DSP Homework 7 Matlab Code

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T = 1/20000;
Omegap = 2*pi*7000*T;
                         Omegas = 2*pi*8000*T;
Lh = 141;
K = 10*Lh;
k = (0:K-1);
Omegak = k*2*pi/K;
OmegaPC = 2*pi*1500*T;
                         OmegaPR = 2*pi*3000*T;
parablength = Omegak.*(Omegak>=0 & Omegak<=OmegaPR);</pre>
% OmegaPC = 2*pi*750*T; OmegaPR = 2*pi*1500*T;
% parablength = Omegak.*(Omegak>=Omegap & Omegak<=OmegaPR);</pre>
sawPer = 1000*2*pi/20000;
xsawPer= Omegak.*(Omegak > OmegaPR);
sinfn = (.7943 - .707) *sawtooth(1/sawPer*xsawPer) + .7;
% sinfn = ((xsinPer - OmegaPC).^2).*sawtooth(1/sinPer*xsinPer)
 + .7943;
plot(xsawPer, sinfn);
xsauce = [0 OmegaPC OmegaPR]; ysauce = [.7943 .8915 .7943]; psauce =
 polyfit(xsauce,ysauce,2);
xu=linspace(0,OmegaPR,10);
parabola = [polyval(psauce,parablength)];
plot(parablength, parabola)
Q = 50.0*(Omegak<=Omegas) + 1.0*(Omegak>=Omegap & Omegak < OmegaPR)
    1.0*(Omegak>=OmegaPR & Omegak < 1.5) + 1*(Omegak>=1.5 & Omegak <
Q(fix(K/2)+2:end) = Q(round(K/2):-1:2);
Hd = (0.*(Omegak>Omegap) + parabola.*(Omegak>=0 & Omegak<=OmegaPR) ...</pre>
     + sinfn.*(Omegak >= OmegaPR & Omegak <=
 Omegap)).*exp(-1j*k*pi*(Lh-1)/K);
Hd(fix(K/2)+2:end) = conj(Hd(round(K/2):-1:2));
1 = (0:Lh-1)'; a = exp(1j*1*Omegak)*Q.'/K; b =
 \exp(1j*l*Omegak)*(Hd.*Q/K).';
a = real(a); b = real(b);
A = toeplitz(a); h = (A \b);
n = (0:Lh-1)';
subplot(211);
stem(n,h);
Omega = linspace(0,pi,1001);
H = polyval(h, exp(1j*Omega)).*exp(-1j*(Lh-1)*Omega);
subplot(212);
plot(Omega, 20*log10(abs(H)))
deltap = 2*max(abs(abs(H(Omega>=Omegap))-1))
```

```
deltas = max(abs(H(Omega<=Omegas)))</pre>
figure;
plot(Q);
Morder = length(h);
[hMax,hMaxIndex] = max(h)
% scale = abs((2^{(16-1)-50})/h(hMaxIndex-1))
scale = abs((2^15)/(abs(sum(h))));
  %Q notation
scale = 2.^nextpow2(scale)
hInt = floor(h*(scale));
subplot(211);
stem(n,hInt);
Omega = linspace(0,pi,1001);
H = polyval(hInt, exp(1j*Omega)).*exp(-1j*(Lh-1)*Omega);
subplot(212);
plot(Omega, 20*log10(abs(H)))
deltap = 2*max(abs(abs(H(Omega>=Omegap))-1))
deltas = max(abs(H(Omega<=Omegas)))</pre>
        fid = fopen('K22_Project_Framework/coef.h','w');
        fprintf(fid, '#define Korder %i \n', uint8(Morder));
        fprintf(fid,'int h[Korder] = { \n');
        for Korder = 1:Morder-1
            fprintf(fid,'%i,\n', hInt(Korder));
        end
        fprintf(fid,'%i }; \n', hInt(Korder));
        fclose(fid);
save('bpg.mat','hInt');
deltap =
    1.9997
deltas =
    0.8921
hMax =
    0.5459
hMaxIndex =
    71
```

scale =

65536

deltap =

4.1156e+04

deltas =

5.8468e+04





