# COMP 551 – Applied Machine Learning Lecture 2: Linear regression

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## Today's Quiz (informal)

Write down the 3 most useful insights you gathered from the article:

"A Few Useful Things to Know About Machine Learning".

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## Supervised learning

- Given a set of <u>training examples</u>:  $x_i = \langle x_{i1}, x_{i2}, x_{i3}, ..., x_{in}, y_i \rangle$ 
  - $\mathbf{x}_{ij}$  is the  $j^{th}$  feature of the  $i^{th}$  example
  - $y_i$  is the desired <u>output</u> (or <u>target</u>) for the  $i^{th}$  example.
  - $X_i$  denotes the  $j^{th}$  feature.
- We want to learn a function f: X<sub>1</sub> × X<sub>2</sub> × ... × X<sub>n</sub> → Y
   which maps the input variables onto the output domain.

tumor size	texture	perimeter		outcome	time
18.02	27.6	117.5		N	31
17.99	10.38	122.8		N	61
20.29	14.34	135.1		R	27
			1	'	

## Supervised learning

- Given a dataset X × Y, find a function: f: X → Y such that f(x) is
  a good predictor for the value of y.
- Formally, f is called the <u>hypothesis</u>.
- Output Y can have many types:
  - If  $Y = \Re$ , this problem is called <u>regression</u>.
  - If Y is a finite discrete set, the problem is called <u>classification</u>.
  - If Y has 2 elements, the problem is called <u>binary classification</u>.

## Prediction problems

The problem of predicting <u>tumour recurrence</u> is called:

#### classification

The problem of predicting the <u>time of recurrence</u> is called:

#### regression

Treat them as two separate supervised learning problems.

tumor size	texture	perimeter		outcome	time
18.02	27.6	117.5		N	31
17.99	10.38	122.8		N	61
20.29	14.34	135.1		R	27
			,		

## Variable types

- Quantitative, often real number measurements.
  - Assumes that similar measurements are similar in nature.
- Qualitative, from a set (categorical, discrete).
  - E.g. {Spam, Not-spam}
- Ordinal, also from a discrete set, without metric relation, but that allows ranking.
  - E.g. {first, second, third}

## The i.i.d. assumption

• In supervised learning, the examples  $x_i$  in the training set are assumed to be independently and identically distributed.

- Independently: Every  $x_i$  is freshly sampled according to some probability distribution D over the data domain X.
- Identically: The distribution D is the same for all examples.

Why?

## Empirical risk minimization

For a given function class *F* and training sample *S*,

Define a notion of error (left intentionally vague for now):

 $L_{S}(f)$  = # mistakes made on the sample S

Define the Empirical Risk Minimization (ERM):

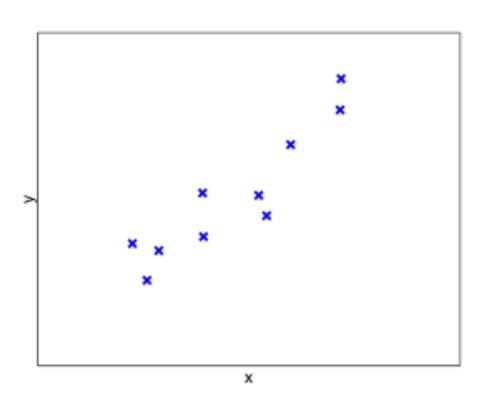
$$ERM_F(S) = argmin_{fin} F L_S(f)$$

where *argmin* returns the function *f* (or set of functions) that achieves the minimum loss on the training sample.

Easier to minimize the error with i.i.d. assumption.

## A regression problem

What <u>hypothesis class</u> should we pick?



