

## Homework Set 2 for Module 2

*Due at the Beginning of Class (12:30 pm) on Wednesday, October 17*

Name: \_\_\_\_\_ Class No: \_\_\_\_\_ - \_\_\_\_ Lab Div: \_\_\_\_\_

Signature: \_\_\_\_\_ Score: \_\_\_\_\_ / 100

1. [20 points] An interrupt-driven printer interface is desired, but implemented with a GAL22V10 PLD instead of discrete logic. Your job is to: (a) complete the ABEL code for the PLD that implements the interface circuit, and (b) complete the circuit connections between the microcontroller, PLD, and printer. The following declarations and initialization routine are provided:

```

; Port declaration
PTT      equ    $0240      ; Port T I/O
DDRT      equ    $0242      ; Port T DDR
PTAD      equ    $0270      ; Port AD I/O
DDRAD     equ    $0272      ; Port AD DDR

; Mask declarations
imask     equ    $01        ; printer interrupt enable mask
cmask     equ    $02        ; device flag clear mask
smask     equ    $04        ; STROBE mask

; Buffer declarations
psize     equ    100t       ; buffer size
pbuf      rmb    psize      ; printer buffer
pin       rmb    1          ; printer IN ptr
pout      rmb    1          ; printer OUT ptr

; Initialization routine
pinit     clr     pin        ; reset buffer to EMPTY condition
          clr     pout

          movb    #$FF,DDRT  ; initialize DDRs
          movb    #$07,DDRAD

          clr     PTT        ; clear all output port pins
          clr     PTAD

          bset    PTAD,cmask  ; clear printer device flag
          bclr    PTAD,cmask

          bset    PTAD,smask  ; provide initial STROBE with
          bclr    PTAD,smask  ; ASCII null character

          cli                     ; enable IRQ interrupts
          rts

```

Part (a). [12 points] ABEL file (targeted for a GAL22V10):

```

MODULE PrtInt
TITLE 'Printer Interrupt PLD'
CLOCK pin 1;
BUSY pin 2;
BUSYBAR pin 23 istype 'com';
STROBEBAR pin 22 istype 'com';
DEVFLAG pin 18 istype 'reg_D';
!IRQ pin 17 istype 'com';
FLAGCLR pin 16;
STROBE pin 15;
PIE pin 14;
EQUATIONS

BUSYBAR = _____;

STROBEBAR = _____;

DEVFLAG.CLK = _____;

DEVFLAG.D = _____;

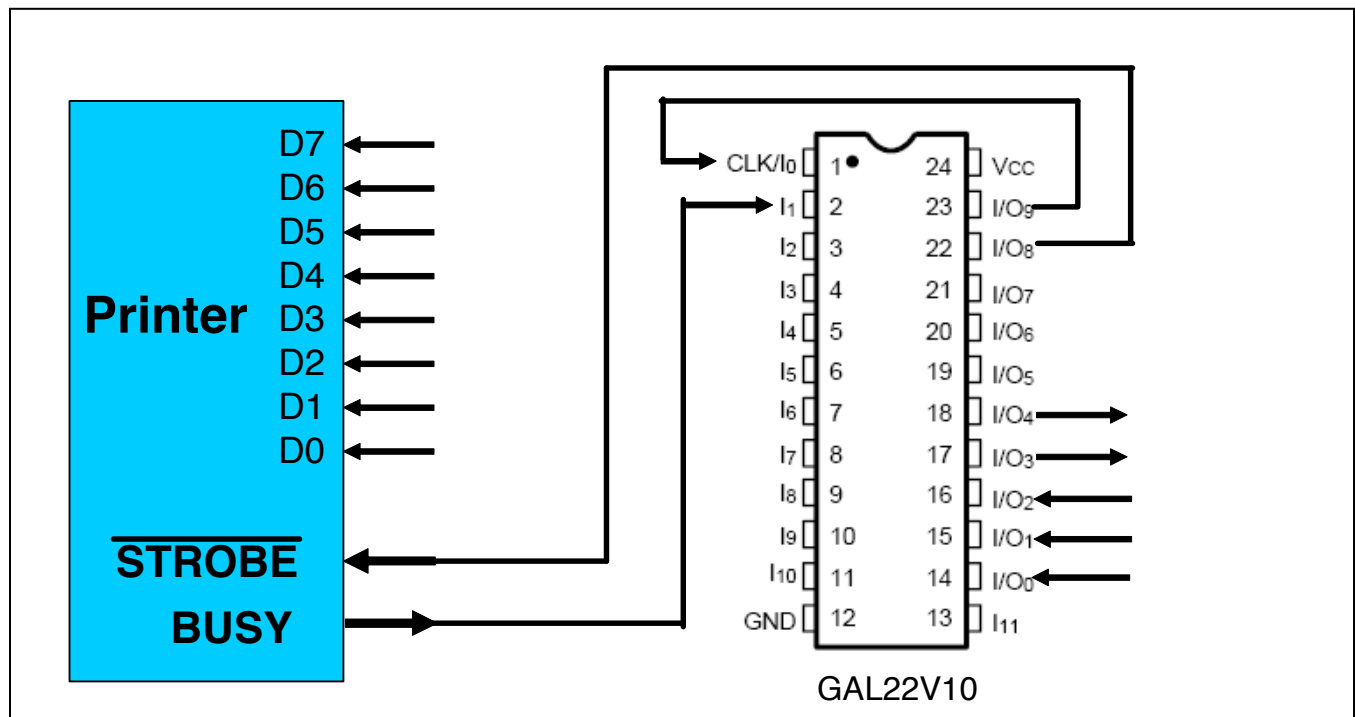
DEVFLAG.AR = _____;

IRQ = _____;

END

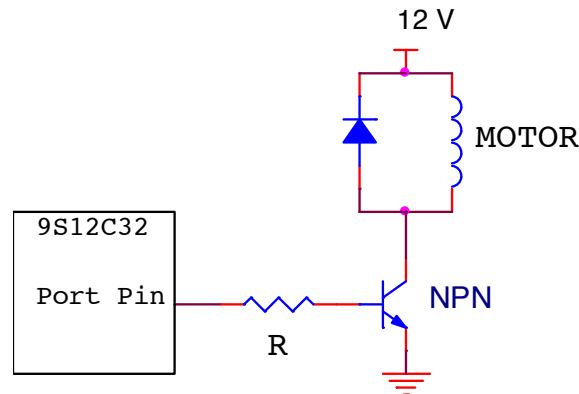
```

