

Software Project Lab-01

Project Name : Leverage Score Sampling

Presented by :
Mahir Faisal
Roll- 1316

Supervised by :
Prof.Dr.Mohammad Shoyaib



Overview

Tasks that I have already completed of my project.

- Input a matrix from file
- Calculate transpose of the matrix
- Multiply two matrix
- Finding coefficients for the polynomial equation from the given matrix
- Calculating determinant of the matrix
- Calculating the inverse of a matrix
- Solving polynomial equation
- Finding eigenvalues of a matrix
- Linear equation solving using Gauss Jordan elimination



Transpose matrix calculation

Transpose matrix of M is M^T such that all rows of the matrix M convert to column of M^T & all column convert to rows

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}^T = \begin{bmatrix} a_{11} & a_{21} & a_{31} \\ a_{12} & a_{22} & a_{32} \\ a_{13} & a_{23} & a_{33} \end{bmatrix}$$

Like,

$M =$

5	-8	9
-6	7	3
10	8	12

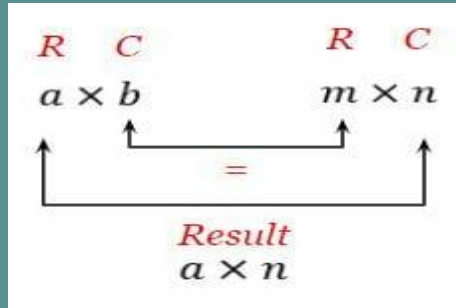
So,

$M^T =$

5	-6	10
-8	7	8
9	3	12

Matrix Multiplication

If we consider two matrix $A(a \times b)$ & $B(m \times n)$, then the criteria for multiplication of AB



$$\begin{bmatrix} a_1 & a_2 & a_3 \\ a_4 & a_5 & a_6 \\ a_7 & a_8 & a_9 \end{bmatrix} \begin{bmatrix} b_1 & b_2 & b_3 \\ b_4 & b_5 & b_6 \\ b_7 & b_8 & b_9 \end{bmatrix} = \begin{bmatrix} c_1 & c_2 & c_3 \\ c_4 & c_5 & c_6 \\ c_7 & c_8 & c_9 \end{bmatrix}$$

Let,

A =

$$\begin{bmatrix} 5 & -8 & 9 \\ -6 & 7 & 3 \\ 10 & 8 & 12 \end{bmatrix}$$

AB =

$$\begin{aligned} & (5 \times 5) + (-8 \times -8) + (9 \times 9) & \dots & \dots \\ & (-6 \times -6) + (7 \times 7) + (3 \times 3) & \dots & \dots \\ & (10 \times 10) + (8 \times 8) + (12 \times 12) & \dots & \dots \end{aligned}$$

B =

$$\begin{bmatrix} 5 & -6 & 10 \\ -8 & 7 & 8 \\ 9 & 3 & 12 \end{bmatrix}$$

AB =

$$\begin{bmatrix} 170 & -59 & 94 \\ -59 & 94 & 32 \\ 94 & 32 & 308 \end{bmatrix}$$

Process of finding Eigenvalues & corresponding Eigenvectors

First of all we have to create a polynomial equation of Eigenvalues λ_i from the characteristic equation $|w-\lambda I| = 0$ of the data matrix M

After solving characteristic equation, we find a polynomial equation, such that

$$C_1\lambda^n + C_2\lambda^{n-1} + \dots + C_{n-1}\lambda + C_n = 0$$

We will use Bairstow algorithm to find n Eigenvalues. According to Bairstow algorithm we have to input the coefficients, that means C_1, C_2, \dots, C_n

Thus we will use Faddeev–LeVerrier algorithm to find those coefficients from the data matrix M . That means the outputs of the Faddeev–LeVerrier algorithm are C_1, C_2, \dots, C_n

Faddeev–LeVerrier algorithm

Initialize a identity matrix, $A_1 =$

$$\begin{bmatrix} 1 & 0 & 0 & \dots & \dots \\ 0 & 1 & 0 & \dots & \dots \\ 0 & 0 & 1 & \dots & \dots \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \vdots & \dots & 1 \end{bmatrix}$$