Observe	Predict	
X	y	
0.86	2.49	
0.09	0.83	
-0.85	-0.25	
0.87	3.10	
-0.44	0.87	
-0.43	0.02	
-1.1	-0.12	
0.40	1.81	
-0.96	-0.83	
0.17	0.43	

## Linear hypothesis

Suppose Y is a <u>linear function</u> of X:

$$f_{\mathbf{W}}(\mathbf{X}) = w_0 + w_1 x_1 + \dots + w_m x_m$$
  
=  $w_0 + \sum_{j=1:m} w_j x_j$ 

- The w<sub>i</sub> are called parameters or weights.
- To simplify notation, we add an attribute  $x_0=1$  to the m other attributes (also called **bias term** or **intercept**).

How should we pick the weights?

## Least-squares solution method

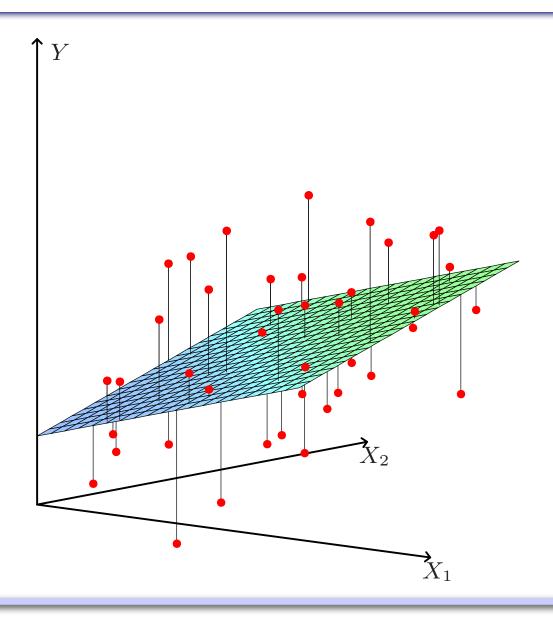
- The linear regression problem:  $f_{\mathbf{w}}(X) = w_0 + \sum_{j=1:m} w_j x_j$ where m = the dimension of observation space, i.e. number of features.
- Goal: Find the best linear model given the data.

   Goal: Find the best linear model given the data.
- Many different possible evaluation criteria!
- Most common choice is to find the w that minimizes:

$$Err(w) = \sum_{i=1:n} (y_i - w^T x_i)^2$$

(A note on notation: Here w and x are column vectors of size m+1.)

## Least-squares solution for $X \in \mathcal{R}^2$



## Least-squares solution method

Re-write in matrix notation: f<sub>w</sub>(X) = Xw

$$Err(\mathbf{w}) = (Y - X\mathbf{w})^T (Y - X\mathbf{w})$$

where X is the n x m matrix of input data,
Y is the n x 1 vector of output data,
w is the m x 1 vector of weights.

To minimize, take the derivative w.r.t. w:

$$\partial Err(\mathbf{w})/\partial \mathbf{w} = -2 X^T (Y-X\mathbf{w})$$

- You get a system of m equations with m unknowns.
- Set these equations to 0:

$$X^{T}(Y-X\mathbf{w})=0$$

## Least-squares solution method

We want to solve for w:

$$X^T (Y - Xw) = 0$$

Try a little algebra:

$$X^T Y = X^T X w$$

$$\mathbf{X}^{T}\mathbf{Y} = \mathbf{X}^{T}\mathbf{X}\mathbf{w} \qquad \mathcal{N} - (\mathbf{X}^{T}\mathbf{X})\mathbf{X}^{T}\mathbf{Y}$$

$$\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$$

(w denotes the estimated weights)

