

LULEÅ UNIVERSITY OF TECHNOLOGY

DEPT. OF COMPUTER SCIENCE, ELECTRICAL AND
SPACE ENGINEERING

X7005E – MASTER THESIS ENGINEERING PHYSICS AND ELECTRICAL ENGINEERING
ELECTRICAL ENGINEERING

Master Thesis Engineering
Physics and Electrical
Engineering *VHF-Unit*

Author
Lundberg, Josef,

Supervisor at the company
Evertsson, Bengt

*Supervisor at the
university*
Johansson, Jonny?

March 14, 2018



Abstract

Surveillance and control has come a long way the last years. Every new mobile phone, most cars and smart watches have a GPS tracing device built in to it. Today it is hard to go anywhere without having some sort way of finding you. The art of finding has been around for a long time and one company that have taken the tracking aspect to the next step is followit. For over 40? years they have built different types of GPS and radio transmitters to keep track of everything from small animals like hares and dogs to Elephants and also vehicles like trucks and excavators.

Contents

1	Acronyms	3
2	Glossary	4
3	Introduction	2
4	Functionality	3
4.1	MCU	4
4.2	Accelerometer	4
5	Casing	5
	References	6
	Appendices	8
A	Large Figures	8
B	Lists	9
B.1	Bill of Materials: Main Printed Circuit Board (PCB)	9
B.2	Bill of Materials: Battery Management PCB	10

1 Acronyms

1. **2S** Two cells in Series *Glossary:* 2S
2. **ADC** Analog-to-digital converter *Glossary:* ADC
3. **API** Application Programming Interface *Glossary:* API
4. **CAD** Computer-aided design *Glossary:* CAD
5. **DRC** Design Rule Check *Glossary:* DRC
6. **ERC** Electronic Rule Check *Glossary:* ERC
7. **GPIO** General Purpose Input Output *Glossary:* GPIO
8. **GPS** Global Positioning System *Glossary:* GPS
9. **I²C** Inter-Integrated Circuit *Glossary:* I²C
10. **IC** Integrated Circuit *Glossary:* IC
11. **IMU** Inertial Measurement Unit 3, *Glossary:* IMU
12. **LDO** Low-dropout regulator 3, *Glossary:* LDO
13. **LED** Light-emitting diode *Glossary:* LED
14. **LGA** Land Grid Array *Glossary:* LGA
15. **LIB** Battery Management System *Glossary:* LIB
16. **MCU** Microcontroller Unit 3, 4, *Glossary:* MCU
17. **NAME** Personal Computer *Glossary:* PC
18. **NMEA** National Marine Electronics Association standard *Glossary:* NMEA
19. **PCB** Printed Circuit Board 2, 9, 10, *Glossary:* PCB
20. **PNG** Portable Network Graphics *Glossary:* PNG
21. **PTC** Positive Temperature Coefficient *Glossary:* PTC
22. **PWB** Printed Wire Board *Glossary:* PWB
23. **RTC** Real time clock 3, *Glossary:* RTC
24. **SEK** Swedish Krona *Glossary:* SEK

- 25. SMD** Surface Mount Device *Glossary:* SMD
- 26. SPI** Serial Peripheral Interface *Glossary:* SPI
- 27. ST** STMicroelectronics 6, *Glossary:* ST
- 28. SWD** Serial Wire Debug *Glossary:* SWD
- 29. TI** Texas Instruments Inc. *Glossary:* TI
- 30. ToF** Time of Flight *Glossary:* ToF
- 31. USB** Universal Serial Bus *Glossary:* USB
- 32. via** vertical interconnect access *Glossary:* VIA

2 Glossary

- 33. IMU** Inertial Measurement Units (IMUs) are integrated circuits that can measure acceleration, rotational velocity and magnetic field strength. 3
- 34. LDO** A low-dropout regulator is a DC linear voltage regulator that can regulate the output voltage even when the supply voltage is very close to the output voltage. 3
- 35. MCU** A Microcontroller Unit (MCU) is a single computer chip designed for embedded applications. 3
- 36. RTC** A Real time clock is an IC that is used to measure time even when the main device is off. 3
- 37. ST** STMicroelectronics (ST) is a French-Italian multinational electronics and semiconductor manufacturer. 6

