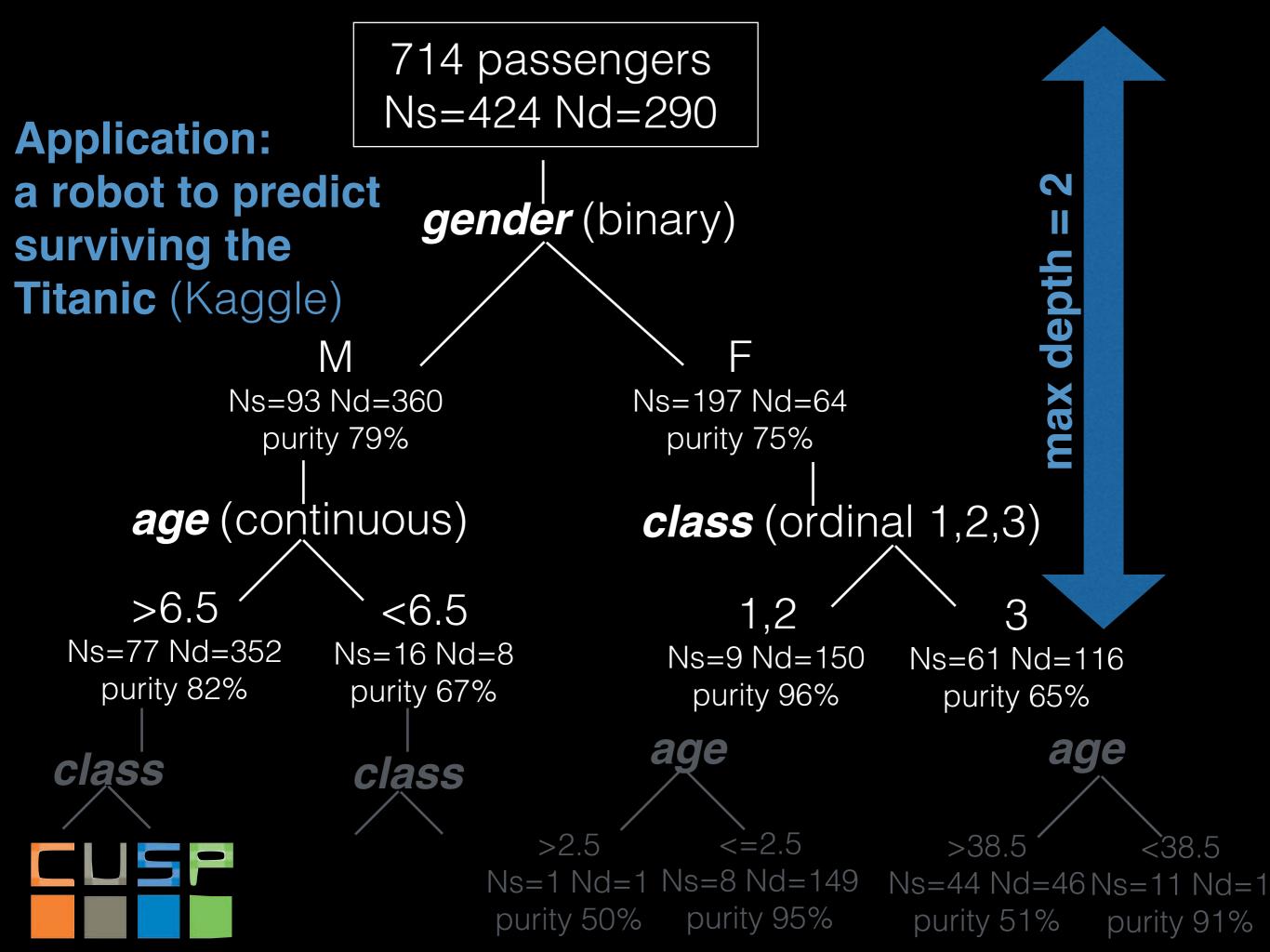


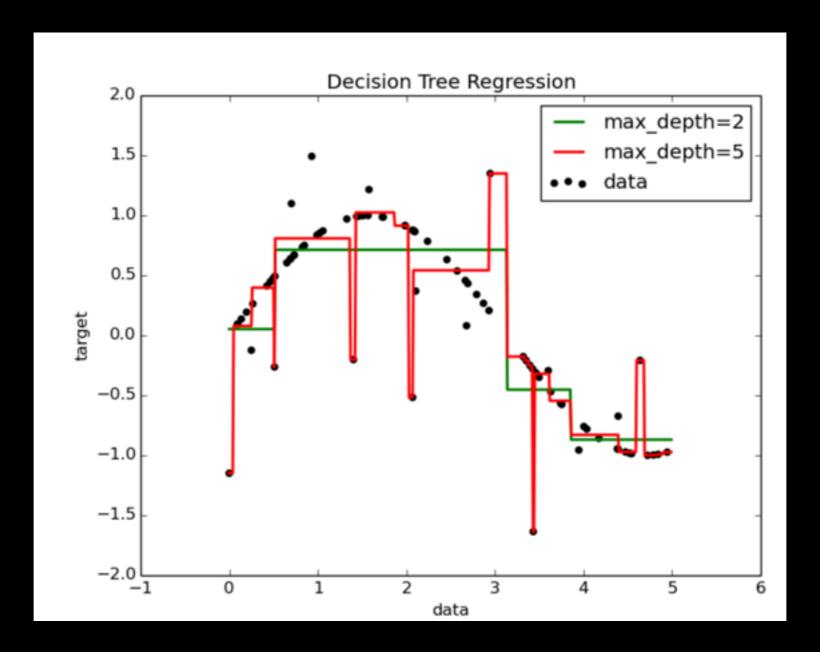


a single tree

parameters: maximum depth (controls overfitting) maximization scheme







http://scikit-learn.org/0.16/modules/tree.html#tree-algorithms-id3-c4-5-c5-0-and-cart

parameters: maximum depth (controls overfitting) maximization scheme

https://scikit-learn.org/stable/modules/generated/sklearn.ensemble.RandomForestClassifier.html



a single tree

parameters: maximum depth (controls overfitting) maximization scheme

gini, entropy (information content), variance...