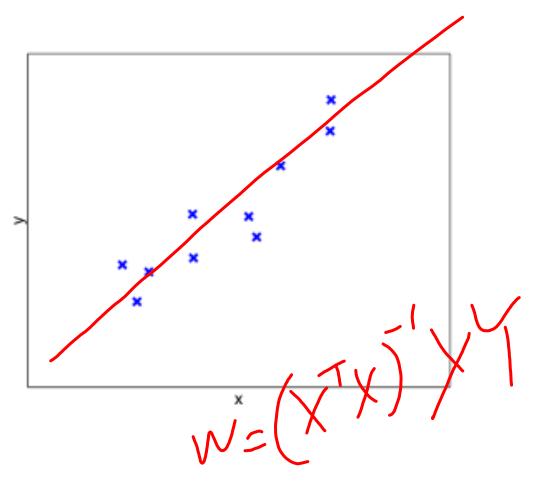
The fitted data:

$$\hat{\mathbf{Y}} = \mathbf{X}\hat{\mathbf{w}} = \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$$

To predict new data  $X' \rightarrow Y'$ :

$$Y' = X'\hat{\mathbf{w}} = X'(X^TX)^{-1}X^TY$$

## Example of linear regression



x	y
0.86	2.49
0.09	0.83
-0.85	-0.25
0.87	3.10
-0.44	0.87
-0.43	0.02
-1.10	-0.12
0.40	1.81
-0.96	-0.83
0.17	0.43

What is a plausible estimate of  $\mathbf{w}$ ?

Try it!

#### Data matrices

$$X^{T}X = \begin{bmatrix} 0.86 & 0.09 & -0.85 & 0.87 & -0.44 & -0.43 & -1.10 & 0.40 & -0.96 & 0.17 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{bmatrix} \times \begin{bmatrix} 0.86 & 1 & 0.09 & 1 & -0.85 & 1 & 0.87 & 1 & 0.87 & 1 & -0.44 & 1 & -0.43 & 1 & -1.10 & 1 & 0.40 & 1 & -0.96 & 1 & 0.17 & 1 \end{bmatrix}$$

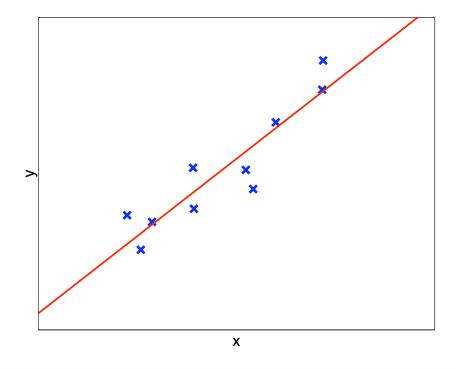
$$= \begin{bmatrix} 4.95 & -1.39 & 10 \end{bmatrix}$$

#### Data matrices

## Solving the problem

$$\mathbf{w} = (X^T X)^{-1} X^T Y = \begin{bmatrix} 4.95 & -1.39 \\ -1.39 & 10 \end{bmatrix}^{-1} \begin{bmatrix} 6.49 \\ 8.34 \end{bmatrix} = \begin{bmatrix} 1.60 \\ 1.05 \end{bmatrix}$$

So the best fit line is y = 1.60x + 1.05.



## Interpreting the solution

- Linear fit for a prostate cancer dataset
  - Features X = {Icavol, Iweight, age, Ibph, svi, Icp, gleason, pgg45}
  - Output y = level of PSA (an enzyme which is elevated with cancer).
  - High coefficient weight (in absolute value) = important for prediction.

Term	Coefficient	Std. Error
Intercept	$w_0 = 2.46$	0.09
lcavol	0.68	0.13
lweight	0.26	0.10
age	-0.14	0.10
lbph	0.21	0.10
svi	0.31	0.12
lcp	-0.29	0.15
gleason	-0.02	0.15
pgg45	0.27	0.15

## Computational cost of linear regression

• What operations are necessary?



- Overall: 1 matrix inversion + 3 matrix multiplications
- $-X^TX$  (other matrix multiplications require fewer operations.)
  - $X^T$  is mxn and X is nxm, so we need  $nm^2$  operations.
- $-(X^TX)^{-1}$ 
  - $X^TX$  is mxm, so we need  $m^3$  operations.