Then we calculate,

$$A_m = MA_{m-1} + C_{n-m+1}I$$

$$C_{n-m} = -\frac{1}{m} \text{tr}(A_m)$$

Let

$M =$

$$\begin{bmatrix} 3 & 1 & 5 \\ 3 & 3 & 1 \\ 4 & 6 & 4 \end{bmatrix}$$

$$C_3 = 0$$

$A_1 =$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$MA_1 =$

$$\begin{bmatrix} 3 & 1 & 5 \\ 3 & 3 & 1 \\ 4 & 6 & 4 \end{bmatrix}$$

Where,

M is the given matrix

n is the dimension of the matrix M

C are the coefficients of the polynomial equation

I is an identity matrix

$\text{tr}(A_m)$ = trace of the matrix A_m

$$\begin{aligned} C_2 &= -\frac{1}{1} (3+3+4) \\ &= -10 \end{aligned}$$

$A_2 =$

$$\begin{bmatrix} -7 & 1 & 5 \\ 3 & -7 & 1 \\ 4 & 6 & -6 \end{bmatrix}$$

$MA_2 =$

$$\begin{bmatrix} 2 & 26 & -14 \\ -8 & -12 & 12 \\ 6 & -14 & 2 \end{bmatrix}$$

$$C_1 = -\frac{1}{2} (-8) = 4$$

$A_3 =$

$$\begin{bmatrix} 6 & 26 & -14 \\ -8 & -8 & 12 \\ 6 & -14 & 6 \end{bmatrix}$$

$MA_3 =$

$$\begin{bmatrix} 40 & 0 & 0 \\ 0 & 40 & 0 \\ 0 & 0 & 40 \end{bmatrix}$$

$$C_0 = -\frac{1}{3} (120) = -40$$

Furthermore, $A_4 = MA_3 + C_0 I = 0$ which confirms the above calculations

It's very glad to know that $(-1)^3.C_0 = 40$ is the determinant of the given matrix M

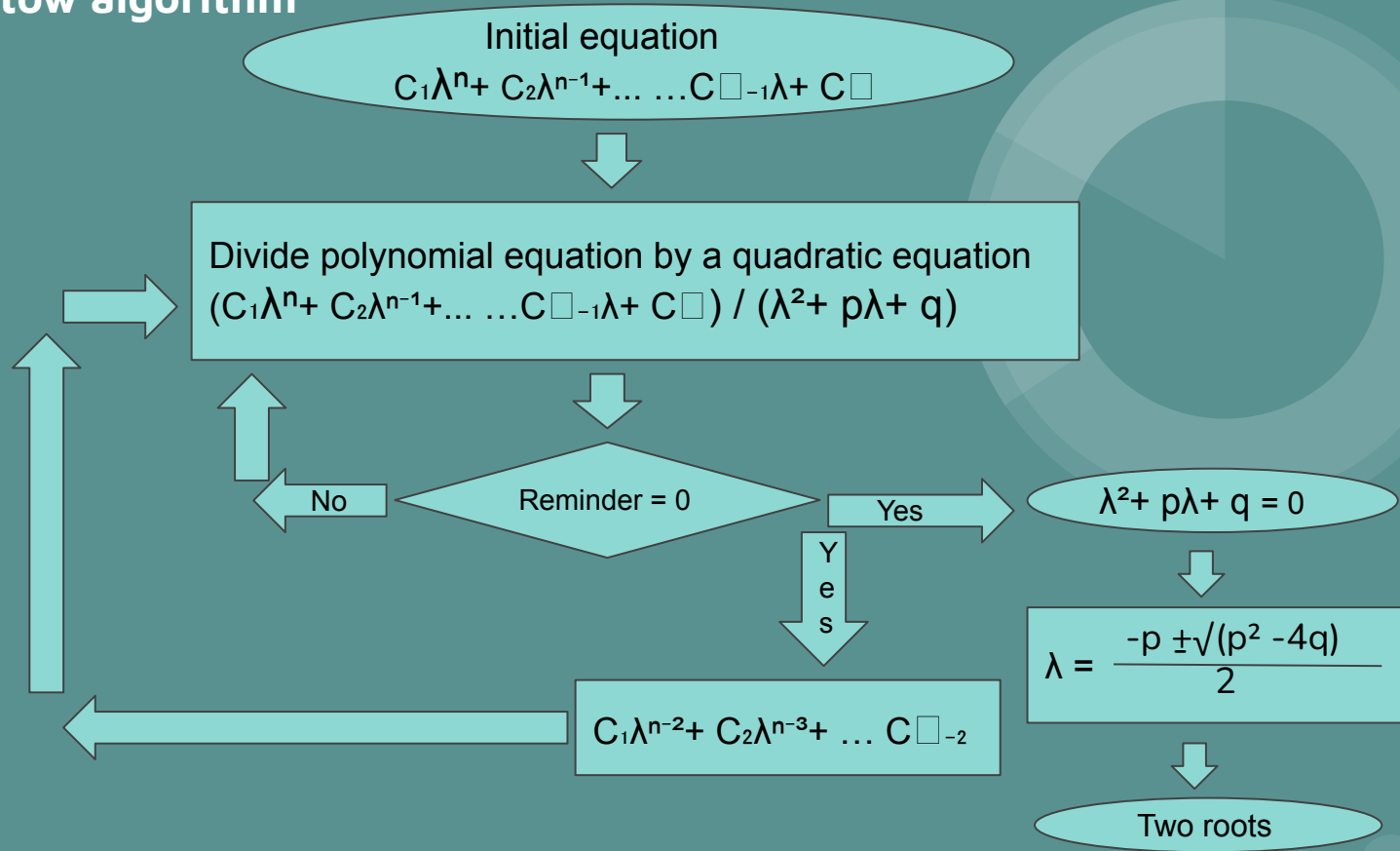
It's also an interesting part that the inverse of the given matrix is $(-1/C_0).A_3$