3 Introduction

This is not a new area of products for Followit, they have made radio sending units for over 40? years. When new and improved technology arrives every year you need to make new products to have the latest most efficient and effective systems. Every generation of a component will most likely have a smaller physical size, have more advanced features and draw less power. They want to make a new unit. Customers have been asking for a simple, small and cheap radio unit from the company to complement their more advanced and powerful GPS based products. With this type of product they could produce them in a larger number and get gain new sale territories. By having such small product it can be used in new areas that they never could before. The smaller the animal you want to track gets the smaller equipment you could strap to them. This is one of the reasons that this product is so sought for in the business.

4 Functionality

The product is constructed with a number of components, which all have a central role of the final product. They can all be seen in Figure 1. A list of the major components and their function can be seen below

- Microcontroller Unit (MCU): The central part of any integrated system, handles all the calculations and the program code.
- Radio: All the communications with the rest of the world will be handled by the radio, sending on the VHF and UHF band.
- Inertial Measurement Unit (IMU): Movement detection is measured with a accelerometer, this to determine if the unit is in motion or laying still.
- Low-dropout regulator (LDO): A Low-dropout regulator can supply the system with a smoother voltage because no switching is actually taking place.
- Hall sensor: The hall sensor is used as a switch for the system by sensing if a magnet is nearby and then turning off the circuit.
- Real time clock (RTC): A real time clock is important to acquire data at a specific set time, it is important that the clock is exact over the whole life of the product.

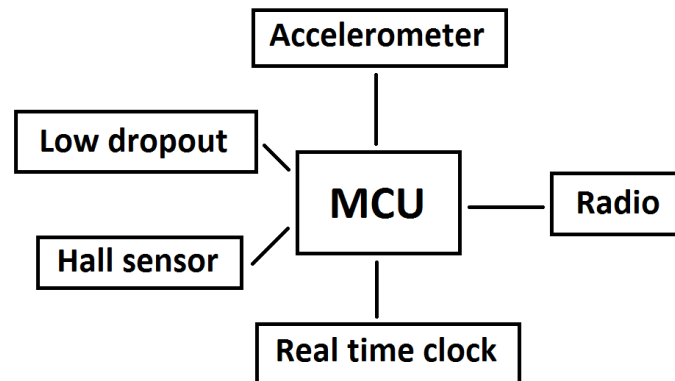


Figure 1: The prototype connection

Source: Aurthor

Each of the components in this project is carefully chosen to get the functionality and effect that the company is after. To ensure the system works as intended the company have acquired development boards to each of the components. Every components needs to be tested to ensure their individual functionality. Each development board is connected to the micro controllers board. First off the glsmcu have to be set up in a correct way with all it parameters and then the other components could be connected and initilized one after another. The whole connection can be seen in Figure 2

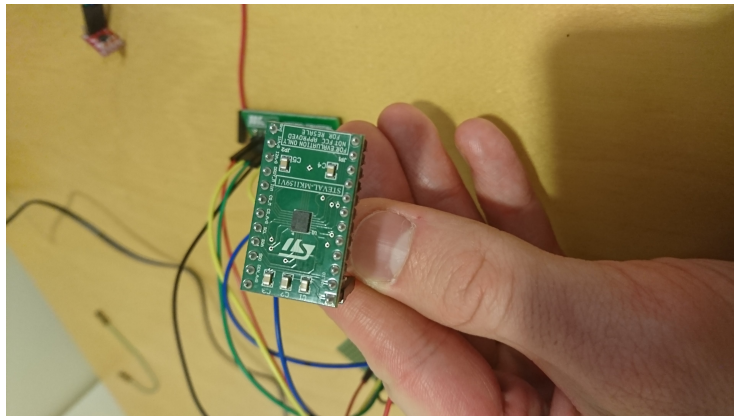


Figure 2: The prototype connection

Source: [Aurthor](#)

The MCU can dtad

4.1 MCU

The MCU used for this project is a processor type that is used by this company many times before and has been chosen to this project for its and low power draw.

