Eigenfunction of the Harmonic Oscillator and its Eigenvalues

Consider the following LTIC system which describes the mass of a block which is oscillating via a spring:

$$y''(t) + \frac{b}{m}y'(t) + \frac{k}{m}y(t) = x(t)$$
 (1)

The eigenfunction of any LTIC system is the exponential function $y(t) = e^{\lambda t}$. Where λ is a constant. To see this we simply substitute this solution into (1) to see:

$$\left(\lambda^2 + \frac{b}{m}\lambda + \frac{k}{m}\right)e^{\lambda t} = x(t) \tag{2}$$

I.e if the output is $y(t) = e^{\lambda t}$, then the input x(t) is a re-scaling of this input function. We know that if we let x(t) = 0 to investigate the natural behaviour of the system (the zero input response) we require the following restriction on λ to satisfy (2):

$$\lambda^2 + \frac{b}{m}\lambda + \frac{k}{m} = 0 \tag{3}$$

What exactly is equation (3)? From an introductory ODE class one knows that equation (3) gives all possible solutions to the equation (1) when x(t) = 0. However, this equation is much more fundamental to the system at hand, and those who have investigated ODEs under Laplace transforms may find the following results quite familiar.

To further investigate equation (3), let us try to find it under different circumstances. Firstly, let x''(t) = v'(t) and x'(t) = v(t), then we obtain the following system of equations:

$$\begin{cases} v'(t) = -\frac{b}{m}v(t) - \frac{k}{m}x(t) \\ x'(t) = v(t) \end{cases}$$

We may write this system as the following matrix equation:

$$\begin{bmatrix} x'(t) \\ v'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{b}{m} \end{bmatrix} \begin{bmatrix} x(t) \\ v(t) \end{bmatrix}$$
 (4)

This equation effectively describes the **state space** or **phase space** of the system. This is because given any initial $x(t_0), v(t_0)$ we may find $x'(t_0), v'(t_0)$ and the plot of all such points shows how the system evolves over time.

It may seem as if we are off track with regards to rediscovering equation (3), however we are still on the case. Consider the position vector to some point in the phase space $(x(t_k), v(t_k))$, and let L be the line which is the span of this position vector. The question we wish to ask is: "Which sets of initial data, when acted on by the system, remain on the line L defined by this initial data?" Or phrased differently: "What are the eigenvalues of the matrix equation (4)?" To find the eigenvalues all we need is to set the determinant $\det(A - \lambda I d_n)$ for the matrix in (4) to zero:

$$P(\lambda) = \det = \begin{bmatrix} -\lambda & 1\\ -\frac{k}{m} & -\frac{b}{m} - \lambda \end{bmatrix} = \lambda^2 + \frac{b}{m}\lambda + \frac{k}{m} = 0$$
 (5)

Equations (4) and (6) are identical. So we have determined that when substitution the eigenfunction into the system we obtain the equation for the eigenvalues for the matrix which describes the system. Further we know can state the following:

The linear combination of eigenfunctions for the harmonic oscillator ODE, when evaluated at the eigenvalues for the matrix which describes the harmonic oscillator system, is the general solution to the ODE at hand.

We know this to be true since two solutions λ_1, λ_2 to equation (3) give rise to the general solution

$$x(t) = \alpha e^{\lambda_1 t} + \beta e^{\lambda_1 t}$$

for the system described by equation (1) with y(t) = 0.

There is more to be uncovered by considering the Laplace transform of equation (1) where x(t) = 0 and initial conditions $y(t_0) = \xi$, $y'(t_0) = \eta$:

$$\mathcal{L}\left\{y''(t) + \frac{b}{m}y'(t) + \frac{k}{m}y(t)\right\}(s) = \mathcal{L}\left\{y(t)\right\}(s)\left(s^2 + \frac{b}{m}s + \frac{k}{m}\right) = \left(s + \frac{b}{m}\right)\xi + \eta \tag{6}$$

We may rewrite equation (7) as

$$\mathcal{L}\left\{y(t)\right\}(s) = \frac{\left(s + \frac{b}{m}\right)\xi + \eta}{s^2 + \frac{b}{m}s + \frac{k}{m}} \tag{7}$$

Those with signal processing experience know that (8) describes the frequency content of (1). Notice that when the denominator of (8) is zero, then we have a frequency, s, which is an eigenvalue of (4).