So, $M^{-1} = (-1/(-40)).A_3$

$M^{-1} =$

$$\begin{bmatrix} 3/20 & 13/20 & -7/20 \\ -1/5 & -1/5 & 3/10 \\ 3/20 & -7/20 & 3/20 \end{bmatrix}$$

Bairstow algorithm



Bairstow algorithm (continued)

The quadratic equation $x^2 + px + q = 0$ starts with a initial guess p & q , then it will change iteratively

a is the array of coefficients, found from Faddeev–LeVerrier algorithm

Initial p & q are, $p = (a_{n-1}/a_n)$, $q = (a_{n-2}/a_n)$, if($p = 0$) $p=0.1$, if($q=0$) $q=0.1$

b is the array such that...

$$b_n = a_n$$

$$b_{n-1} = a_{n-1} + b_n * p$$

Then, for $i = (n-2)$ to 0

$$b_i = a_i + (b_{i+1} * p) + (b_{i+2} * q)$$

Another array c such that...

$$c_n = b_n$$

$$c_{n-1} = b_{n-1} + c_n * p \text{ and so on}$$

Iterative approach for changing p, q

$$\Delta p = \frac{b_0 c_3 - b_1 c_2}{c_2 c_2 - c_1 c_3}$$

$$\Delta q = \frac{b_1 c_1 - b_0 c_2}{c_2 c_2 - c_1 c_3}$$

$$p' = p, \quad q' = q$$

$$p = p + \Delta p$$

$$q = q + \Delta q$$

Bairstow algorithm (continued)

Root finding

```
last = false ; phi = 1.0e-12 ;  
if( n = 1 ) root = ( a[n-1] / a[n]  
); else if(n=2) last = true ;  
    call-> printRoot( a[n], a[n-1],  
a[n-2]);  
    else while(1)  
        cal_col(a,b) ; cal_col(b,c) ;  
        cal_p_q() ;  
        ratio_p =  $\Delta p/p'$  ; ratio_q =  $\Delta q/q'$  ;  
        if(abs(b0<=phi) & abs(b1<=phi) or  
abs(ratio_p<=phi) or abs(ratio_q<=phi))  
            call-> printRoot(1,p,q) ;  
        if(n=4) last = true ;  
        call-> printRoot(b[n],b[n-1],b[n-2]) ; break ;  
        if(n=3) root = b[n-1] / b[n] ; break ;  
        call-> reduce_equation() ;
```

reduce_equation()

reform the array a, such that

$a_i = b_{i+2}$; $n = (n-2)$; for $i=0$ to $(n-1)$;

remove_error(double v)

int i = v ;

if (abs(i - v) <= phi) v = (double) i ;

