

# Jury Andrea D'Onofrio

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## Education

Dalle Molle Institute for Artificial Intelligence USI-SUPSI (IDSIA), Master Thesis	Sept 2023 - Sept 2024
Università della Svizzera Italiana, MSc in Artificial Intelligence	Sept 2022 - Sept 2024
Università degli Studi di Milano-Bicocca, BSc in Informatics	Sept 2018 - Mar 2022

## Experience

Sales Business Supporter   Lenovo srl, Segrate (IT)	Feb 2022 - Aug 2022
<ul style="list-style-type: none"><li>Generated statistical performance analysis, (Pre-) processed data for B.I. - Tool depiction</li><li>Managed and utilized the CoData database and Microsoft Office suite for analysis</li><li>Configured custom-to-order products to meet specific client needs</li></ul>	

## Projects

Autonomous Navigation for Nanodrones   IDSIA USI-SUPSI, Lugano (CH)	Sept 2023 - Sept 2024
<ul style="list-style-type: none"><li>Developed an autonomous obstacle avoidance system for nanodrones using sensor fusion on the Crazyflie 2.1 platform</li><li>Integrated vision-based CNNs with an ultrasonic sensor for navigation in low-visibility environments, achieving up to 6.87% improvement in accuracy in smoke-filled scenarios compared to baseline models, while maintaining efficiency with at most 3 FPS less than the baselines</li><li>Utilized Python for data post-processing, model training, validation, and testing, while Webots was used to simulate data collection in the created environments</li></ul>	
Stability Analysis in Graph Neural Networks   USI, Lugano (CH)	Feb 2024 - May 2024
<ul style="list-style-type: none"><li>Verified stability claims and anti-squashing properties of the Anti-Symmetric Deep Graph Network (A-DGN) on the PubMed dataset, achieving an accuracy improvement up to 30% compared to traditional GCN architectures</li><li>Conducted analysis and simulations using Python for stability verification</li></ul>	
Sensor-Based Mapping and Pathfinding in Robotics   USI, Lugano (CH)	Feb 2023 - May 2023
<ul style="list-style-type: none"><li>Developed algorithms for mapping unknown spaces with Robomaster S1 in CoppeliaSim</li><li>Focused on sensor-based room mapping, visualization, and path-finding for real-time processing and accuracy</li><li>Leveraged Python, Matplotlib, Seaborn, and ROS2 for algorithm development and visualization</li></ul>	
Enhanced Code Search with Machine Learning   USI, Lugano (CH)	Sept 2023 - Dec 2023
<ul style="list-style-type: none"><li>Optimized search in a knowledge management system by processing large Python codebases</li><li>Trained models (LSI, TF-IDF, and Doc2Vec), achieving 95% precision with LSI</li><li>Employed Python, ast, deap, Gensim, JSON, Matplotlib, Numpy, nltk, os, Pandas, random, Seaborn, shutil, and Sklearn for code search and data analysis. Used t-SNE for performance visualization</li></ul>	
Smart Intrusion Detection for IoT Devices   USI, Lugano (CH)	Sept 2022 - Dec 2022
<ul style="list-style-type: none"><li>Developed a smart intrusion detection system integrating ToF sensors, a camera, and fingerprint authentication for real-time occupancy monitoring</li><li>Built the system using Arduino for sensor integration and real-time monitoring, achieving approximately 80% reliability due to the sensitivity of the fingerprint sensor</li></ul>	

## Technologies

**Programming:** C, C#, CSS, Java, HTML,  $\text{\LaTeX}$ , Matlab, Python, SQL

**Libraries:** Matplotlib, Numpy, Pandas, Polars, PyTorch, Scikit-learn, Seaborn, TensorFlow

**Tools:** Android Studio, Arduino, GAP8, Git, Linux, ROS2, Tableau, VS Code, Weights & Biases

**Methodologies:** Agile, Scrum

**Languages:** Italian (Native), English (C1)

**Hobbies:** Football, Karate, Swimming, Volleyball