 We can do linear regression in polynomial time, but handling large datasets (many examples, many features) can be problematic. Gradiert Solution

#### An alternative for minimizing mean-squared error (MSE)

- Recall the least-square solution:  $\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$
- What if X is too big to compute this explicitly (e.g.  $m \sim 10^6$ )?

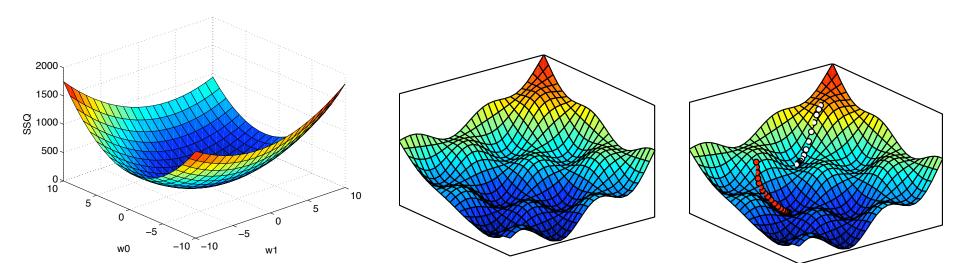
• Go back to the gradient step:  $Err(w) = (Y - Xw)^T (Y - Xw)$ 

$$\partial Err(\mathbf{w})/\partial \mathbf{w} = -2 X^{T} (Y - X\mathbf{w})$$

$$\partial Err(\mathbf{w})/\partial \mathbf{w} = 2(X^T X \mathbf{w} - X^T Y)$$

## Gradient-descent solution for MSE

Consider the error function:



- The gradient of the error is a vector indicating the direction to the minimum point.
- Instead of directly finding that minimum (using the closed-form equation), we can take small steps towards the minimum.

## Gradient-descent solution for MSE

We want to produce a sequence of weight solutions, w<sub>0</sub>, w<sub>1</sub>, w<sub>2</sub>...,
 such that: Err(w<sub>0</sub>) > Err(w<sub>1</sub>) > Err(w<sub>2</sub>) > ...

The algorithm:

Given an initial weight vector  $\mathbf{w}_0$ , Do for k=1, 2, ...

 $\mathbf{w}_{k+1} = \mathbf{w}_k - \alpha_k \frac{\partial Err(\mathbf{w}_k)}{\partial \mathbf{w}_k}$ End when  $|\mathbf{w}_{k+1} - \mathbf{w}_k| < \varepsilon$ 

• Parameter  $\alpha_k > 0$  is the step-size (or <u>learning rate</u>) for iteration k.

# Convergence

• Convergence depends in part on the  $\alpha_k$ .

- If steps are too large: the w<sub>k</sub> may oscillate forever.
  - This suggests that  $\alpha_k \to 0$  as  $k \to \infty$ .

• If steps are too small: the  $\mathbf{w}_k$  may not move far enough to reach a local minimum.

#### Robbins-Monroe conditions

• The  $\alpha_k$  are a Robbins-Monroe sequence if:

$$\sum_{k=0:\infty} \alpha_k = \infty$$

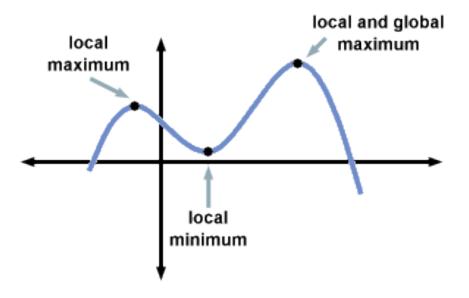
$$\sum_{k=0:\infty} \alpha_k^2 < \infty$$

These conditions are sufficient to ensure convergence of the  $\mathbf{w}_k$  to a **local minimum** of the error function.

E.g. 
$$\alpha_k = 1/(k+1)$$
 (averaging)  
E.g.  $\alpha_k = 1/2$  for  $k = 1, ..., T$   
 $\alpha_k = 1/2^2$  for  $k = T+1, ..., (T+1)+2T$   
etc.