Bairstow algorithm (continued)

printRoot(double x, double y, double z)

```
if( !last )
    y = -1*remove_error(y) ;
    z = -1*remove_error(z) ;
else
    y = remove_error(y) ;
    z = remove_error(z) ;

determine = (y*y) - 4*x*z ;
if(determine>0)
    determine = sqrt( determine) ;

root_1 = remove_error((( -y) - determine) / (2*x)) ;
root_2 = remove_error((( -y) + determine) / (2*x)) ;
```

Gauss Jordan Elimination

Consider a Augmented Matrix Ab

for $i=0$ to Row

$L = Ab_{ii}$;

for $j = 0$ to Col+1

$Ab_{ij} = Ab_{ij} / L$;

for $k=0$ to Col+1

if ($k \neq i$) $M = -Ab_{ki}$;

$Ab_{kj} = Ab_{kj} + M * L$

Ab_{ij} ;

So, the value of all variable of the linear equation are...

for $i=0$ to Row

$Ab_{i\beta}$; where β = number of column

Let, the linear equation

$$x - 2y = -4$$

$$-5y + z = -9$$

$$4x - 3z = -10$$

Augmented Matrix

$Ab =$

$$\begin{array}{ccc|c} 1 & -2 & 0 & -4 \\ 0 & -5 & 1 & -9 \\ 4 & 0 & -3 & -10 \end{array}$$

After applying Gauss Jordan...

$Ab =$

$$\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 6 \end{array}$$

So, variables...

$$x = 2$$

$$y = 3$$

$$z = 6$$

Singular Value Decomposition

Here SVD is used for **Sampling a data which is considered as a matrix**

Let, the data matrix is M ($m \times n$), such that...

$$M = U \Sigma V^T$$

For square matrix $m = n$

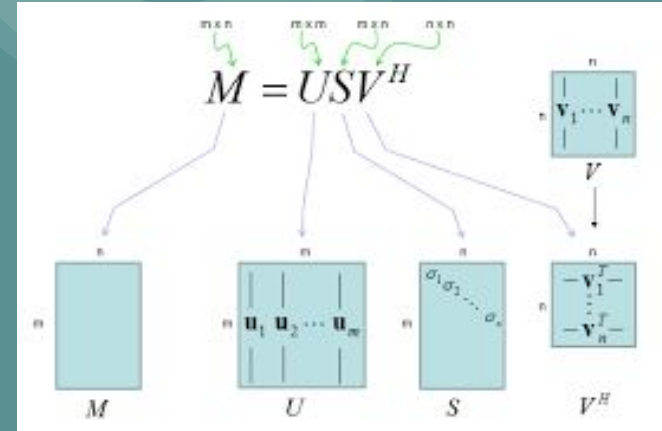
Where,

U is a $m \times m$ orthonormal eigenvectors of $M M^T$

Σ is a $m \times n$ diagonal matrix of the singular values
Which are the square roots of the eigenvalues of

$M^T M$

V^T is a $n \times n$ orthonormal eigenvectors of $M^T M$



Procedure of computing SVD of the given matrix M

First of all we need to compute the left singular vector by finding Eigenvalues of $w = M M^T$

Solving characteristic equation $|w - \lambda I| = 0$

We find m eigenvalues & eigenvectors U_i for the corresponding eigenvalues

Now, create the left singular vector U from the normalize vectors U_i such that ...

$$U = \begin{bmatrix} U_1 & U_2 & \dots & \dots & \dots & U_m \end{bmatrix}$$

Now, we compute the right Eigenvector by finding eigenvalues of $w = M^T M$

Solving characteristic equation $|w - \lambda I| = 0$

We find n eigenvalues & eigenvectors V_i for the corresponding eigenvalues

Now, create the right singular vector V from the normalize vectors V_i such that ...

$$V = \begin{bmatrix} V_1 & V_2 & \dots & \dots & \dots & V_n \end{bmatrix}$$

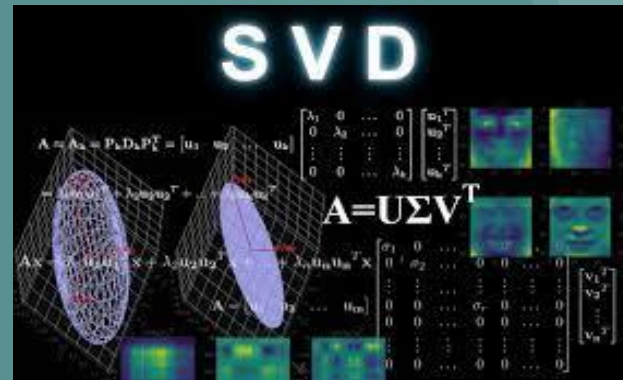
Then, calculate V^T

$$V^T = \begin{bmatrix} V_1^T & V_2^T & \dots & \dots & \dots & V_n^T \end{bmatrix}$$

