Subspace of R"

O includes (D)

Transpose $(A_{ij})^{\mathsf{T}} = A_{ji}$ Inverse Vectors = CTAT Rn - nx1 matru Linear combo 1>row > Ecol, Ecol2 Ecol3 12 COI -> Zrow, Zrow, Zrows to becomes 1 nxi col Rotation Matrix Ao = [cos o -sino coso] (multiply by A, Y 0= & Row Echelon O o rows @ bottom @ leading entries to right of prev 3 entres under leading -> 0 Reduced RE On RE form ② leading entries = \emptyset 3 contries above & below leading are Ø Free Variables - Found in nonpivot cols -∞ solutions - Linear Dependant > n>m - Ax = Ø non Ø solution -> as solutions Linear Independence - A文 = Ø Ø solution → I solution

set of vectors

Consistancy

Multiplication

> every \$ ∈ IRM, Ax= b has solution

→ B linear combo of col vectors in A

[> RRE of [AIB] has no [a... \$ 1d]

-> RREF (A) has privat in every row

(+ AX = B is consistant

- (Amxr)(Brxn) = ABmxn

- entry is = Z (Arowi-Boolj)

- AB = BA = In if RRE(A) = In - [A B] roco ors [In A-1B] - A [2 b] -> A-1 = 1 - [d-b] - (AB)-1 = B-1 A-1 - clementary row ops are invertible & reversible - P = (E,)(E2)... (EN) 4 PA = R & P-1=A Oset up [Alln] @ Find RRE(A) so [RIB] 3 if R = In, A-1 = B Column Correspondance - if RRE(A) = R, if J# col R is lin combo of other col in R. then it call a same is also lin combo of same col in A as R 4 same coeff. - used often in lin dep spans / sets of vectors LU Decomposition row - U = RE(A) no exch -L=In w/ ri+crj >ri on u means Ly = -C [%] = U & [%] = L -A文部→LU文=B_where -AX=B→ LUX=B where

UX=3→ Ly=B

OFind L&U

(Desolve for y y [LIB]

(Desolve for x y [U]y] - Exam 2 (3.1-5,3)for each BERn - nullity = 0; rank = n - nullity = 0; rank = n - 1 vector is a multiple of another is all possible vectors which can be achieved as linear combos of a -1c 15 \$ in the span of 5? ⇒ coun To be made by the vectors in s? ープ belongs to S if Ax = マ is consistent O augment [A17] @find RE of [AIT] (+ cols of A span Rm

@ closed under addition 立+立 21 02 、m 知る分 @ closed under scalar mult でin, so is cc - subspace = span of vector set - generating set = vectors in the set of the span Basis (exclude {\$} 3) to lin indep generating set * null space - all vectors who are solutions to AX = \$\text{0}\$ set other free vers O Find RE or RRE of A free vors @ null A = span of coefficients & of free variables = column space - subspace
general ted by col vectors COIA = Span EAT, AZ, ... 3 トラウィレ COIYS O [AI改] @ rref 1 consistant? >> basis of Col A O rref A @ basis = pivot cols of ag A (not prot of rrefA) -row space - cubspace generated by rows of A > m1: rowsA = cols AT 4 m 2: non prows of rref(4) Dimension 13 # vectors in basis of V - prove set B boas of V Determinant oxn -Cofactor Expansion 2 B lin indep A = [a b c] a (12 f1) - b (19 f1) + c (1g 51) Allati) -d(1hel) +9(1271) - det d or diag = product of diagonal - if det = 0, lin indep & invertible -det (AB) = (det A)(det B) $-det(A^{-1}) = \frac{1}{det}A$ - row swap -> detB = -detA - row mult -> detB = kdetA for each row multiplied - det using row ops O Find RE form @det = product diag 3 apply Cramer's Rule (Ax=b) $M_1 = \begin{bmatrix} \overrightarrow{b} & \overrightarrow{A_2} & \overrightarrow{A_3} \end{bmatrix} M_2 = \begin{bmatrix} \overrightarrow{A_1} & \overrightarrow{b} & \overrightarrow{A_3} \end{bmatrix}$ O Find det A 2) Find det of Mi's 3 x = [detM, detMz --]T