Part (b). [8 points] Schematic (label all input/output signals):



2. [10 points] Calculate a suitable value for  $R$ , given that the motor coil requires 5 A of current to operate, that the NPN switching transistor has a  $V_{BEsat} = 0.6$  V and an  $h_{FE} = 600$ , and that the 9S12C32 port pin is programmed to operate in “full drive” mode (i.e., pin can source up to 10 mA at  $V_{OH} = 4.2$  V or sink up to 10 mA at  $V_{OL} = 0.8$  V). Determine the EIA 5% (E24) resistor value that should be used (show calculations).

**Reference:** <http://www.daycounter.com/Calculators/Standard-Resistor-Value-Calculator.phtml>



Calculation of  $R$  value:

Choice of EIA 5% (E24) resistor value:

3. [10 points] Determine the **interrupt rate** and **error range** (associated with running *slow* vs. running *fast*) for a one-second time base if RTICTL is initialized to **\$5A**, as well as the value of RTICNT that should be used for each case. Calculate the “wall clock” error (in minutes) that accumulates for each case after 24 hours of operation. Then answer the following questions: (a) Does either case (slow vs. fast) represent the *minimum error attainable* for a one-second RTI-based timer? (b) Does either case represent the *maximum error attainable* for a one-second RTI-based timer?

“slow” interrupt rate: \_\_\_\_\_ ms “slow” RTICNT: \_\_\_\_\_ “slow” error after 24 hrs: \_\_\_\_\_ min

“fast” interrupt rate: \_\_\_\_\_ ms “fast” RTICNT: \_\_\_\_\_ “fast” error after 24 hrs: \_\_\_\_\_ min

Does either case represent the *minimum error attainable* for a one-second RTI-based timer?

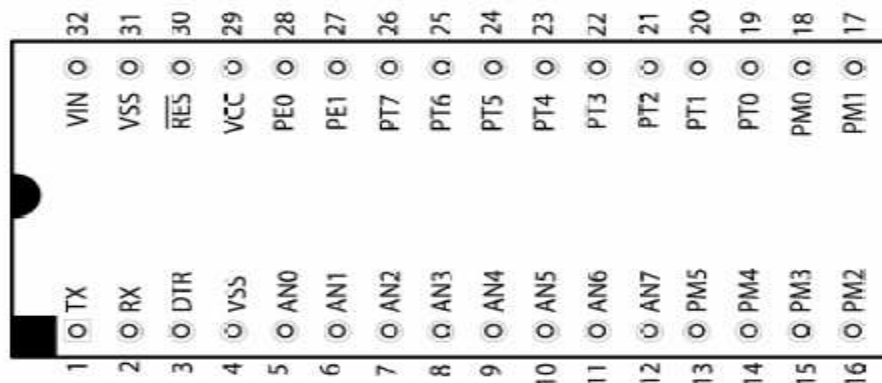
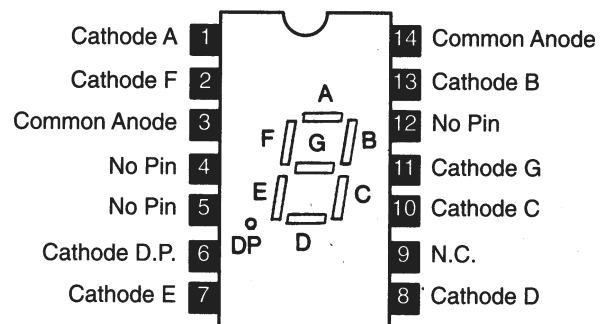
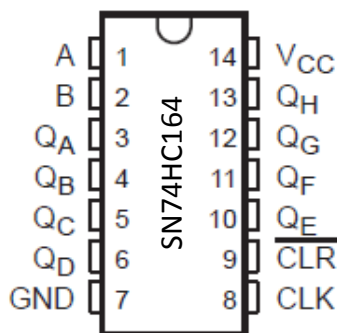
Does either case represent the *maximum error attainable* for a one-second RTI-based timer?