#### Local minima

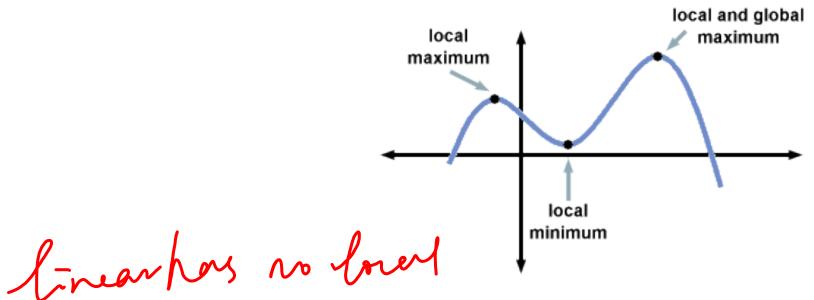
Convergence is <u>NOT</u> to a global minimum, only to local minimum.



The blue line represents the error function. There is <u>no guarantee</u> regarding the amount of error of the weight vector found by gradient descent, compared to the globally optimal solution.

## Local minima

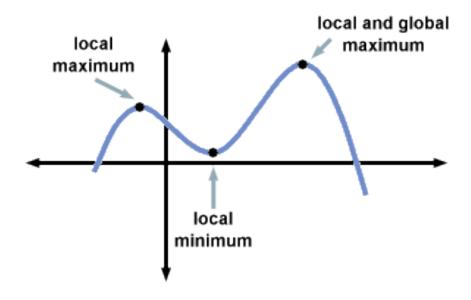
Convergence is <u>NOT</u> to a global minimum, only to local minimum.



- For linear function approximations using Least-Mean Squares (LMS) error, this is not an issue: only ONE global minimum!
  - Local minima affects many other function approximators.

#### Local minima

Convergence is <u>NOT</u> to a global minimum, only to local minimum.



- For linear function approximations using Least-Mean Squares (LMS) error, this is not an issue: only ONE global minimum!
  - Local minima affects many other function approximators.

Repeated random restarts can help (in all cases of gradient search).



- Consider the usual criteria: (Y XV)
- Assume X can be decomposed:  $\begin{cases} X = QR \\ \text{where Q is an } nxm \text{ orthogonal matrix (i.e. } Q^TQ=I), \text{ and } R \text{ is an } mxm \text{ upper triangular matrix.} \end{cases}$
- Replace X in equation above:  $(QR)^TY = (QR)^T(QR)w$
- Distribute the transpose:  $R^TQ^TY = R^TQ^TQRW$
- Let  $Q^TQ=I$  and multiply by  $(R^T)^{-1}$   $Q^TY=Rw$
- Solution:  $\hat{\mathbf{w}} = R^{-1}Q^{T}Y$  The fitted outputs are:  $\hat{Y} = QQ^{T}Y$
- This method is more numerically stable than others, and R-1 is fast to compute because upper triangular.
- Alternately, we can use singular value decomposition.

## What you should know

- Definition and characteristics of a supervised learning problem.
- Linear regression (hypothesis class, cost function, algorithm).
- Closed-form least-squares solution method (algorithm, computational complexity, stability issues).
- Gradient descent method (algorithm, properties).

#### To-do

- Reproduce the linear regression example (slides 15-18), solving it using the software of your choice.
- Suggested complementary readings:
  - Ch.2 (Sec. 2.1-2.4, 2.9) of Hastie et al.
  - Ch.3 of Bishop.
  - Ch.9 of Shalev-Schwartz et al.
- Write down midterm date in agenda: Nov. 22, 6-8pm, Leacock 132.
- Tutorial times (appearing soon): www.cs.mcgill.ca/~jpineau/comp551/schedule.html
- Office hours (confirmed): www.cs.mcgill.ca/~jpineau/comp551/syllabus.html