For calculating diagonal matrix Σ , we need n singular values which are the square root of the eigenvalues of $M^T M$

$$\Sigma =$$

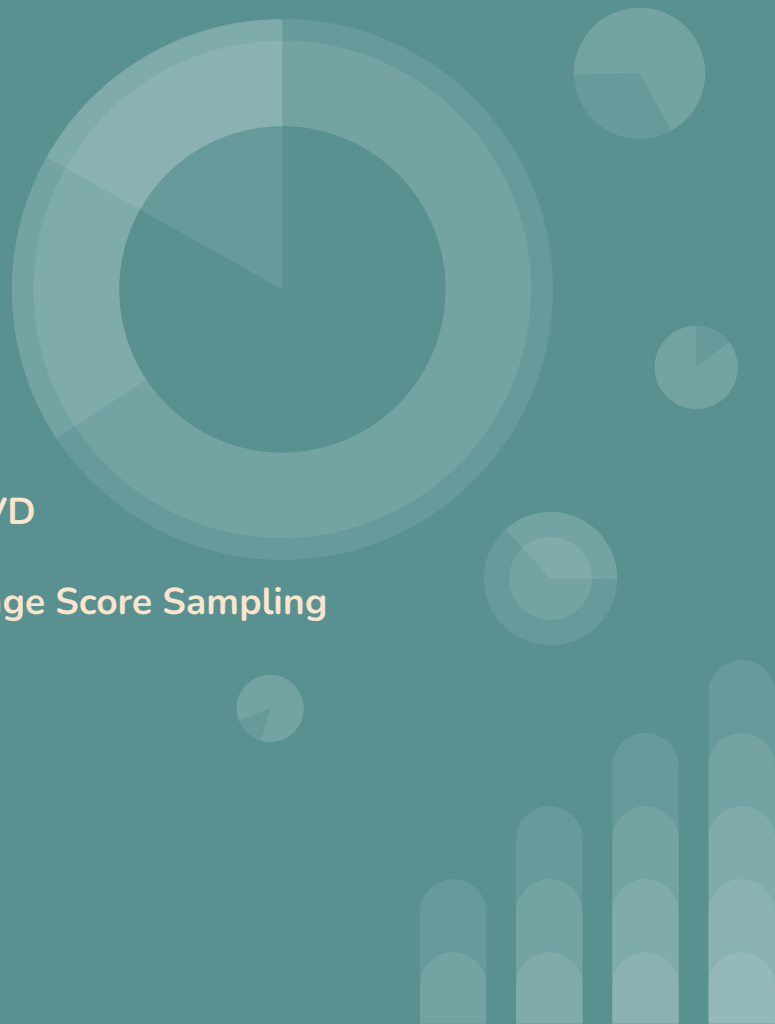
$$\begin{array}{cccc} \sigma_1 & 0 & 0 & \dots \\ 0 & \sigma_2 & 0 & \dots \\ \vdots & \vdots & \vdots & \ddots \\ \vdots & \vdots & \vdots & \sigma_{\square} \end{array}$$



Overview(again)

Tasks that will be done at the next step

- Echelon form of a Matrix
- Eigenvector calculation
- Singular value Decomposition(SVD)
- Probability from SVD
- **Pseudo inverse of the matrix using SVD**
- **Leverage Score Sampling**
- Probability Estimation based on **Leverage Score Sampling**



Challenges Faced

- Passing a 2D array to a function & finding result
- Mathematical notation conversion to code
- Finding coefficients for polynomial(characteristic) equation
- Defining Regular inverse of the matrix
- Calculating eigenvalues from the polynomial equation
- Separate real & complex eigenvalues
- Solving eigenvectors for corresponding eigenvalues
- Define orthonormal vectors
- Handling big line of code for the first time

Lines of code

775+

Thank You