4. [20 points] Show how a 7-segment common anode LED display could be interfaced to your microcontroller module using a 74HC164 8-bit shift register. Calculate the value of current limiting resistor needed for each segment based on the D.C. characteristics of the 74HC164 (see data sheet posted on homework page) – assume the forward voltage of each LED segment is **2.1 V** at a (maximum) forward current of 20 mA, and that “maximum brightness” of the display is desired. Determine the EIA 10% (E12) resistor value that should be used and complete the circuit, below.

**NOTE: A “0” in a shift register bit will turn the corresponding segment “on” (i.e., current must be sunk by a 74HC164 output pin to turn on the corresponding LED segment). Assume data is shifted out “DP” first, followed by segment g, segment f, etc.**

Calculation of R value:

Choice of EIA 10% (E12) resistor value:



5. [20 points] Write an initialization routine that configures the microcontroller port pins used by the interface you designed for Problem 4. Then, write a device driver `out7` that takes the 7-segment display code passed in the A register (ordered **DP-g-f-e-d-c-b-a** from *msb* to *lsb*) and “clocks” it into the 74HC164 shift register. Identify any timing constraints imposed on your interface based on the 74HC164’s A.C. characteristics. Finally, determine the total number of cycles required to execute your `out7` routine.

Initialization routine:

Device driver:

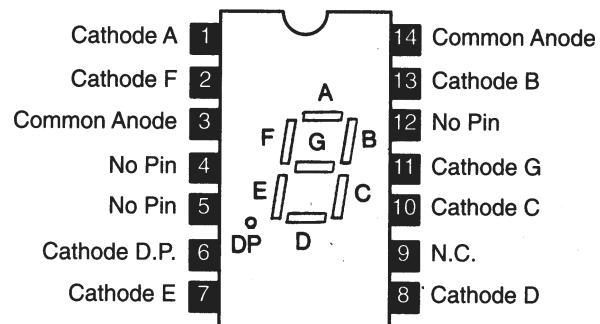
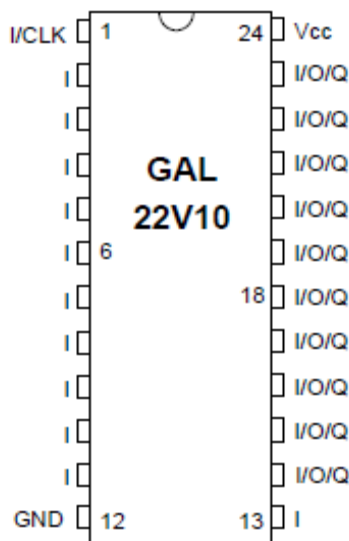
Timing constraints and total cycle count:

6. [20 points] Repeat Problem 4 using a GAL22V10 (programmed as shown) in place of the 74HC164. Calculate the value of current limiting resistor needed for each LED segment based on the D.C. characteristics of the GAL22V10 (see data sheet posted on homework page) – assume the forward voltage of each LED segment is **2.1 V** at a (maximum) forward current of 20 mA, and that “maximum brightness” of the display is desired. Determine the EIA 10% (E12) resistor value that should be used and complete the circuit, below. *Note which of the two designs (74HC164 vs. GAL22V10) yields the “brightest” display.*

**NOTE: A “1” in a shift register bit will turn the corresponding segment “on” (i.e., current must be sunk by a GAL22V10 output pin to turn on the corresponding LED segment). Assume data is shifted out “DP” first, followed by segment g, segment f, etc.**

Calculation of R value:

Choice of EIA 10% (E12) resistor value:



```

MODULE shiftreg
TITLE '8-bit Shift Register'
DECLARATIONS
clock pin 1;
serial_in pin 2;
!q0..!q7 pin 14..21 istype 'reg';

EQUATIONS
[q1..q7] := [q0..q6];
q0 := serial_in;
[q0..q7].clk = clock;
END

```