4.2 Accelerometer

The accelerometer used is a

5 Casing

The *VHF-Unit* system has some different types of components and sensors, which all need to be housed in a watertight casing for safety and robustness. Some design ideas for this part was to make it easy to mount, small physical footprint, all the electronics in the same enclosure and watertight. The case was revised and worked on over the whole length of the course, redefining and remodeling the construction over time.

References

- [1] <https://www.autodesk.com/products/fusion-360/overview>
- [2] <ltu.diva-portal.org/smash/get/diva2:1039147/FULLTEXT01.pdf>
- [3] <http://www.te.com/commerce/DocumentDelivery/DDEController?Action=srchtrrv&DocNm=FX19&DocType=DS&DocLang=English>
- [4] <http://www.lygte-info.dk/info/battery%20protection%20UK.html>
- [5] KiCad library entry for voltage regulator component lm1117 by *ObKo*, 2012, <https://github.com/ObKo/kicad-libraries/blob/master/libraries/lm1117.lib>.
- [6] Overvoltage and Reverse-voltage Protection in Automotive Systems, Application note 760, *Maxim integrated*, Apr 02, 2002, <https://www.maximintegrated.com/en/app-notes/index.mvp/id/760>.
- [7] STMicroelectronics (ST), Application note: AN4907, *VL53L0X ranging module cover window guidelines*, http://www.st.com/content/ccc/resource/technical/document/application_note/group0/9d/93/be/33/13/be/46/19/DM00326504/files/DM00326504.pdf/jcr:content/translations/en.DM00326504.pdf
- [8] Duygun, M., Kutlu, L. & Sickles, R.C., Journal of Productivity Analysis, 2016, 46: 155, <https://doi.org/10.1007/s11123-016-0477-z>
- [9] Power Guy, *Constant Current Constant voltage*, May 26, 2016, San Diego, USA, <https://www.us.tdk-lambda.com/media/292143/tdk-lambda-blog-052616.pdf>.
- [10] D.L. Hall and J. Llinas, *An introduction to multisensor data fusion*, Proceedings of the IEEE, 85(1):6 –23, jan 1997.
- [11] B.R. Grover H, Patrick, *Introduction to random signals and applied Kalman filtering*, 1997.
- [12] Society of Naval Architects and Marine Engineers (SNAME), *Principles of Naval Architecture*, 1989, Vol. III, *SNAME*.
- [13] Dr. Oliver Nelles, *nonlinear system identification*.
- [14] Noureldin., Karamat T.B., Georgy J., 2013, *Basic Navigational Mathematics, Reference Frames and the Earth's Geometry*. In: *Fundamentals of Inertial Navigation, Satellite-based Positioning and their Integration*, Springer, Berlin, Heidelberg.
- [15] D.L. Hall and J. Llinas. *An introduction to multisensor data fusion*, Proceedings of the. IEEE, 85(1):6 –23, jan 1997.
- [16] Henry Stark, John W Woods, *Probability and Random Processes with Applications to Signal Processing*, 4/E 2012, Pearson Higher Education.
- [17] Donald E. Catlin, *Estimation, Control, and the Discrete Kalman Filter*, 1989.

- [18] Weicker, P., *A Systems Approach to Lithium-ion Battery Management*, Boston, Artech House, 2014.

Appendices

A Large Figures

B Lists

B.1 Bill of Materials: Main PCB

Main Board Components	Package	Quantity
<i>Capacitors:</i>		
18p	0805	2
100n	0805	21
1u	0805	2
2.2u	0805	1
4.7u	0805	4
10u	Electrolytic SMD 5x5.3	6
<i>Resistors:</i>		
220	0805	1
1k	0805	2
1k	potentiometer	2

B.2 Bill of Materials: Battery Management PCB

Battery Management Circuit	Package	Quantity
30.1k	0603	1
32.4k	0603	2
Power P-MOS	SOT-23	1

The project; complete with all software code, the application, hardware files and more, can be found online in the github-repo:

<https://github.com/Jurriz/VHF-Unit>

