Diwaakar Jayaprakash

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Summary

Mechanical engineering undergraduate with hands-on experience in CAD modeling, motion analysis, and interdisciplinary tools like MATLAB and Python. Seeking to apply design and data analysis skills in tech-driven environments.

Education

IIITDM Kancheepuram – B.Tech in Mechanical Engineering

2023 - Present

Relevant Courses: Kinematics & Design of Machines, Material Science, Heat Transfer, Manufacturing Processes

Technical Skills

- Design & CAD: SolidWorks (Motion Analysis), Fusion 360, OnShape, AutoCAD
- Simulation & Analysis: Basic FEA, CFD
- **Programming:** Python, MATLAB (basic), MySQL, C++
- Core Engineering: Machine Design, Kinematics, Material Selection
- Manufacturing: CNC Machining, 3D Printing, Laser Cutting
- Documentation: Canva, MS PowerPoint, MS Sheets / Google Sheets

Projects

Science Cache System, MaRS Rover Society (Startup, Est. 2020)

Apr - Aug 2024

- Designed a modular system for efficient sample storage and retrieval.
- Created CAD models using Fusion 360 and OnShape; fabricated for IRC 2025.

Mini Rover - Chassis Design, MaRS Rover Society

Sep – Oct 2024

• Designed rover chassis and performed motion/structural simulations in **SolidWorks**.

IRC 2025 – Science Cache System, MaRS Rover Society

Nov 2024 – Feb 2025

• Led cache system integration for competition using CAD and rapid prototyping tools.

Experience & Internships

Tech Mahindra – ASML Semiconductor Dept. Intern, Bangalore

May – Jul 2025

- $\bullet\,$ Analyzed semiconductor machinery components under ASML workflow.
- Used MATLAB for CPD data analysis, visualization, and trend extraction.
- Coordinated across mechanical and data teams for design validation and workflow clarity.

Assistant – EV Safety & Battery Systems

Mar – Apr 2025

- Assisted in thermal and load-based analysis using ANSYS and thermal cameras.
- Supported conveyor design and hands-on testing with machining tools and fixtures.

Mechanical Team Member, MaRS Rover Society (Startup)

Mar 2024 – Present

- Designed the Science Cache and Ubiquity Holder for IRC 2025 competition.
- Currently developing the **Gripper** and **Modular Chassis** for ERC 2025.
- Hands-on with CNC machining, 3D printing, and laser cutting for rover parts.

Achievements

- European Rover Challenge (ERC 2025) Ranked 4th globally among 50+ teams.
- International Rover Challenge (IRC 2025) Ranked 16th globally among 50+ teams.