a single tree

issues:

variance - different trees lead to different results

solution: a forest



a single tree

issues:

variance - different trees lead to different results *solution*: a forest

- run many tree models,
- look at the ensemble result



Ensemble methods:

Random forest:

- trees run in parallel (independently of each other)
- each tree uses a random subset of observations/features (boostrap - bagging)
- class predicted by majority vote: what class do most trees think a point belong to?

Gradient boosted trees:

- trees run in series (one after the other)
- each tree uses different weights for the features learning the weighs from the previous tree
- the last tree has the prediction



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Random forest:

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Gradient boosted trees:

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More parameters:

- BOTH: d
 - BOTH: depth, criterion, min sample to split, min sample in leaf
 - RF: number of trees, number of features/tree
 - GB: loss function, learning rate, number of boosts

How good is my model?

https://scikit-learn.org/stable/modules/model_evaluation.html



	<i>H</i> ₀ is True	<i>H</i> ₀ is False
H₀is falsified	Type I error False Positive important message gets spammed	True Positive
H₀is not falsified	True Negative	Type II error False negative Spam in your Inbox



False Negative

LR =

True Negative

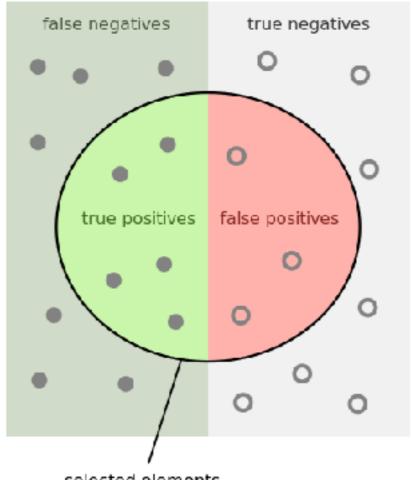
	<i>H</i> ₀ is True	H₀ is False
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H₀is not falsified	True Negative	Type II error False negative Spam in your Inbox



Precision = (TP)/(TP + FP)

Recall = (TP)/(TP + FN)

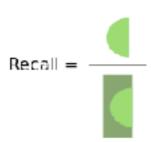
relevant elements



selected elements

How many selected items are relevant?

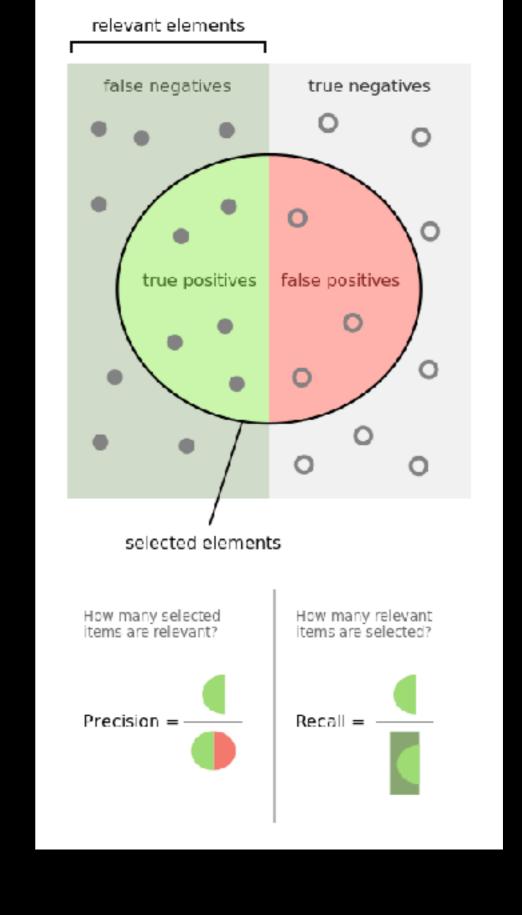
How many relevant items are selected?





Precision = (TP)/(TP + FP)

Recall = (TP)/(TP + FN)





Accuracy = (TP+TN)/(TP+TN+FP+FN)



How good is my model?

https://scikit-learn.org/stable/modules/model_evaluation.html

Is my model overfitting?

cross validation:



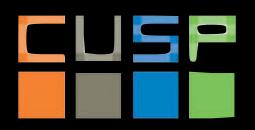
super important missing topic: pruning! when is my tree overfitting?



dont just do linear regression!

http://scikit-learn.org/0.16/ modules/tree.html#treealgorithms-id3-c4-5-c5-0and-cart





XII: decision trees

Reading:

An excellent use of viz for data exploration and transition to inferential analysis https://blog.data.gov.sg/how-we-caught-the-circle-line-roguetrain-with-data-79405c86ab6a#.iz1r655xo

Lee Shangqian, Daniel Sim & Clarence Ng



Decision trees:

http://what-when-how.com/artificial-intelligence/decision-tree-applications-for-data-modelling-artificial-intelligence/

https://www.ncbi.nlm.nih.gov/pmc/articles/PMC4466856/

https://www.ncbi.nlm.nih.gov/pmc/articles/PMC4380222/

