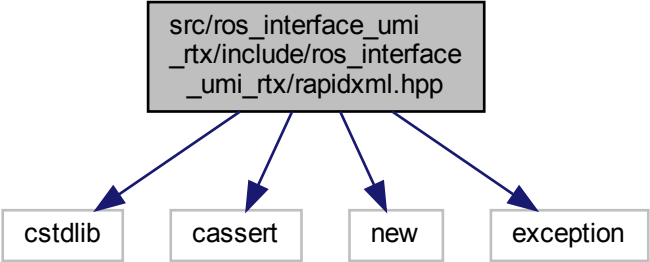


src/ros_interface_umi
_rtx/include/ros_interface
_umi_rtx/rapidxml.hpp



```
graph TD; A["src/ros_interface_umi_rtx/include/ros_interface_umi_rtx/rapidxml.hpp"] --> B[cstdlib]; A --> C[cassert]; A --> D[new]; A --> E[exception];
```

The diagram illustrates the dependencies of the file `src/ros_interface_umi_rtx/include/ros_interface_umi_rtx/rapidxml.hpp`. A central grey box at the top contains the file path. Four blue arrows point downwards from this box to four separate white boxes below, each representing a dependency: `cstdlib`, `cassert`, `new`, and `exception`.

cstdlib

cassert

new

exception