Oshow B contained inv 3 dim V = # vectorsin B -dim (Null) = # free vars [dim(Row) = rank = dim (Col) = dim (RowT - any basis of Vhas dim (v) # of vectors (gen sets ≥ dim # vectors) Eigenvalues & Evectors - AV = XV (multiplying 4 by evector only stretches vector) - evector has I evalue -evalue can have >1 evector Ode+ (A-)I) for char poly 3 x = roots of char poly 3 null (A-XI) or rect (A-XI) gives exectors for > 8 -if det A=0, 0 is an exalue geo mutiplicity = alg mult - diag values in Amotox

Diagonalization - A = PDP-1 - A is similar to D -> same charater poly same evalues & # independent evectors - P = [evectors] - D= [x, x2...] - A diagonalizable if > evectors of A form abasis for Rn > Zmultiplicites=n 2 dim(espace) = multiplicity of corresponding X -An = PDnp-1 Norm & Dot Product norm = || V || = \(\nabla_1^2 + \nabla_2^2 + \dots + \nabla_1^2 \) unit vector マニリツリ dot product v.v= u,v,+u,v,+. by MTN, t m. n= 0 コマーマース・マース・マース・マース・ス・ス・コール・ス・ス・コール = 112 - WII Adot pt 10-71 ≤ 11011-11711 1호구하기 스 11호기 + 11호기 Orthogonal -set of vectors ortho if each pair is ortho will be linindep > if dim=n, will be a basis for Rn -Gramm Schmidt () V = W , W & S 3 4 = 17 - 6107 N'N' DI (vi) ..., vis 15, an MARCAD orthogonal bases of Ro orthogonal compliment - (Row A) = Null A = Noll AT - dims + dims+= n - basis of St = basis Noll A Ortho decomp は=(は、水)パナ・・・・ (はな)が www s vector in subspace closest to it Projection Matrix ? Pw=CCCTCJ-1CT Lacols of C for basis of W マートラス 谷一分=学 Wota terp=11211

eigen span

are evalues

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Least Square Approx
-line of best fit w min Edist2
                                                    [a,] = (CTC)-1CTy
                                                                  C = \begin{bmatrix} \vec{v}_1, \vec{v}_2 \end{bmatrix} \vec{v}_1 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec{v}_2 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec{v}_2 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec{v}_3 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec{v}_4 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec{v}_3 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec{v}_4 = \begin{bmatrix} \vec{v}_1 \end{bmatrix} \vec
                  line > y= ao+ aix
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Orthogonal Matrices

- nxn matrix is orthogonal if cols are an orthonormal basis of R"
- eguivalents
 - a orthogonal
 - -> can use to test - QTQ = In orthogonality
 - Q-1 = QT
 - v. v = 0 v. 0v
 - 115011 = 11511 -
- properties
 - de+ Q = ±1
 - product of 2 ortho matrices is ortho
 - QT & W-1 ortho

Symmetric Matrices (AT=A)

- Asymm y evectors ust who have distinct evalues hush, ull (but if WIV & distinct -> A not always symm)
- A symm iff evectors of A are orthonorm basis of Rn
- if A symm, A is diagonalizable & Portha > PTAP=D
- Find ortho diag
 - 1) Find evalues I evector
 - 2) Make evectors into orthonorm y GrammSchmidt
- Spectral decomposition (if Asymm)) same $A = PDP^{T}, P = [\vec{\alpha}_{1}, ..., \vec{\alpha}_{n}] D = [^{\lambda_{1}} \cdot ...]$
 - $= \lambda_1 \overrightarrow{\alpha_1} \overrightarrow{\alpha_1}^T + \dots + \lambda_n \overrightarrow{\alpha_n} \overrightarrow{\alpha_n}^T$
 - $= \lambda_1[P_1] + \cdots + \lambda_n[P_n]$