11th basic algebra			
2022年9月25日 星期日 上午9:56			
kerrel.		\mathcal{O}	
Change-of-basis		2	
0 3			
isomorphic (isomorphis	sm)	3	
1 1			
linear map: 1: U	→ V correspond to	o a matrix A.	
linear maps between	L ()		
linear maps between			
column vectors, th	e cottespondence res	pects addition and	l scolar
	Lo. Iscofim	f(u)+f(u)=f(+fx)	μ)
1: 11 - 11 M	ultiplication.	$\frac{1}{\sqrt{1}}$	ไร
	7	$f_{1}(u) + f_{2}(u) = f_{1} + f_{2}(u)$ $A_{1} u + A_{2} \cdot u = (A_{1} + A_{2})$ $A_{2} u + A_{2} \cdot u = (A_{1} + A_{2})$	·(h)
The vector subspace o	f the domain U wit	th L(u) = 0, whi	ch is called
il hand of I	han)	$A \cdot u = 0$	
the kernel of 1 (100° 2.)		
corresponds to the nu	Il space of A.		
The linear map	1 is one-one	if and only if be	er L = 0.
Corrollary: 2+ 1: U->	V 15 a linear ma	p between finite -	dimensional
vector spaces over IF,	then.		
Corrollary: zf 1: U-> vector spaces over IF, dim(dom	ain(L)) = $dim(kern)$	el (L)) + dim (imag	ge(L).
Theorem: Let 1: U= finite -dimension and the to the text of the	PV and $M: V \rightarrow W$	l. be linear maps	betwen
finite -dimensi	onal vector spaces.	and let $P \triangle a$	and 12
0+0+····+0 + 0 F	— · /	1 '	

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finite -dimensional vector spaces. and let 1, \( \Delta \) and \( \Delta \)
                                                        be ordered basis of U, V, W. ML: U \rightarrow W
               Then the composition ML is linear the corresponding matrix is given by.

\frac{ML}{\Delta P} = \frac{M}{\Delta D} \frac{V = A_1 \cdot k}{W = A_2 \cdot A_1 \cdot k}

\frac{ML}{\Delta P} = \frac{M}{\Delta D} \frac{ML}{\Delta P} \frac{W = A_2 \cdot A_1 \cdot k}{\Delta D} \frac{ML}{\Delta 
               (0,1,9) (0,0,4) (0,1,0)
                                                     let u be the jth member of P.
                                                   jth when of (M^2) = j^{th} \omega l m n of (M) (Sp). II.
                        Change - of - basis
                                                                                                                                                                                                                                                                  (AP)(PP)
                                                                                                                                                                                                                                                         I: V→U IL: V→U IL: V→ u.
                                                                                                                                                                                                                                                                                                                                        basic > basis
                                  y"(t) = y(t)
                                                                                                                                                                get+se-t.
                                                                                                                                                                                                                                                                                                                                                                                                                                                        (2, e_2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                   (0,1) -> Q1
                                                                                                                                                                                                                                                                                                                                                                                                                                                     (1,0)-762
                        et = cosht +sinht (\Delta P) = (\frac{1}{1})
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et = cosht t sinht

et = cosht t sinht

(dldt) = (
$$\frac{1}{\Delta P}$$
) $\frac{1}{\Delta P}$ = ($\frac{1}{1-1}$)

L = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) $\frac{1}{\Delta P}$ = ($\frac{1}{1-1}$) change - of - basis

I = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) $\frac{1}{\Delta P}$ = ($\frac{1}{1-1}$) change - of - basis

I = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) $\frac{1}{\Delta P}$ = ($\frac{1}{\Delta P}$) change - of - basis

I = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) change - of - basis

I = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) = ($\frac{1}{\Delta P}$) coso distributed basis is the standard ordered basis $\frac{1}{\Delta P}$.

Another ordered basis is the standard ordered basis $\frac{1}{\Delta P}$.

Another ordered basis $\frac{1}{\Delta P}$ and $\frac{1}{\Delta P}$ = ($\frac{1}{\Delta P}$) = ($\frac{1}$

otasiea basis I (in domain and tange).
Then 'Yany other ordered basis Δ , the matrix of L is of the form
C-1. A. C. for some invertible matrix C. sepending on 2).
If A is a square matrix, the any square matrix of the form
C-IAC is said to be similar. to: aguivalence class.
15 (), x x x.
1). xux. 1). xux. 2) xuy, yux. 37. xuy, yux.
37. xny. ynz. ±.xn3
Two vector space U and V are said to be isomorphic if
there is a one to one linear map of U onto V.
isomorphism. $U \stackrel{\sim}{=} V$.
allowed to be infinite-dimensional.
16 October 2022.
16. October 2022. 3 pm (+8)