

ADVANCED DATA STRUCTURES (COP5536)
SPRING 2018
PROJECT REPORT

Submitted By:
SHRIVINAYAK BHAT
47971819
shrivinayak.bhat@ufl.edu

This project implements Job scheduler which is a simplified version of CFS ie Completely Fair Scheduler of Linux OS.

The data structures used here include Min Heap and Red Black Trees. The implementation language is C++.

The source code has 3 classes which provide the required abstraction.

1) Class Scheduler -

This is the top level class which provides the scheduler functionality as described in the problem statement. The methods that belong to this class are.

- void printjob(int JobID); prints the matching job id
 - void printjob(int JobIDlow,int JobIDhigh); prints the range of jobIDs
 - void nextjob(int JobID); prints the next greatest job wrt inorder traversal
 - void prevjob(int JobID); prints last highest job id wrt inorder traversal
 - void insert(int JobID, int time); inserts new job
 - scheduler(); constructor that initializes the counter and creates objects of class heap & rbt
 - void syncTime(int time); calls dispatch method until counter matches the timestamp of current comand
 - int dispatch(int); schedules jobs
 - int ifjob(); checks if there are any jobs in the queue.
-

2) Class heap

This class facilitates the Min Heap data structure.

The methods are

- `heapnode* insert(int, int, int,rbtnode*)`; insert a new node into the heap.
- `struct heapnode* removeMin()`; remove the item from top of the heap ie minimum executed time.
- `void swapJob(struct heapnode* a,struct heapnode* b)`; swap the positions of two nodes
- `void heapify()`; fix heap properties after a remove min
- `void updateMin(int exec_time)` // updates the root and re arranges the heap
- `heap(int)` // constructor
- `void execute(int)` // function to execute a job

3) Class rbt

This class is responsible for all features of a red black tree data structure.

The methods are

- `void rotateleft(rbtnode *&, rbtnode *&)`; do a left rotation
- `void rotateright(rbtnode *&, rbtnode *&)`; do a right rotation
- `void fixtree(rbtnode *&, rbtnode *&)`; fix rbt properties after insert operation
- `rbt()`; constructor to initialize the tree
- `rbtnode* insert(const int &n)`; insert new node into the tree
- `rbtnode* findnode(int jobid)`; find node based on job id
- `void nextnode(int jobid)`; find next node in inorder traversal
- `void prevnode(int jobid)`; frind prev node in inorder traversal
- `void inorder(int, int)`; print all values in inorder travel in the range low-high
- `void deletenode(rbtnode*)`; - delete a node from the tree
- `void fixviolation(rbtnode*)`; fix violation caused by deletion

The flow of control is shown in the next page

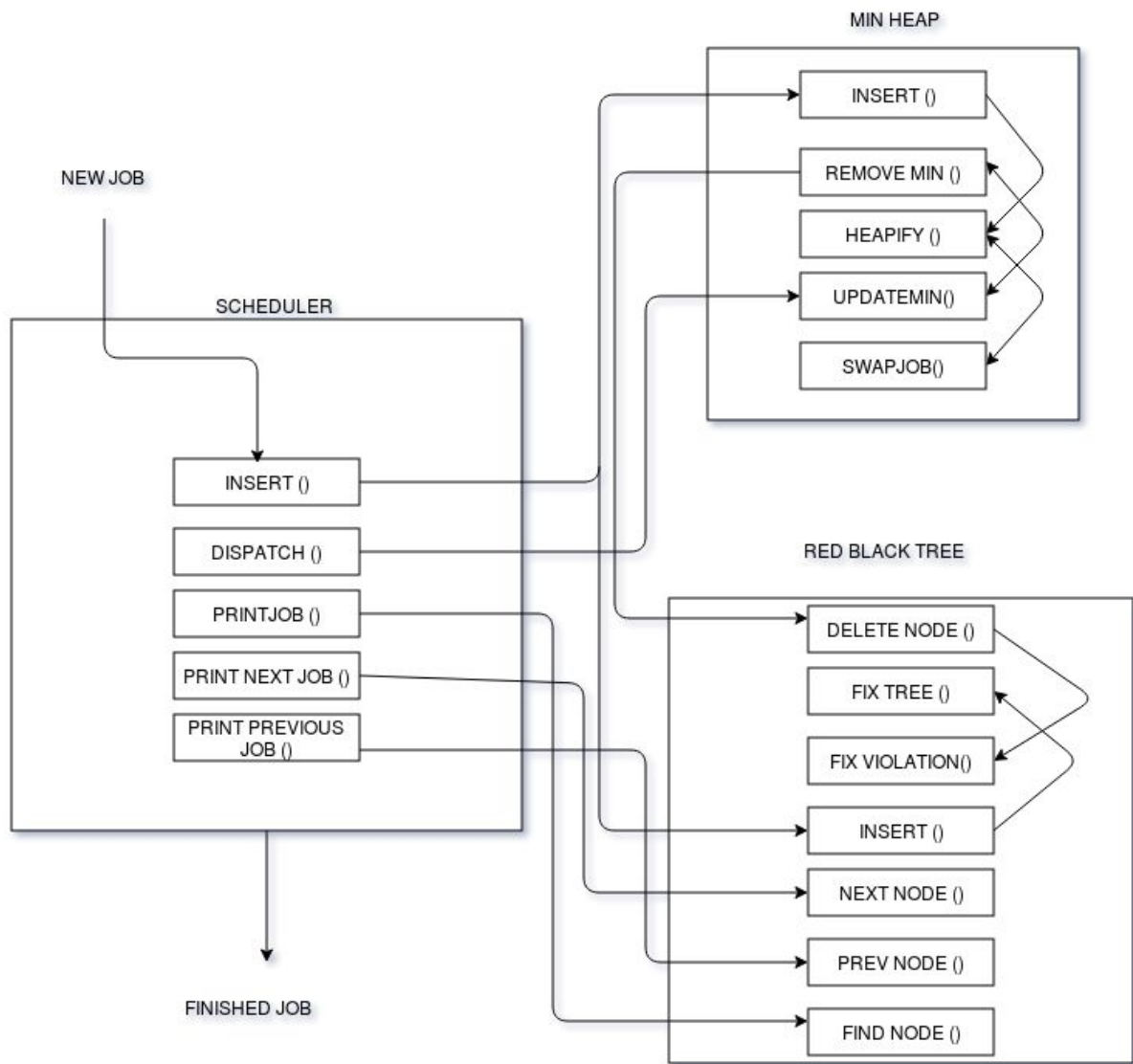


Figure showing the control flow of a scheduler.