Multivariate probabilty and statistics

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Date of Presentation

Overview

This presentation is \dots

Random variables

Random variable is...

Random vectors

Random vector is...

$$\mathbf{z} = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{pmatrix}$$

Probability density

$$p_z(a) = \frac{p(z \text{ is in } [a, a + \nu])}{\nu}$$

$$p_z(a) = \frac{p(z_i \text{ is in } [a_i, a_i + \nu] \text{ for all } i)}{\nu^n}$$

Marginal and joint probabilities

(Definition, examples)

Marginal:

$$p_{z_1}(z_1) = \int p(z_1, z_2) dz_2$$

or more rigorosly:

$$p_{z_1}(\nu_1) = \int p(\nu_1, \nu_2) d\nu_2$$

Conditional probabilities

(continuous case, discrete case)

$$p(z_2|z_1=a) = \frac{p_z(a,z_2)}{\int p_z(a,z_2)dz_2}$$

or more concisely:

$$p(z_2|z_1=a)=\frac{p_z(a,z_2)}{p_{z_1}(a)}=\text{e.t.c.}$$

for discrete case the integral is replaced by sum, that is

$$P_{z_1}(z_1) = \sum_{z_2} P_{\mathbf{z}}(z_1, z_2)$$

Independence

definition

$$p(z_2|z_1) = p(z_2)$$
 for every z_1 and z_2

which implies that

$$\frac{p(z_1,z_2)}{p(z_1)}=p(z_2)$$
 or otherway around that $p(z_1,z_2)=p(z_1)p(z_2)$

for all z_1 and z_2S

Expectation

(continuous, discrete (maybe otherway around would be more intuitive?))

$$E\{z\} = \int p_z(z)zdz$$

(write the components?)

its linear:

$$E\{a\mathbf{z}+b\mathbf{z}\}=aE\{\mathbf{z}\}+bE\{\mathbf{z}\}$$

similarily for any matrix M

$$E\{Mz\} = ME\{z\}$$

Variance, covariance and correlation

$$(dim = 1, covariance matrix)$$

$$var(z_1) = E\{z_1^2\} - (E\{z_1\})^2 = E\{(z_1 - E\{z_1\})^2\}$$

covariance and correlation

$$cov(z_1, z_2) = E\{z_1z_2\} - E\{z_1\}E\{z_2\}$$

$$corr(z_1, z_2) = \frac{cov(z_1, z_2)}{\sqrt{var(z_1)var(z_2)}}$$

Covariance Matrix

$$\mathbf{C}(\mathbf{z}) = \begin{pmatrix} cov(z_1, z_1) & cov(z_1, z_2) \dots cov(z_1, z_n) \\ cov(z_2, z_1) & cov(z_2, z_2) \dots cov(z_2, z_n) \\ \vdots & \ddots & \vdots \\ cov(z_n, z_1) & cov(z_n, z_2) \dots cov(z_n, z_n) \end{pmatrix}$$

or more concisely:

$$\mathbf{C}(\mathbf{z}) = E\{\mathbf{z}\mathbf{z}^T\} - E\{\mathbf{z}\}E\{\mathbf{z}\}^T$$

Independence and covariance

the relation

Bayesian inference

Baye's rule

Non informative priors

definition

Bayesian inference as a incremental learning process

Explanation



(statistical model, estimation, likelihood & log-likelihood)

Maximum likelihood and maximum posteriori

(definition, definition)



Examples from the template on the next slides:

Tables and Figures

- Use tabular for basic tables see Table 1, for example.
- You can upload a figure (JPEG, PNG or PDF) using the files menu.
- ▶ To include it in your document, use the includegraphics command (see the comment below in the source code).

Item	Quantity
Widgets	42
Gadgets	13

Table 1: An example table.

Readable Mathematics

Let X_1, X_2, \ldots, X_n be a sequence of independent and identically distributed random variables with $\mathsf{E}[X_i] = \mu$ and $\mathsf{Var}[X_i] = \sigma^2 < \infty$, and let

$$S_n = \frac{X_1 + X_2 + \dots + X_n}{n} = \frac{1}{n} \sum_{i=1}^{n} X_i$$

denote their mean. Then as n approaches infinity, the random variables $\sqrt{n}(S_n - \mu)$ converge in distribution to a normal $\mathcal{N}(0, \sigma^2)$.