

Chp1-pre-slam

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 1. CPP
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1. Project Structure

total 17 directories, 57 files

the file system of this project named 'preslam':

- `.vscode` contains the configure files for VSCode
- `bin` the binary output directory
 - `preslam`
- `build` the cmake binary directory for build
- `include` the include directory contains cpp head files
 - `helloslam.h`
- `lib` the lib output directory
 - `libhelloslam.so`
- `src` directory constains cpp source files
 - `helloslam.cpp`
- `.gitignore` the gitignore file
- `CMakeLists.txt` the cmake file
- `main.cpp` the main source file
- `readme.md` the readme file

2. Main Apis

1. CPP

■ void hello_slam()

```
1  /**
2   * @brief a no-return function to print "hello, slam!"
3   */
```

2. CMake

```
1  # Sets the minimum required version of cmake
2  cmake_minimum_required(VERSION 3.10)
```

```
1  # Set the name of the project
2  project(preslam VERSION 0.0.1)
```

```
1  # Add include directories to the build
2  include_directories(${CMAKE_SOURCE_DIR}/include)
```

```
1  # Add a library to the project using the 'helloslam.cpp'
2  add_library(${LIB_NAME} SHARED ${CMAKE_SOURCE_DIR}/src/helloslam.cpp)
```

```
1  # Add an executable to the project using the 'main.cpp'
2  add_executable(${CMAKE_PROJECT_NAME} ${CMAKE_SOURCE_DIR}/main.cpp)
```

```
1  # link the lib to the executable
2  target_link_libraries(${CMAKE_PROJECT_NAME} PRIVATE ${LIB_NAME})
```

3. Source Code

1. CPP

■ helloslam.h

```
1  #pragma once
2
3  #include <iostream>
4
5  namespace ns_chp1 {
6  /**
7   * @brief a no-return function to print "hello, slam!"
8   */
9  void hello_slam();
10 } // namespace ns_chp1
```

■ helloslam.cpp

```

1 #include "helloslam.h"
2
3 namespace ns_chp1 {
4 void hello_slam() {
5     // print "Hello, slam!"
6     std::cout << "Hello, slam!" << std::endl;
7     return;
8 }
9 } // namespace ns_chp1

```

■ main.cpp

```

1 #include "helloslam.h"
2
3 int main(int argc, char const *argv[]) {
4     // call 'hello_slam'
5     ns_chp1::hello_slam();
6     return 0;
7 }

```

2. CMake

■ CMakeLists.txt

```

1 # Sets the minimum required version of cmake
2 cmake_minimum_required(VERSION 3.10)
3
4 # Set the name of the project
5 project(preslam VERSION 0.0.1)
6
7 # Add include directories to the build
8 include_directories(${CMAKE_SOURCE_DIR}/include)
9
10 # Set a environment variable to the lib name
11 set(LIB_NAME helloslam)
12
13 # set the lib output directory
14 set(CMAKE_LIBRARY_OUTPUT_DIRECTORY ${CMAKE_SOURCE_DIR}/lib)
15
16 # set the bin output directory
17 set(CMAKE_RUNTIME_OUTPUT_DIRECTORY ${CMAKE_SOURCE_DIR}/bin)
18
19 # Add a library to the project using the 'helloslam.cpp'
20 add_library(${LIB_NAME} SHARED ${CMAKE_SOURCE_DIR}/src/helloslam.cpp)
21
22 # Add an executable to the project using the 'main.cpp'
23 add_executable(${CMAKE_PROJECT_NAME} ${CMAKE_SOURCE_DIR}/main.cpp)
24
25 # link the lib to the executable
26 target_link_libraries(${CMAKE_PROJECT_NAME} PRIVATE ${LIB_NAME})

```